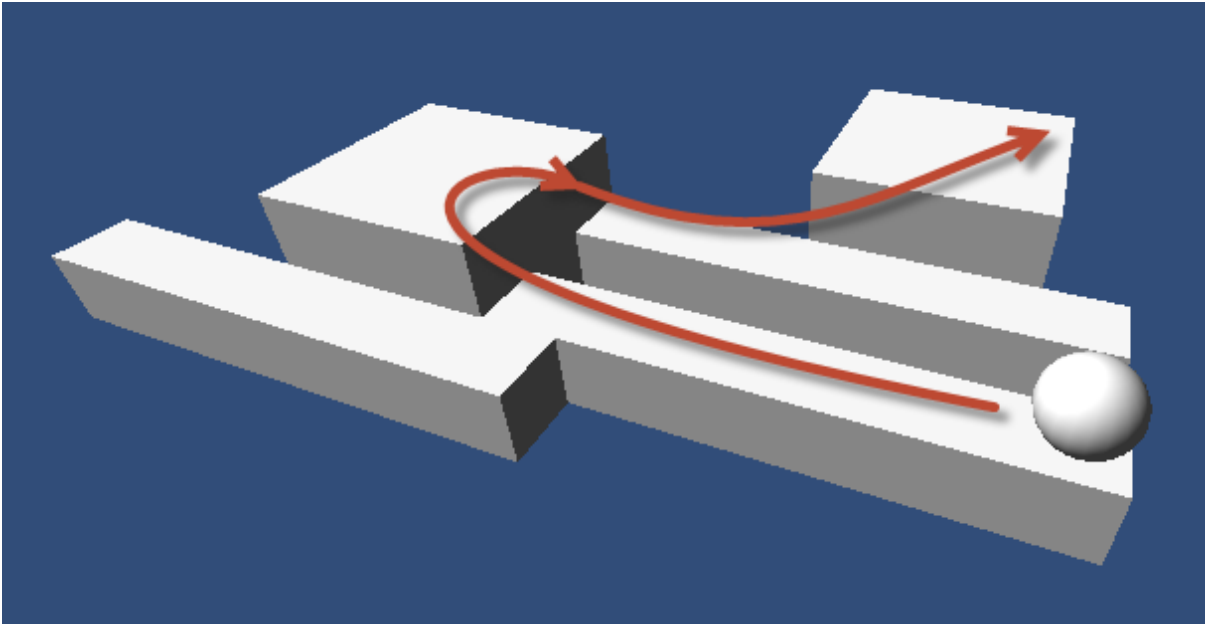
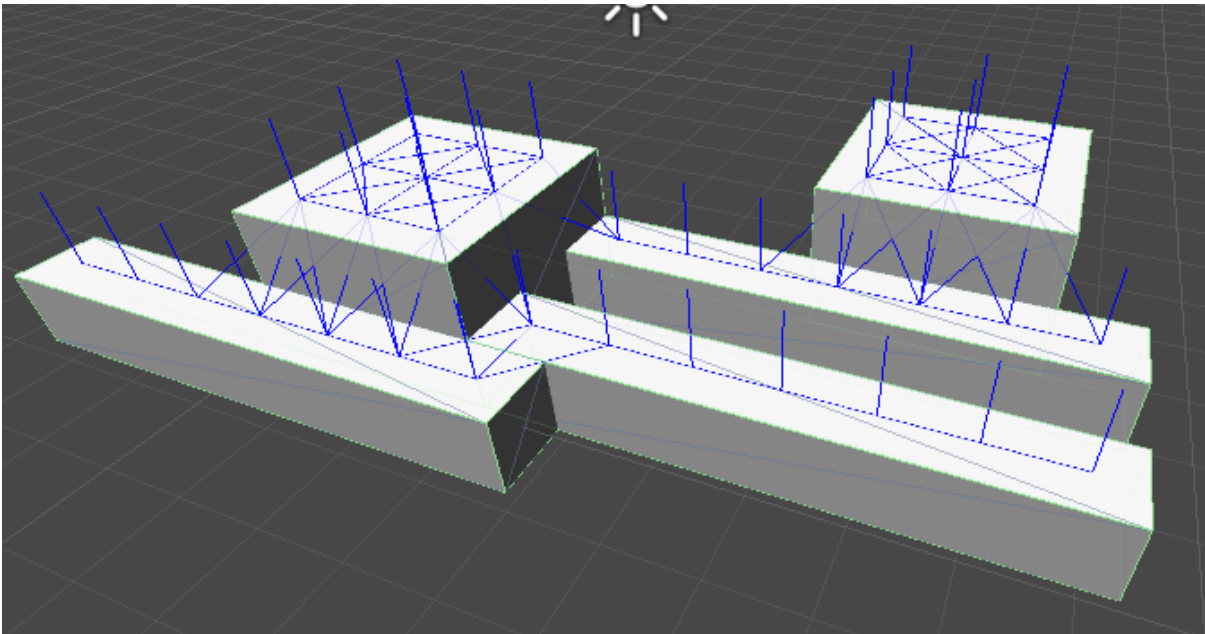
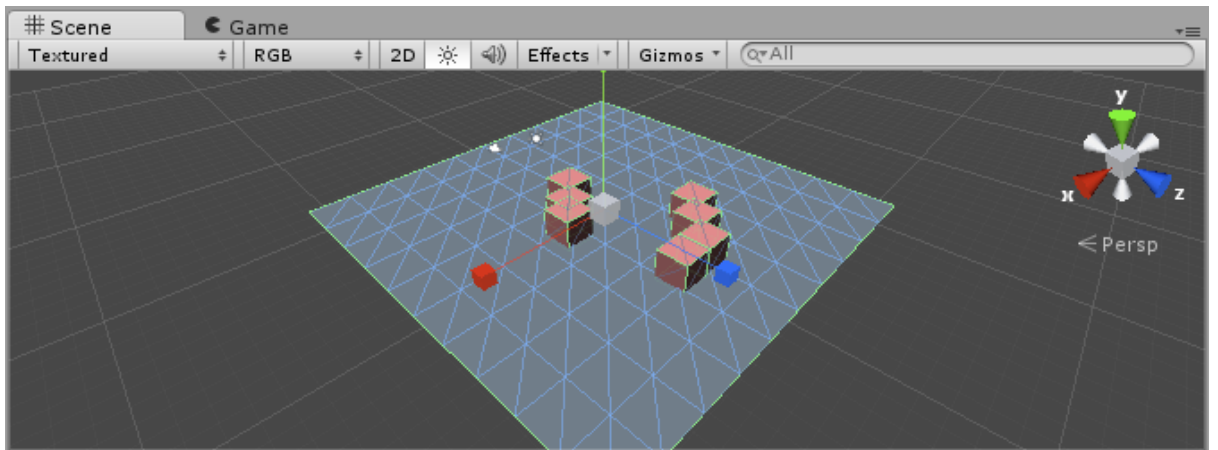
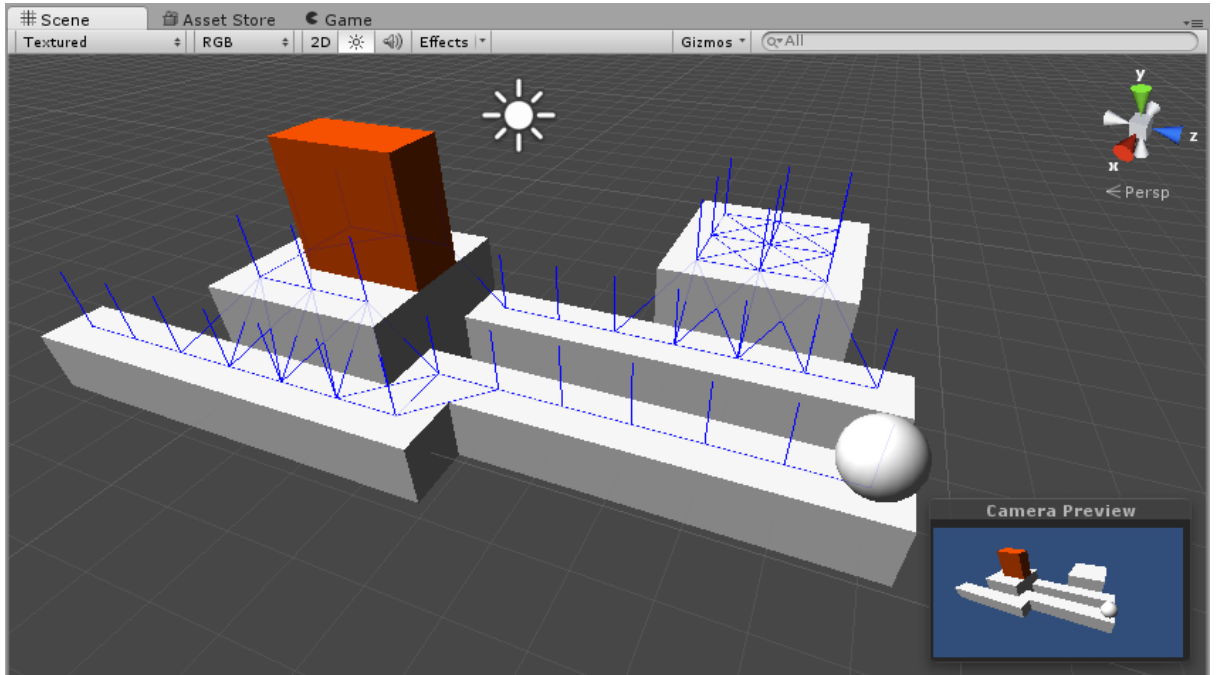
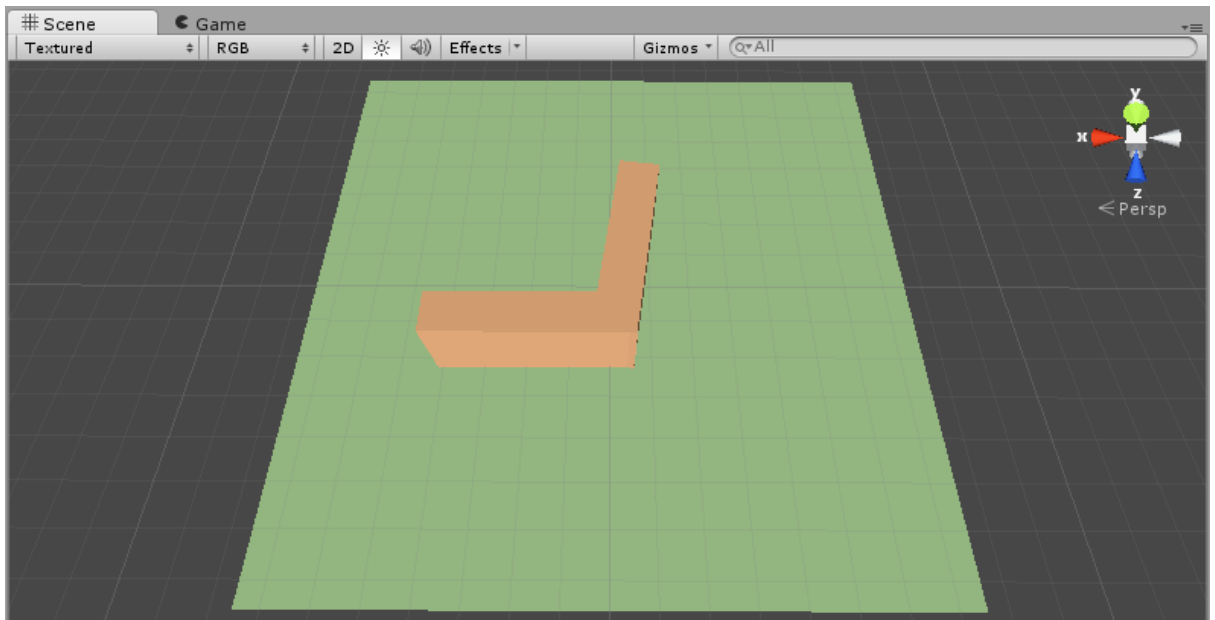
