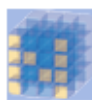


# 1

## NumPy Quick Start



### Numerical Python

A package for scientific computing with Python

Brought to you by: [charris208](#), [jarrodmillman](#), [kern](#), [rgommers](#), [teoliphant](#)

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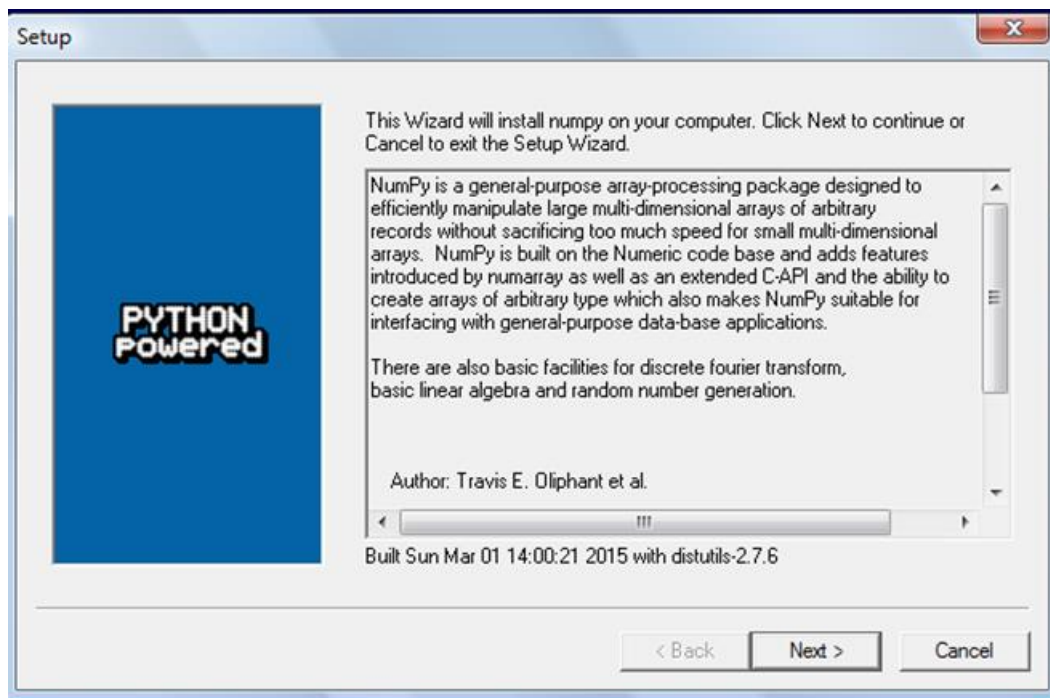
numpy-1.9.2.zip



[Browse All Files](#)

### Description

Numerical Python adds a fast and sophisticated array facility to the Python language. NumPy is the most recent and most actively supported package. Numarray and Numeric are no longer supported.



arange	arctan	argsort	array_equal	arrow
arccos	arctan2	argwhere	array_equiv	
arccosh	arctanh	around	array_repr	
arcsin	argmax	array	array_split	
arcsinh	argmin	array2string	array_str	

# 2

## Beginning with NumPy Fundamentals

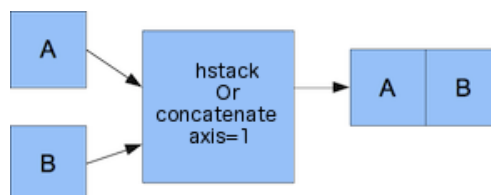
[0,0]	[0,1]
[1,0]	[1,1]

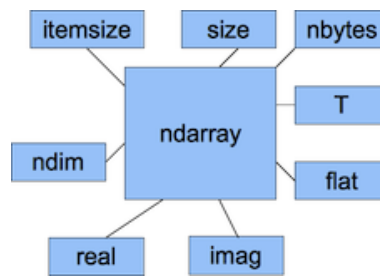
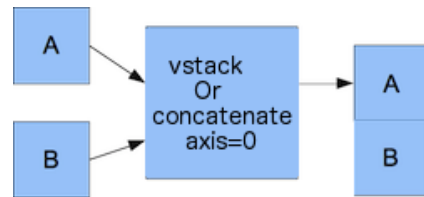
```
In [1]: int(42.0 + 1.j)
```

-----  
**TypeError**

```
<ipython-input-1-5e824780381a> in <modu  
----> 1 int(42.0 + 1.j)
```

**TypeError:** can't convert complex to int





# 3

## Getting Familiar with Commonly Used Functions

$$\frac{1}{n} \sum_{i=1}^n a_i$$

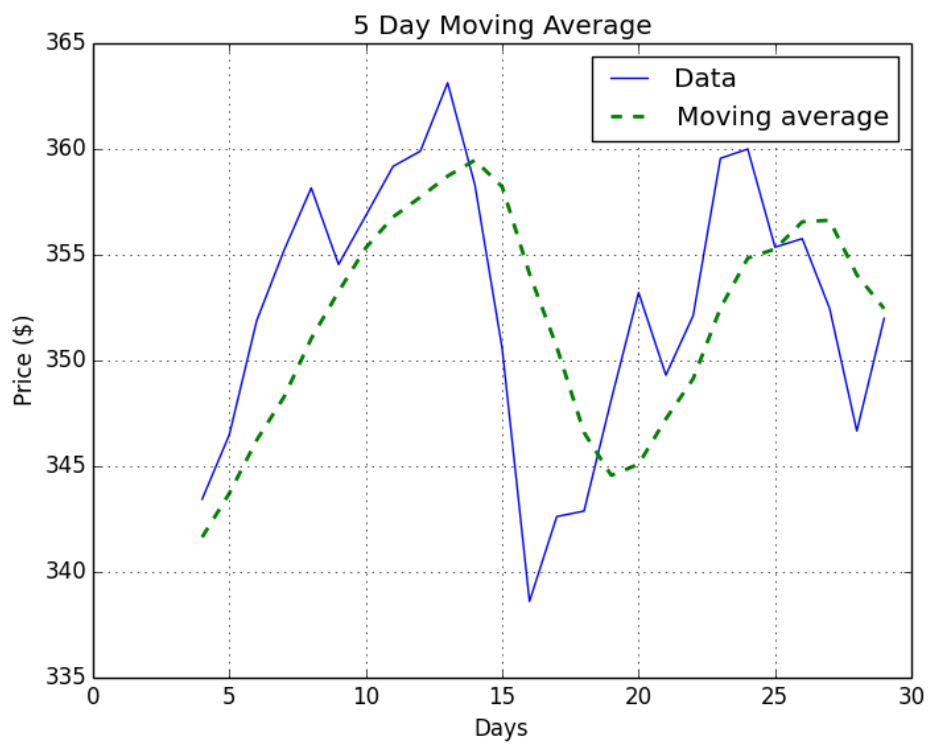
```
sorted = [ 336.1   338.61  339.32  342.62  342.88  343.44  344.32  345.03  346.5
 346.67  348.16  349.31  350.56  351.88  351.99  352.12  352.47  353.21
 354.54  355.2   355.36  355.76  356.85  358.16  358.3   359.18  359.56
 359.9   360.    363.13]
```

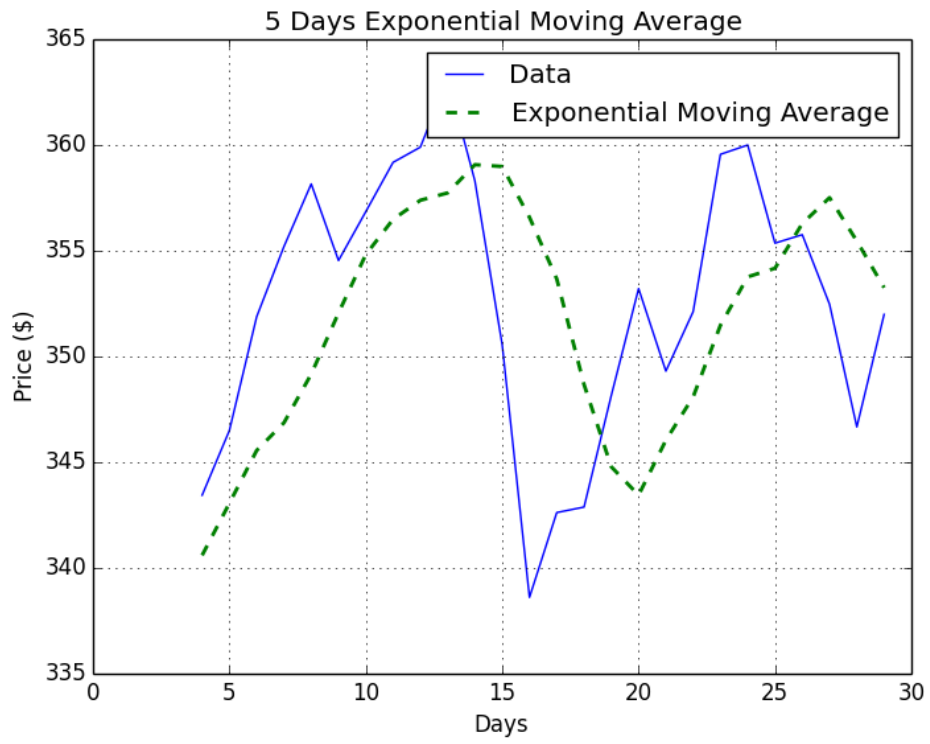
$$\frac{1}{n} \sum_{i=1}^n (a_i - \text{mean})^2$$

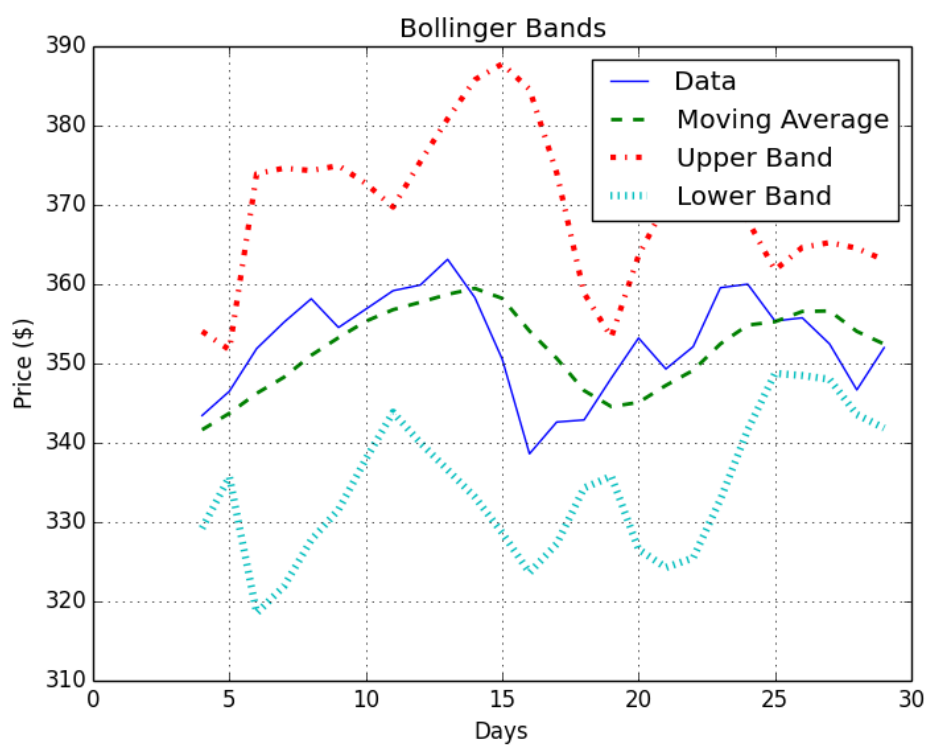
$$\log(a) - \log(b) = \log\left(\frac{a}{b}\right)$$

$$\frac{((N-1)PATR + TR)}{N}$$

$$(f * g)(t) = \int_{-\infty}^{\infty} f(\tau)g(t-\tau)d\tau = \int_{-\infty}^{\infty} f(t-\tau)g(\tau)d\tau$$



