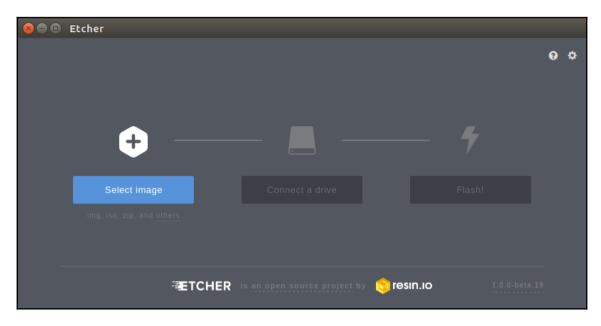
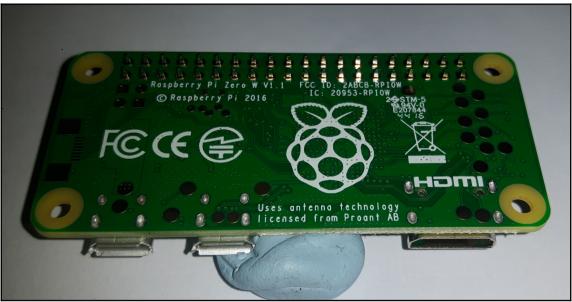
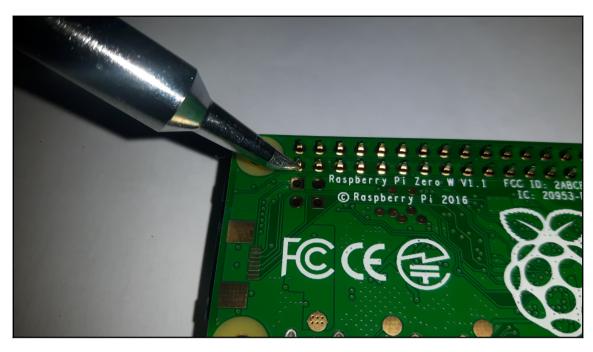
Chapter 1: About the Raspberry Pi





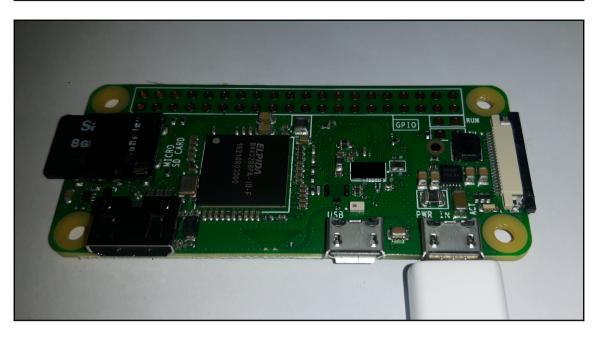




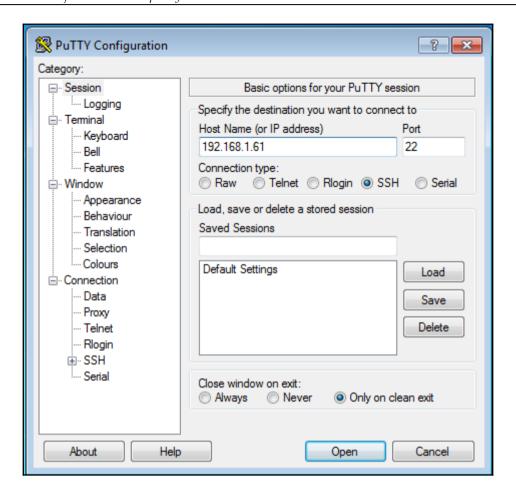








				Go to Access Control to allow or block device
		Access Control: Turn	Refresh	
ired Devices				
#	Device Name	IP Address	MAC Address	Connection Type
1	JON-DESKTOP	190,168.1.17	90 E9 BA 16 F9 D0	wired
2	 Unknown 	192,160,1.60	08:E8:74:A1:29:30	wired
	evices (Wireless intruders also show up here		****	
#	<u>Device Name</u>	IP Address	MAC Address	Connection Type
1	ANDROID-CBMCBCP60AF6077	190.160.1.30	CB:14:79:59:6F:0E	wireless
	ANDROID-45F3285AAM4538F9	192.168.1.30	F4:09:D0:4C:AC:45	wireless
2				
3	RASPBERRYPI	192.168.1.61	B8:27:EB	wireless
		192.168.1.61	B8:27:EB	wireless wireless
3	RASPBERRYPI			
3 4	RASPBERRYPI	192,168.1.30	C4 E9 84 A0 CC 4E	wireless
3 4 5	RASPBERRYPI	192,168.1.30	C4 E9 84 A0 CC 4E	wireless
3 4 5	RASPBERRYPI	192,168.1.30	C4 E9 84 A0 CC 4E	wireless
3 4 5 SHz Wireless Dev	RASPBERRYPI rices (Wireless intruders also show up here)	192,166.1.36	GREEN ARCIDORE GREC ARAS DA MA	wireless wireless



```
pi@raspberrypi:~

pi@raspberrypi:~

pi@raspberrypi:~

pi@raspberrypi:~

classword for pi.

classword:

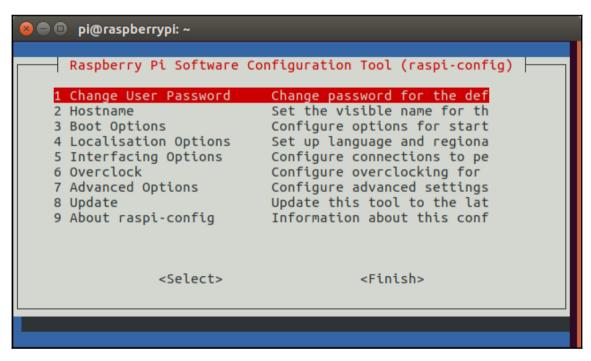
Enter new UNIX password:

Retype new UNIX password:

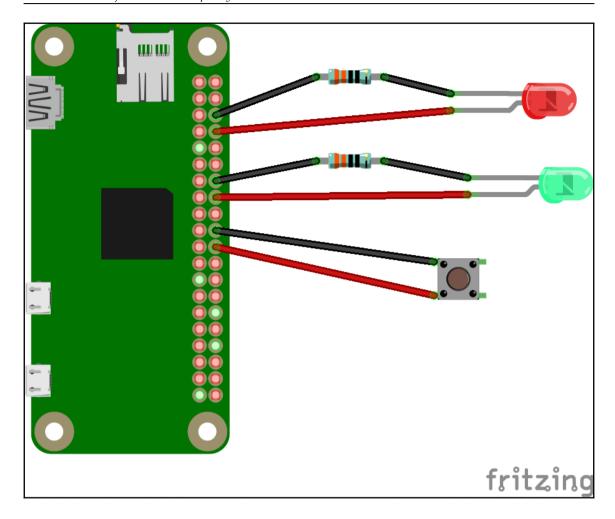
passwd: password updated successfully

pi@raspberrypi:~

pi@raspberrypi:
```



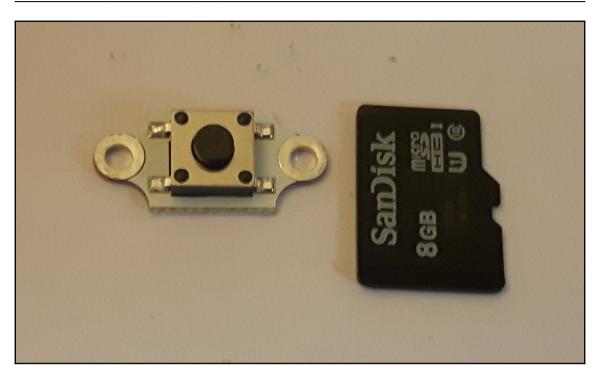
```
🔊 🖨 🗊 🏻 pi@wearablepi: ~
Get:1 http://archive.raspberrypi.org jessie InRelease [22.9 kB]
Get:2 http://mirrordirector.raspbian.org jessie InRelease [14.9 kB]
Get:3 http://archive.raspberrypi.org jessie/main armhf Packages [147 kB]
Get:4 http://mirrordirector.raspbian.org jessie/main armhf Packages [8,981 kB]
Get:5 http://archive.raspberrypi.org jessie/ui armhf Packages [57.6 kB]
Ign http://archive.raspberrypi.org jessie/main Translation-en_GB
Ign http://archive.raspberrypi.org jessie/main Translation-en
Ign http://archive.raspberrypi.org jessie/ui Translation-en GB
Ign http://archive.raspberrypi.org jessie/ui Translation-en
Get:6 http://mirrordirector.raspbian.org jessie/contrib armhf Packages [37.5 kB]
Get:7 http://mirrordirector.raspbian.org jessie/non-free armhf Packages [70.3 kB
Get:8 http://mirrordirector.raspbian.org jessie/rpi armhf Packages [1.356 B]
Ign http://mirrordirector.raspbian.org jessie/contrib Translation-en GB
Ign http://mirrordirector.raspbian.org jessie/contrib Translation-en
Ign http://mirrordirector.raspbian.org jessie/main Translation-en GB
Ign http://mirrordirector.raspbian.org jessie/main Translation-en
Ign http://mirrordirector.raspbian.org jessie/non-free Translation-en_GB
Ign http://mirrordirector.raspbian.org jessie/non-free Translation-en
Ign http://mirrordirector.raspbian.org jessie/rpi Translation-en GB
Ign http://mirrordirector.raspbian.org jessie/rpi Translation-en
Fetched 9,333 kB in 31s (294 kB/s)
Reading package lists... Done
pi@wearablepi:~ $
```