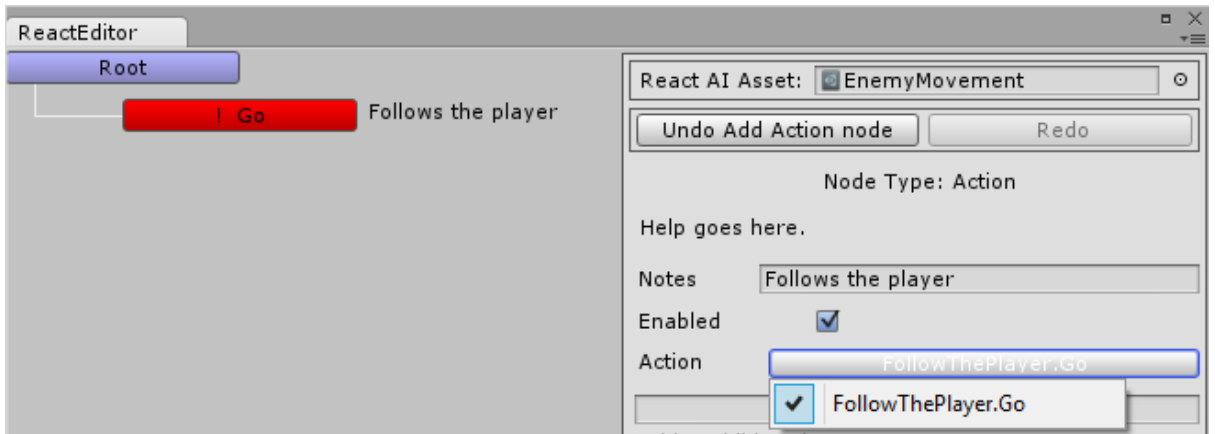
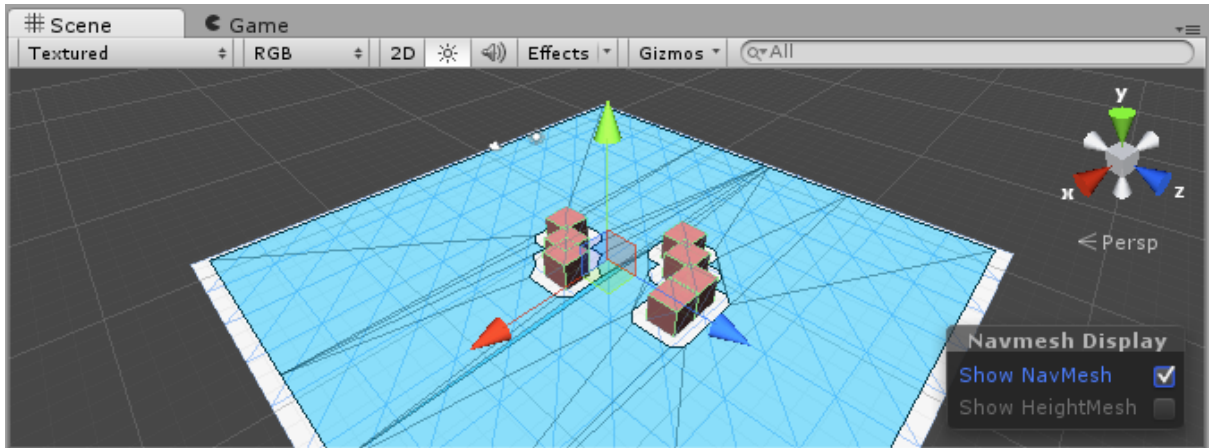
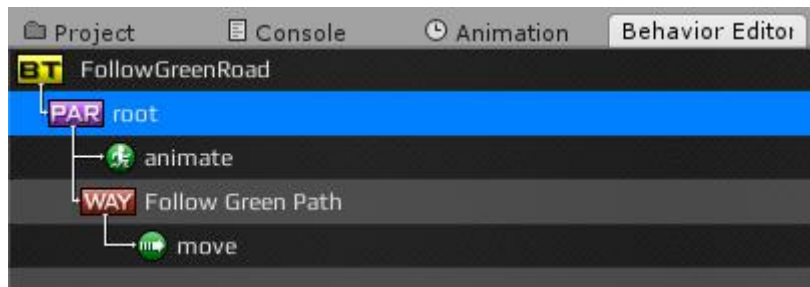
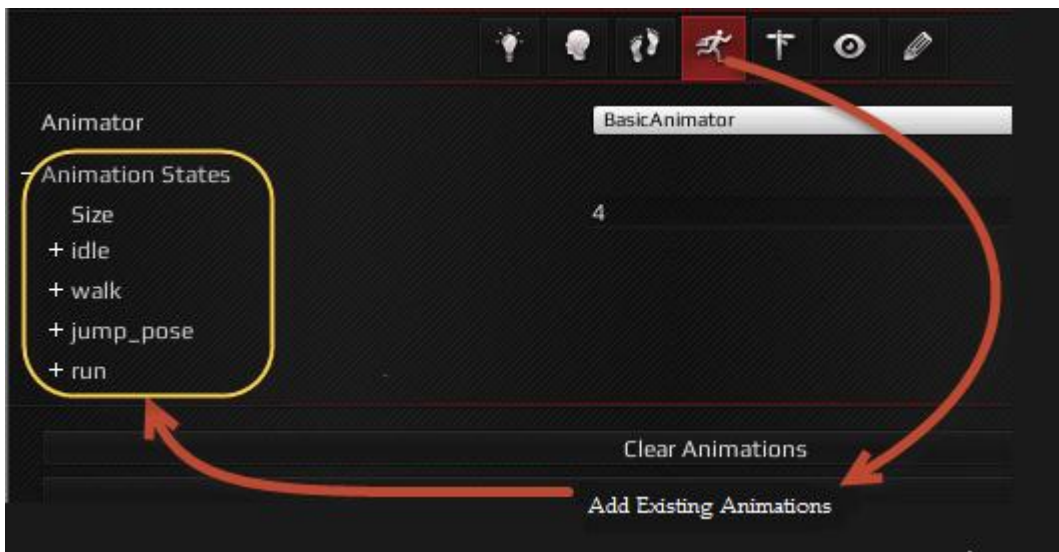
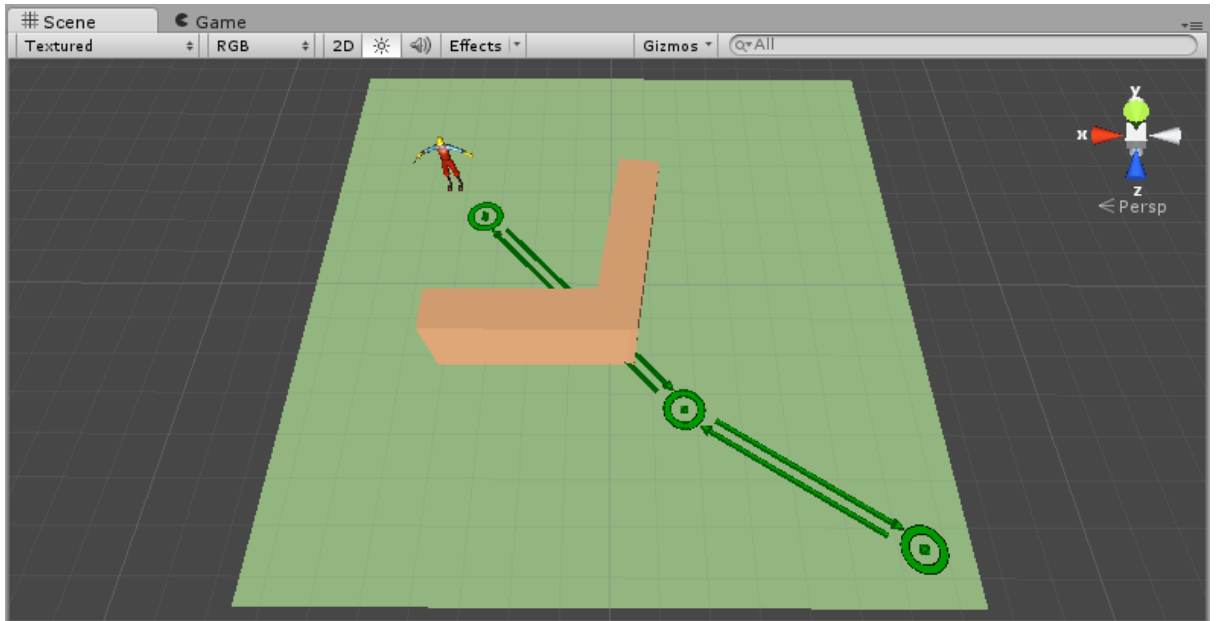


