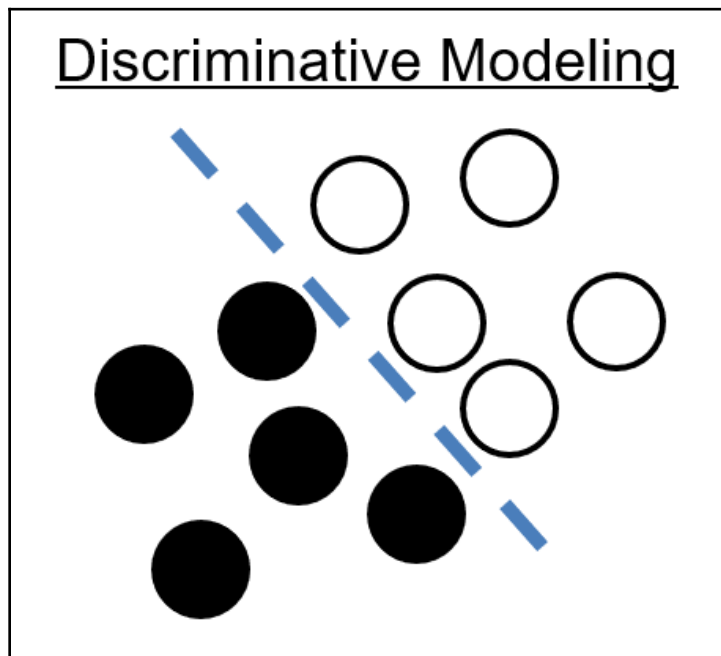
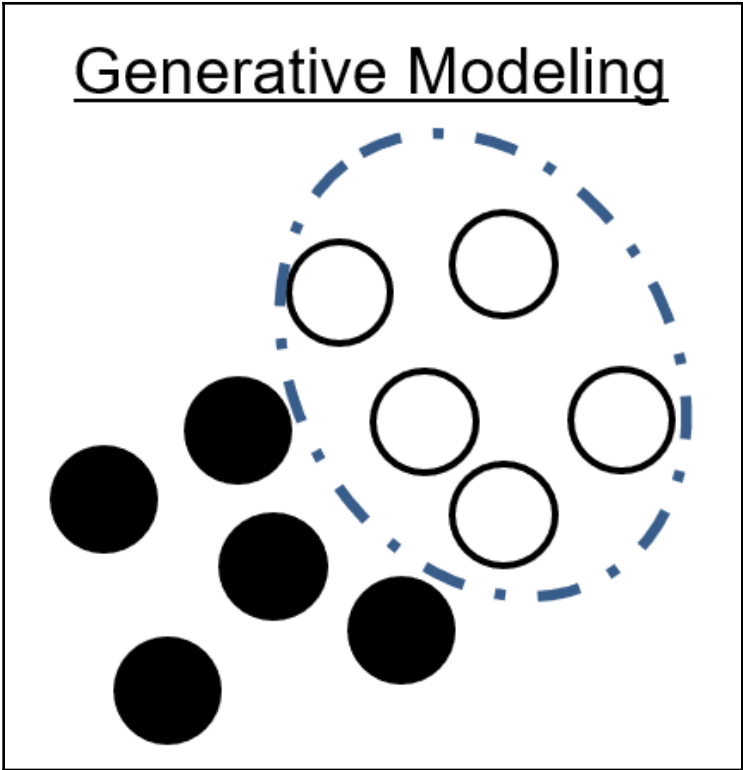
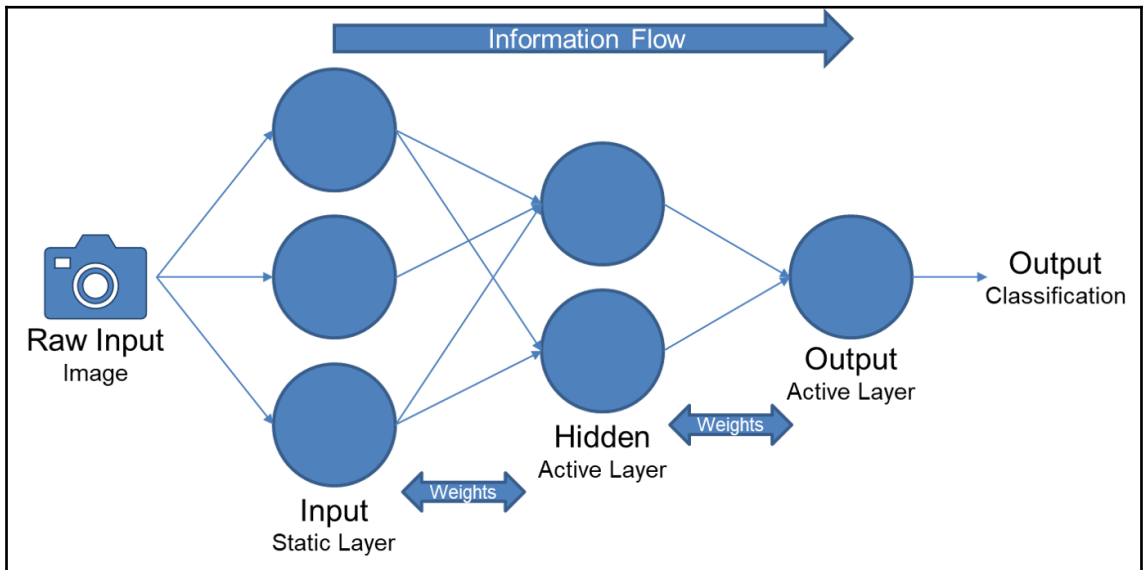
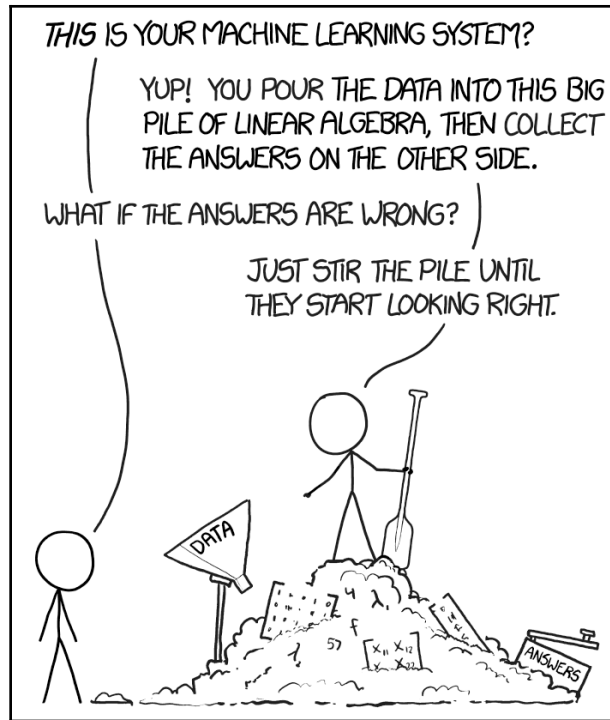