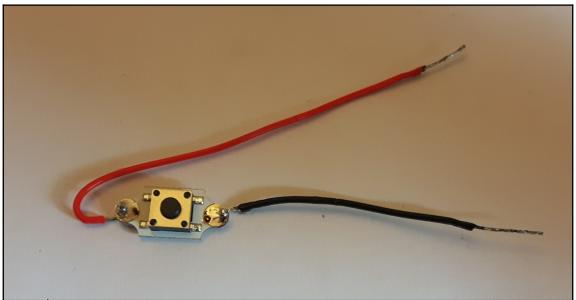


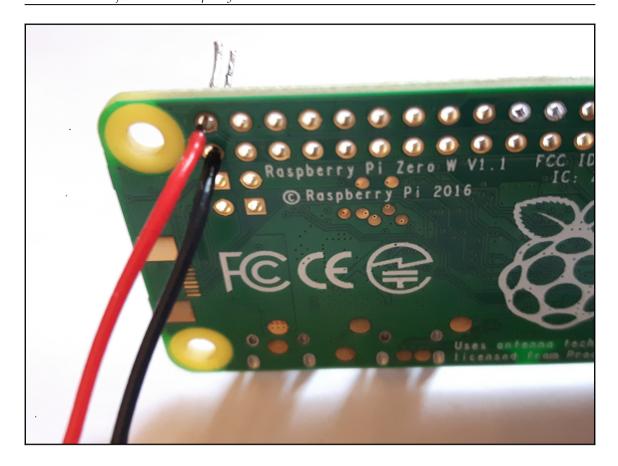
Chapter 2: Scrolling LED Badge

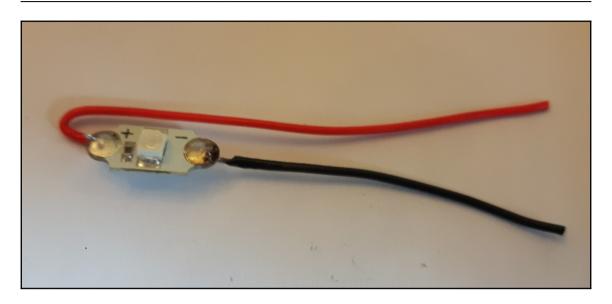
```
pi@wearablepi:~ $ sudo systemctl status scrollBadge.service -l
scrollBadge.service - Scroll Badge Service
Loaded: loaded (/lib/systemd/system/scrollBadge.service; enabled)
Active: active (running) since Mon 2017-04-10 21:17:43 UTC; 40s ago
Main PID: 633 (scrollBadge.py)
CGroup: /system.slice/scrollBadge.service
633 /usr/bin/python3 /home/pi/WearableTech/Chapter2/scrollBadge.py

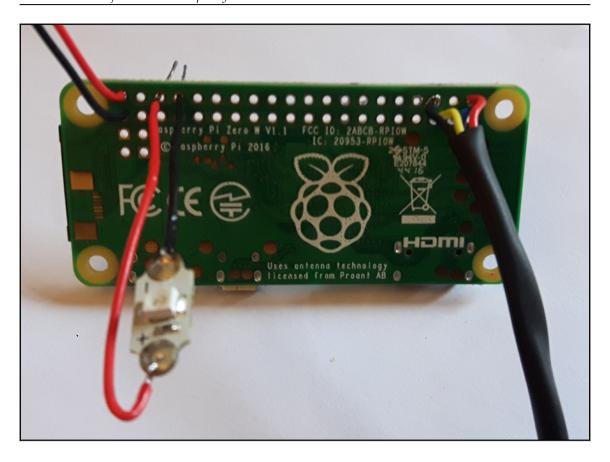
Apr 10 21:17:43 wearablepi systemd[1]: Starting Scroll Badge Service...
Apr 10 21:17:43 wearablepi systemd[1]: Started Scroll Badge Service.
pi@wearablepi:~ $
```