Chapter 1: Pathfinding

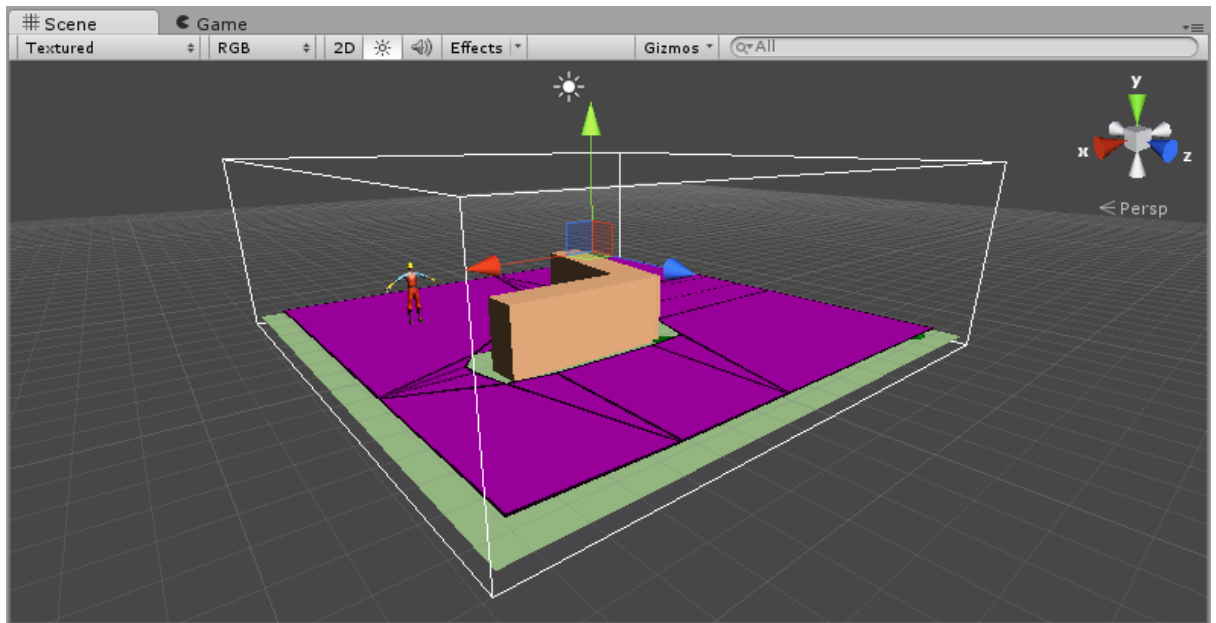




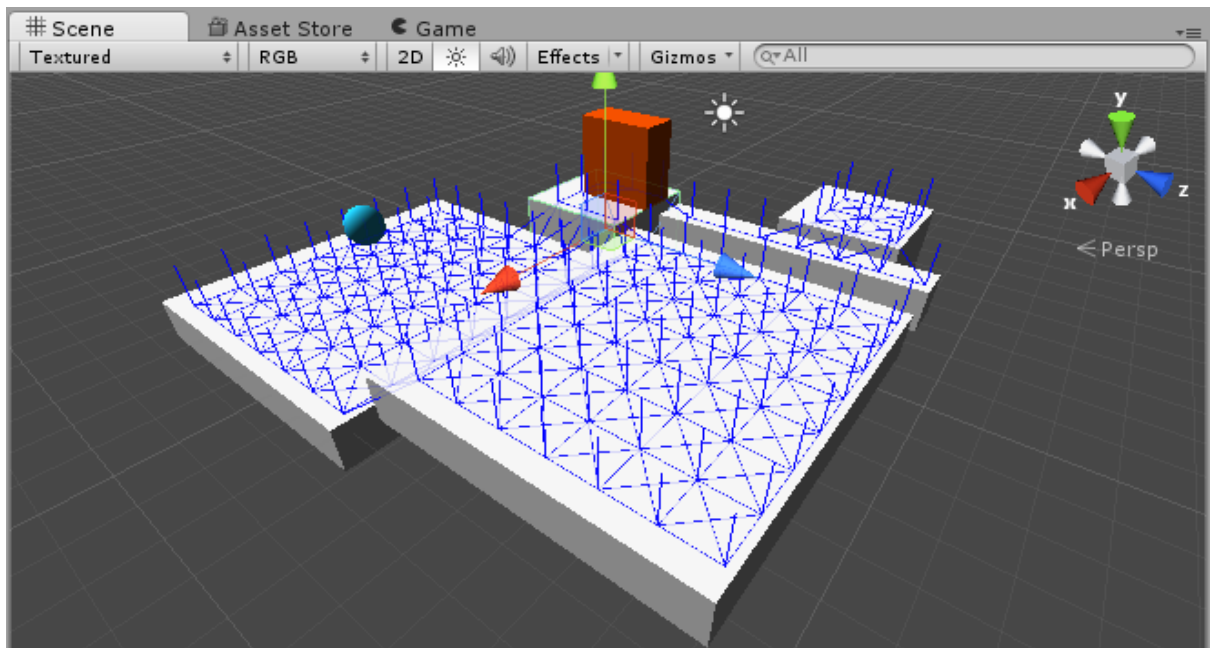




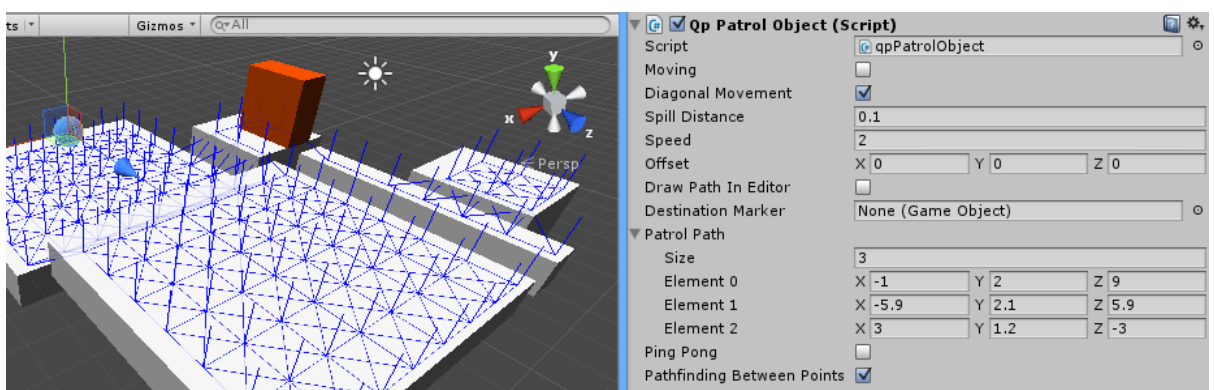
Node Type:	Patrol Route
Name:	Follow Green Path
Repeat:	Never
Pause When Hit:	<input type="checkbox"/>
Waypoint Route:	GreenPath
Loop Type:	One Way
Direction:	Forward
Move Target Variable:	NextWayPoint

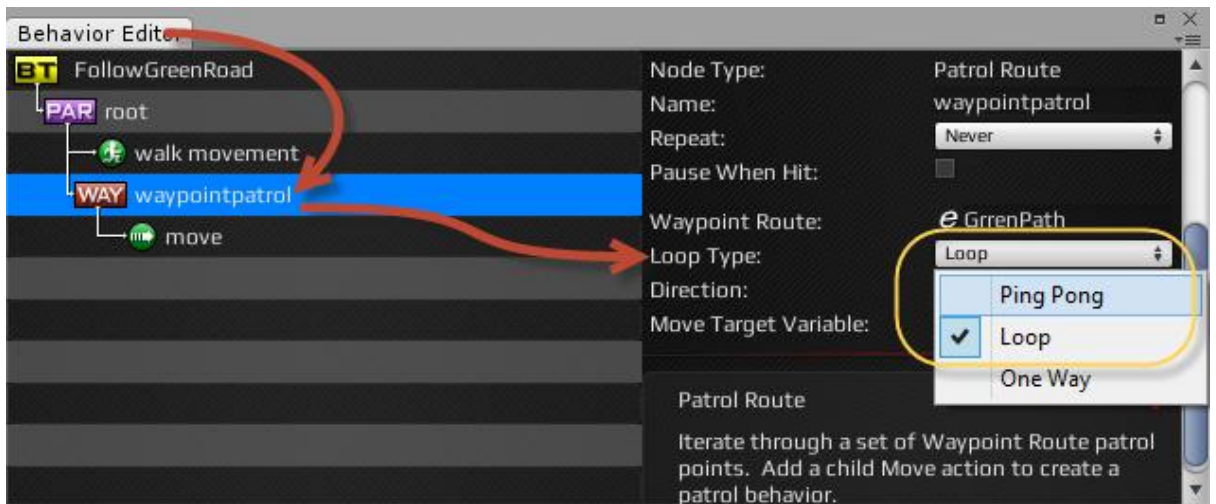
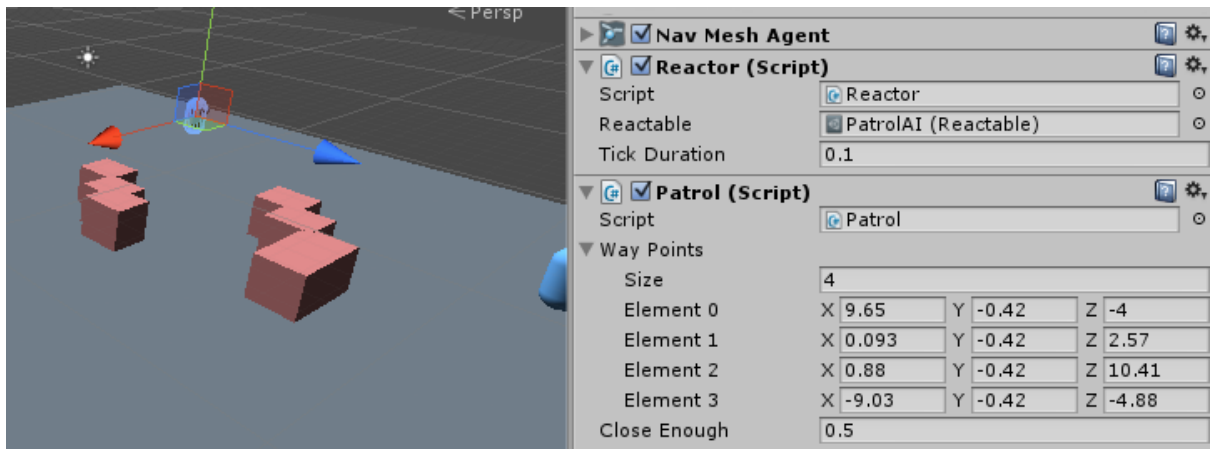