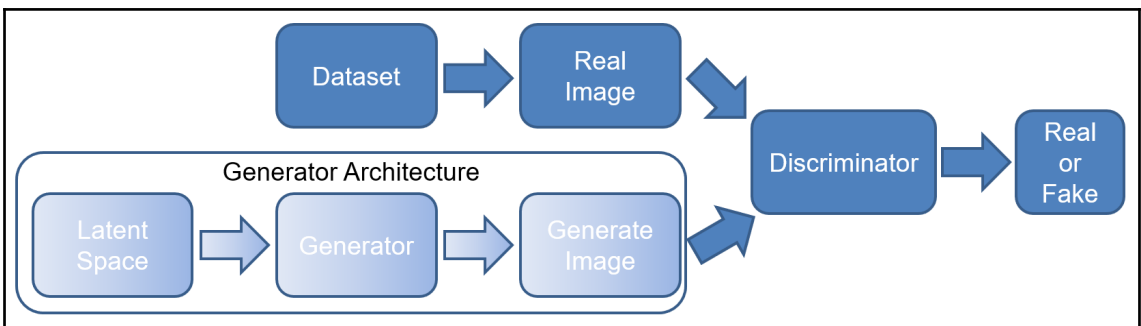
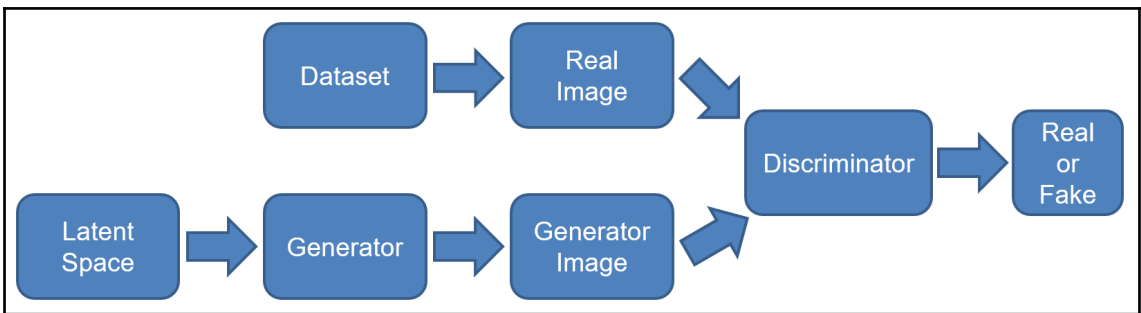
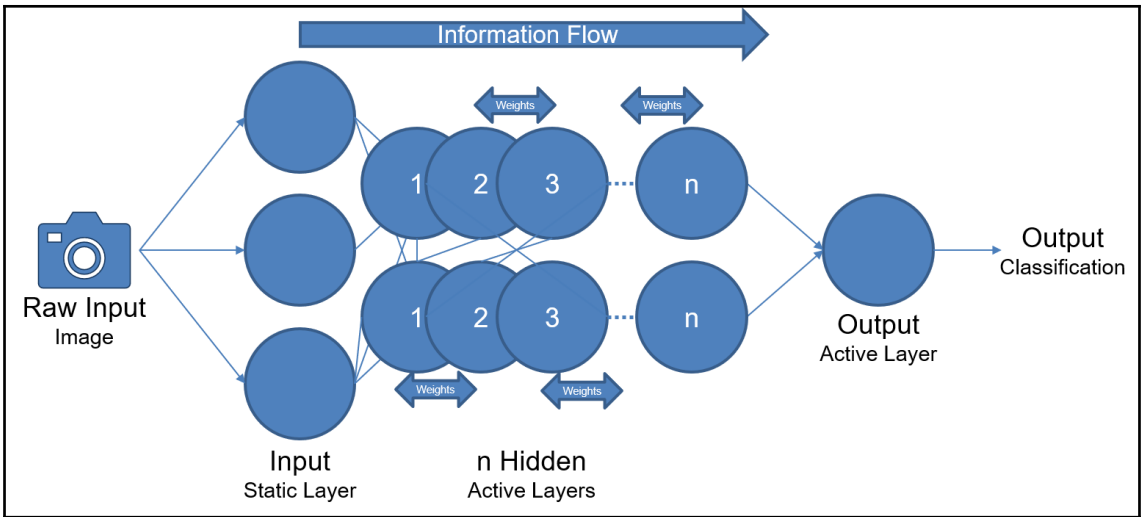
# 1 Graphics

## Chapter 1: What Is a Generative Adversarial Network?

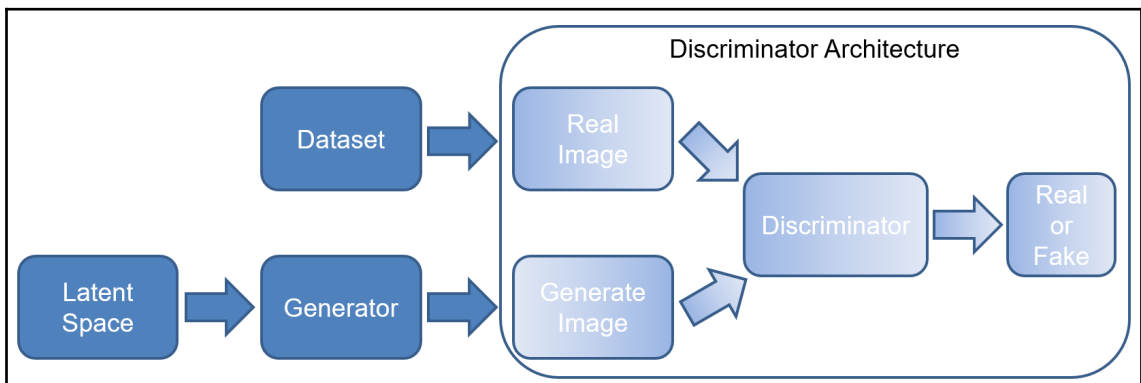






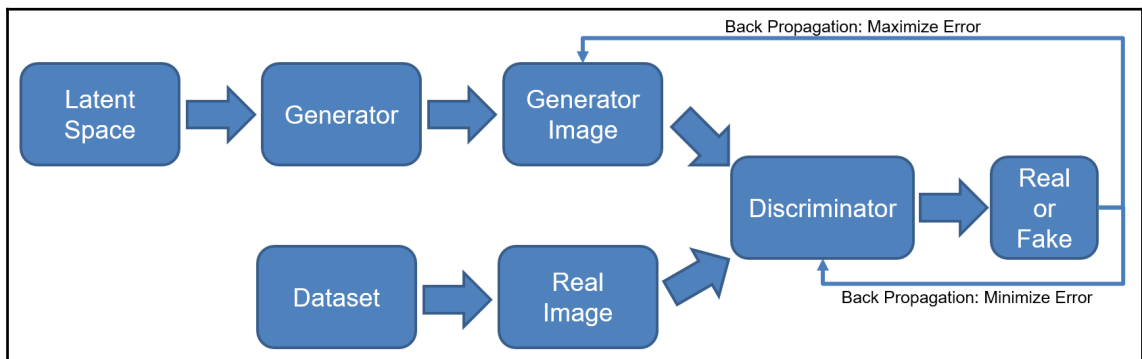


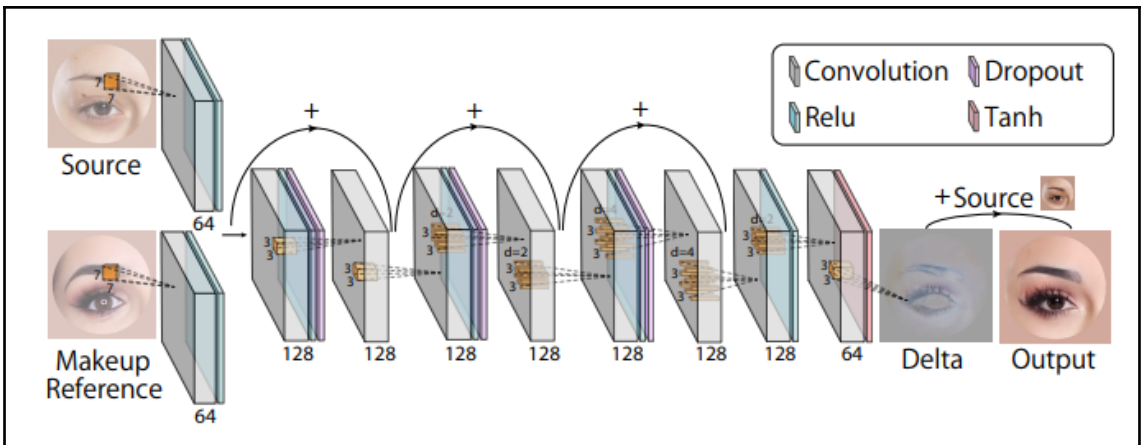
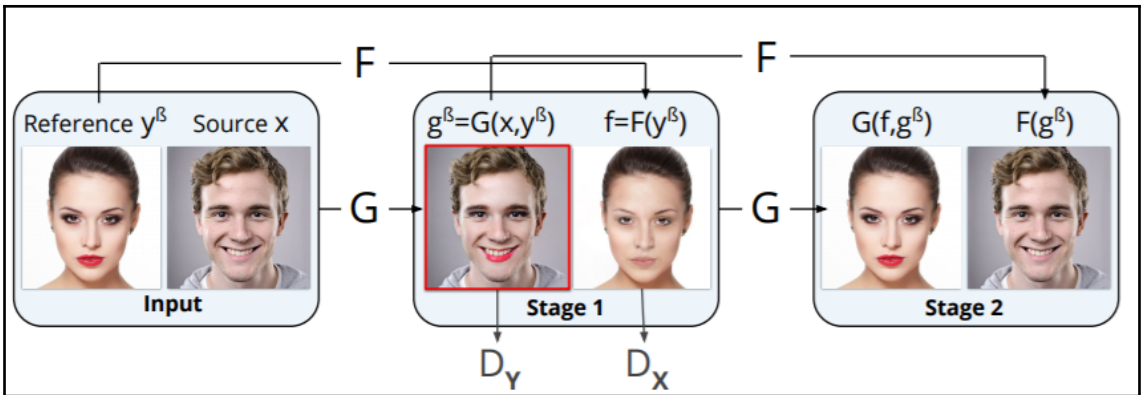
```
1 class Generator:
2
3     def __init__(self):
4         self.initVariable = 1
5
6     def lossFunction(self):
7
8         return
9
10    def buildModel(self):
11
12        return
13
14    def trainModel(self,inputX,inputY):
15
16        return
```