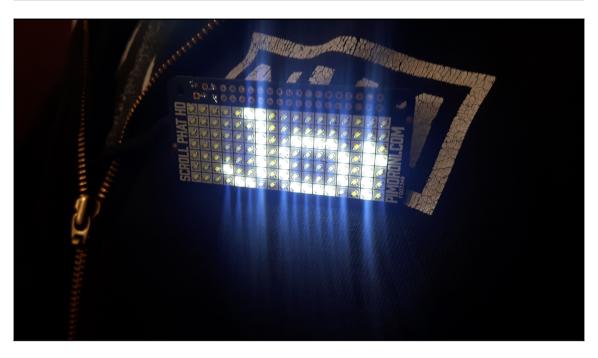


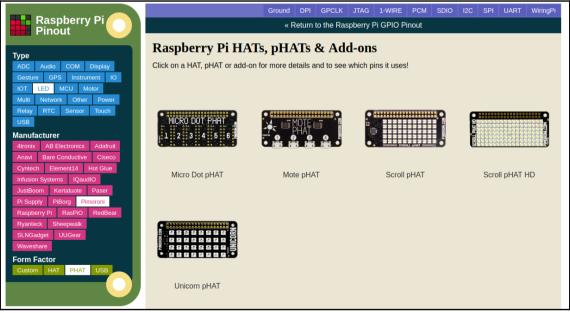


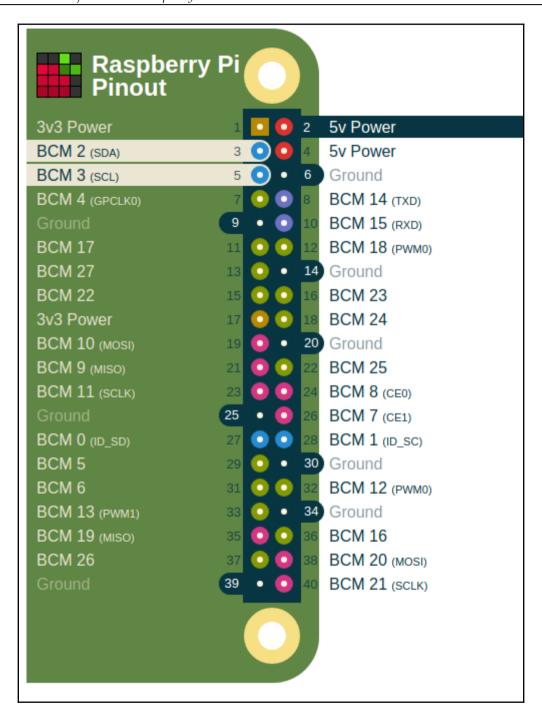


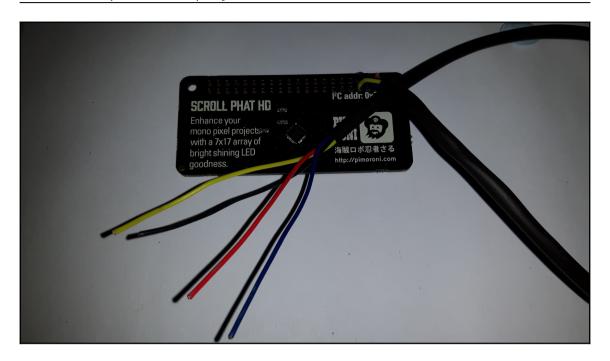


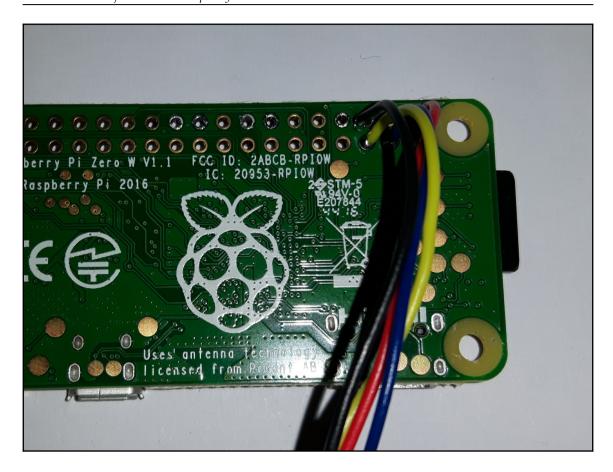


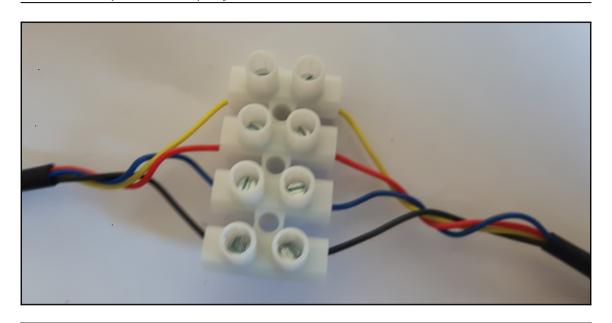


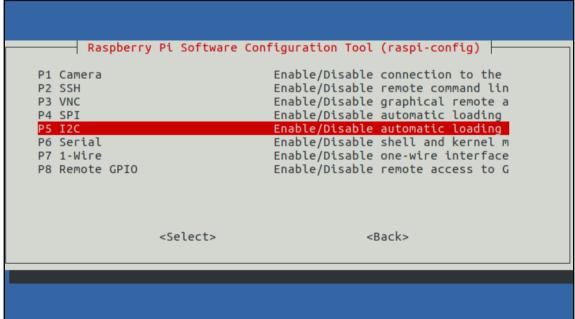




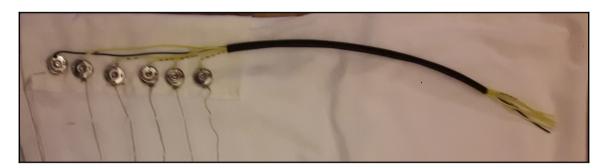


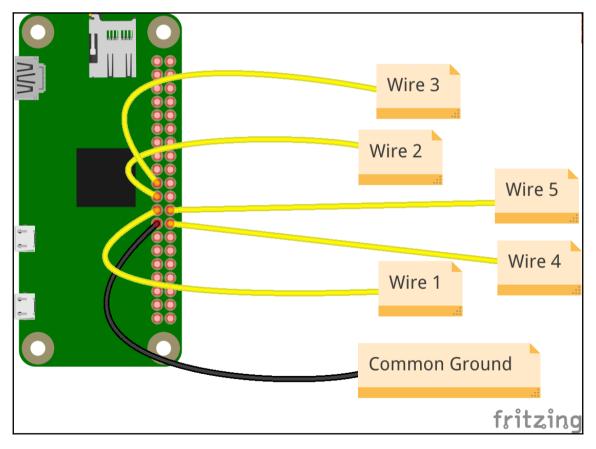






Chapter 3: Sewable LEDs in Clothing





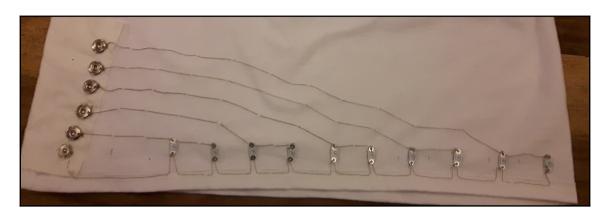










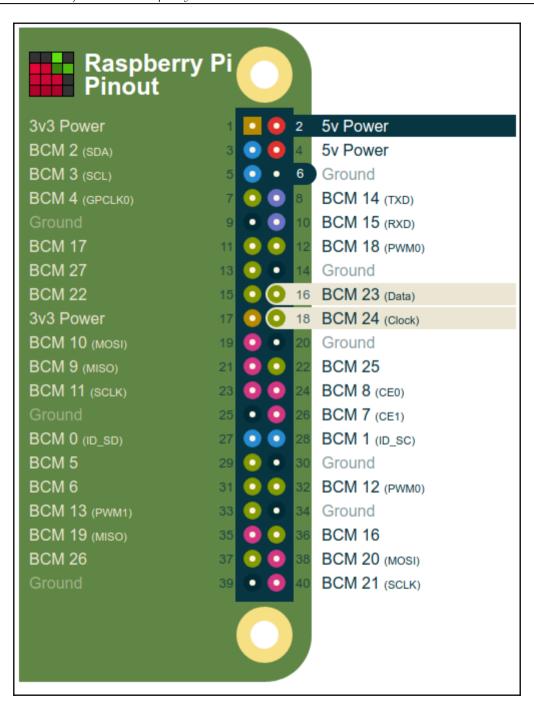


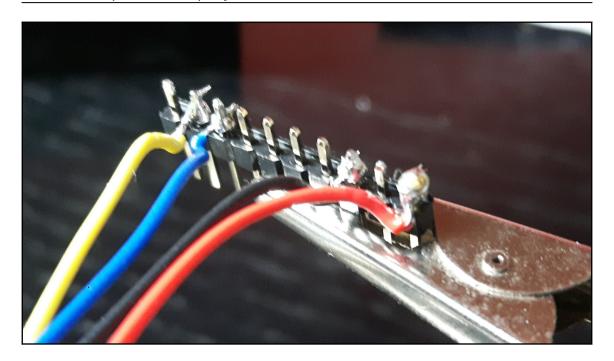


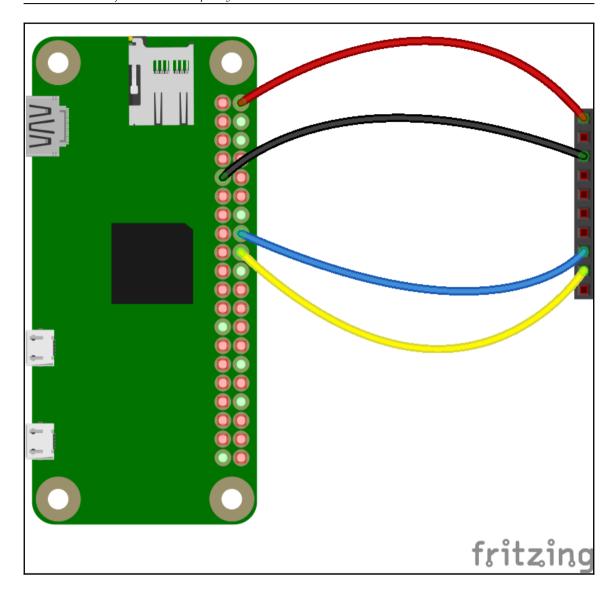
Chapter 4: A Motion-Reactive LED Cap

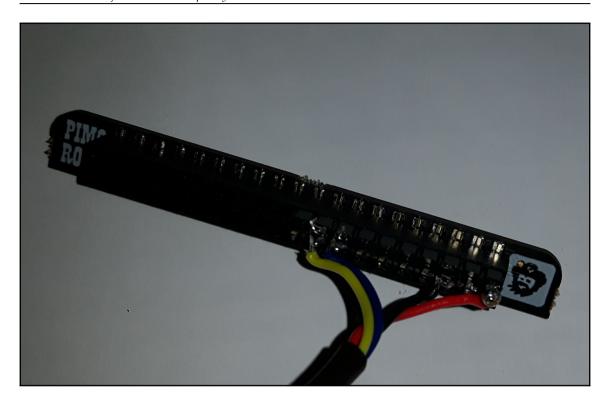
```
pi@wearablepi: ~/WearableTech/Chapter4/adxl345-python
pi@wearablepi: ~/WearableTech/Chapter4/adxl345-python $ ls -l
total 16
-rw-r--r-- 1 pi pi 3181 Apr 30 10:31 adxl345.py
-rw-r--r-- 1 pi pi 634 Apr 30 10:31 example.py
-rw-r--r-- 1 pi pi 1504 Apr 30 10:31 LICENSE.txt
-rw-r--r-- 1 pi pi 893 Apr 30 10:31 README.md
pi@wearablepi: ~/WearableTech/Chapter4/adxl345-python $
```

```
■ pi@wearablepi:
d/WearableTech/Chapter4/adxt345-python
   y = -0.040G
   z = -0.916G
ADXL345 on address 0x53:
  X = -0.028G
  v = -0.044G
   z = -0.916G
ADXL345 on address 0x53:
   x = -0.040G
  y = -0.052G
   z = -0.912G
ADXL345 on address 0x53:
   x = -0.028G
  y = -0.036G
   z = -0.912G
ADXL345 on address 0x53:
   x = -0.032G
  y = -0.048G
   z = -0.900G
```