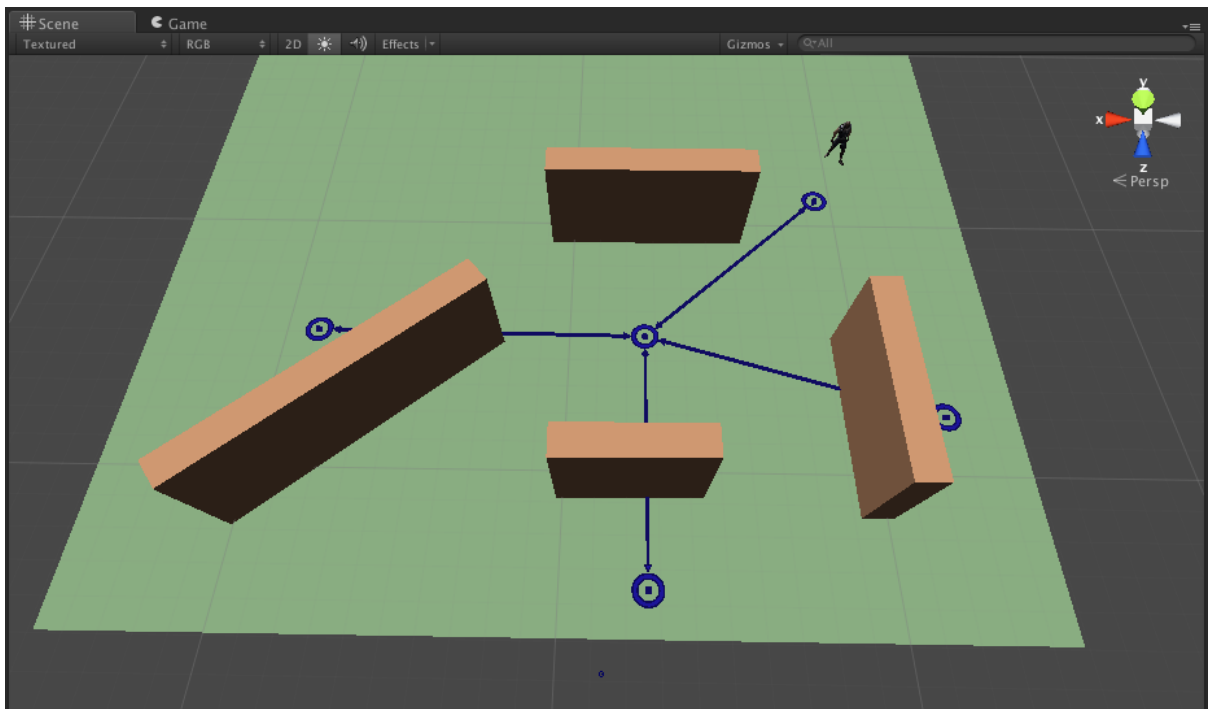
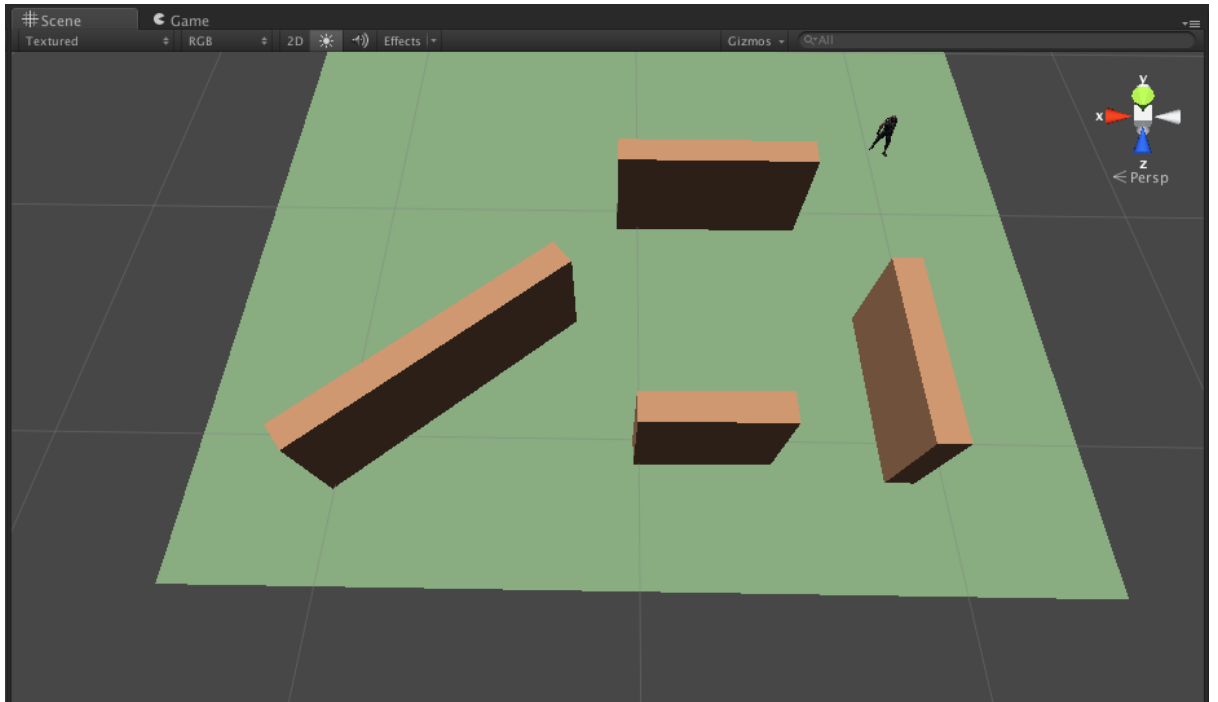
Chapter 2: Patrolling