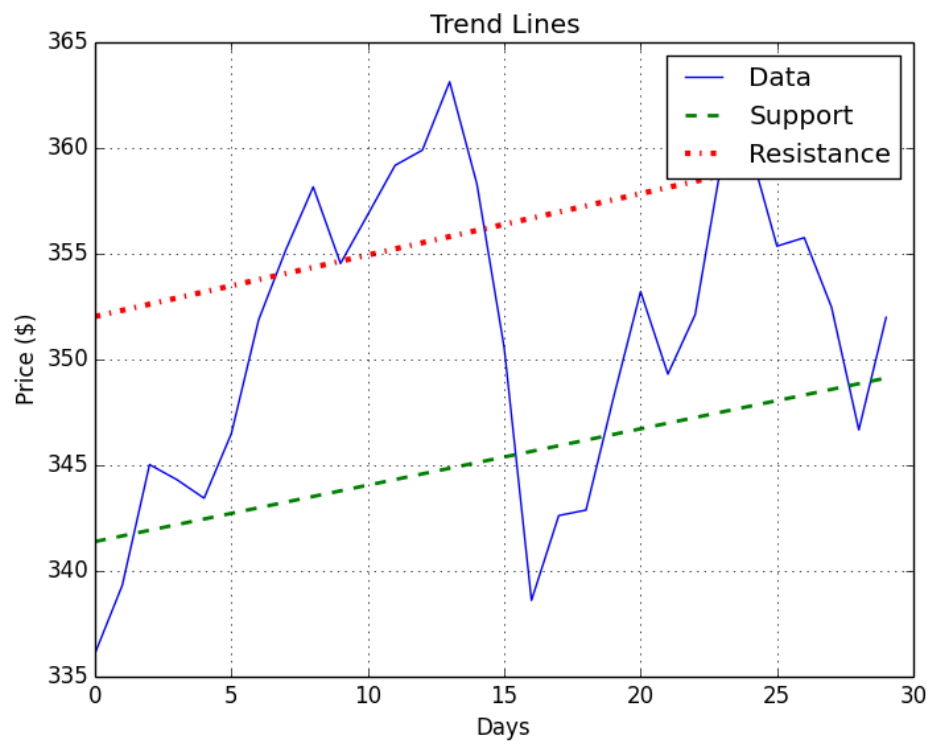




$$p_t = b + \sum_{i=1}^N a_{t-i} p_{t-i}$$

$$\sum_{i=1}^n \left( measured_i - predicted_i \right)^2$$

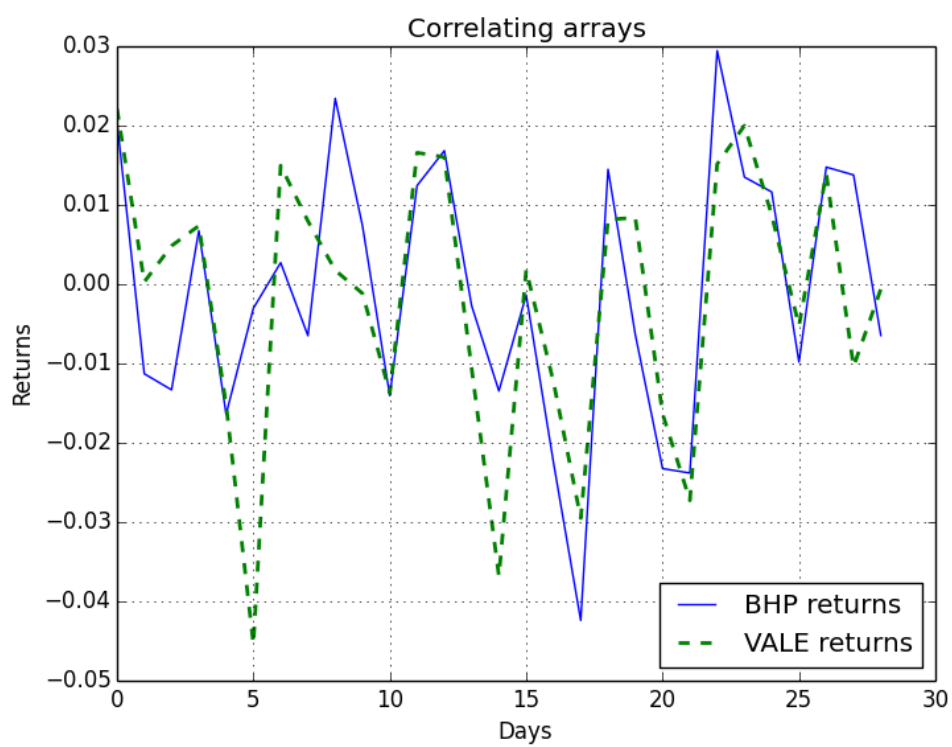




# 4

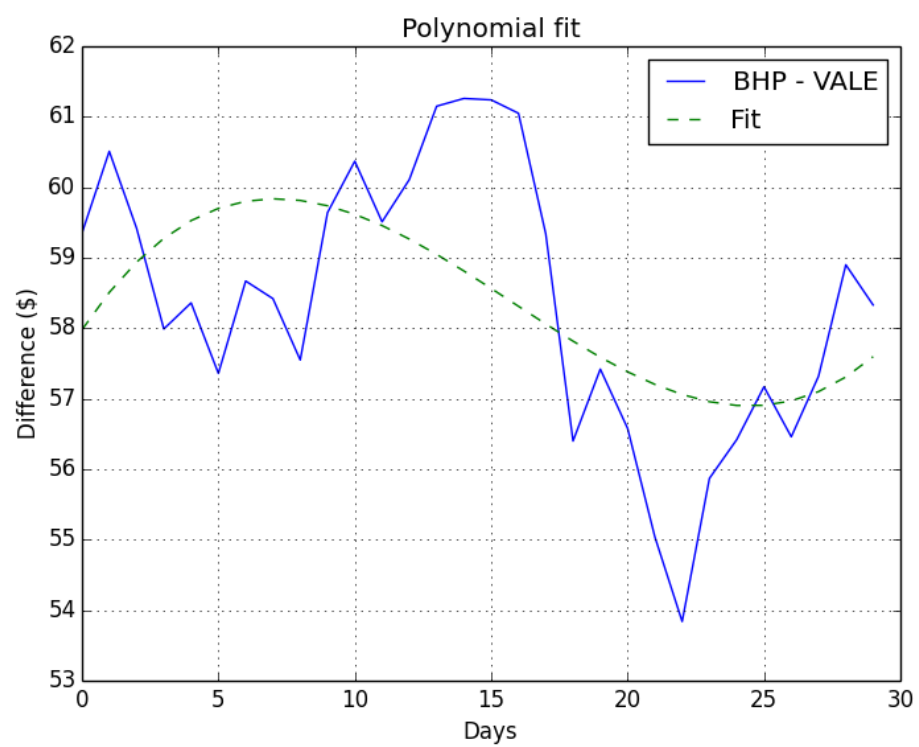
## Convenience Functions for your Convenience

$$\text{cov}(a,b) = \frac{1}{N} \sum_{i=1}^N (a_i - \text{mean}(a))(b_i - \text{mean}(b))$$