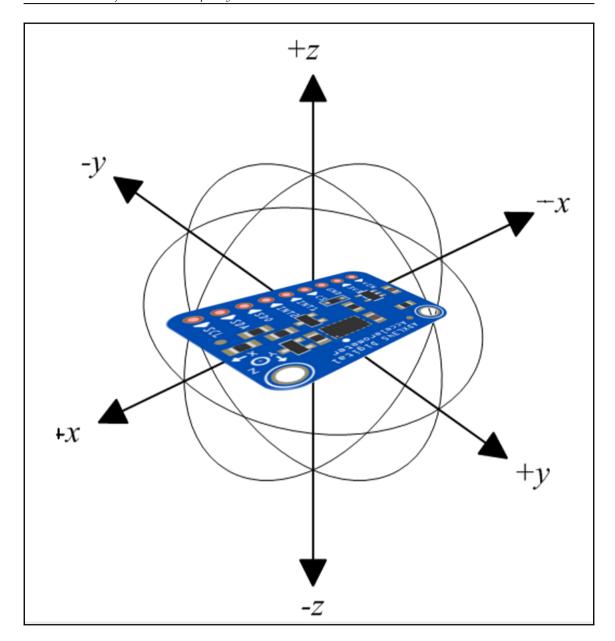


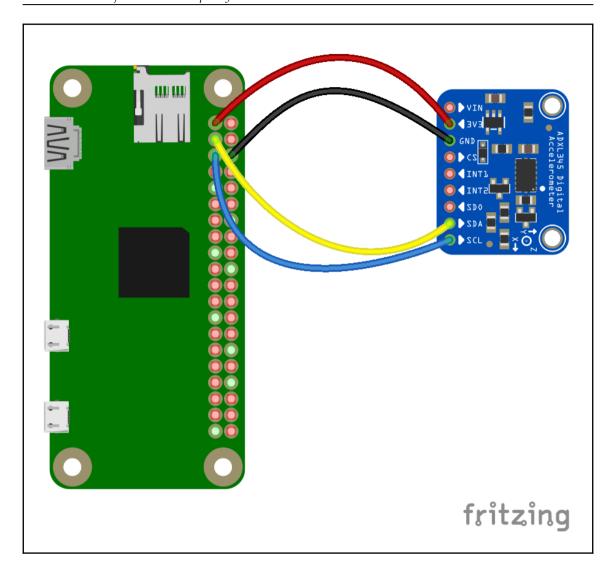






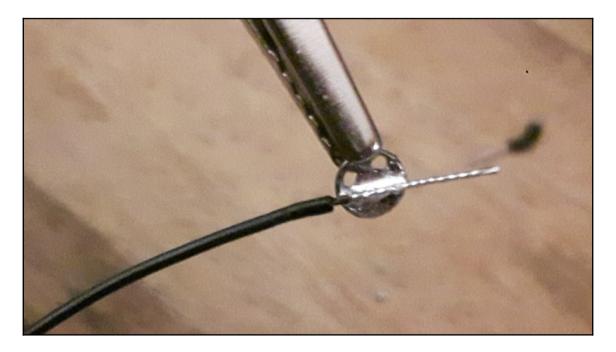


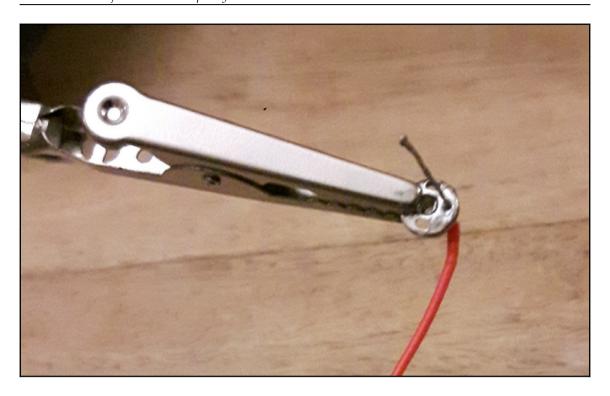


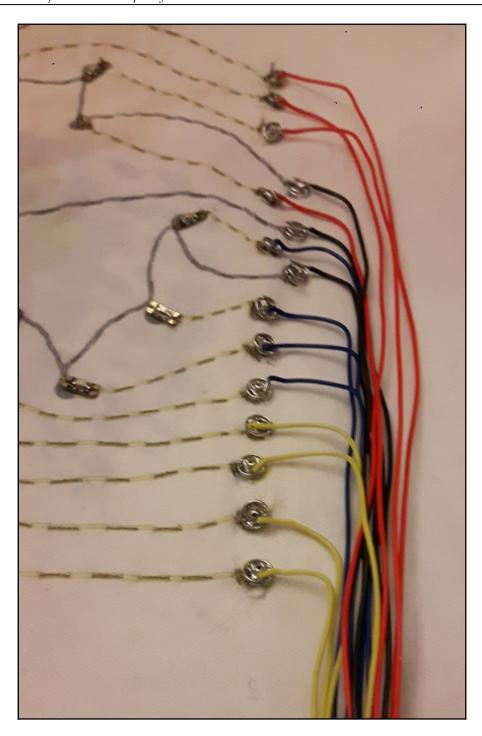




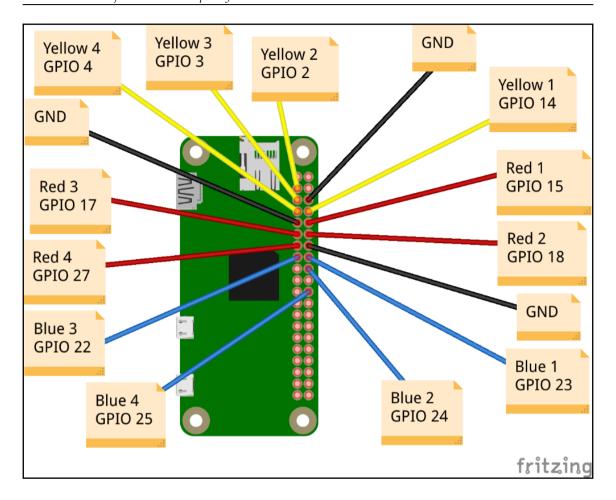
Chapter 5: A Tweet-Activated LED T-Shirt