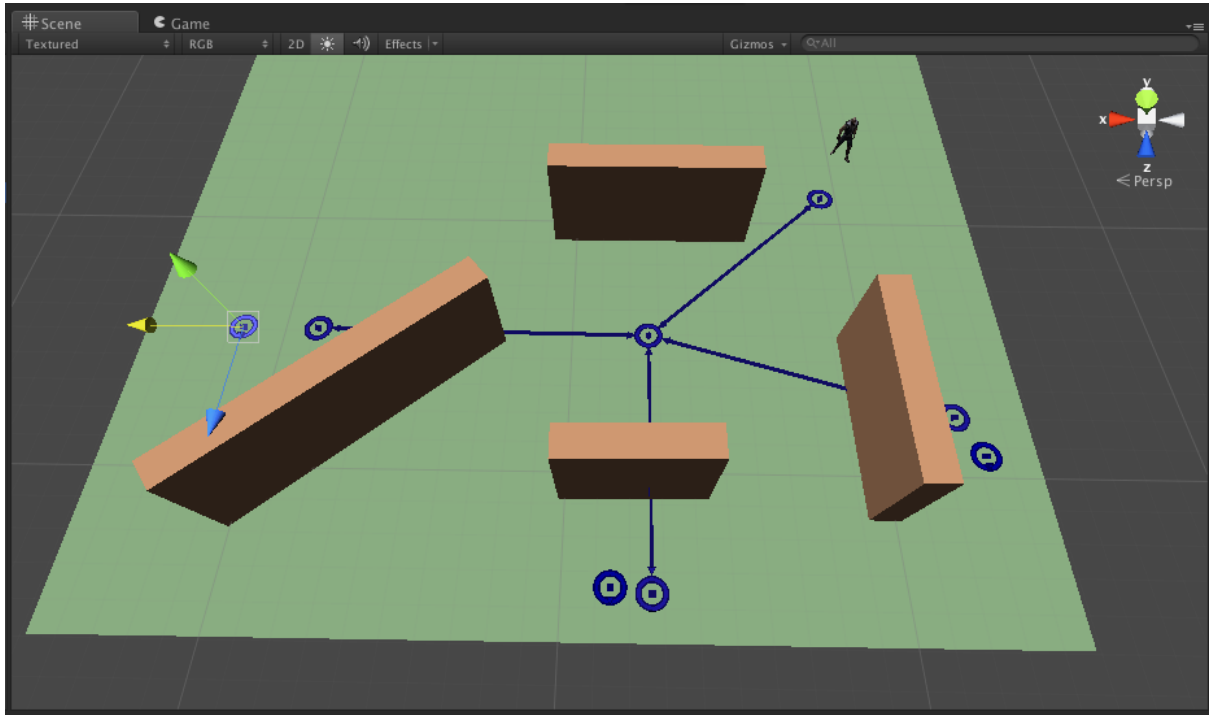


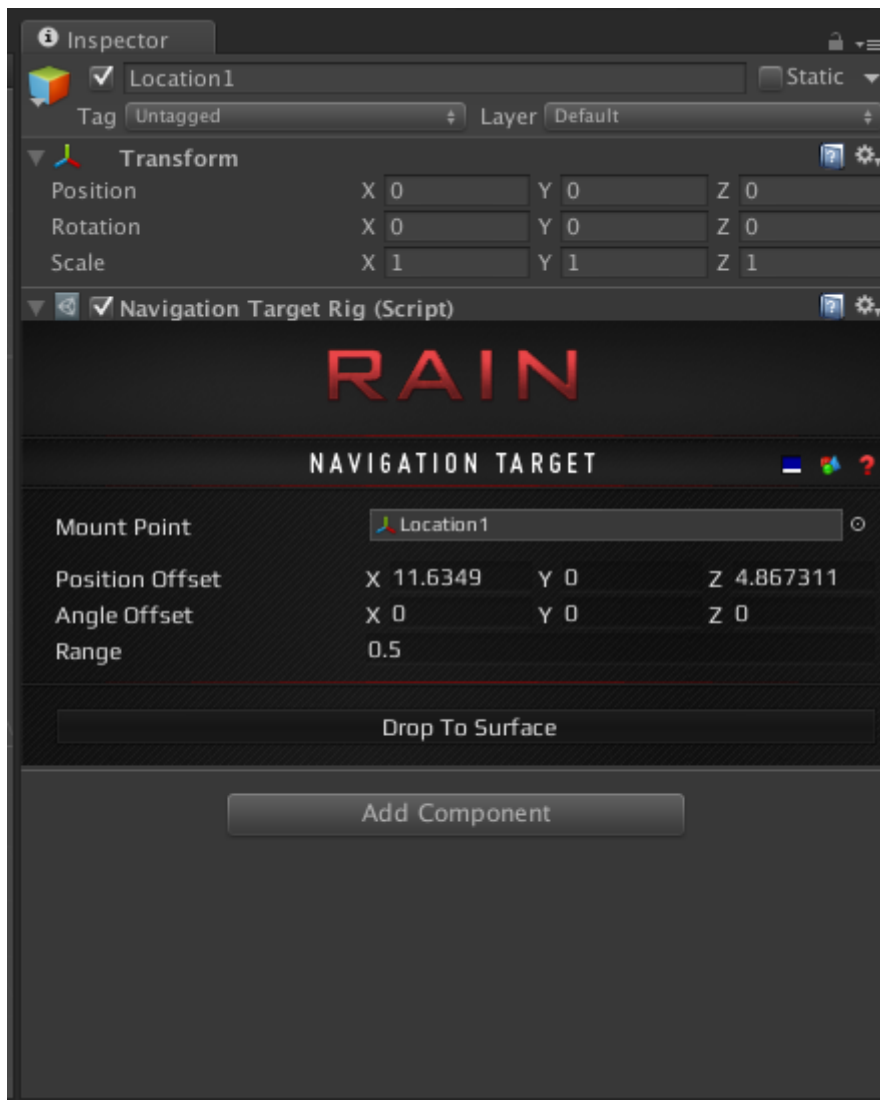
Start point of Grid	X	-50	Y	-50
End point of Grid	X	50	Y	50
Up Direction	y			











Behavior Editor

Patrol

```

    graph TD
      root[SEQ root] --> random[RAN random]
      random --> C1[Choose Location 1]
      random --> C2[Choose Location 2]
      random --> C3[Choose Location 3]
  
```

Behavior Tree: Patrol

Reload

Import XML

Export XML

Node Type: Expression

Name: Choose Location 1

Repeat: Never

Debug Break:

Weight: e

Expression: e location = navigationtarget

Returns: Evaluate

Expression

Evaluate an expression. Returns success, failure, or either based on evaluating the expression. Expression examples: 'health = 5' or 'target != null'

Behavior Editor

PatrolSimple

```

    graph TD
      PatrolSimple[SEQ PatrolSimple] --> Patrol[SEQ Patrol]
      Patrol --> ChooseLocation[RAN Choose Location]
      ChooseLocation --> L1[location = navigationtarget("Location1")]
      ChooseLocation --> L2[location = navigationtarget("Location2")]
      ChooseLocation --> L3[location = navigationtarget("Location3")]
      Patrol --> waypointpath[WAY waypointpath]
      waypointpath --> animate[animate]
      waypointpath --> Move[PAR Move]
      Move --> move[move]
  
```

Behavior Tree: Current AI (MAX)

Node Type: Waypoint Path

Name: waypointpath

Repeat: Never

Debug Break:

Waypoint Network: e "PatrolNetwork"

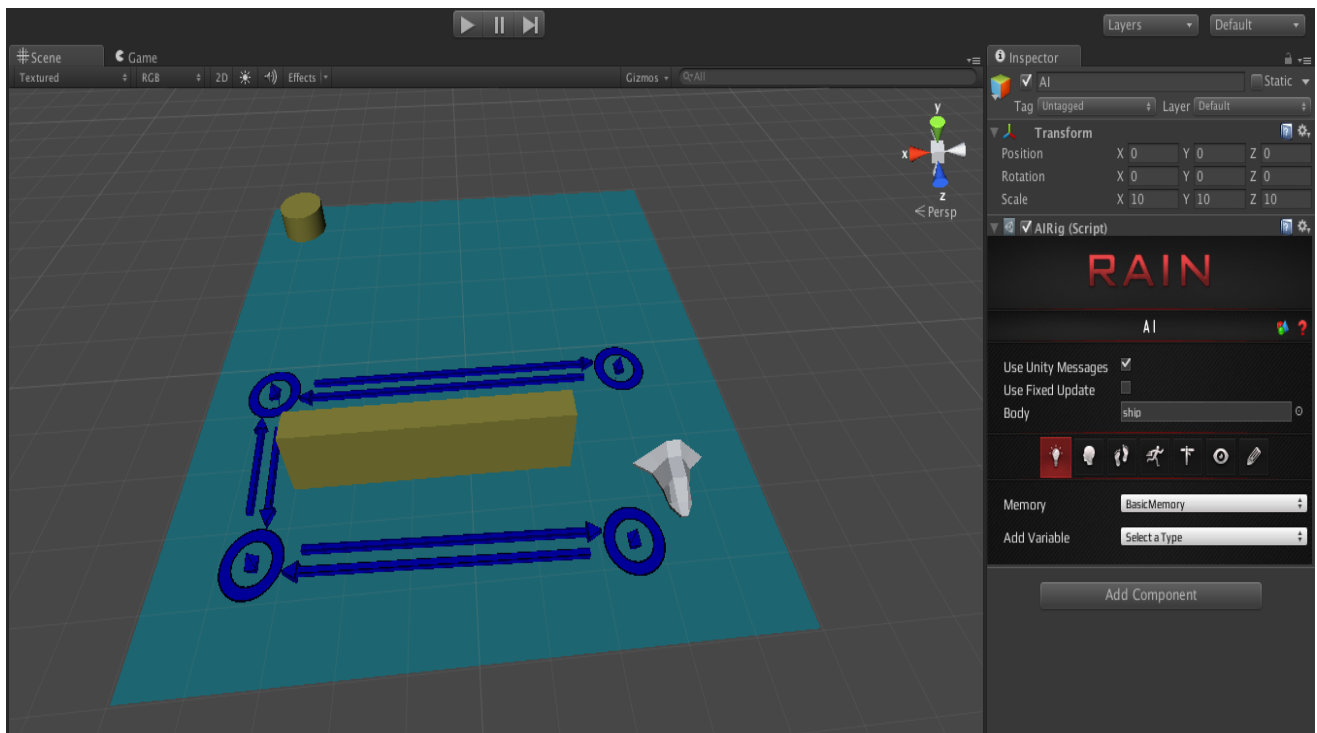
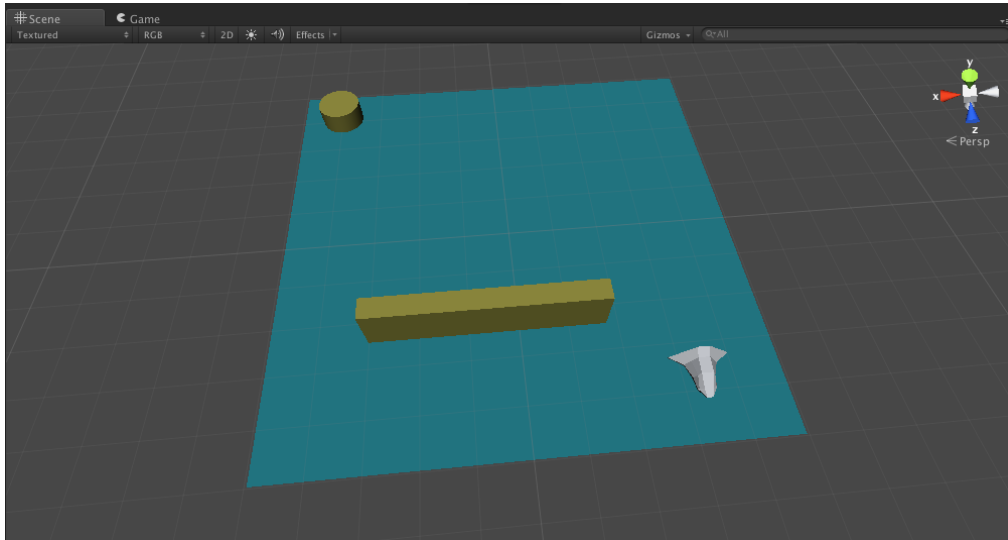
Path Target: e location