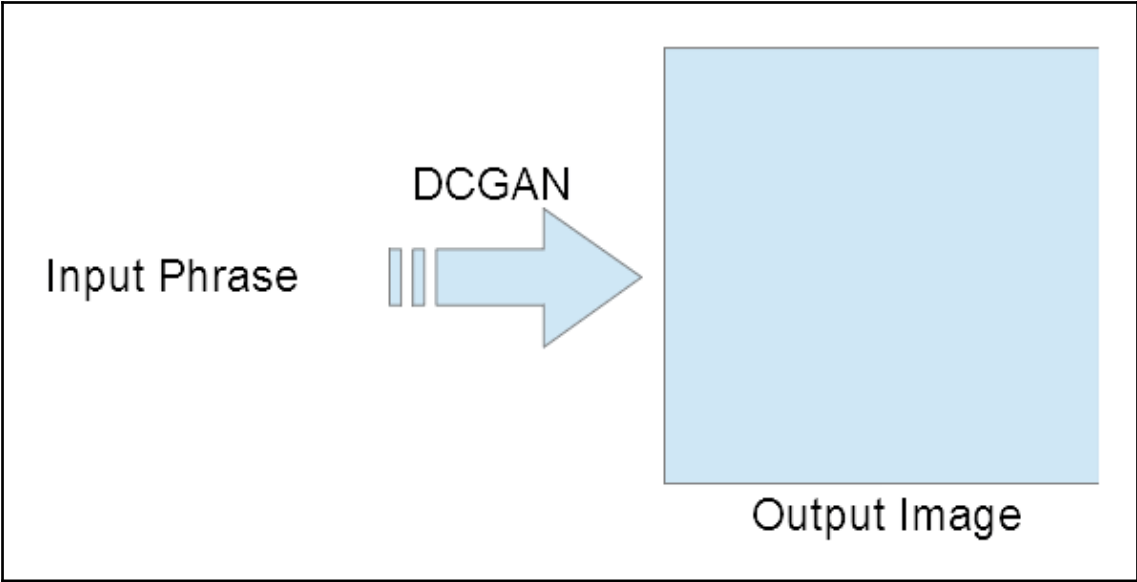
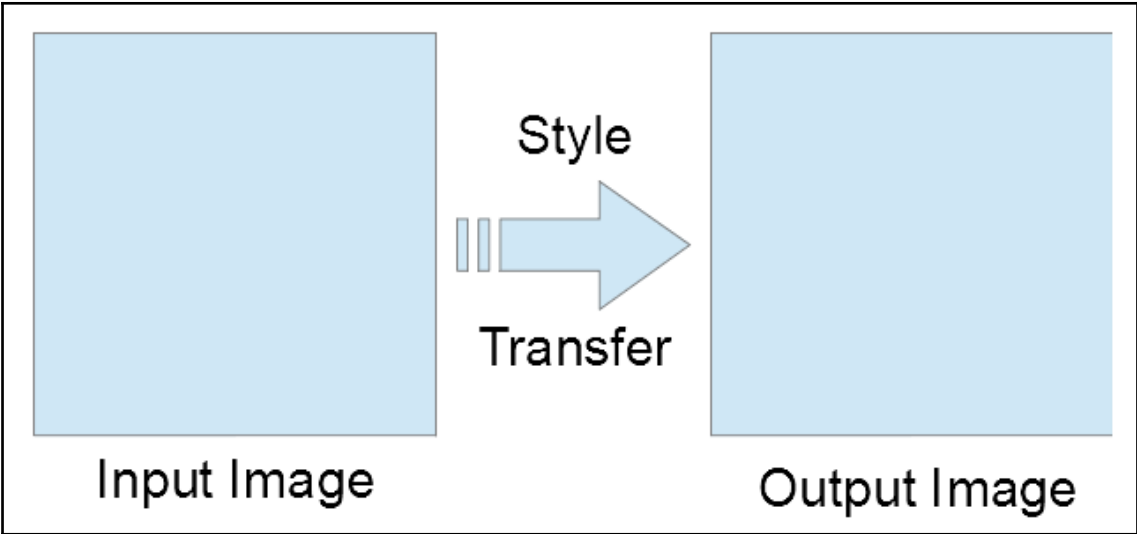
```
1  class Discriminator:
2
3      def __init__(self):
4          self.initVariable = 1
5
6      def lossFunction(self):
7
8          return
9
10     def buildModel(self):
11
12         return
13
14     def trainModel(self,inputX,inputY):
15
16         return
```

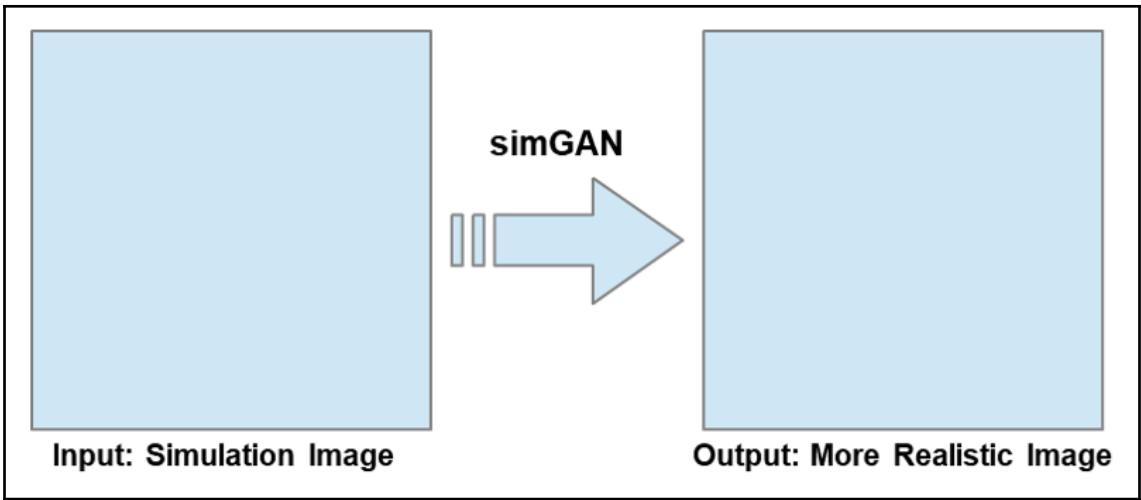
```
1 class Loss:
2
3     def __init__(self):
4         self.initVariable = 1
5
6     def lossBaseFunction1(self):
7
8         return
9
10    def lossBaseFunction2(self):
11
12        return
13
14    def lossBaseFunction3(self):
15
16        return
```