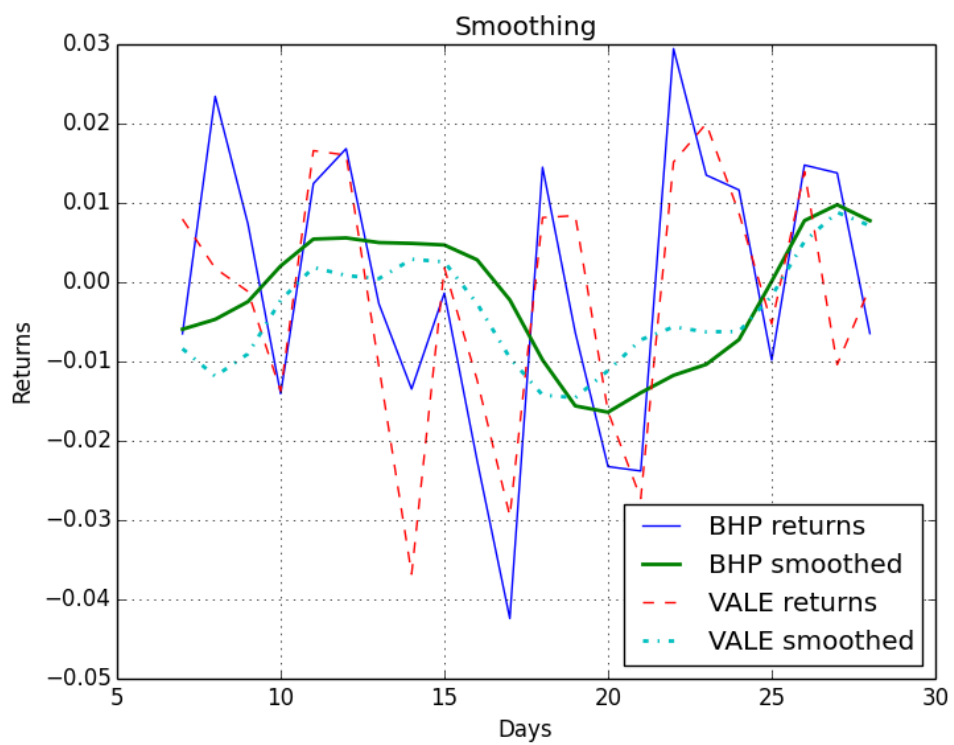


$$\sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x-a)^n$$

$$f^{(n)}(a)$$



$$w(n) = 0.5 - 0.5 \cos\left(\frac{2\pi n}{N-1}\right)$$



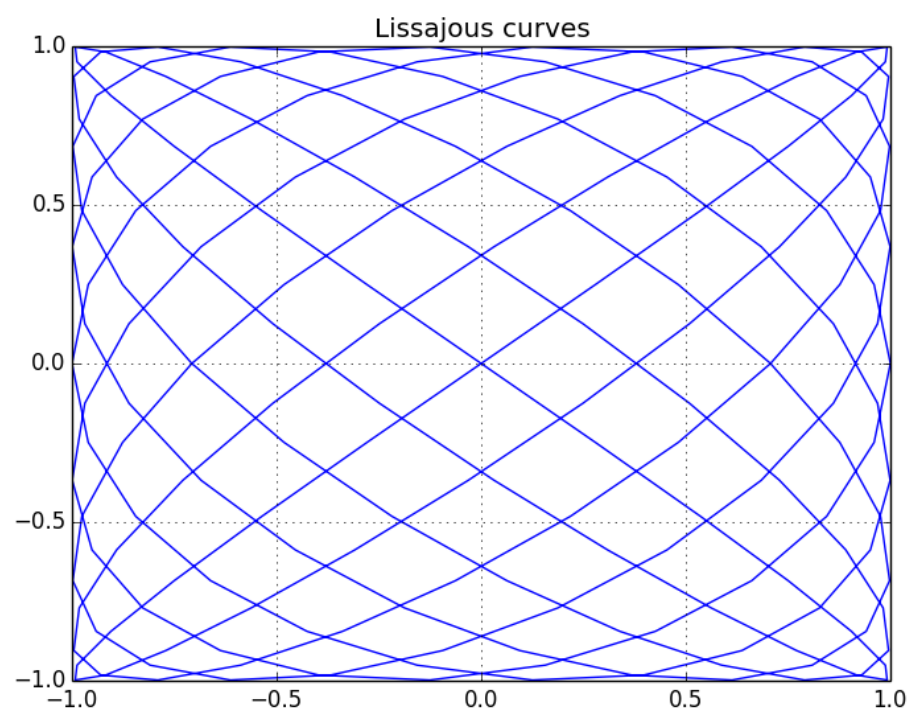
# 5

## Working with Matrices and ufuncs

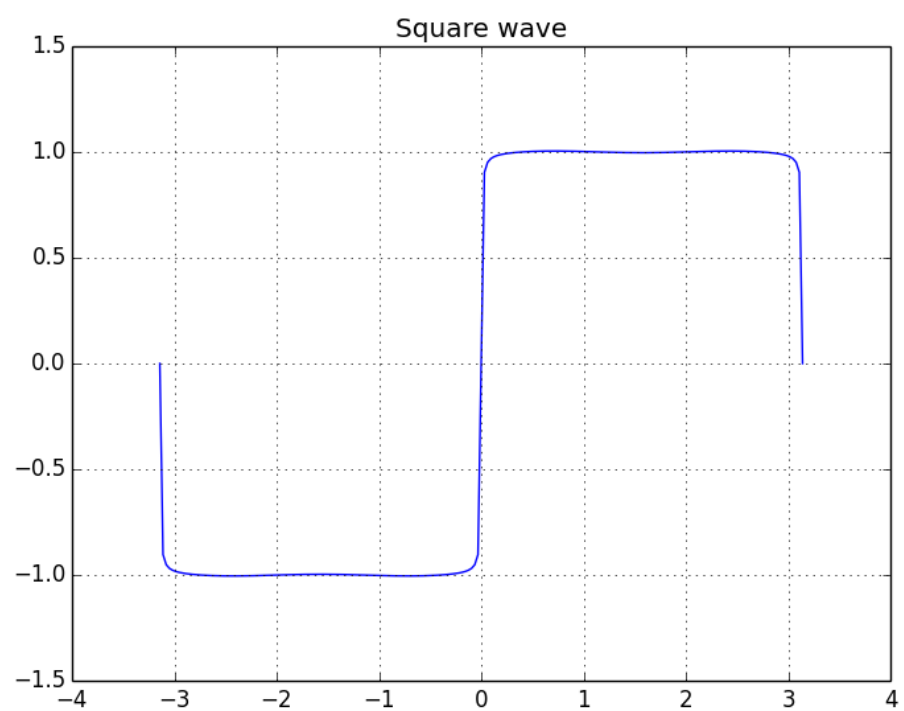
$$F_n = F_{n-1} + F_{n-2}$$

$$F_n = \frac{\varphi^n - (-\varphi)^{-n}}{\sqrt{5}}$$

$$\varphi = \frac{1 + \sqrt{5}}{2}$$

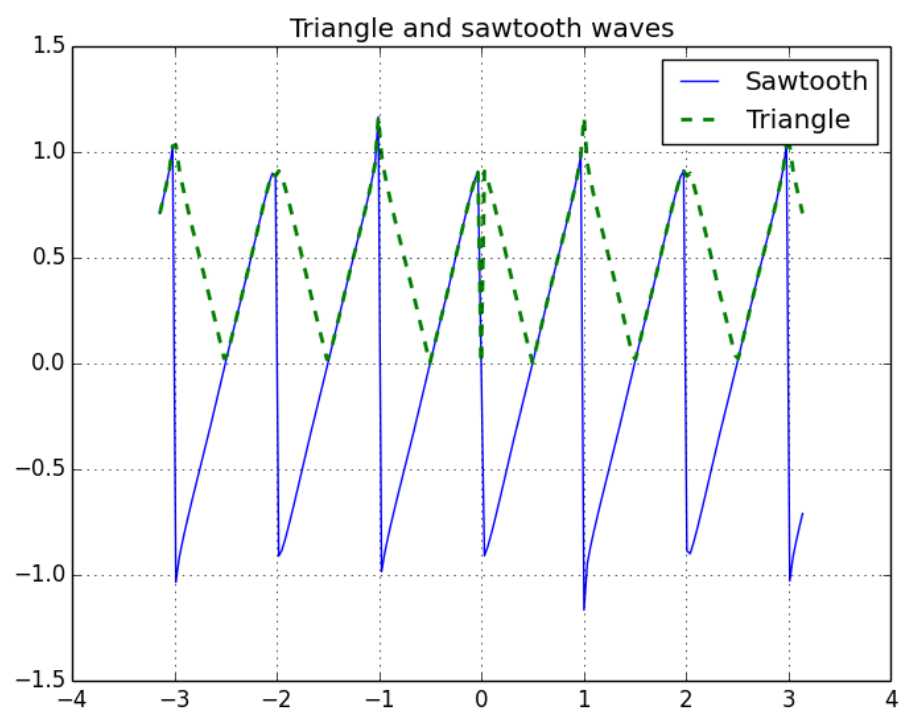


$$\sum_{k=1}^{\infty} \frac{4 \sin(2\pi(2k-1)ft)}{(2k-1)\pi}$$



$$\sum_{k=1}^{\infty} \frac{-2 \sin(2\pi kft)}{k\pi}$$





# 6

## Moving Further with NumPy Modules

$$\sum_i A_{ij} B_i$$

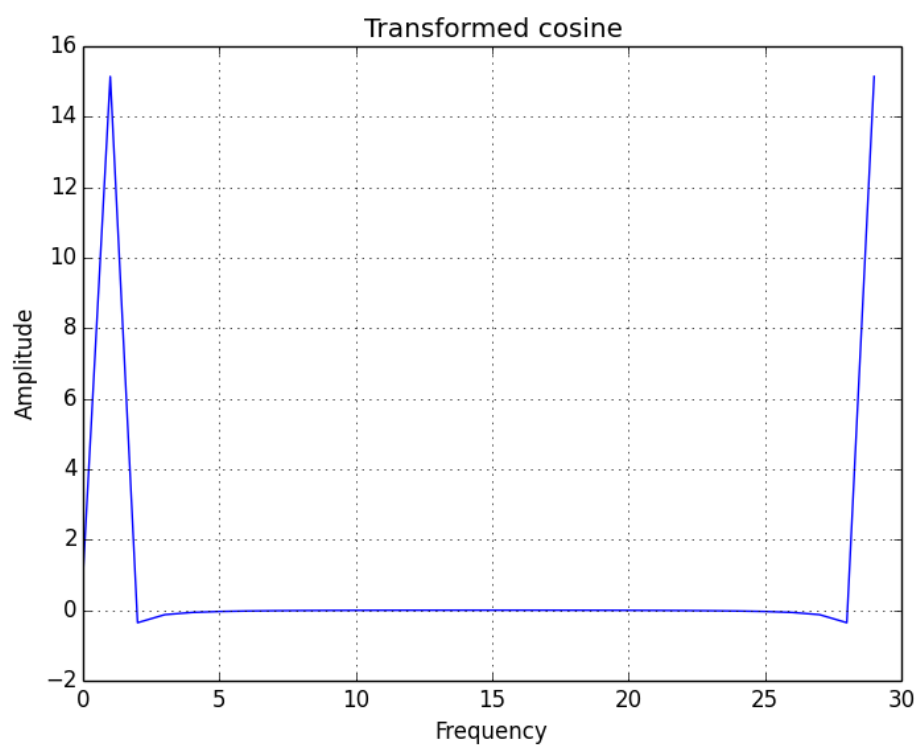
A

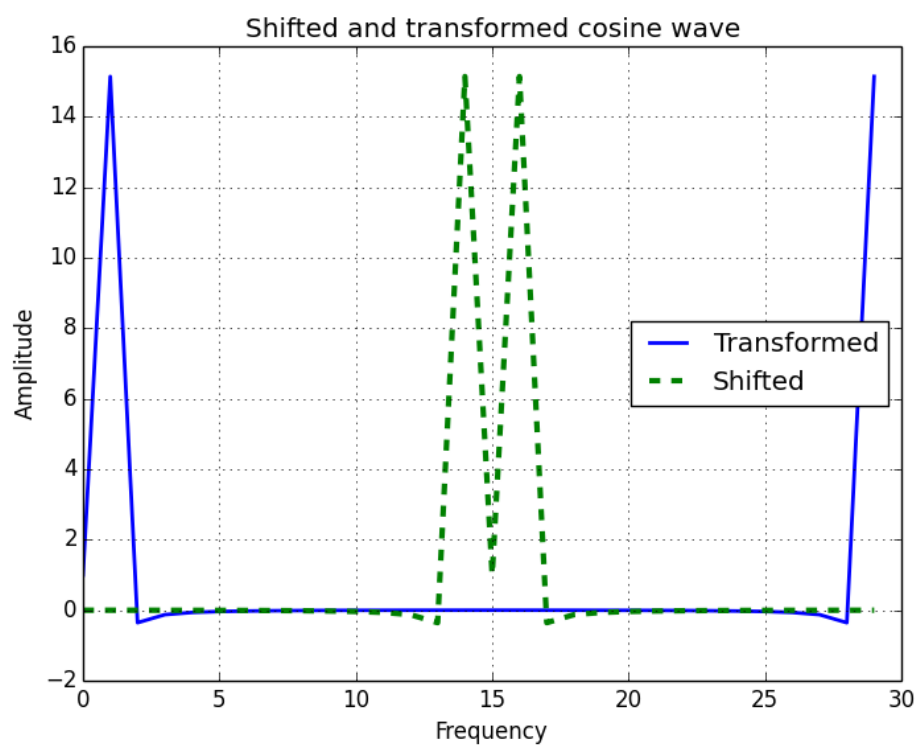
```
[[ 1 -2  1]
 [ 0  2 -8]
 [-4  5  9]]
```