Move Target Variable: moveTarget

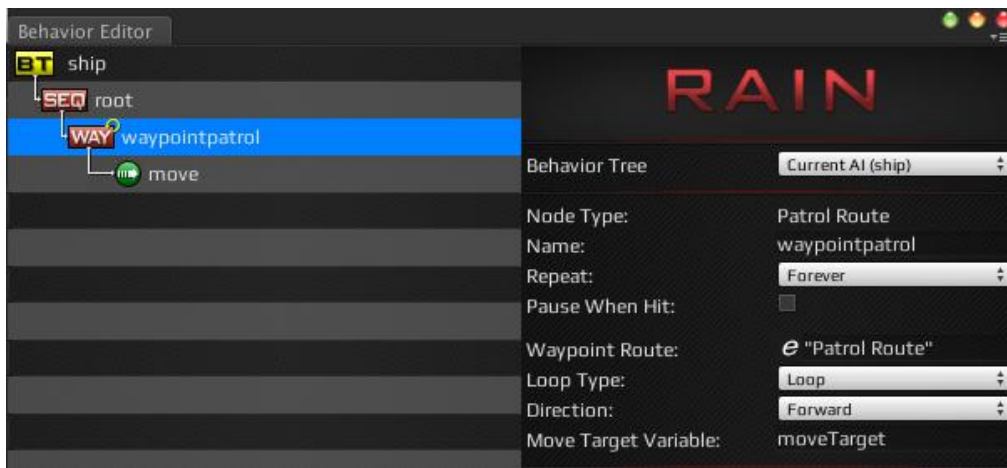
Waypoint Path

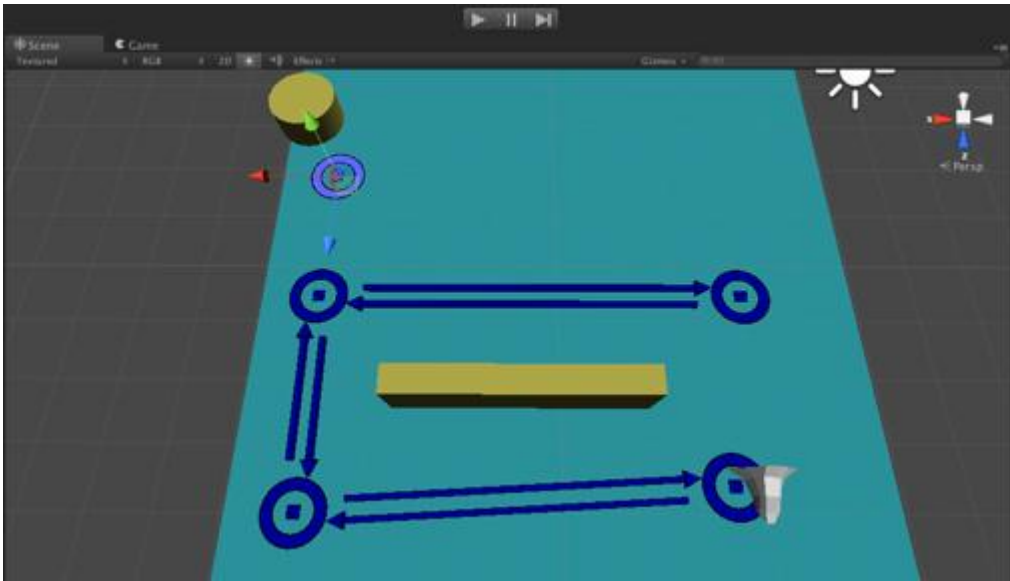
Choose move targets based on traversing a Waypoint Network toward a final path target. Add a child Move action to move along a waypoint path.

Chapter 3: Behavior Trees



The scene after performing the given steps





Behavior Editor

```
graph TD; BT[BT ship] --> SEQ[SEQ root]; SEQ --> CON[CON constraint]; CON --> WAY[WAY waypointpatrol]; WAY --> move((move));
```

RAIN

Behavior Tree: ship

Reload

Import XML

Export XML

Node Type: Constraint

Name: constraint

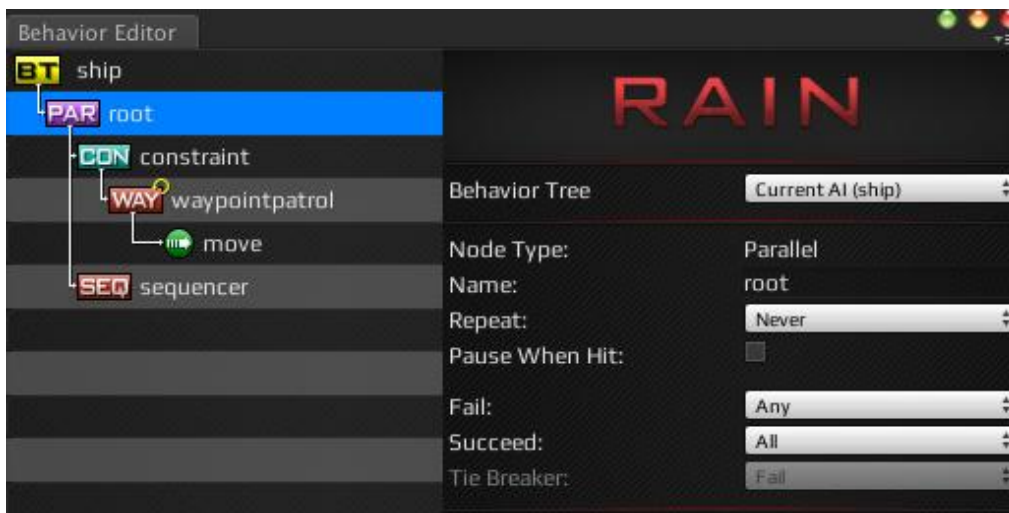
Repeat: Never

Pause When Hit:

Constraint: `donePatroling == false`

Constraint

Process child nodes as long as the constraint condition is true.



Behavior Editor

BT ship

```

    graph TD
      root[PAR root] --> constraint1[CON constraint]
      root --> sequencer[SEQ sequencer]
      constraint1 --> waypointpatrol[WAY waypointpatrol]
      waypointpatrol --> move1[move]
      sequencer --> constraint2[CON constraint]
      constraint2 --> timer[timer]
  
```

RAIN

Behavior Tree: Current AI (ship)

Node Type: Timer

Name: timer

Pause When Hit:

Seconds: 5

Returns: success

Timer

Pause for some number of seconds before continuing.

Behavior Editor

BT ship

```

    graph TD
      root[PAR root] --> constraint1[CON constraint]
      root --> selector[SEL selector]
      constraint1 --> waypointpatrol[WAY waypointpatrol]
      waypointpatrol --> move1[move]
      selector --> constraint2[CON constraint]
      constraint2 --> timer[timer]
      selector --> expression[E expression]
      selector --> move2[move]
  
```

RAIN

Behavior Tree: Current AI (ship)

Node Type: Expression

Name: expression

Repeat: Never

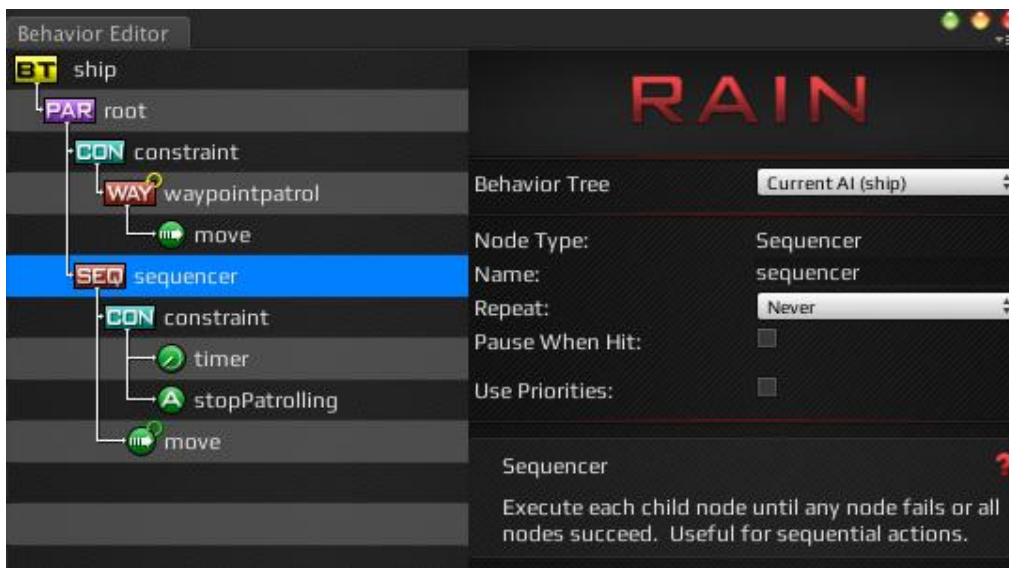
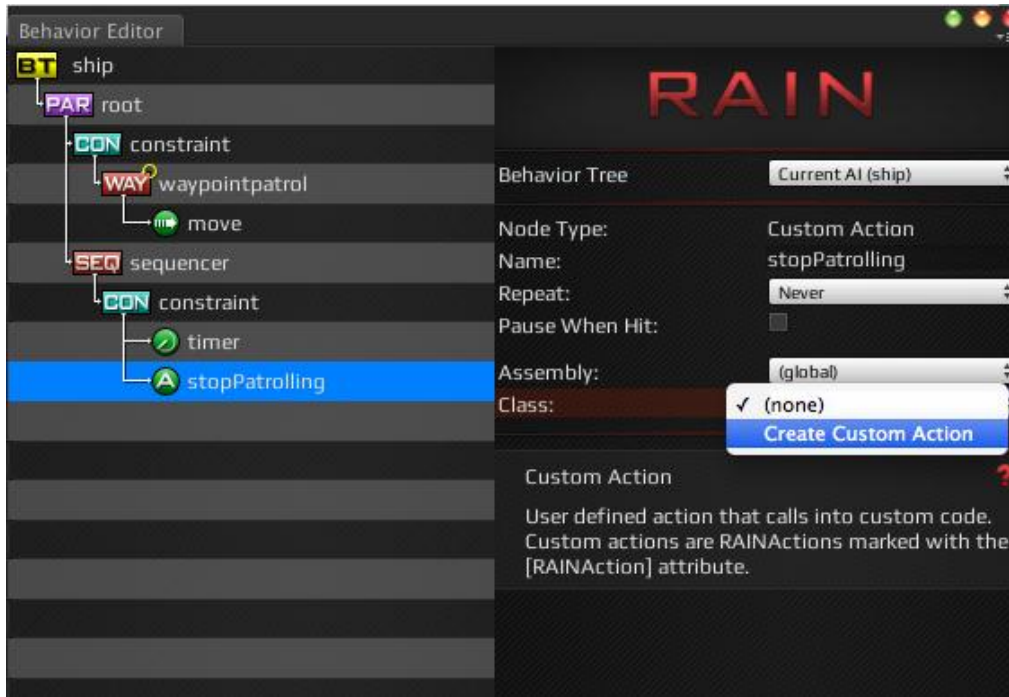
Pause When Hit:

Expression: donePatrolling=true

Returns: evaluate

Expression

Evaluate an expression. Returns success, failure, or either based on evaluating the expression. Expression examples: 'health = 5' or 'target != null'



Behavior Editor

BT ship

- PAR root
 - CON constraint
 - WAY waypointpatrol
 - move
 - SEL selector
 - CON constraint
 - timer
 - stopPatrolling
 - move

RAIN

Behavior Tree: Current AI (ship)

Node Type: Selector

Name: selector

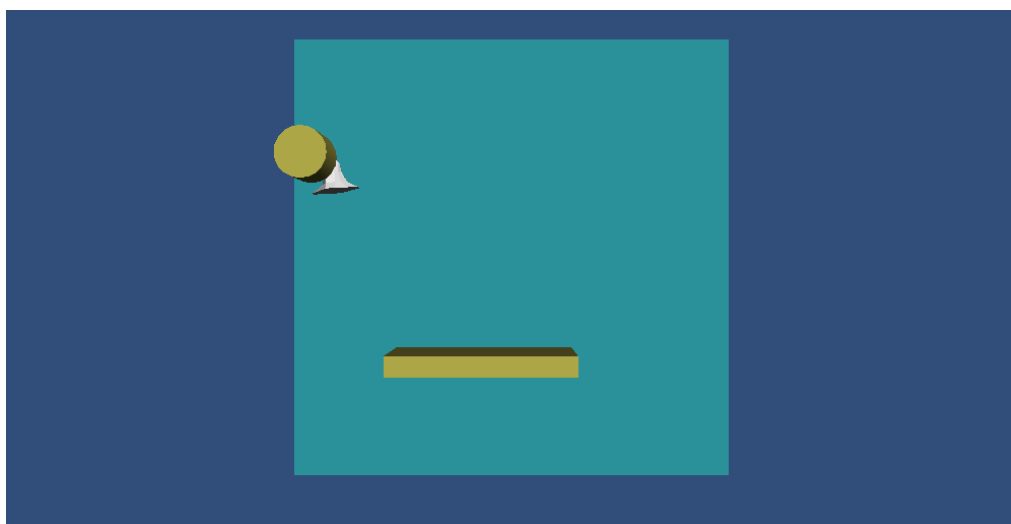
Repeat: Never

Pause When Hit:

Use Priorities:

Selector ?