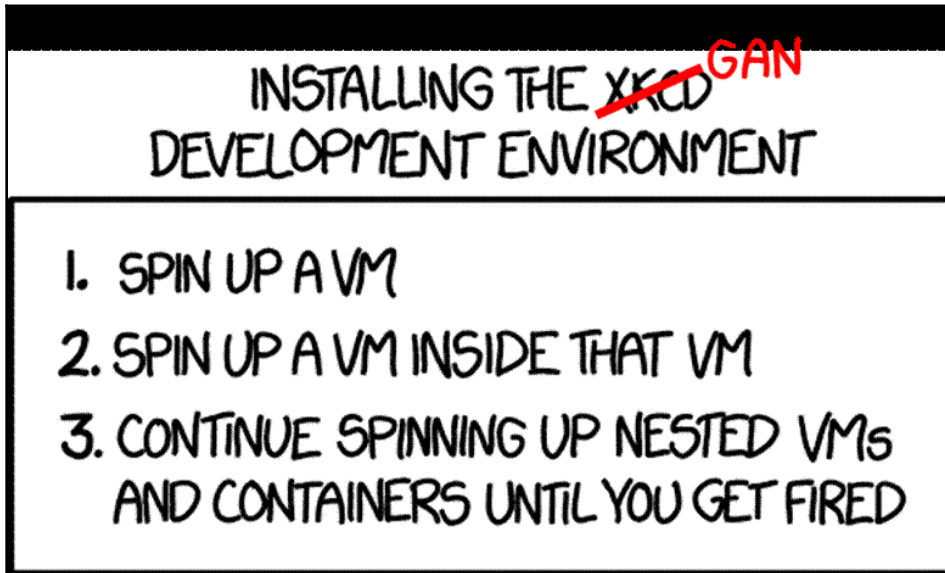








## Chapter 2: Data First, Easy Environment, and Data Prep

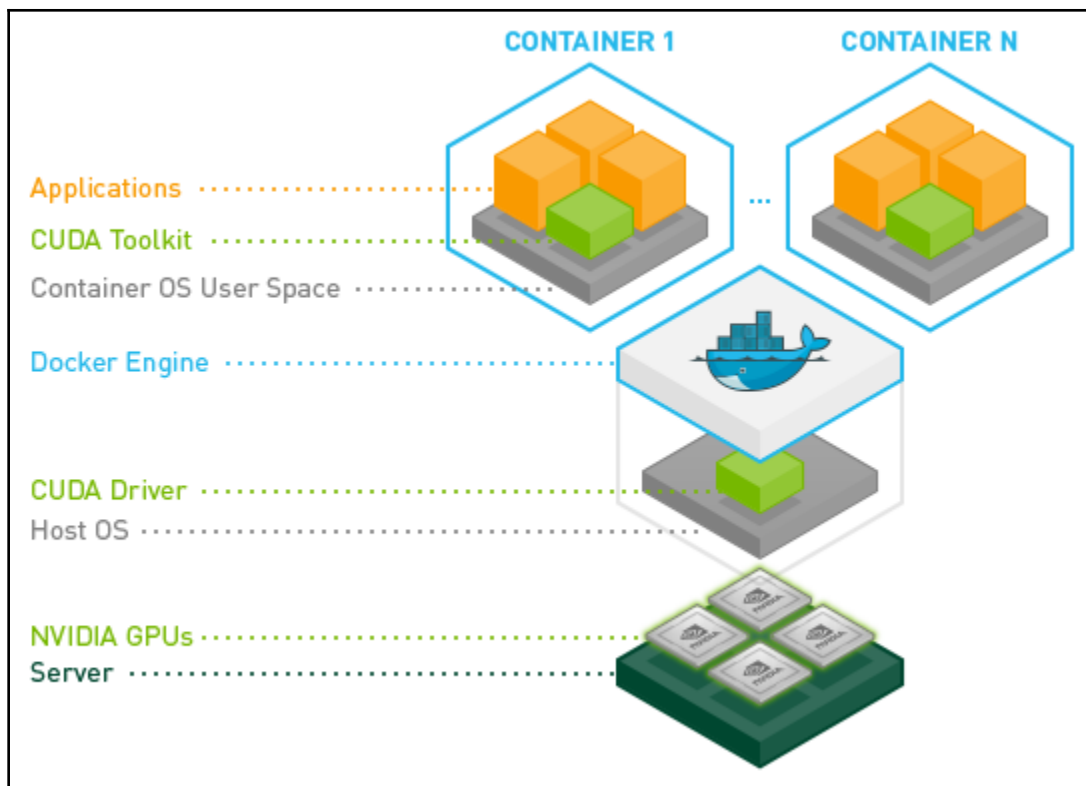


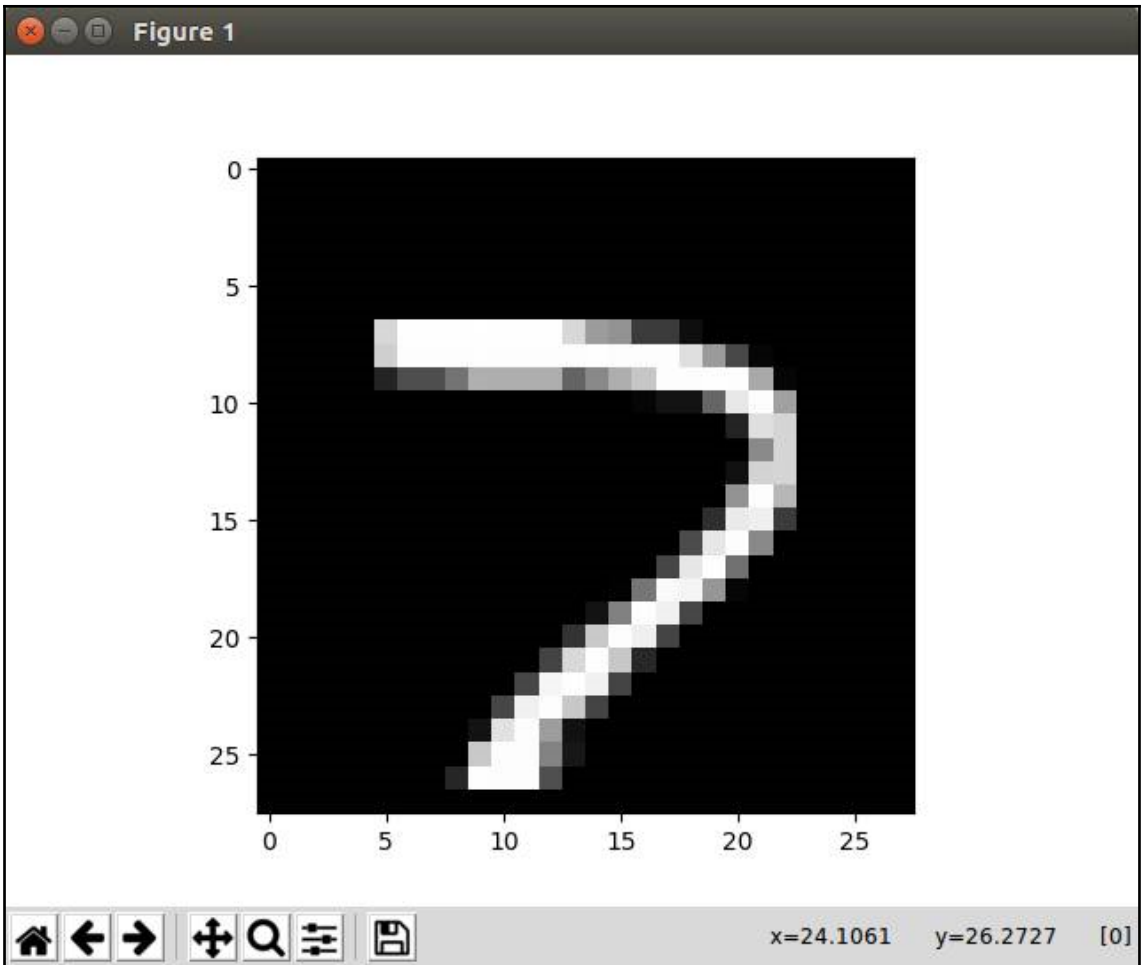
```

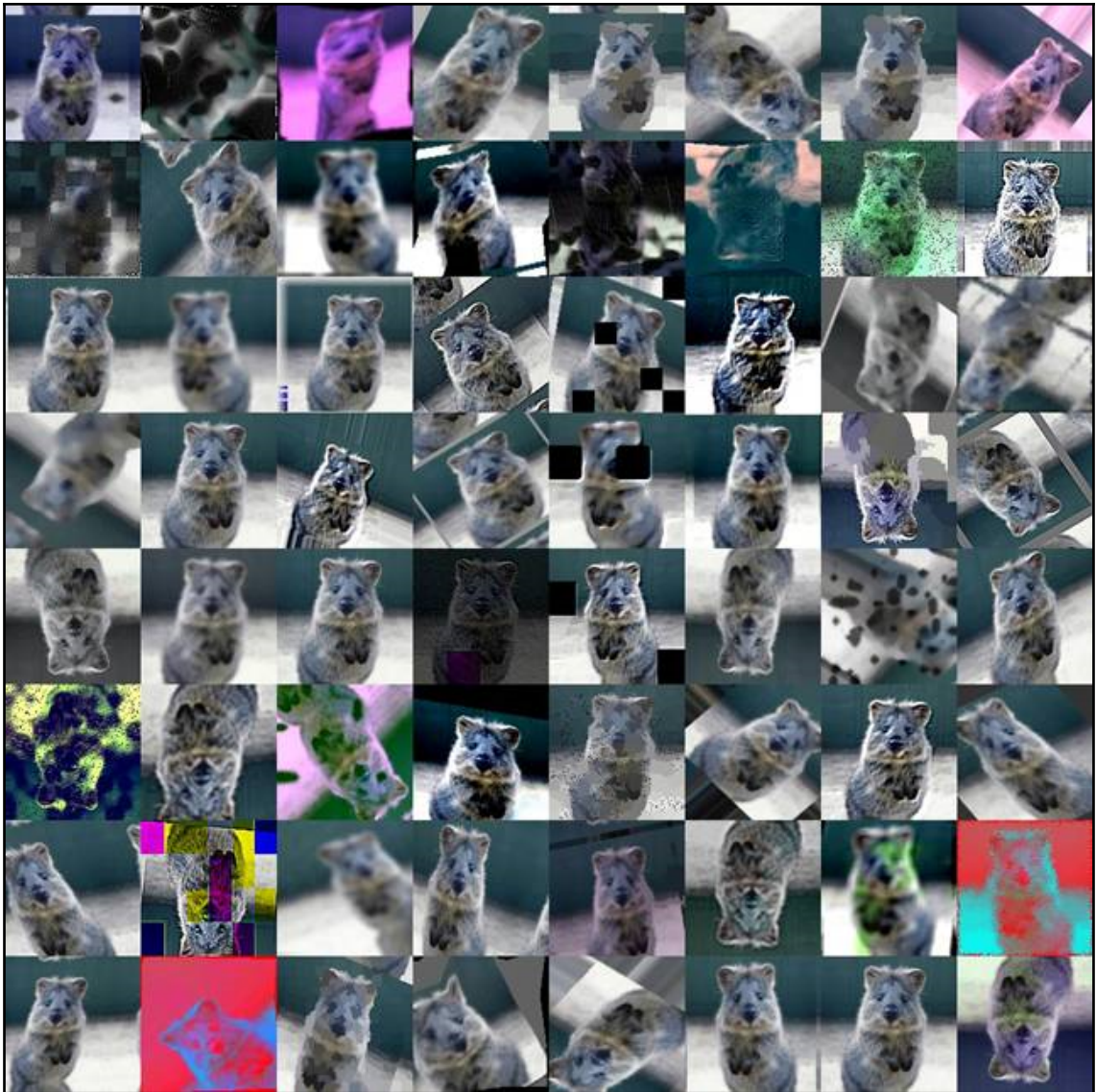
NVIDIA-SMI 384.90                Driver Version: 384.90
-----+-----+-----+-----+-----+-----+-----+
GPU  Name          Persistence-M| Bus-Id        Disp.A | Volatile Uncorr. ECC |
Fan  Temp   Perf   Pwr:Usage/Cap|      Memory-Usage | GPU-Util  Compute M. |
-----+-----+-----+-----+-----+-----+
  0   Tesla K80           Off   | 00000000:00:04.0 Off  |      0          0   |
N/A   34C    P0      70W / 149W | 11439MiB / 11439MiB |      0%      Default  |
-----+-----+-----+-----+-----+

Processes:
GPU      PID    Type   Process name      GPU Memory
-----+-----+-----+-----+-----+
  0      5880   C      python3           10860MiB
  0      5916   C      python3           341MiB
  0      6154   C      python3           225MiB
-----+-----+-----+-----+-----+

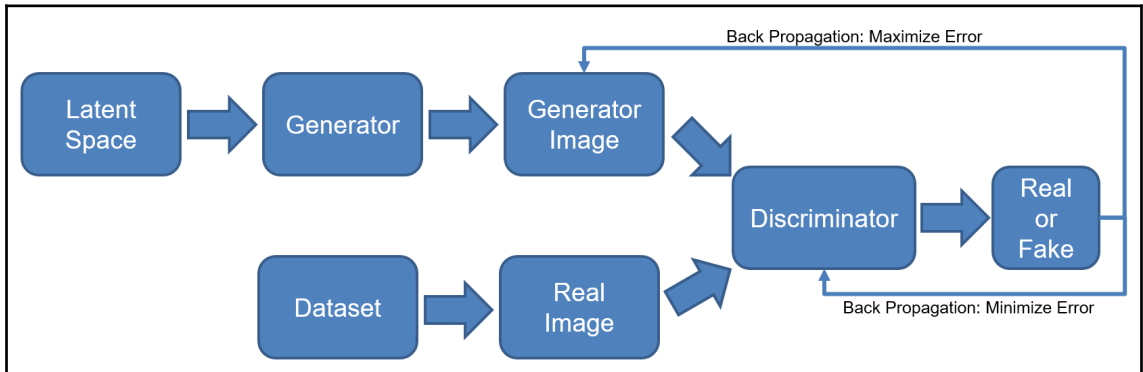
```