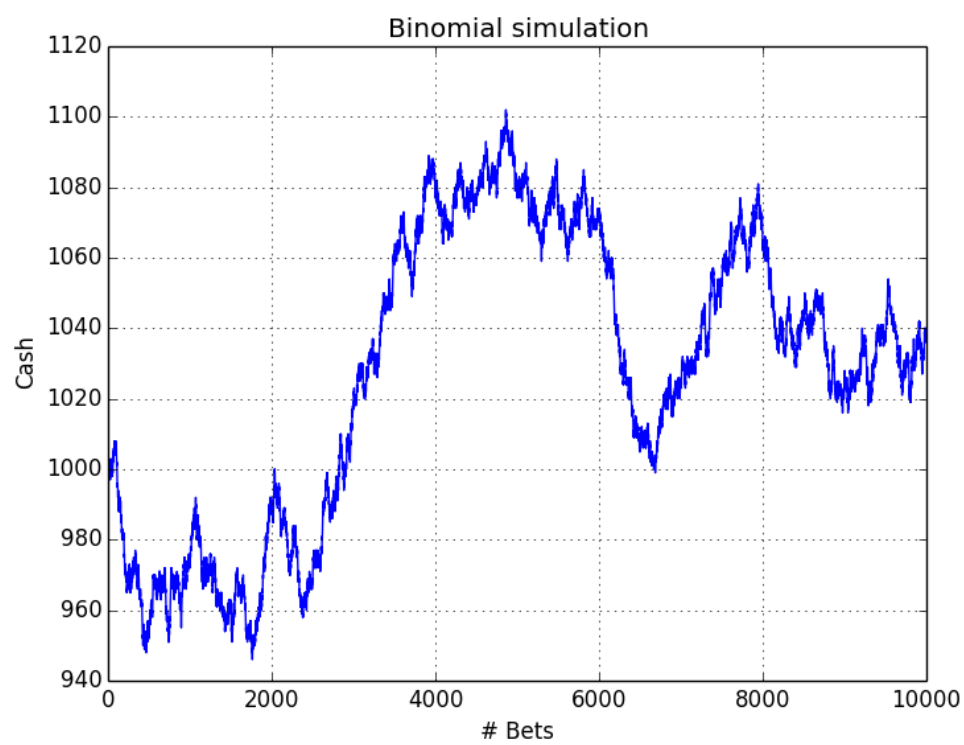
b

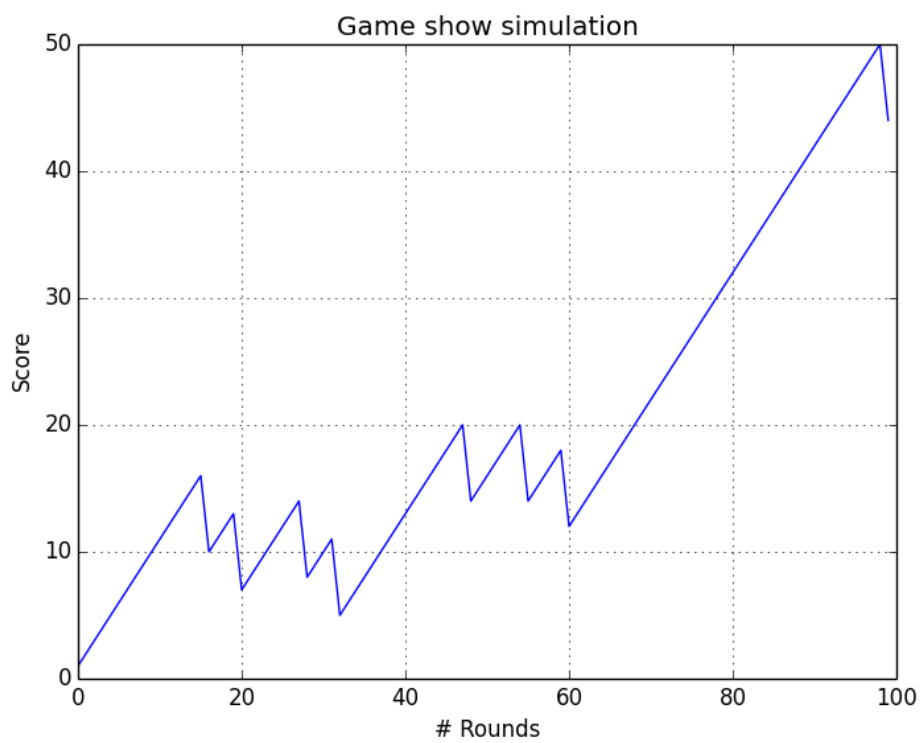
```
[ 0  8 -9]
```

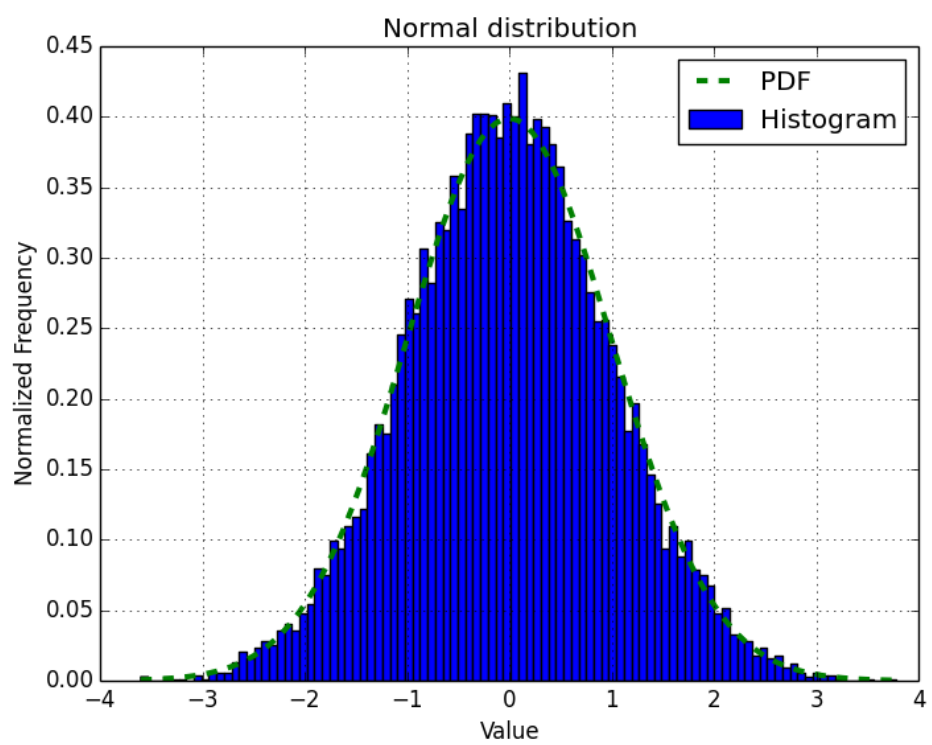
$$M = U \Sigma V^*$$

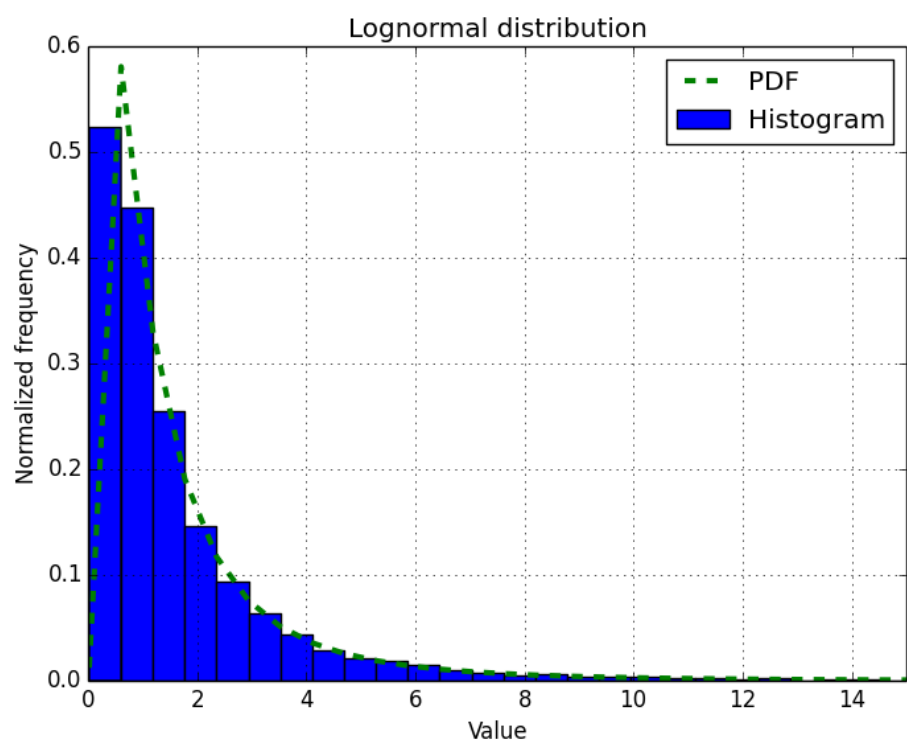












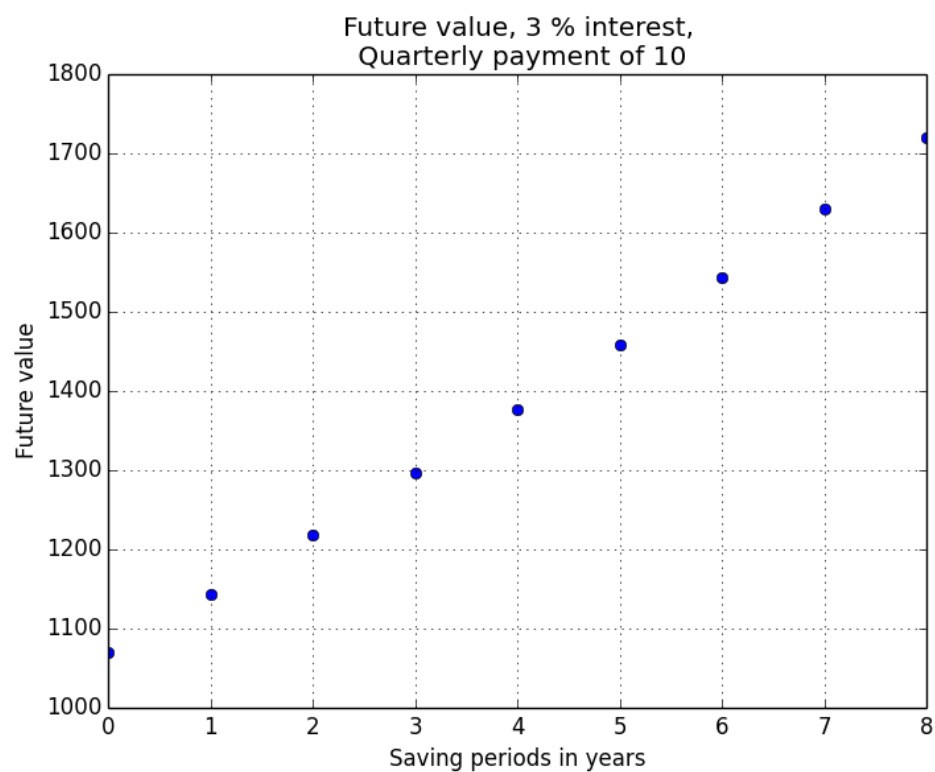
$$z = \frac{x - \mu}{\sigma}$$



# 7

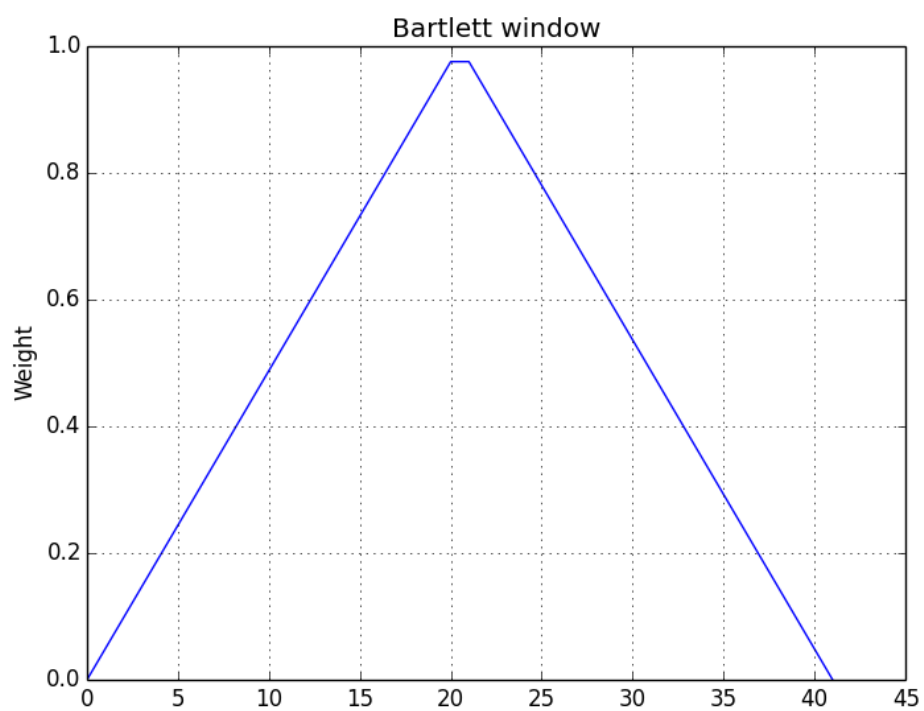
## Peeking Into Special Routines

$$PV(1+r)^n$$

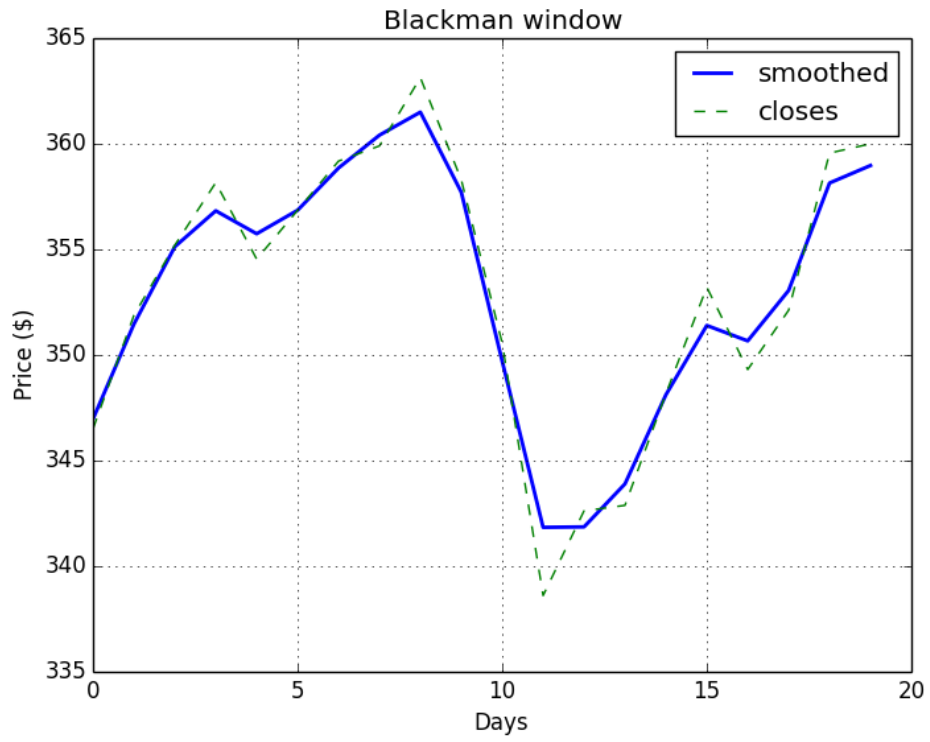


$$\sum_{t=0}^N \frac{R_t}{(1+r)^t}$$

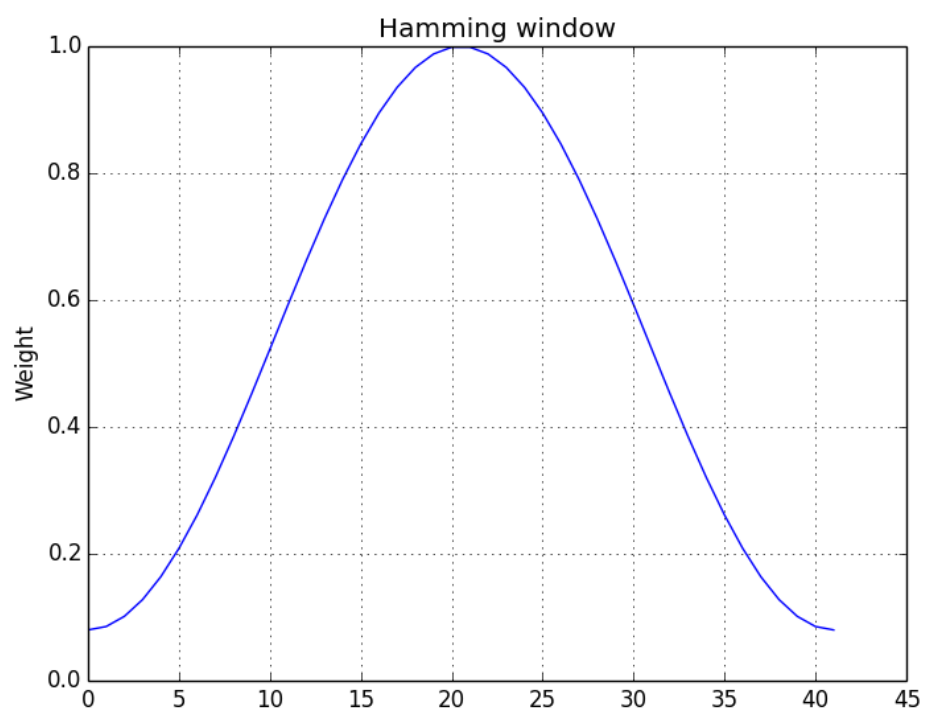
$$w(n) = 1 - \left| \frac{n - \frac{N-1}{2}}{\frac{N-1}{2}} \right|$$