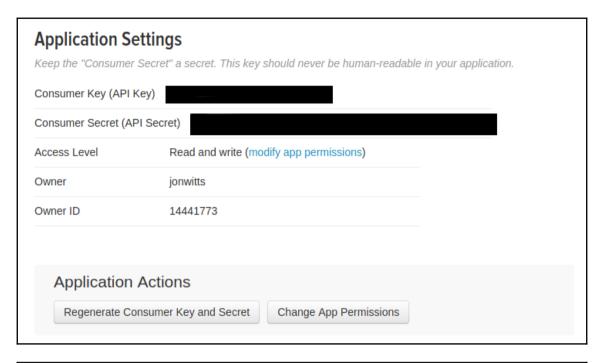


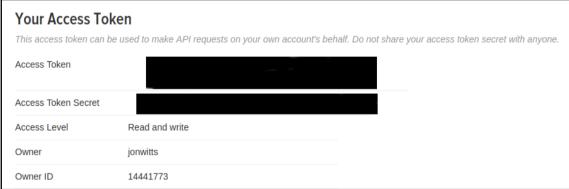






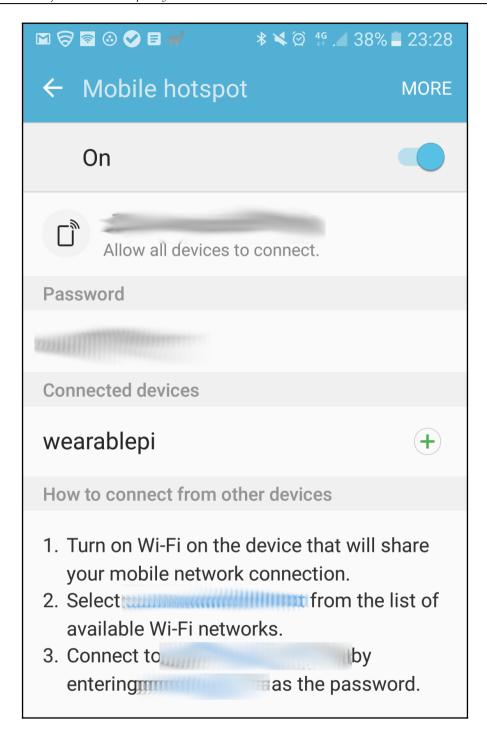
Name *	
TweetShirt	
Your application name. This	s is used to attribute the source of a tweet and in user-facing authorization screens. 32 characters max.
Description *	
Twitter reactive LED Pi	i Zero t shirt
	, which will be shown in user-facing authorization screens. Between 10 and 200 characters max.
Your application description Website *	
Your application description Website * http://www.jonwitts.co.u Your application's publicly a created by your application	
Your application description Website * http://www.jonwitts.co.u Your application's publicly a created by your application	uk accessible home page, where users can go to download, make use of, or find out more information about your application and will be shown in user-facing authorization screens.
Your application description Website * http://www.jonwitts.co.u Your application's publicly a created by your application (If you don't have a URL yell	uk accessible home page, where users can go to download, make use of, or find out more information about your application and will be shown in user-facing authorization screens.



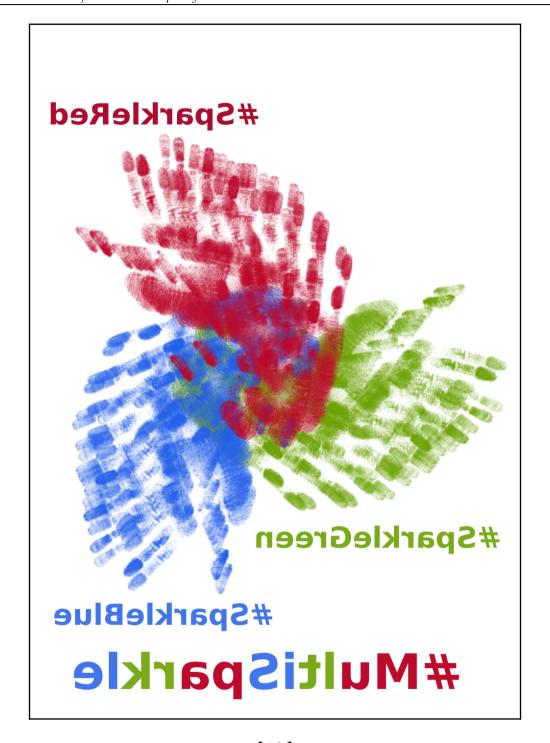


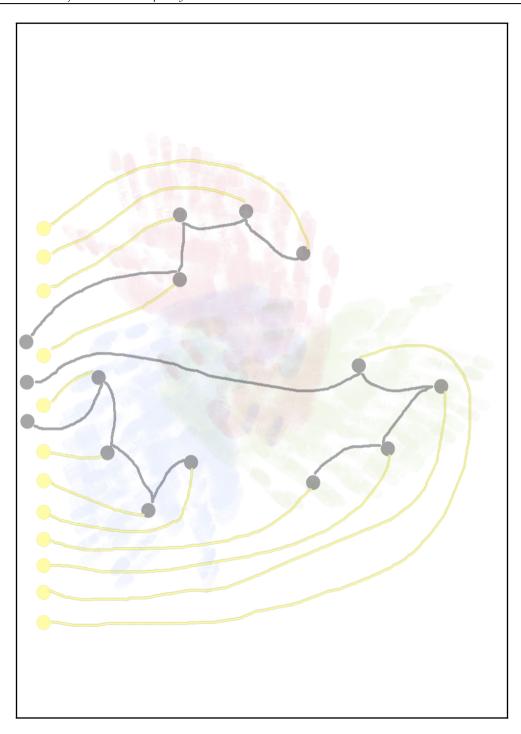
pi@wearablepi:~/WearableTech/Chapter5 \$./helloTweet.py
Tweeted: Hello world from my first Python tweet!
pi@wearablepi:~/WearableTech/Chapter5 \$