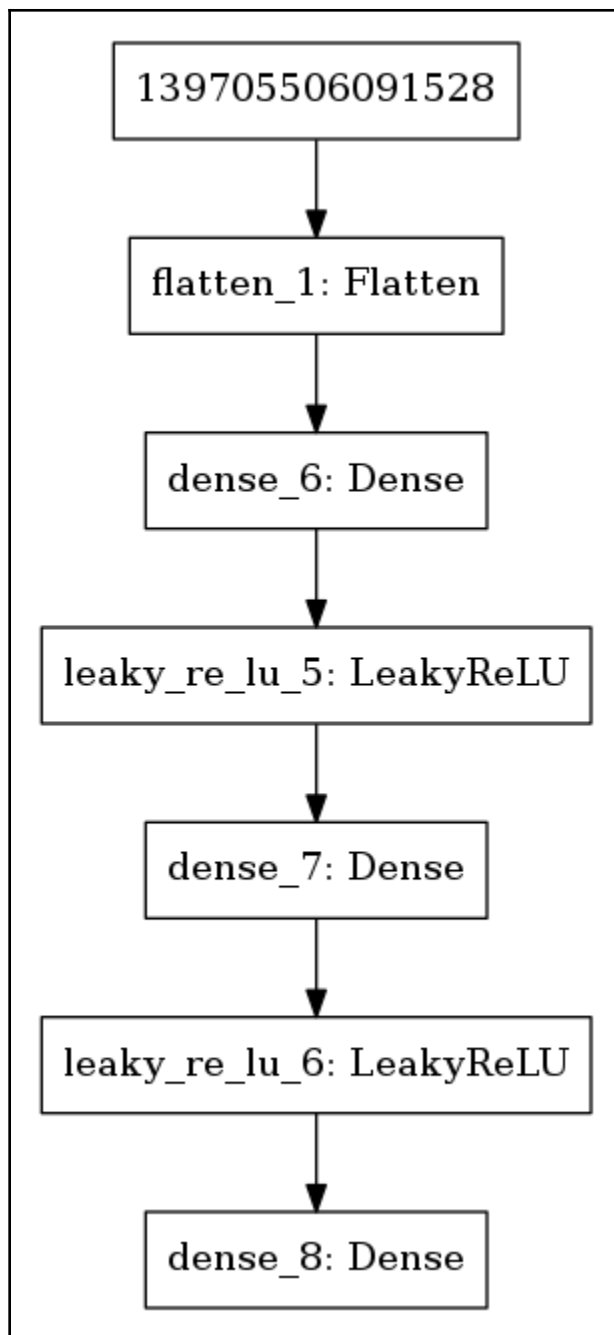




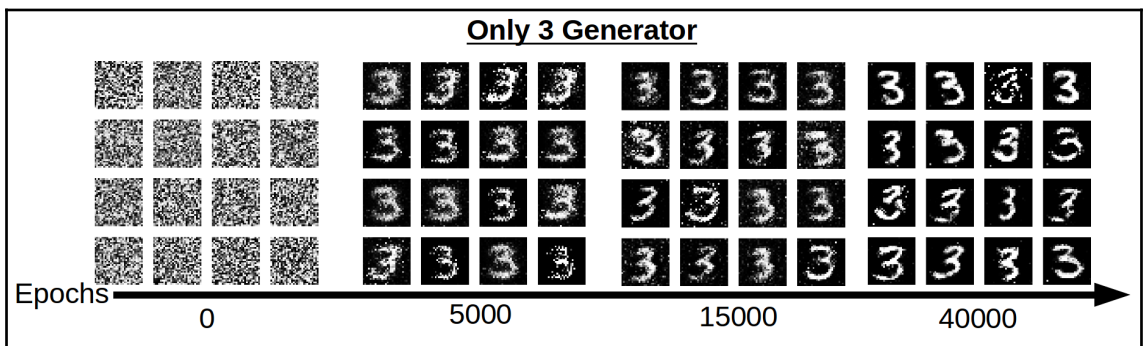
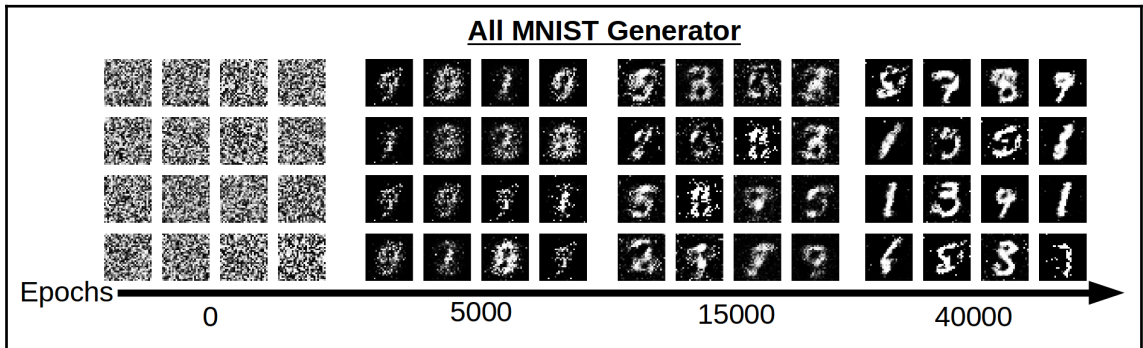
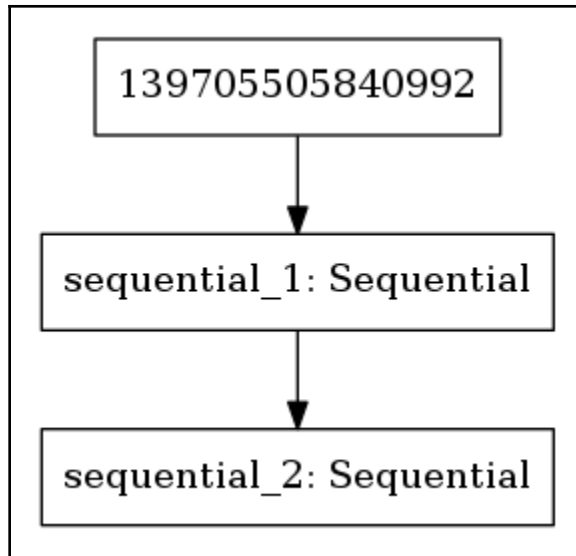