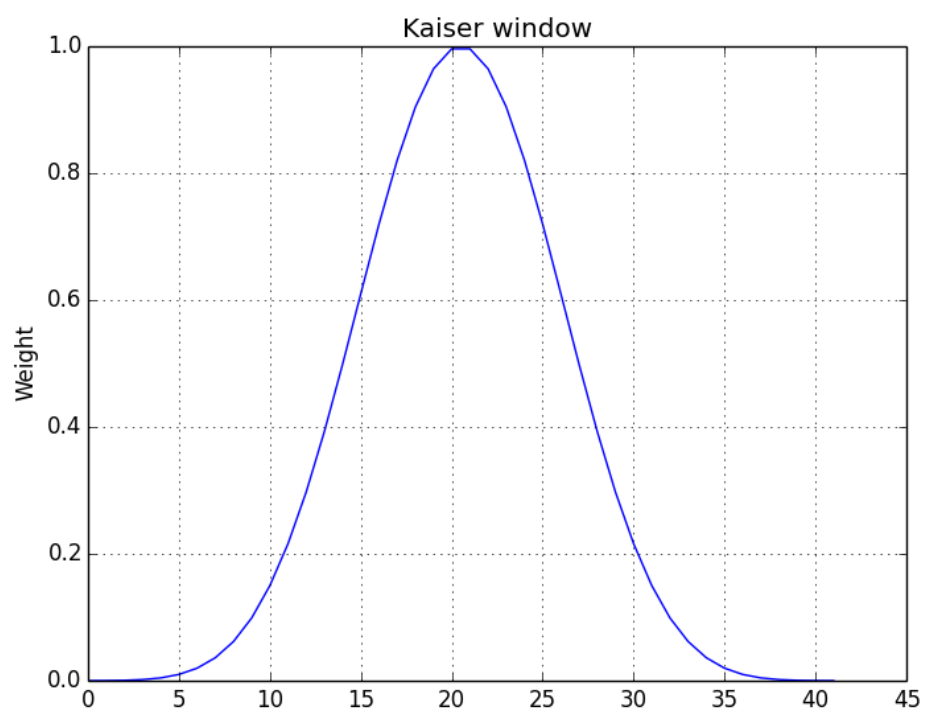
$$w(n) = 0.42 - 0.5 \cos\left(\frac{2\pi n}{M}\right) + 0.08 \cos\left(\frac{4\pi n}{M}\right)$$



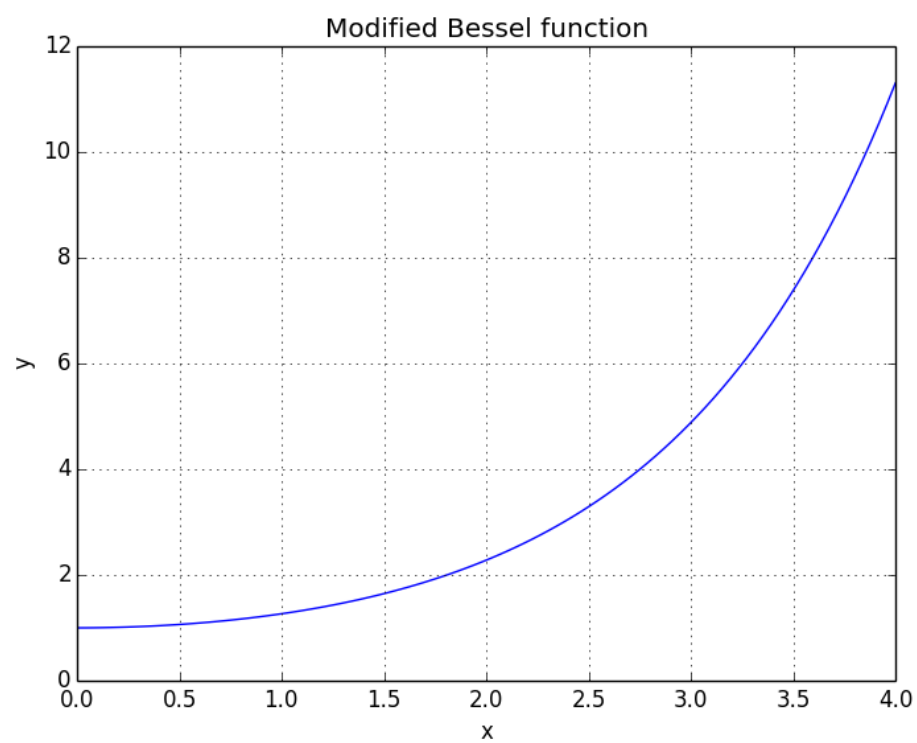
$$w(n) = 0.54 + 0.46 \cos\left(\frac{2\pi n}{M-1}\right) \quad 0 \leq n \leq M-1$$

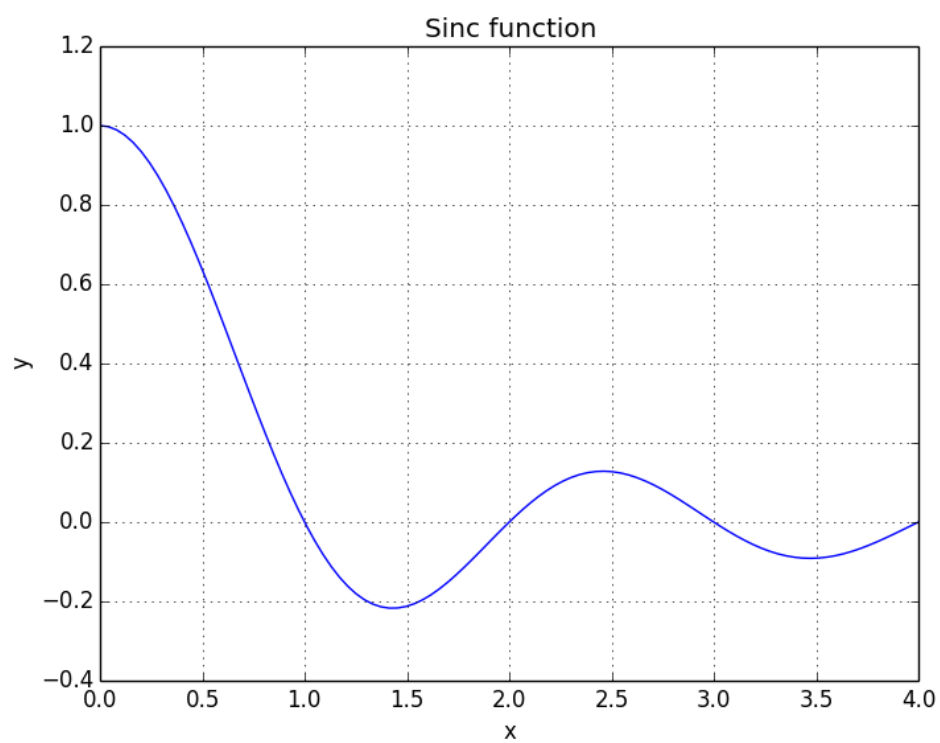


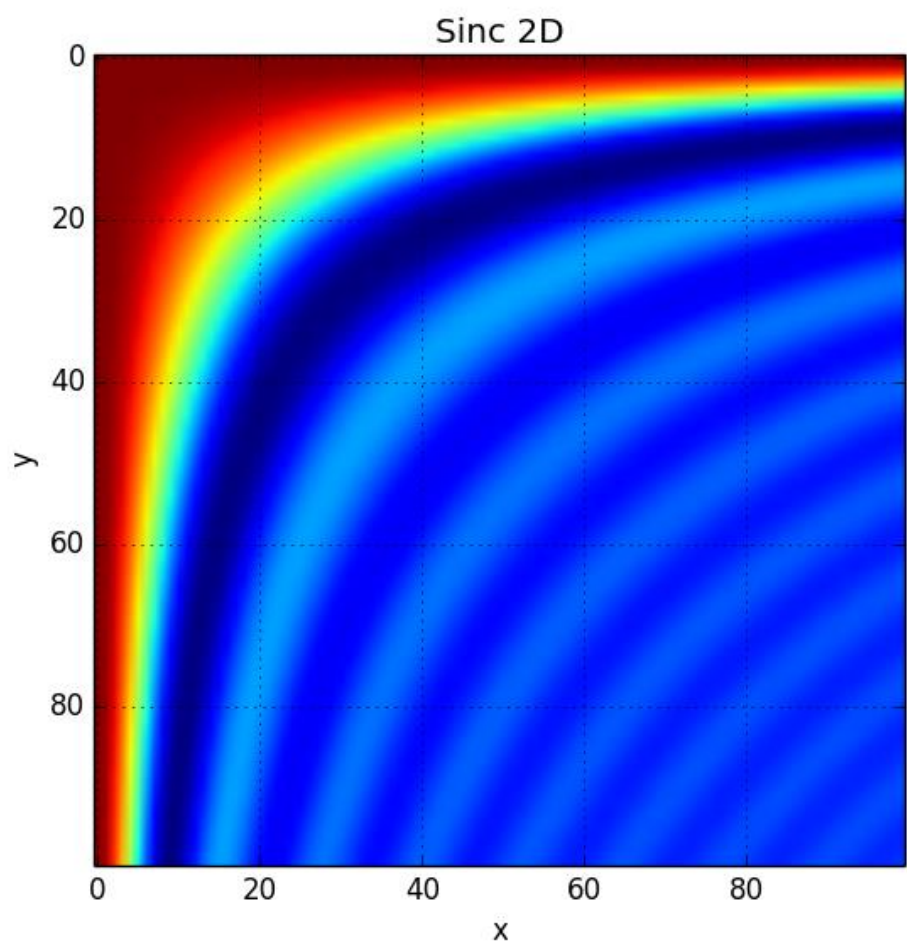
$$w(n) = I_0 \left( \beta \sqrt{1 - \frac{4n^2}{(M-1)^2}} \right) / I_0(\beta)$$