Execute child nodes until any node succeeds or all nodes fail. Useful for if/then logic.



Behavior Editor

ship

PAR root

CON constraint

WAY waypointpatrol

move

SEL selector

CON constraint

timer

stopPatrolling

move

RAIN

Behavior Tree: Current AI (ship)

Node Type: Constraint

Name: constraint

Repeat: Never

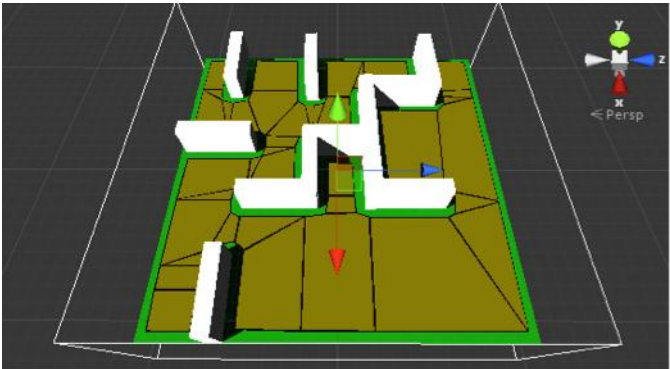
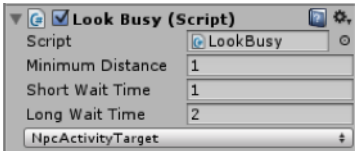
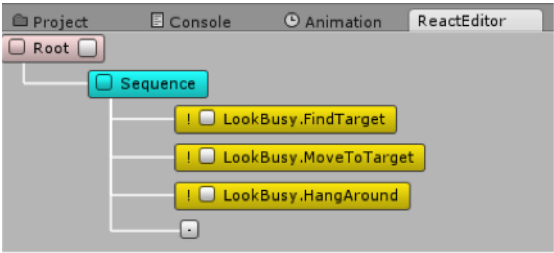
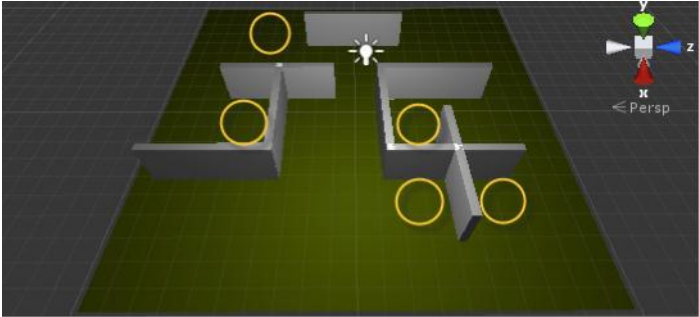
Pause When Hit:

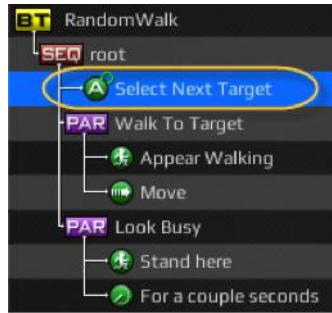
Constraint: `donePatrolling == false`

Constraint

Process child nodes as long as the constraint condition is true.

Chapter 4: Crowd Chaos

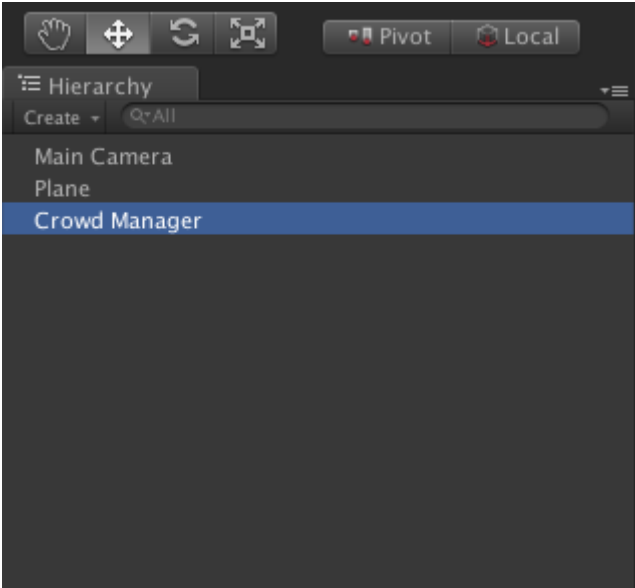
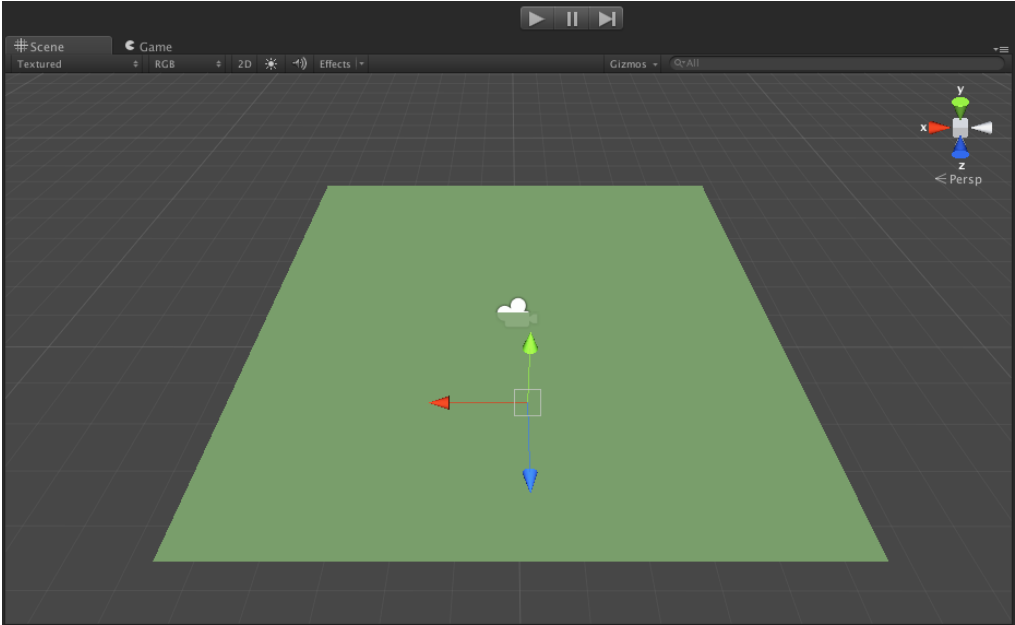


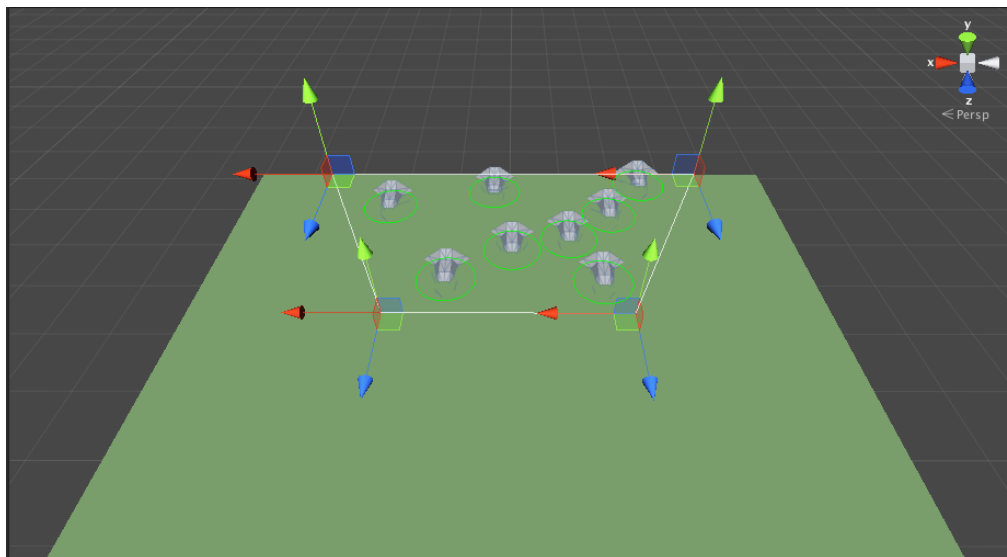
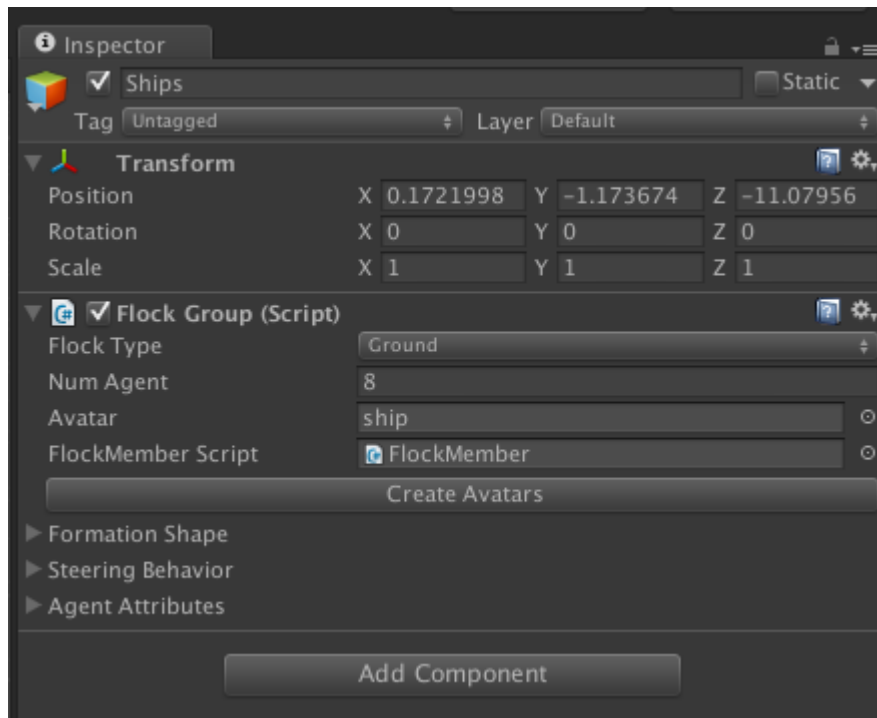