# Chapter 3: My First GAN in Under 100 Lines

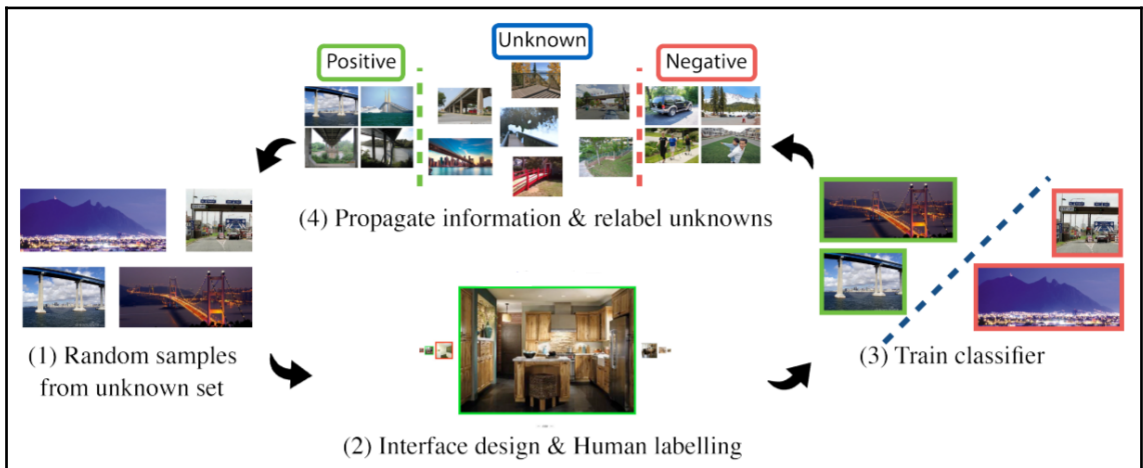
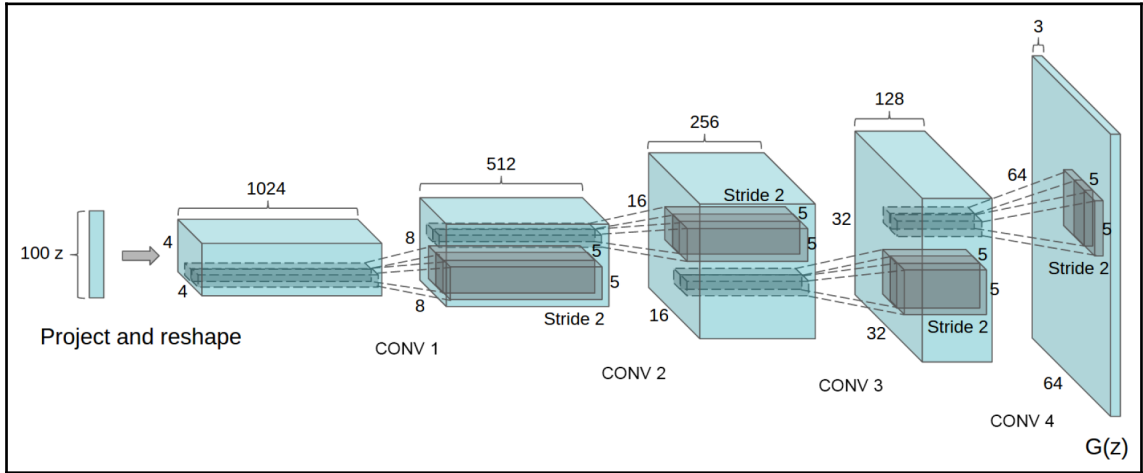