$$\frac{\sin(\pi x)}{\pi x}$$



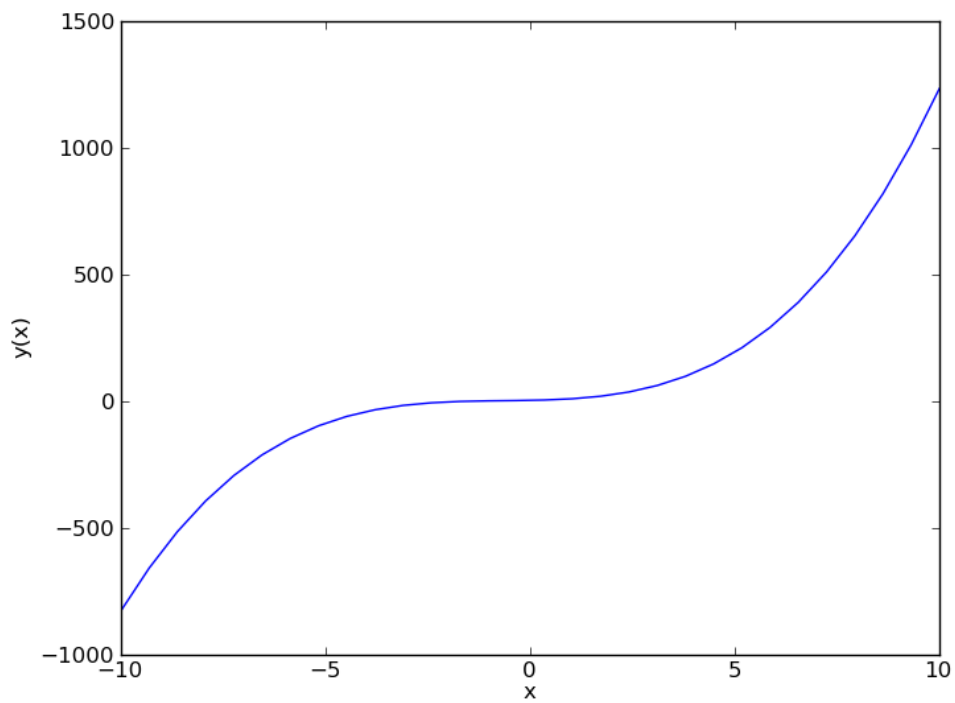


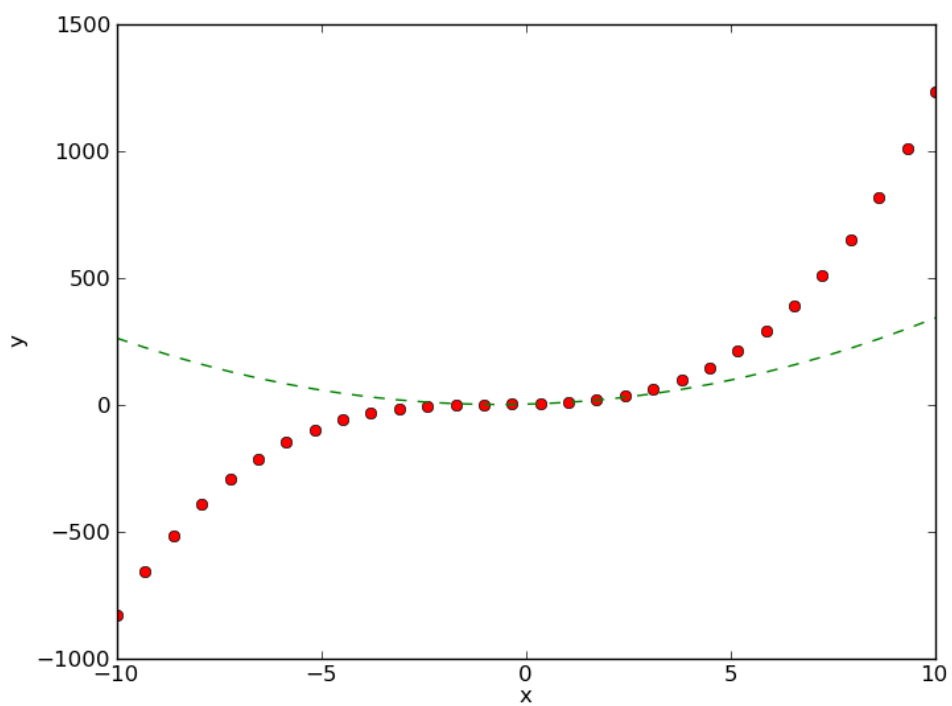


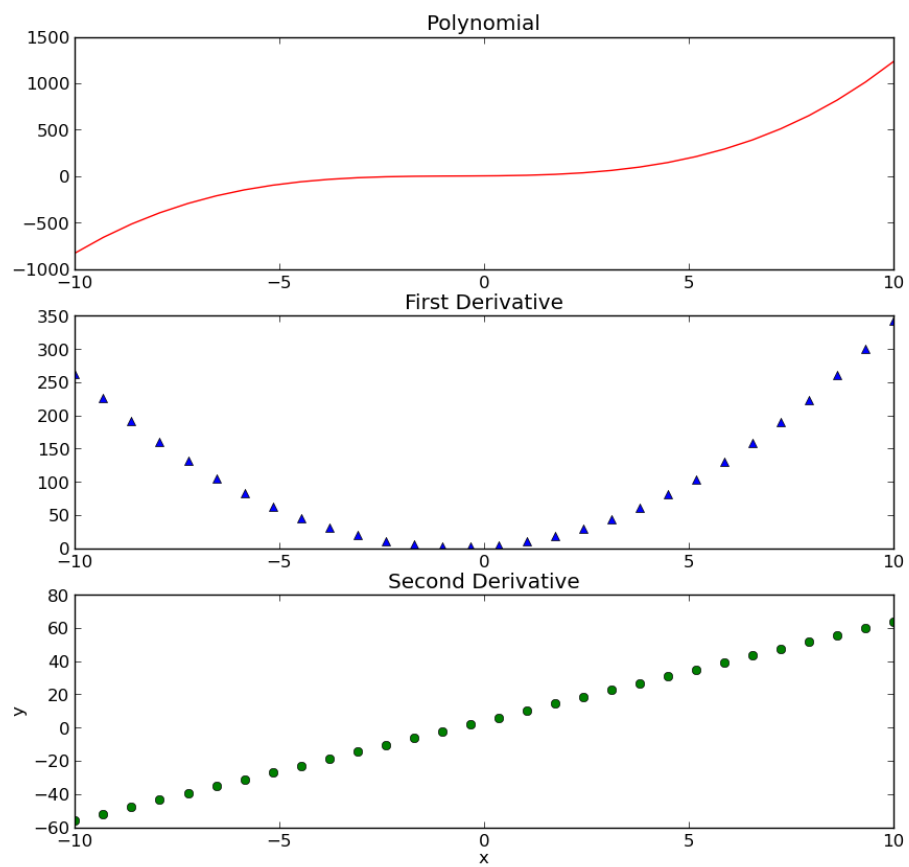


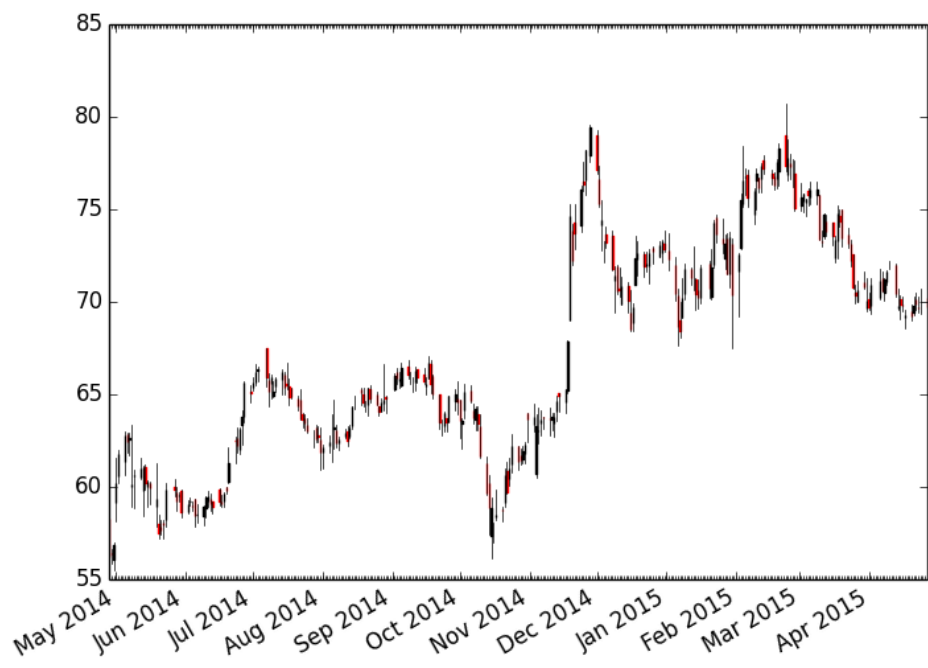
# 9

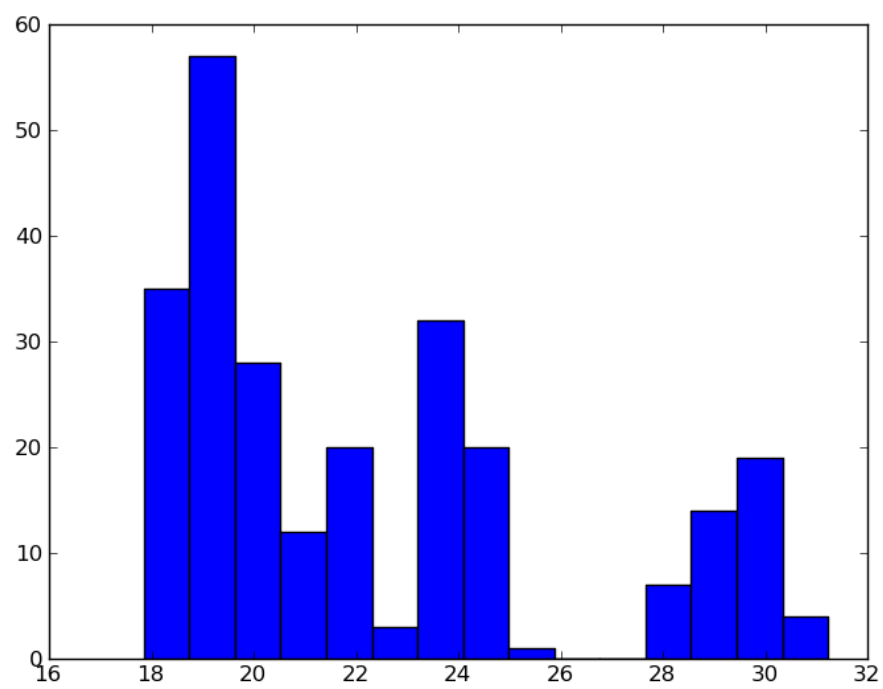
## Plotting with matplotlib

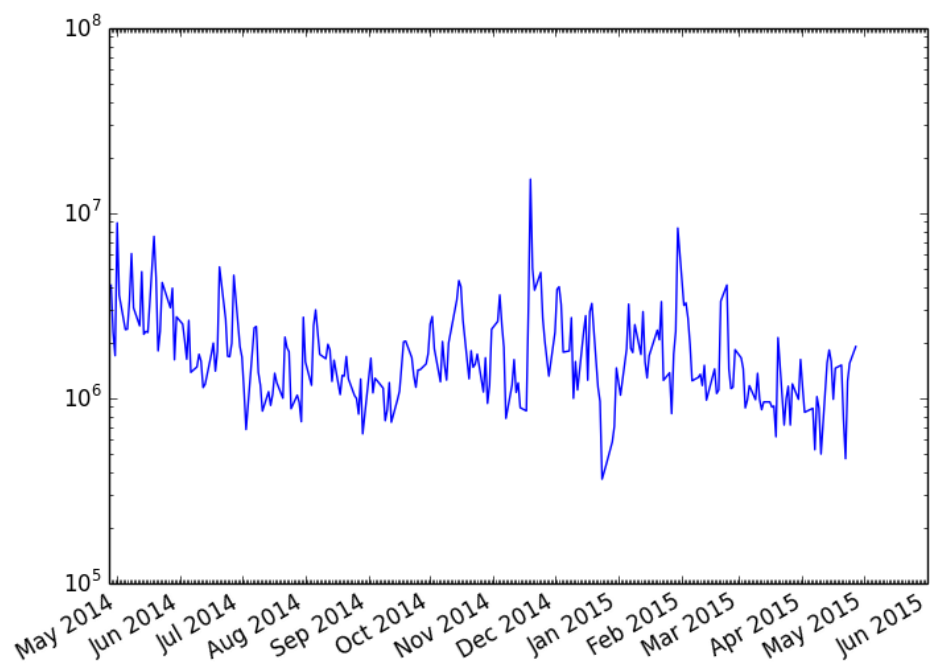


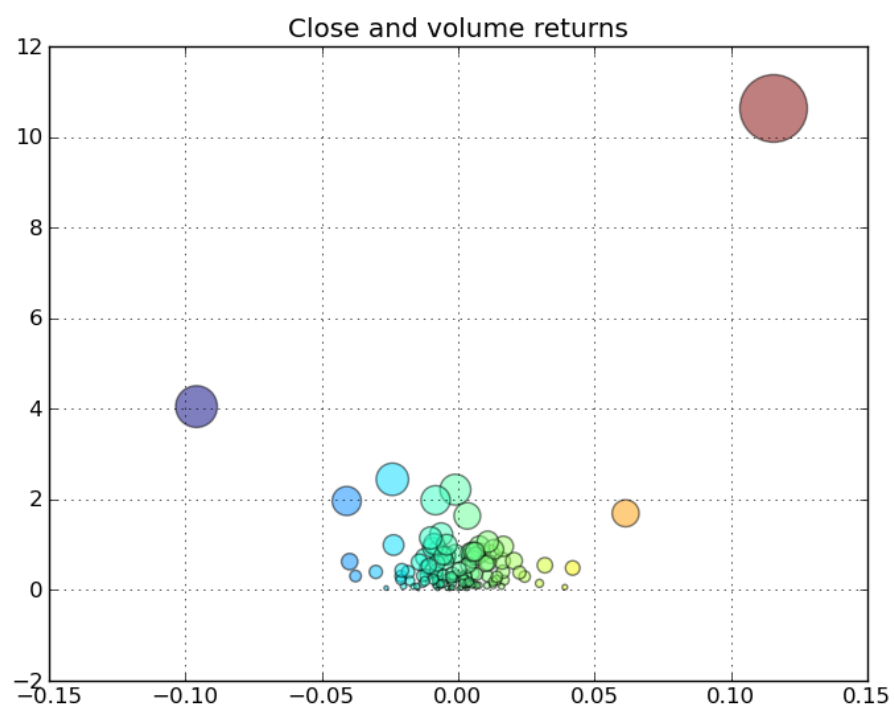


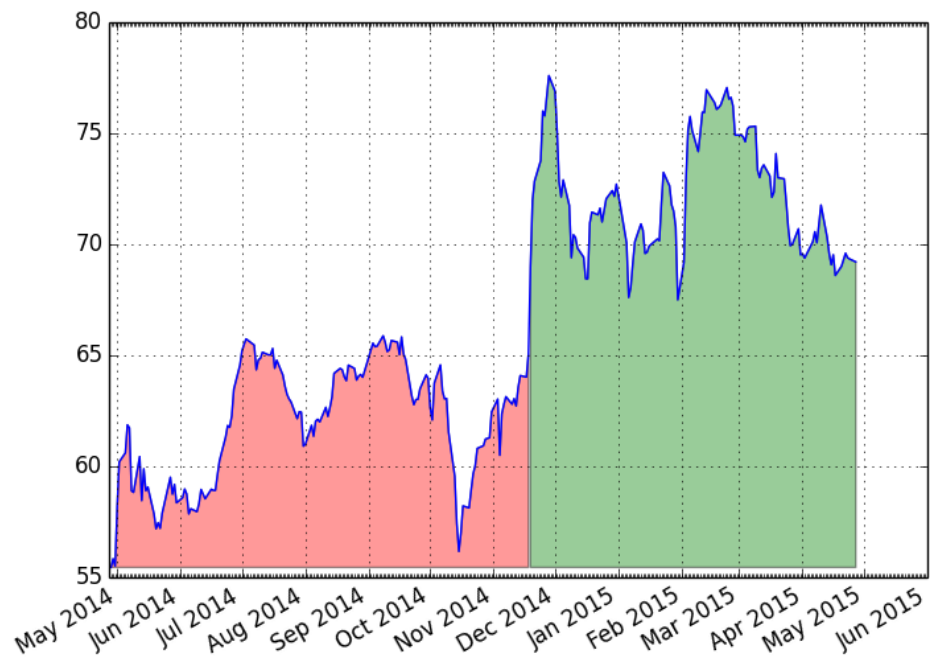




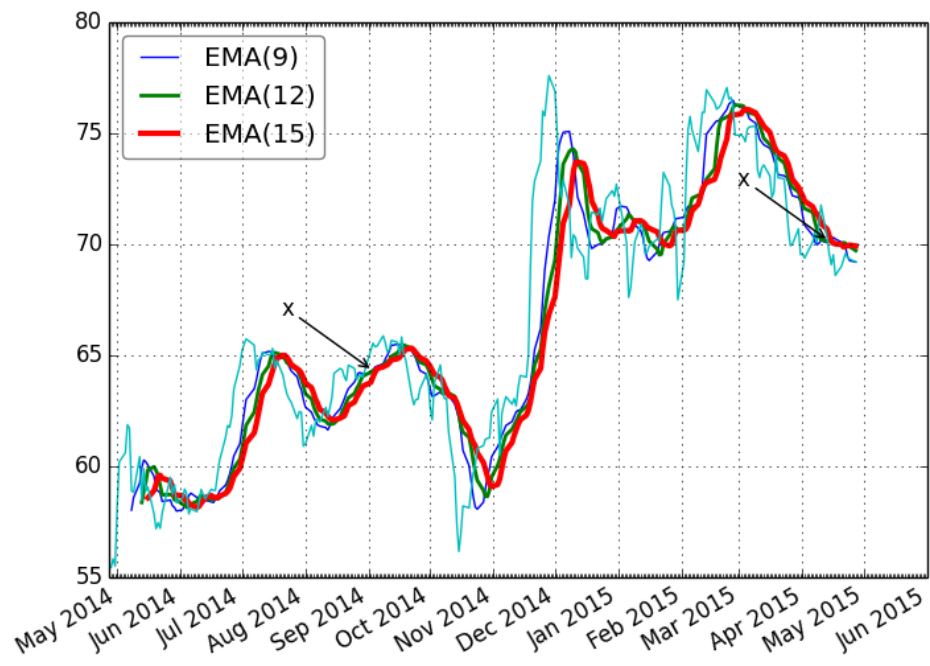