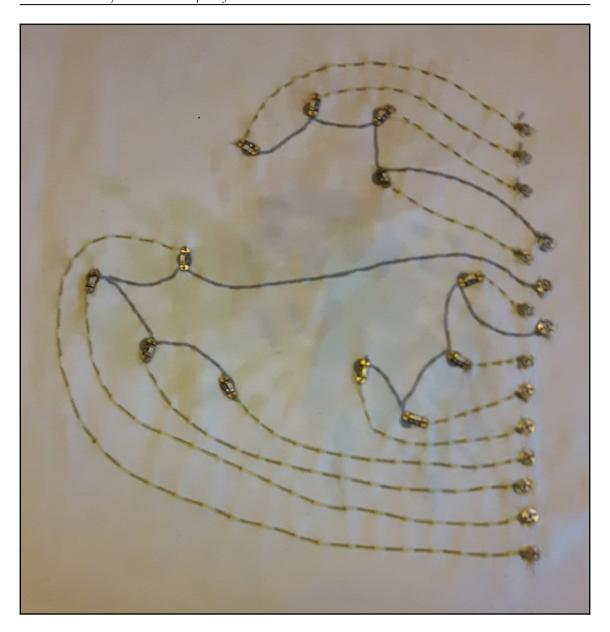




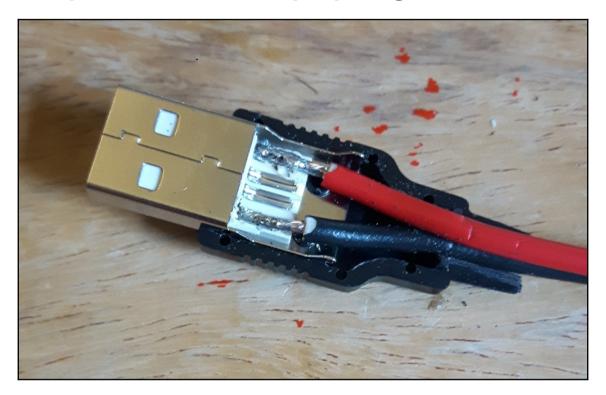


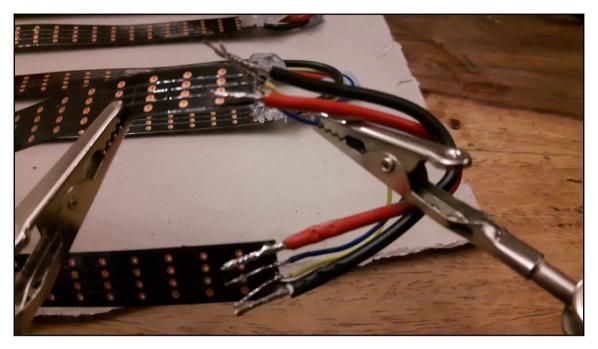


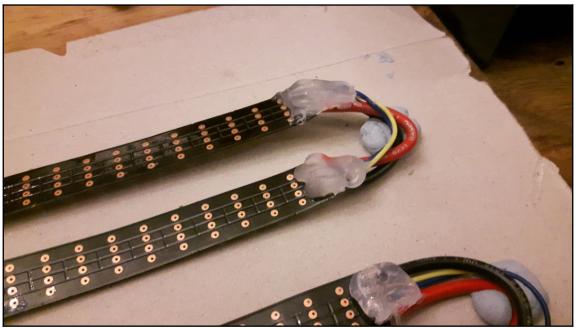


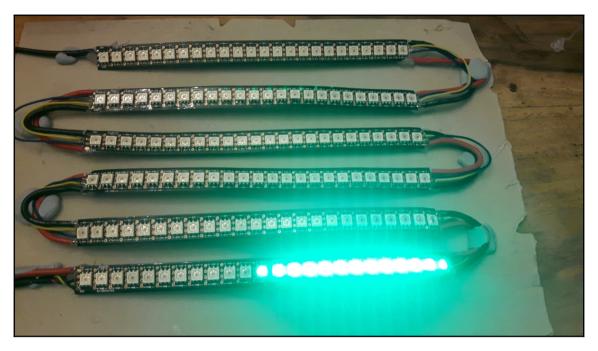


Chapter 6: An LED Laptop Bag

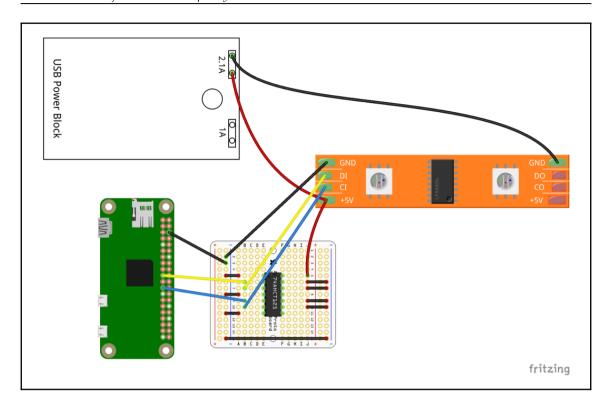


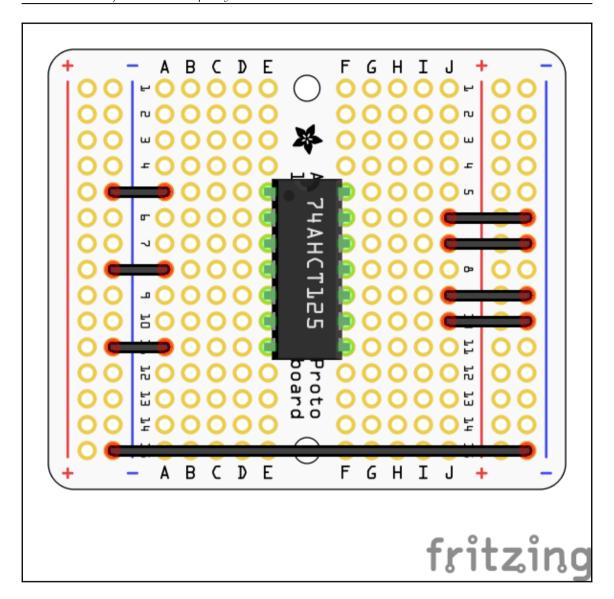


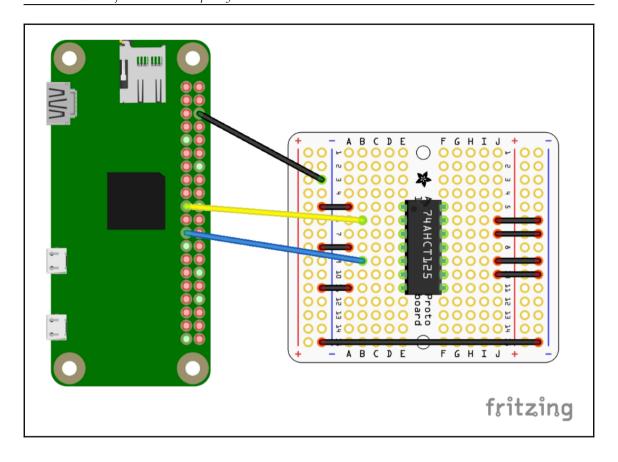


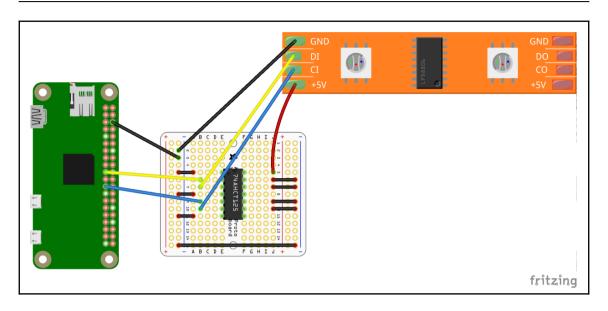






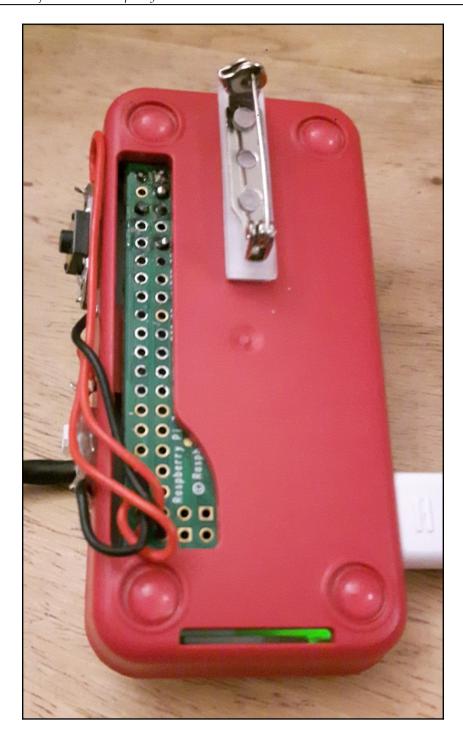




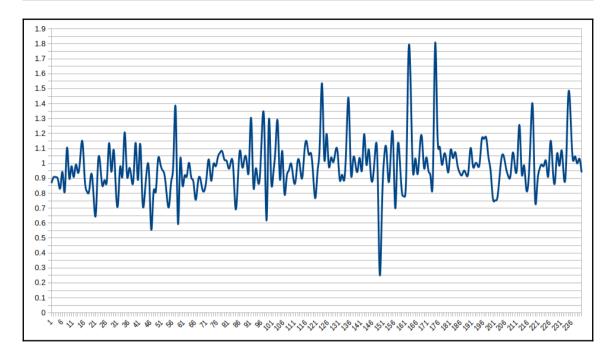


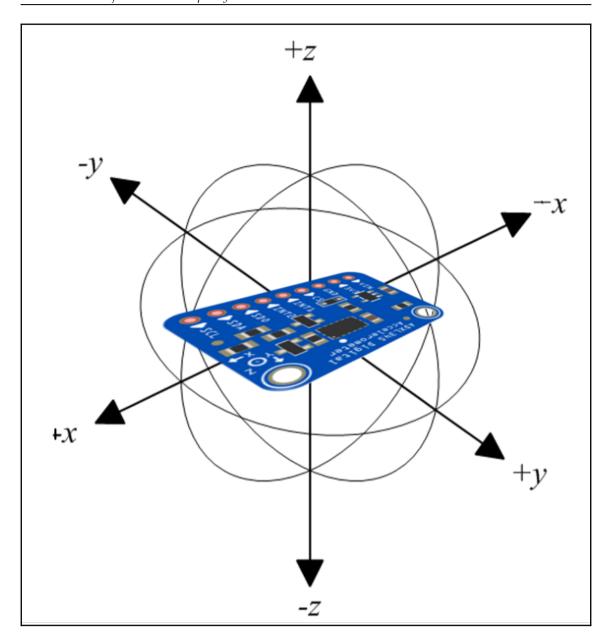
Chapter 7: Creating Your Own Pedometer

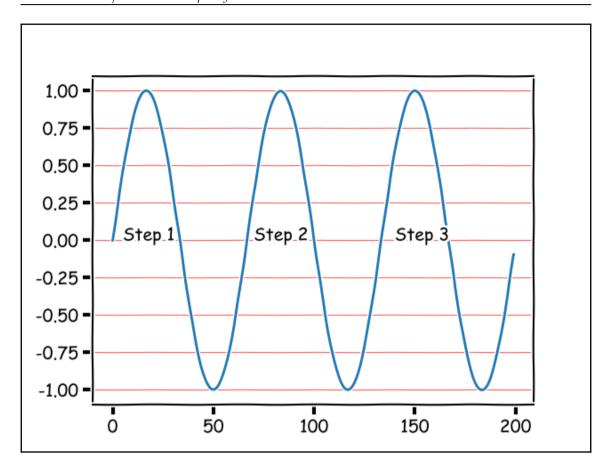


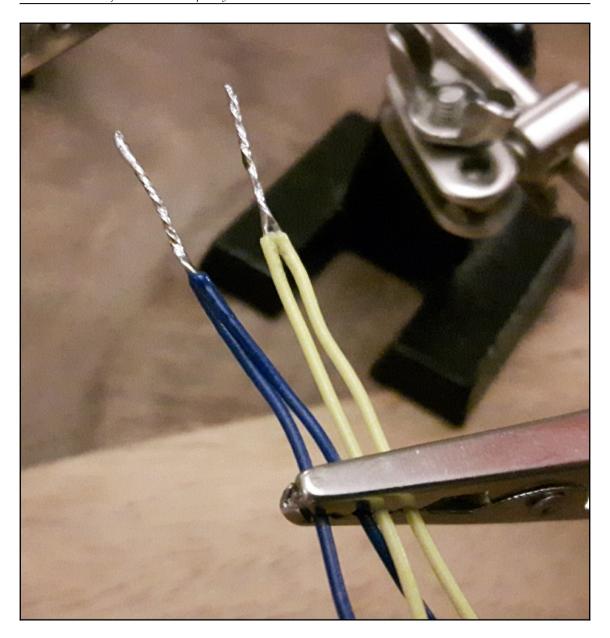


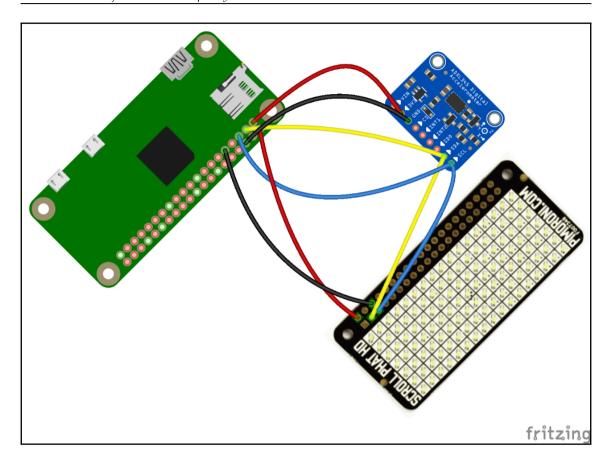
```
pi@wearablepi: ~/WearableTech/Chapter7
1.0.868
2,0.908
3,0.908
4,0.888
5,0.836
6,0.94
7,0.812
8,1.104
9,0.904
10,0.98
11,0.908
12,0.992
13,0.936
14,1.04
15,1.144
16,0.896
17,0.812
18,0.816
19,0.932
20,0.78
21,0.66
22,1.004
23,0.988