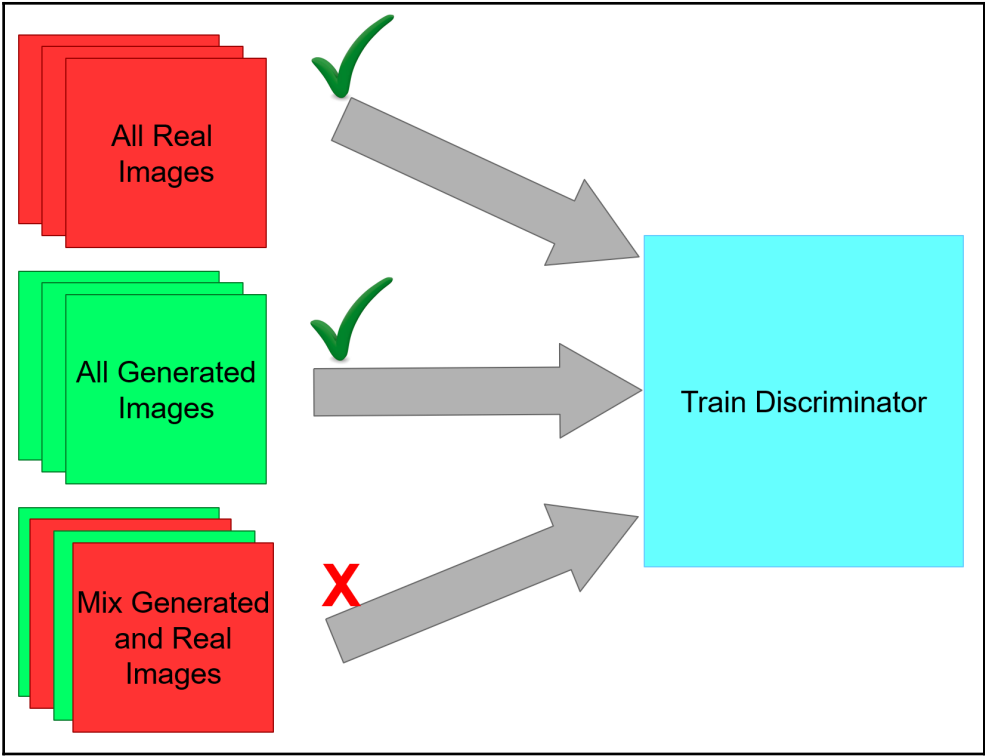


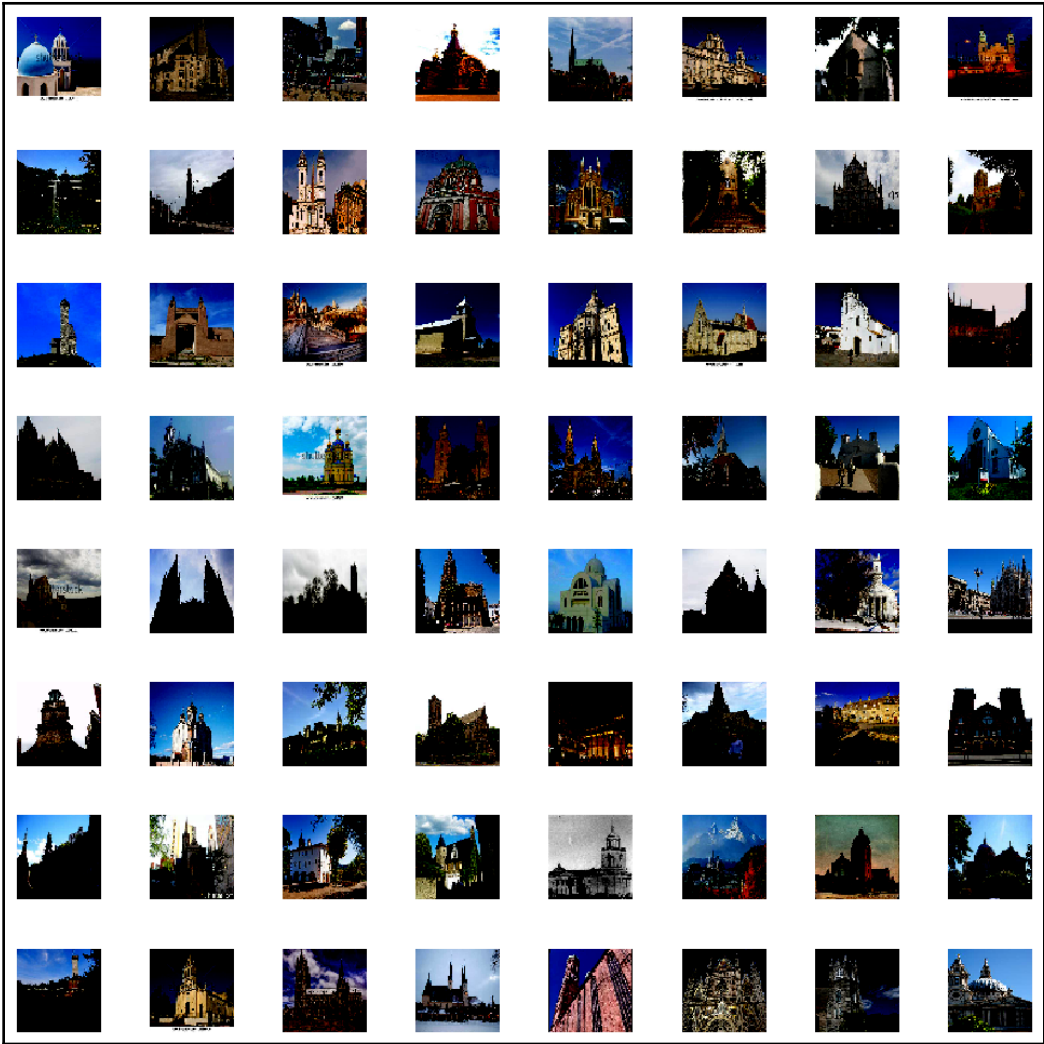


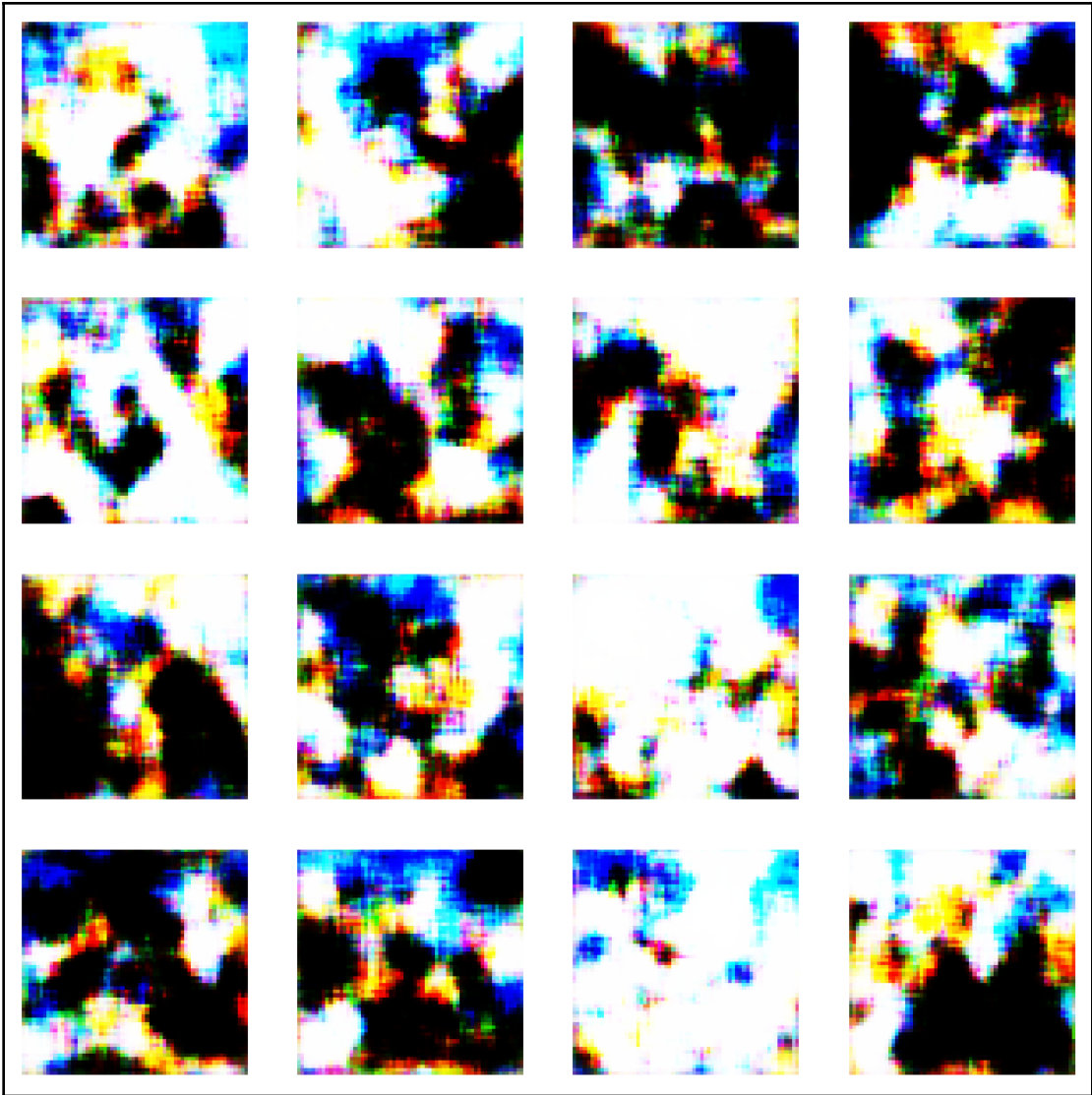


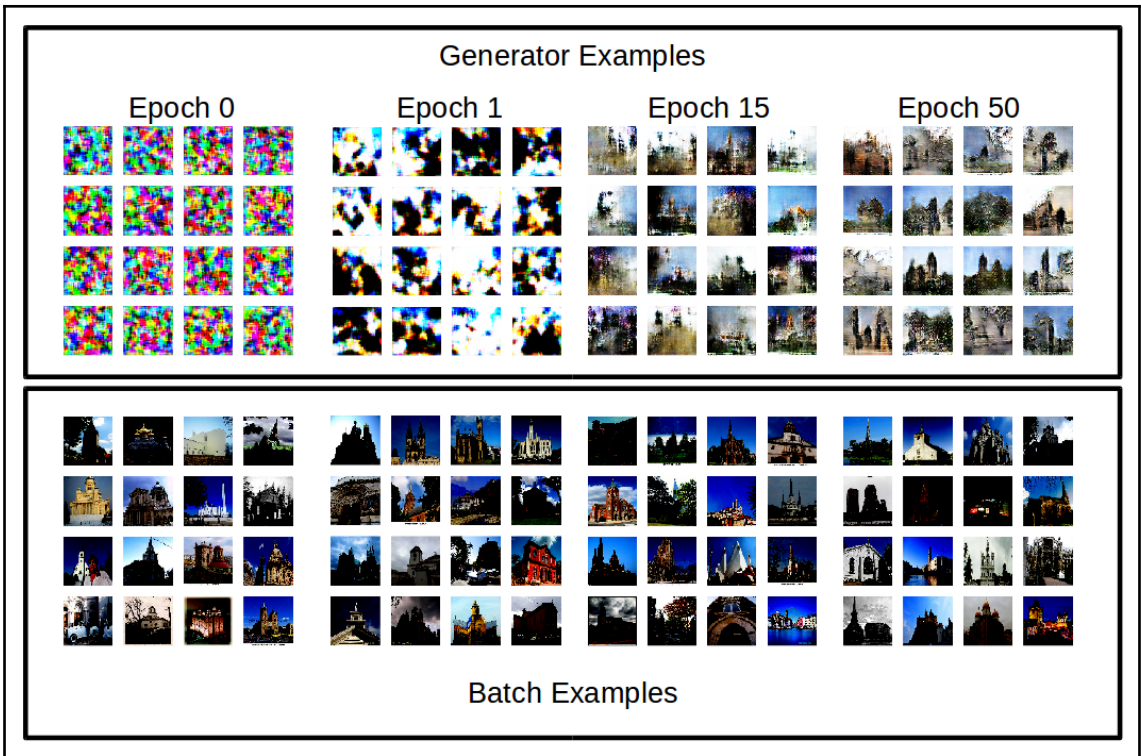
# Chapter 4: Dreaming of New Outdoor Structures Using DCGAN