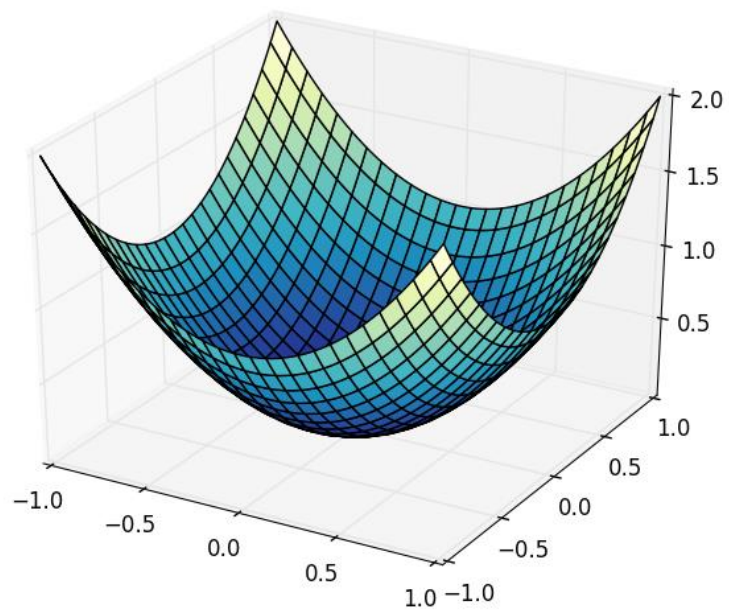


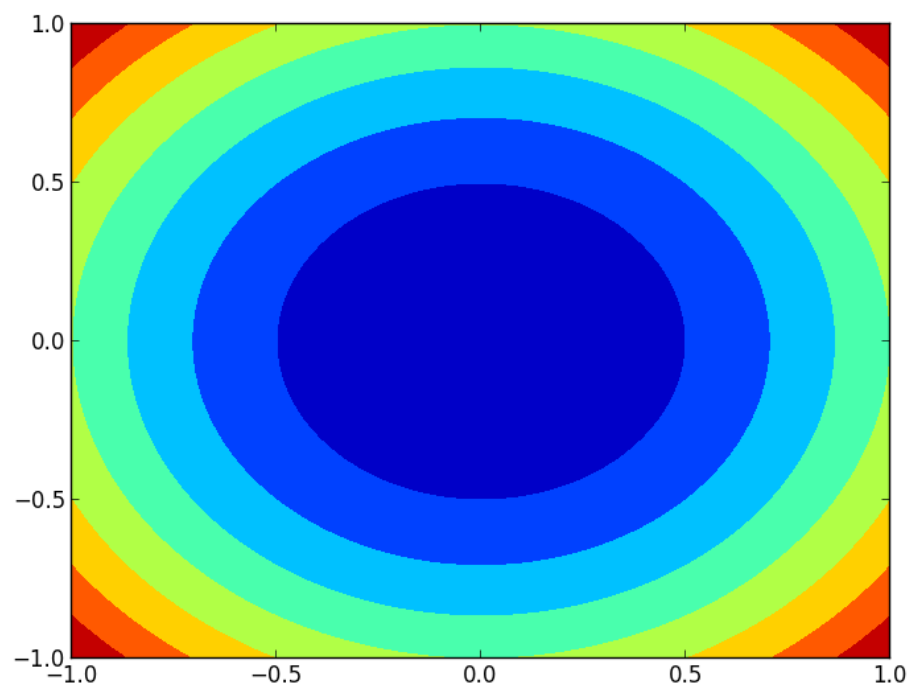


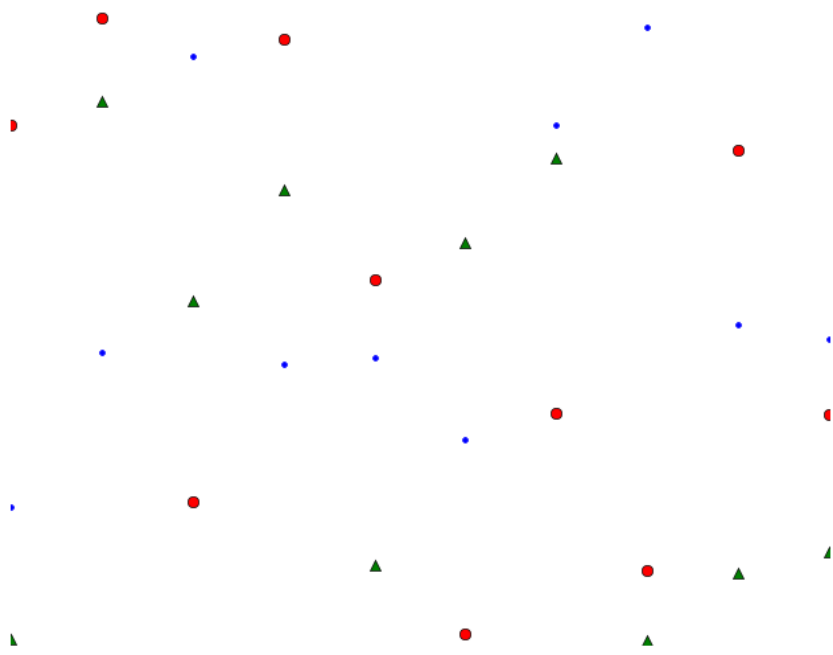




$$z = x^2 + y^2$$

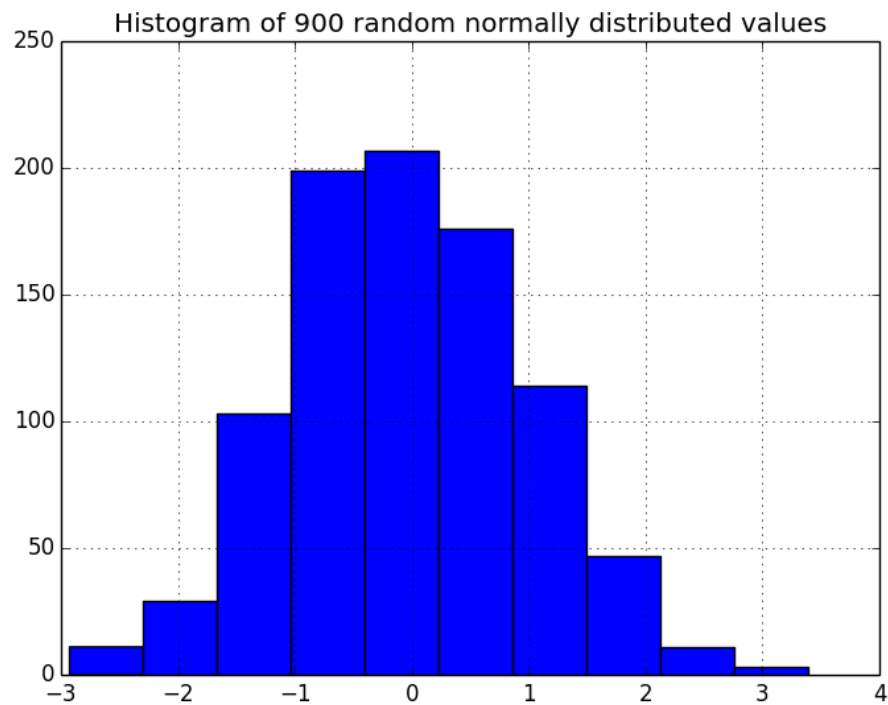


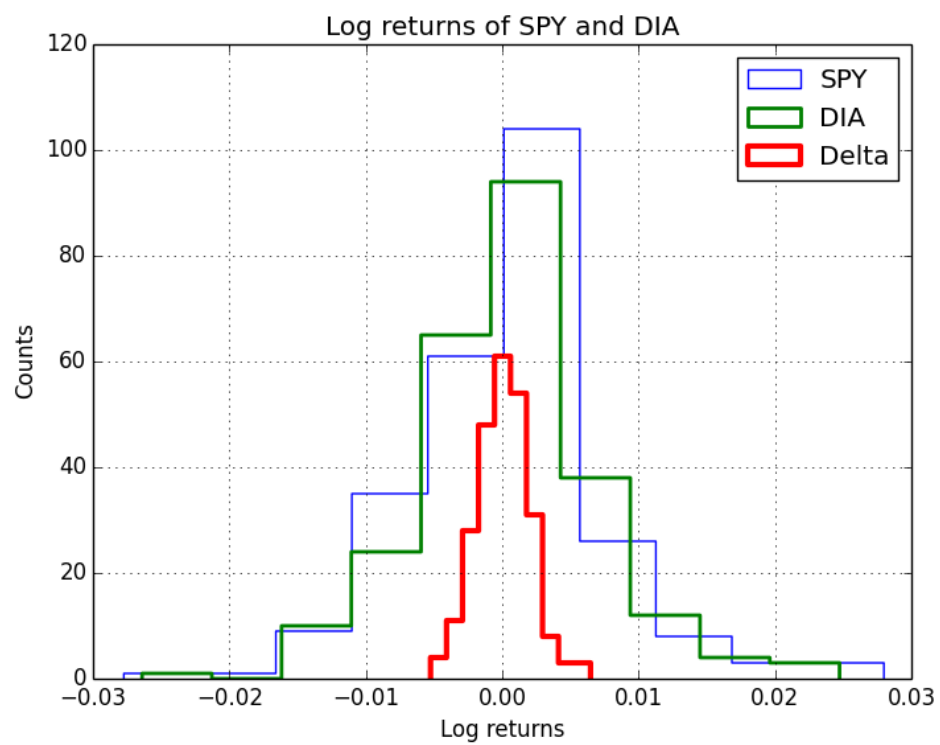


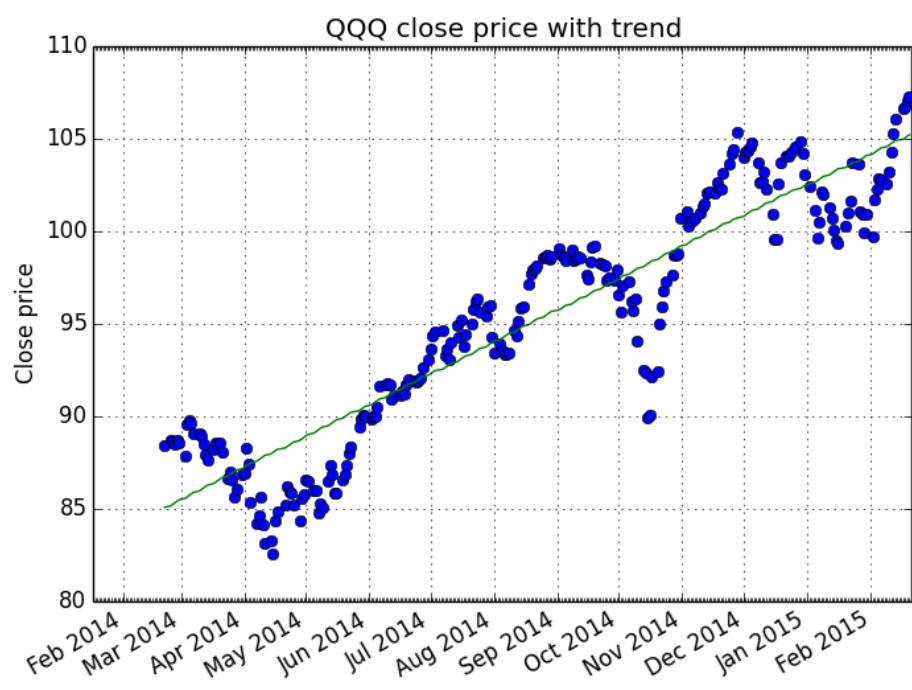


# 10

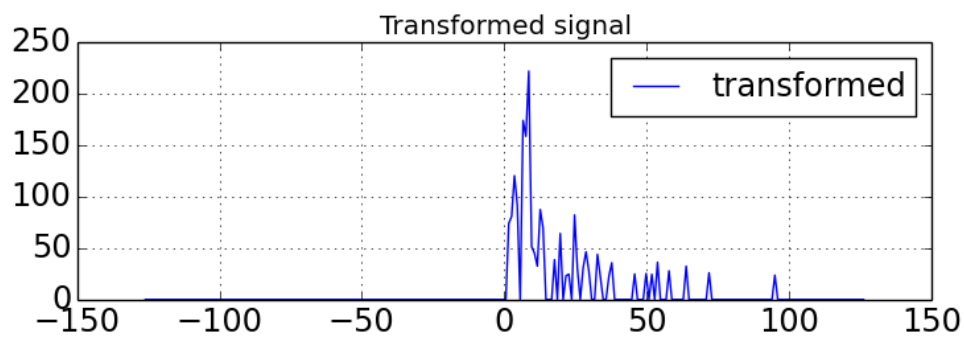
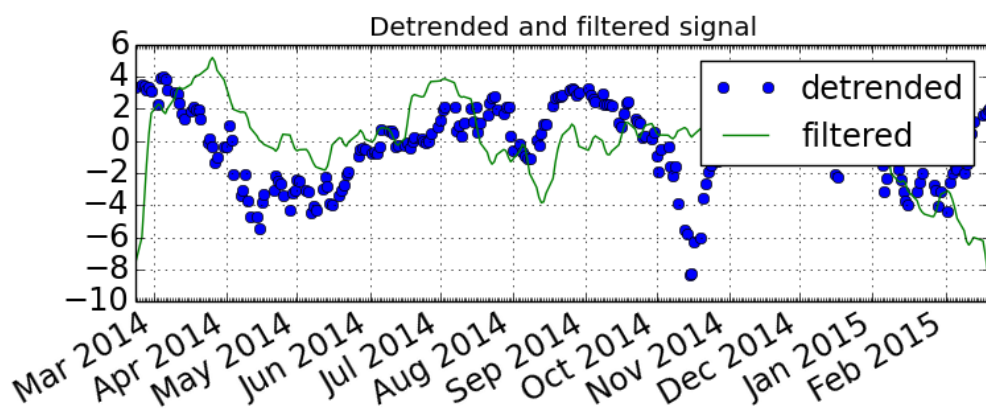
## When NumPy is Not Enough – SciPy and Beyond



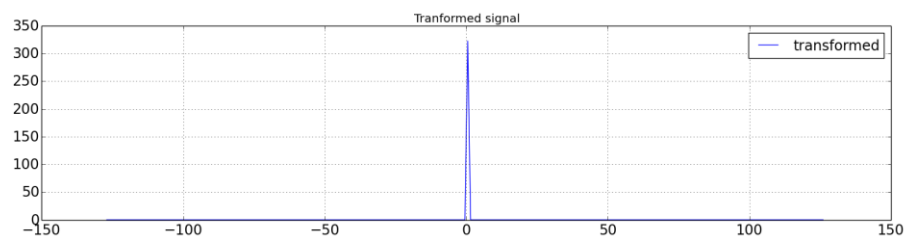