steps.csv
```



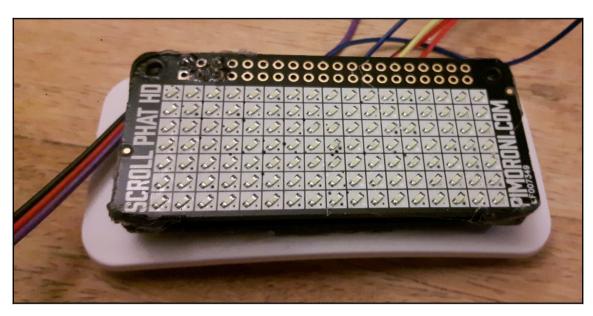


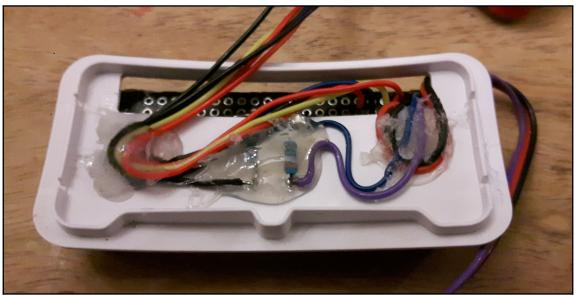




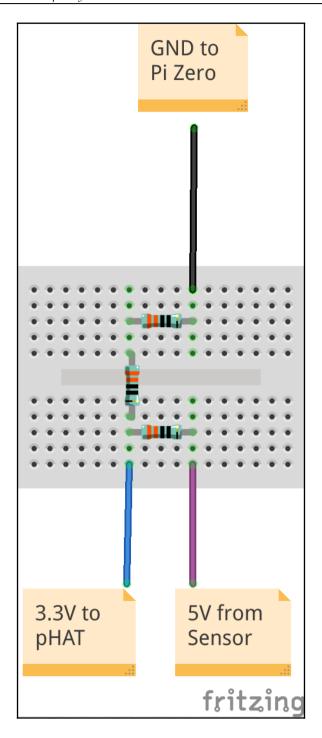


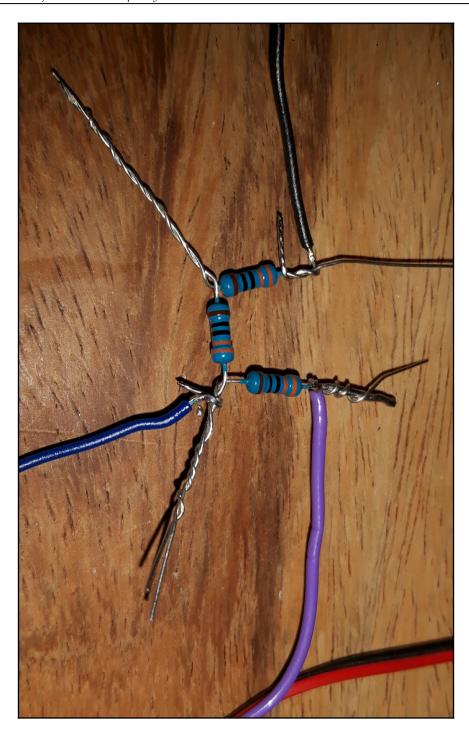
Chapter 8: Creating Your Own Heart Rate Monitor

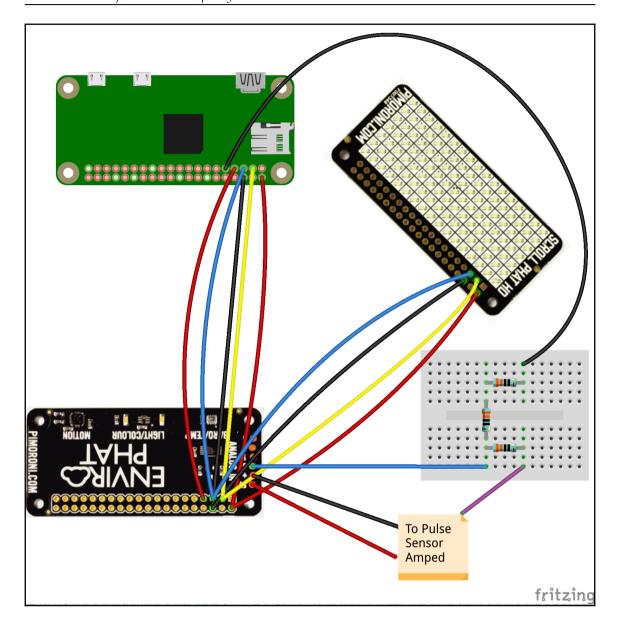


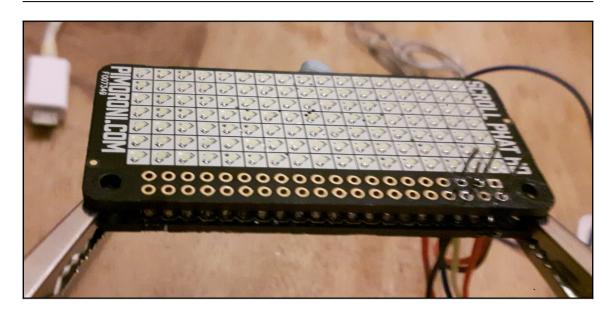


```
😝 🖨 💷 pi@wearablepi: ~/WearableTech/Chapter8
Pulse Voltage = 1.807
Pulse Voltage = 1.897
Pulse Voltage = 1.534
Pulse Voltage = 1.45
Pulse Voltage = 1.816
Pulse Voltage = 2.077
Pulse Voltage = 1.492
Pulse Voltage = 1.396
Pulse Voltage = 1.93
Pulse Voltage = 1.768
Pulse Voltage = 1.423
Pulse Voltage = 1.336
Pulse Voltage = 1.348
Pulse Voltage = 2.425
Pulse Voltage = 1.552
Pulse Voltage = 1.45
Pulse Voltage = 1.552
Pulse Voltage = 2.959
Pulse Voltage = 1.531
^CTraceback (most recent call last):
 File "./pulseTest.py", line 9, in <module>
    sleep(0.25)
KeyboardInterrupt
pi@wearablepi:~/WearableTech/Chapter8 $
```