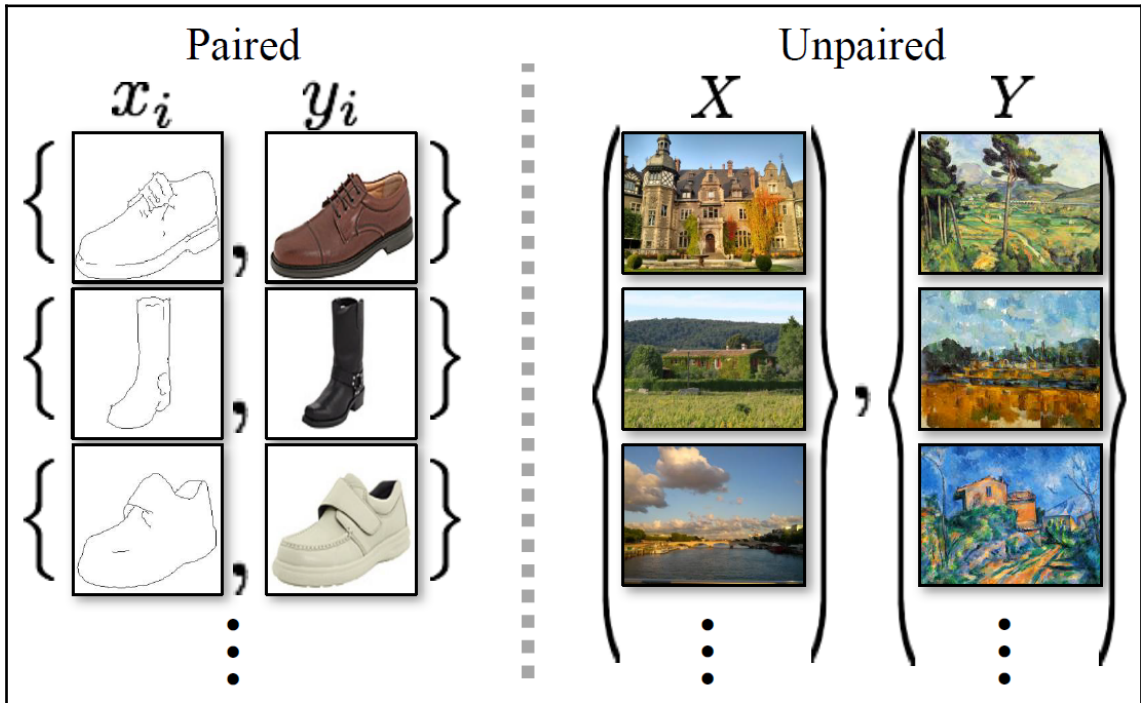






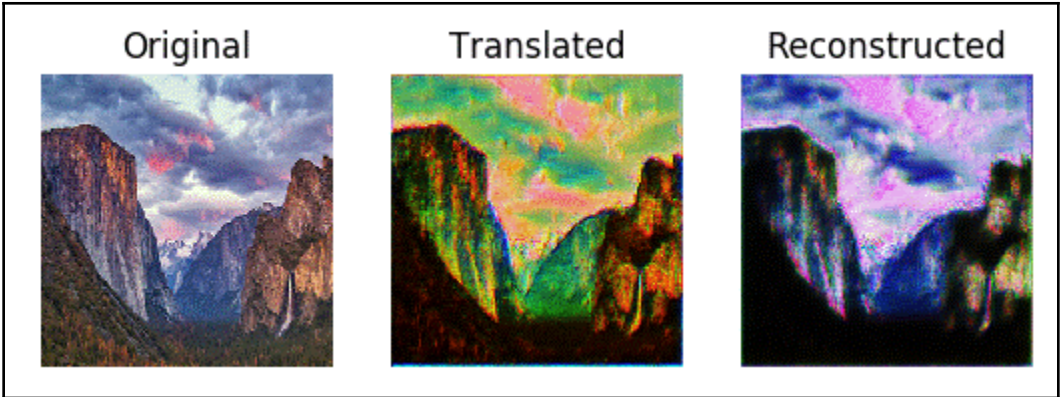


## Chapter 5: Pix2Pix Image-to-Image Translation

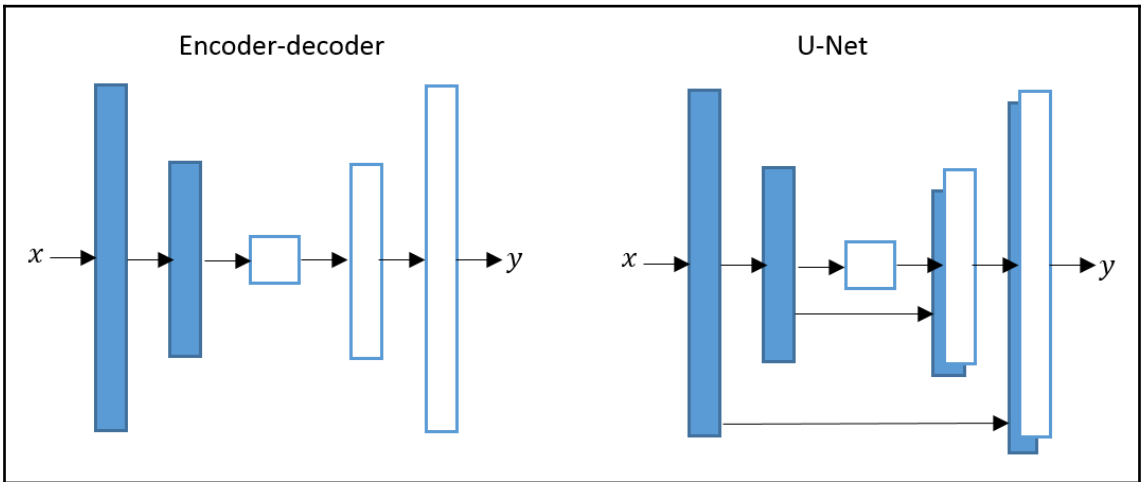
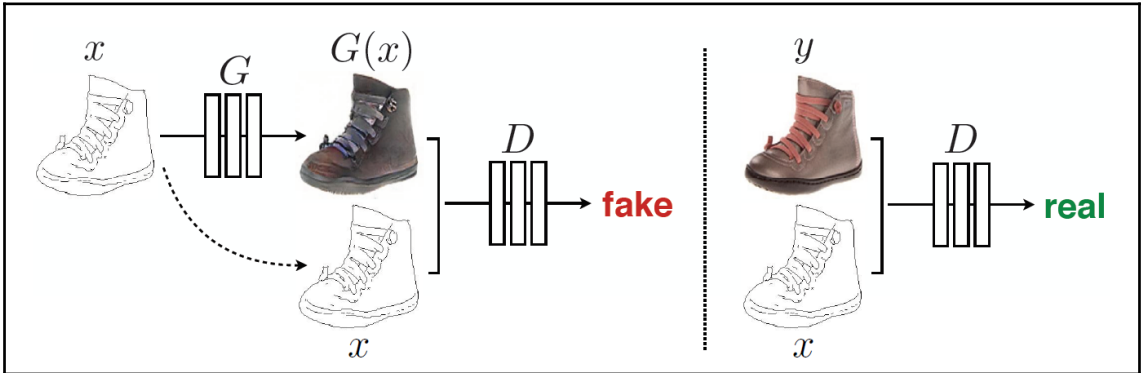




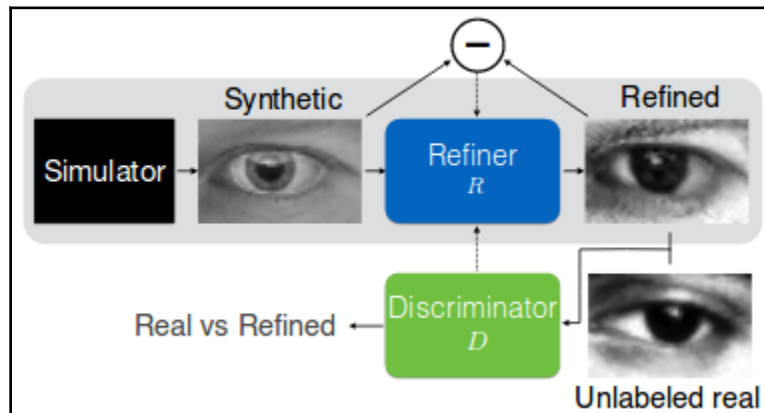




# Chapter 6: Style Transferring Your Image Using CycleGAN



## Chapter 7: Using Simulated Images To Create Photo-Realistic Eyeballs with SimGAN



**Algorithm 1:** Adversarial training of refiner network  $R_\theta$ 

**Input:** Sets of synthetic images  $\mathbf{x}_i \in \mathcal{X}$ , and real images  $\mathbf{y}_j \in \mathcal{Y}$ , max number of steps ( $T$ ), number of discriminator network updates per step ( $K_d$ ), number of generative network updates per step ( $K_g$ ).

**Output:** ConvNet model  $R_\theta$ .




```

for  $t = 1, \dots, T$  do
  for  $k = 1, \dots, K_g$  do
    1. Sample a mini-batch of synthetic images  $\mathbf{x}_i$ .
    2. Update  $\theta$  by taking a SGD step on mini-batch loss  $\mathcal{L}_R(\theta)$  in (4).
  end
  for  $k = 1, \dots, K_d$  do
    1. Sample a mini-batch of synthetic images  $\mathbf{x}_i$ , and real images  $\mathbf{y}_j$ .
    2. Compute  $\tilde{\mathbf{x}}_i = R_\theta(\mathbf{x}_i)$  with current  $\theta$ .
    3. Update  $\phi$  by taking a SGD step on mini-batch loss  $\mathcal{L}_D(\phi)$  in (2).
  end
end

```

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# Chapter 8: From Image to 3D Models Using GANs