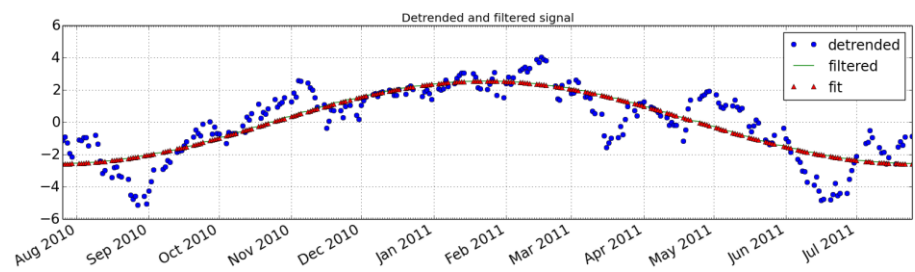




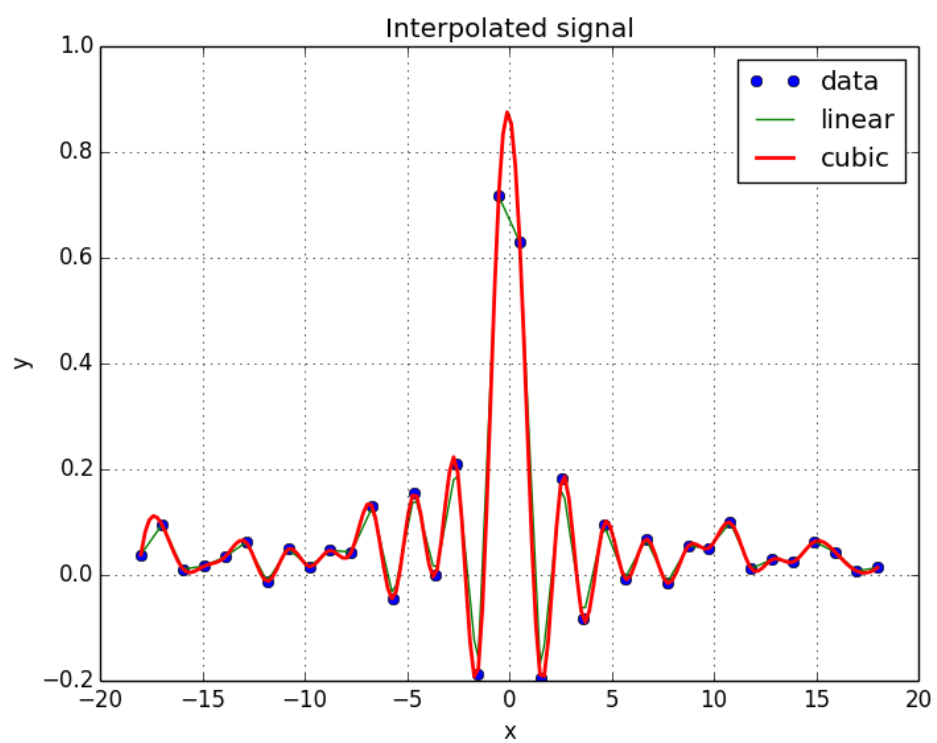
$$\sum_{t=-\infty}^{\infty} x[t]e^{-i\omega t}$$







$$\int_{-\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi}$$



Original Image



Median Filter

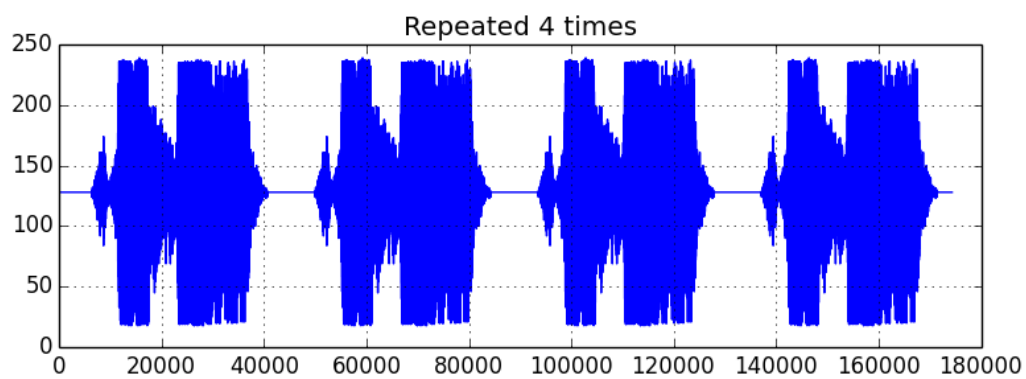
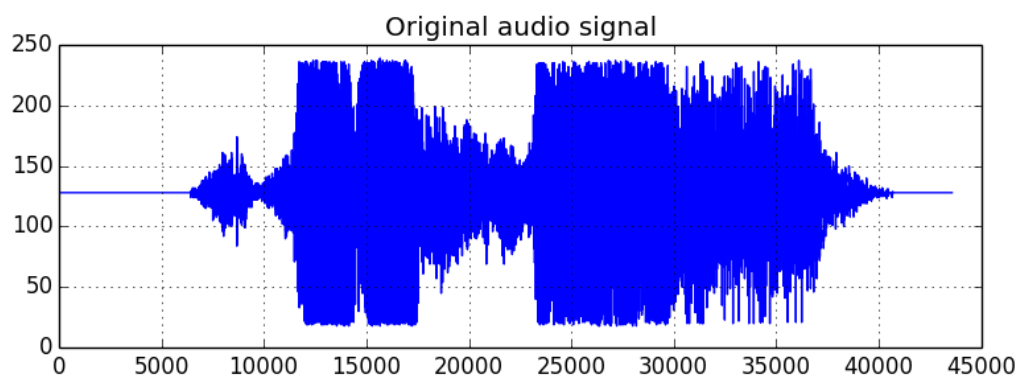


Rotated



Prewitt Filter

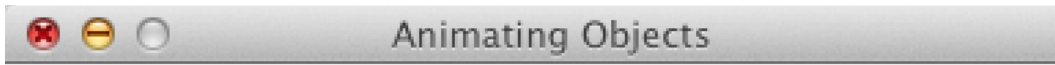




# 11

## Playing with Pygame





Animating Objects