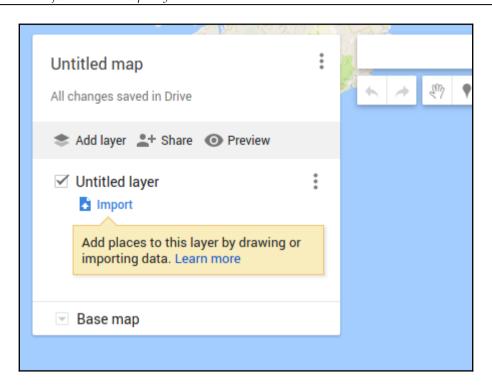


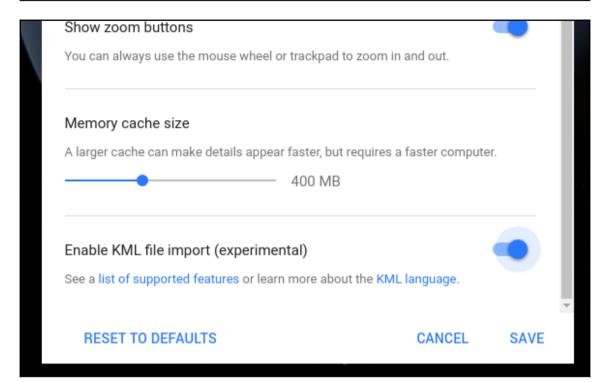


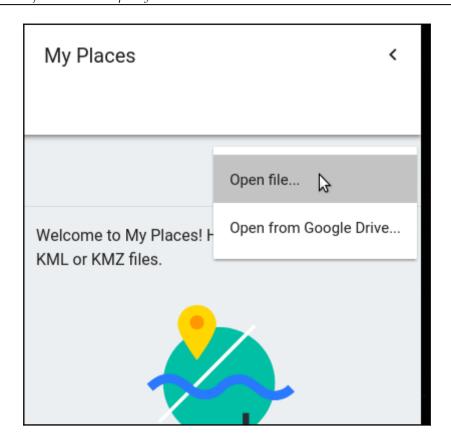


Chapter 9: Creating Your Own GPS Tracker

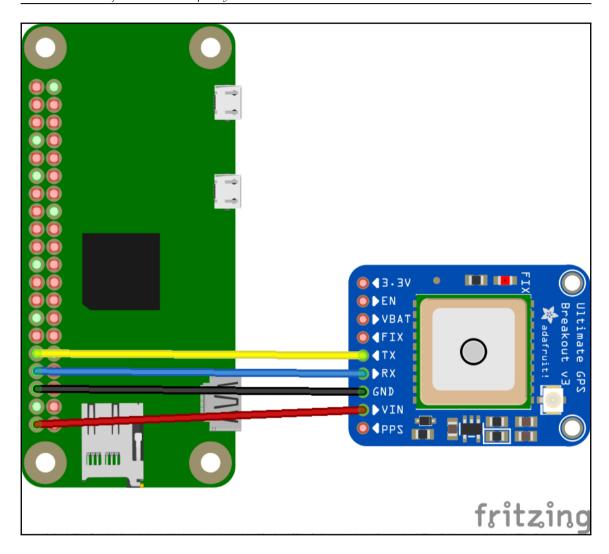
```
😑 🗊 pi@wearablepi: ~/WearableTech/Chapter9
               2017-07-09T15:30:42.000Z
                                             PRN:
                                                     Elev:
                                                            Azim:
                                                                   SNR:
                                                                         Used:
  Latitude:
                53.762900 N
                                               27
                                                     76
                                                            124
                                                                   27
  Longitude:
                0.361576 W
                                                8
                                                     64
                                                            289
                                                                   39
                                                     55
  Altitude:
               -4.1 m
                                               10
                                                            113
                                                                   33
               0.0 kph
                                               18
                                                     43
                                                            069
                                                                   33
  Speed:
  Heading:
               38.5 deg (true)
                                               16
                                                      29
                                                            179
                                                                   24
                                              120
                                                     27
                                                                   32
  Climb:
               0.0 m/min
                                                            198
               3D FIX (15 secs)
                                               11
                                                     21
                                                            263
                                                                   40
  Status:
  Longitude Err:
                    +/- 1 m
                                               21
                                                     19
                                                           070
                                                                   32
                   +/- 2 m
+/- 7 m
  Latitude Err:
                                                     14
                                                            280
                                                                   41
  Altitude Err:
                                               30
                                                            315
                                                                   24
                                                     14
  Course Err:
                    n/a
                    +/- 17 kph
  Speed Err:
  Time offset:
                    0.671
  Grid Square:
                    I093ts
```

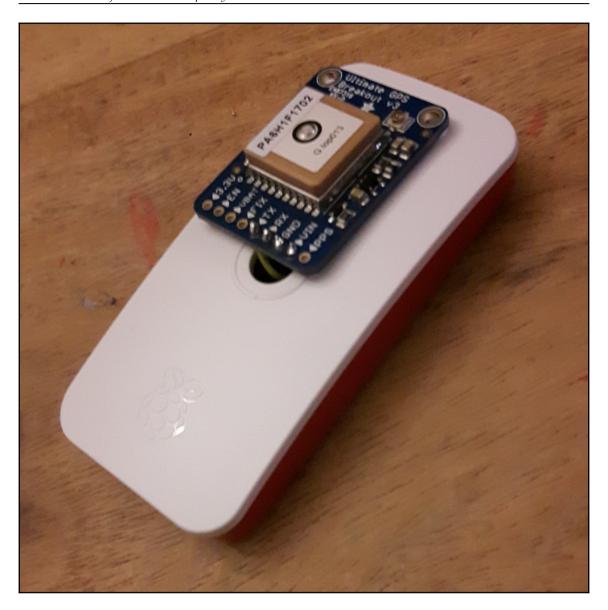




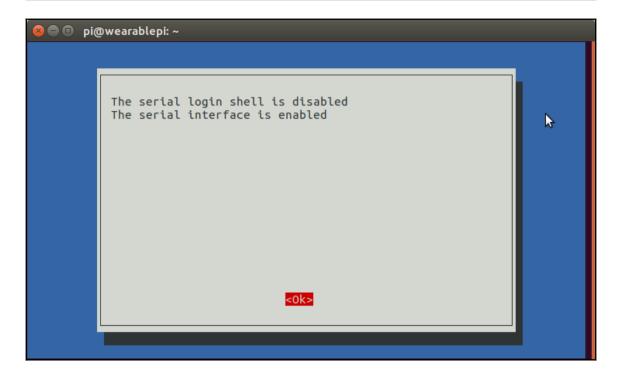












```
🙎 🖨 🗊 🏻 pi@wearablepi: ~
$GPVTG,280.51,T,,M,0.03,N,0.05,K,D*30
$GPRMC,151320.000,A,5345.7752,N,00021.6992,W,0.04,274.47,090717,,,D*74
間以GPVTG,274.47,T,,M,0.04,N,0.07,K,D*39
6992,W,0.04,274.47,090717,,,D*74
間以GPGSA,A,3,27,08,07,11,18,21,10,16,15,26,,,1.12,0.82,0.76*0D
$GPRMC,151320.000,A,5345.7752,N,00021.6992,W,0.04,274.47,090717,,,D*74
$GPVG,274.47,T,,M,0.04,N,0.07,K,D*39
15,26,,1.06,0.75,0.75*00
♦^♦$GPRMC,151321.000,A,5345.7752,N,00021.6992,W,0.03,280.51,090717,,,D*7E
51320.000,A,5345.7752,N,00021.6992,W,0.04,274.47,090717,,,D*74
$GPVG,274.47,T,,M,0.04,N,0.07,K,D*39
15,26,,1.06,0.75,0.75*00
*^*$GPVTG,280.51,T,,M,0.03,N,0.05,K,D*30
6992,W,0.03,280.51,090717,,,D*7E
51320.000,A,5345.7752,N,00021.6992,W,0.04,274.47,090717,,,D*74
$GPVG,274.47,T,,M,0.04,N,0.07,K,D*39
15,26,,1.06,0.75,0.75*00
♦^♦$GPGGA,151322.000,5345.7752,N,00021.6993,W,2,11,0.75,2.1,M,47.0,M,0000,0000*7
```