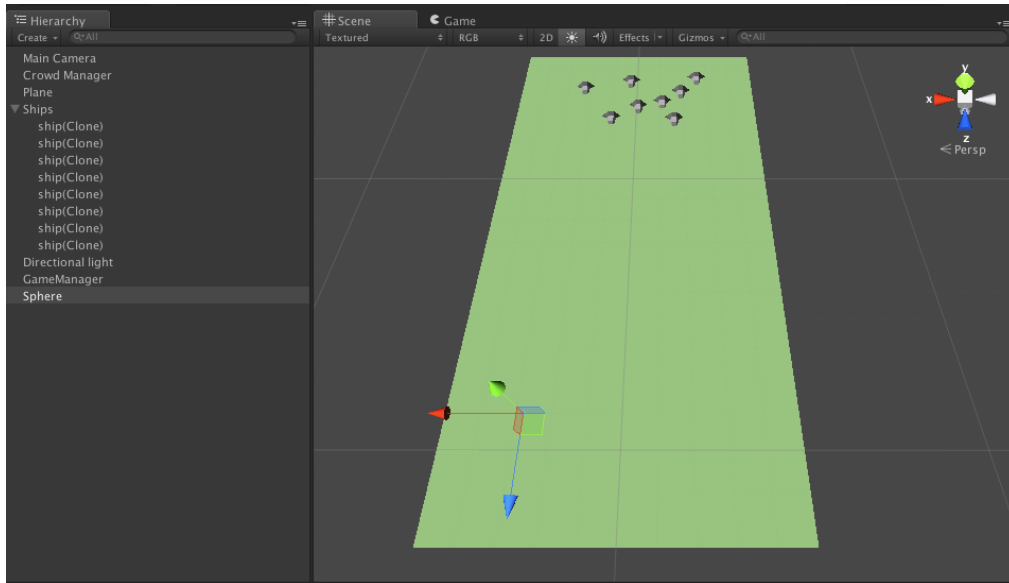
Custom action name:

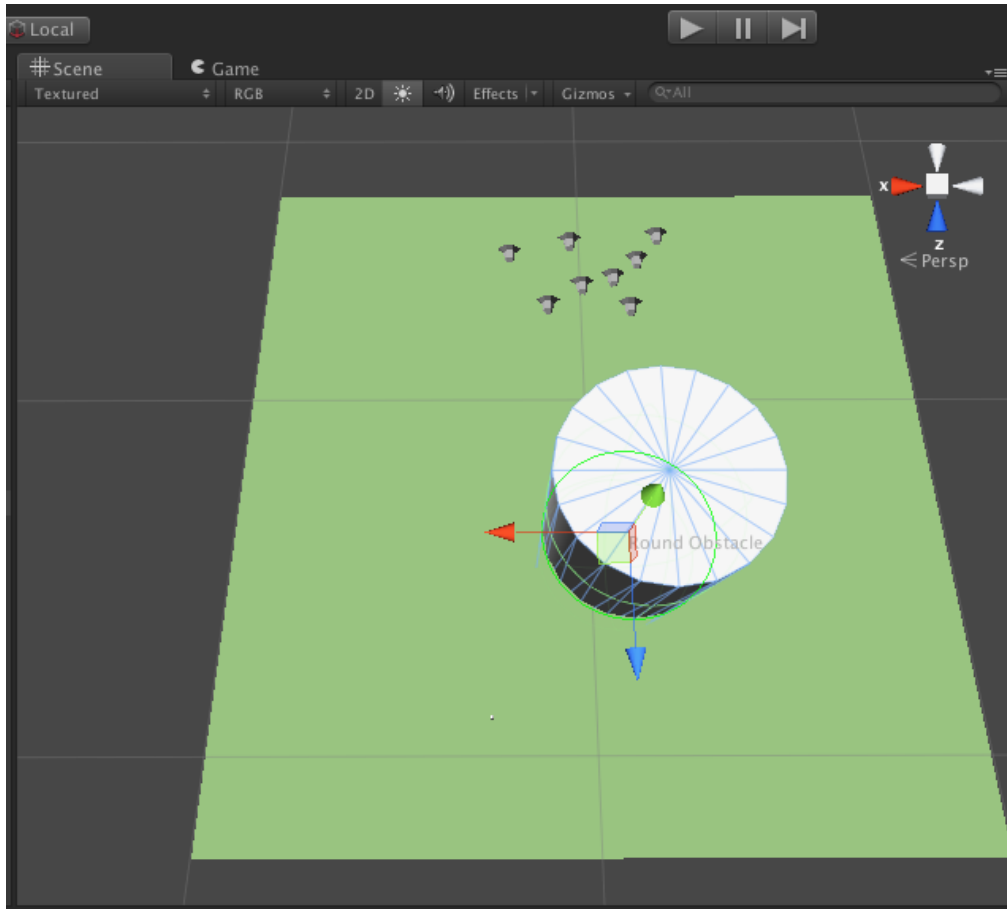
Script type:

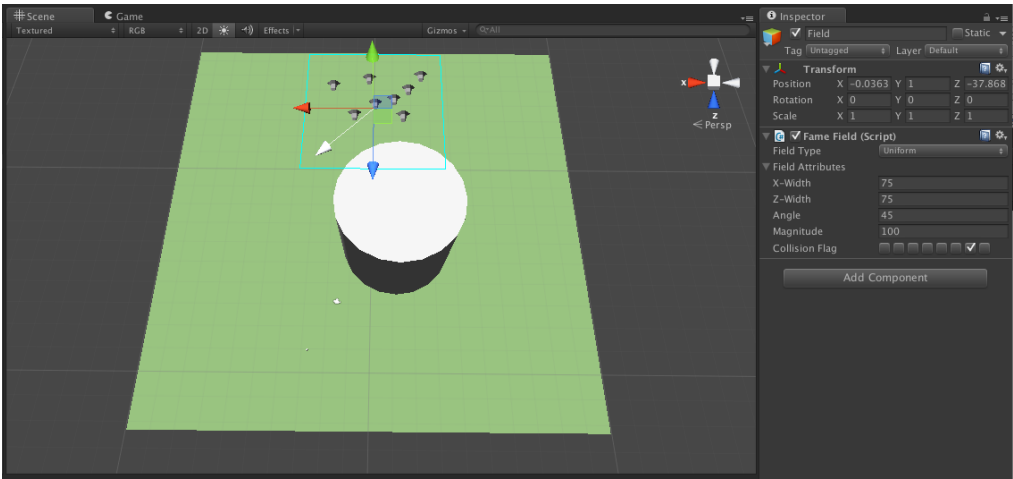
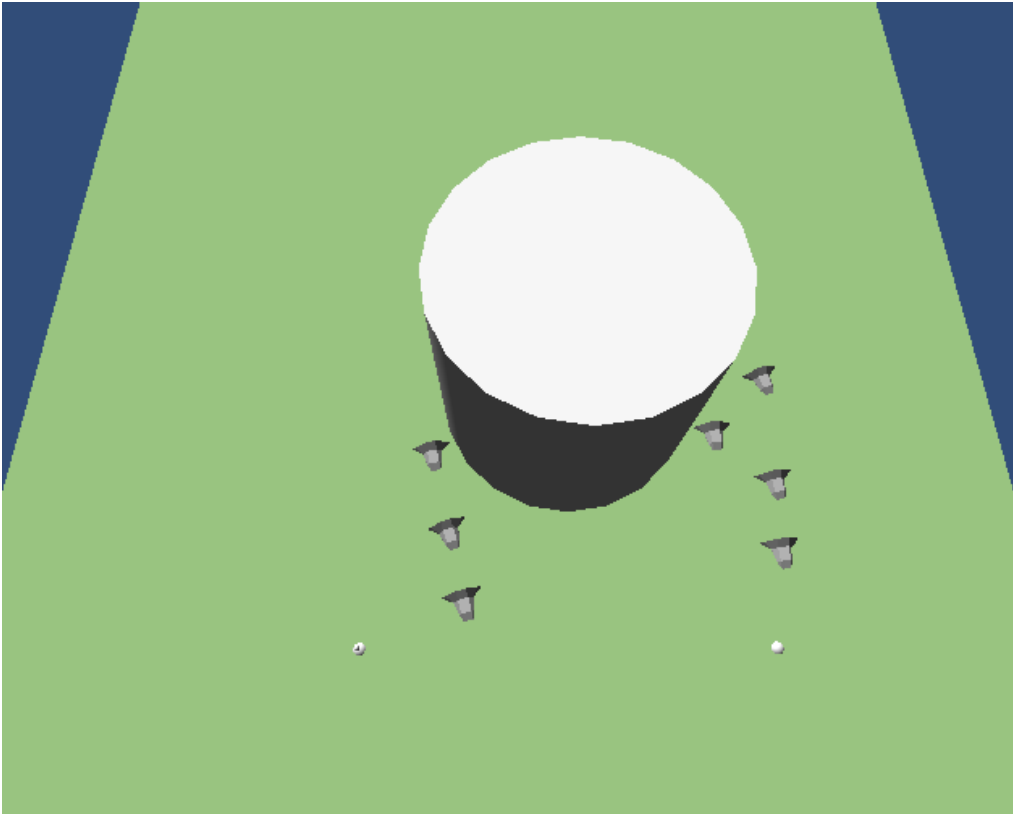
Chapter 5: Crowd Control

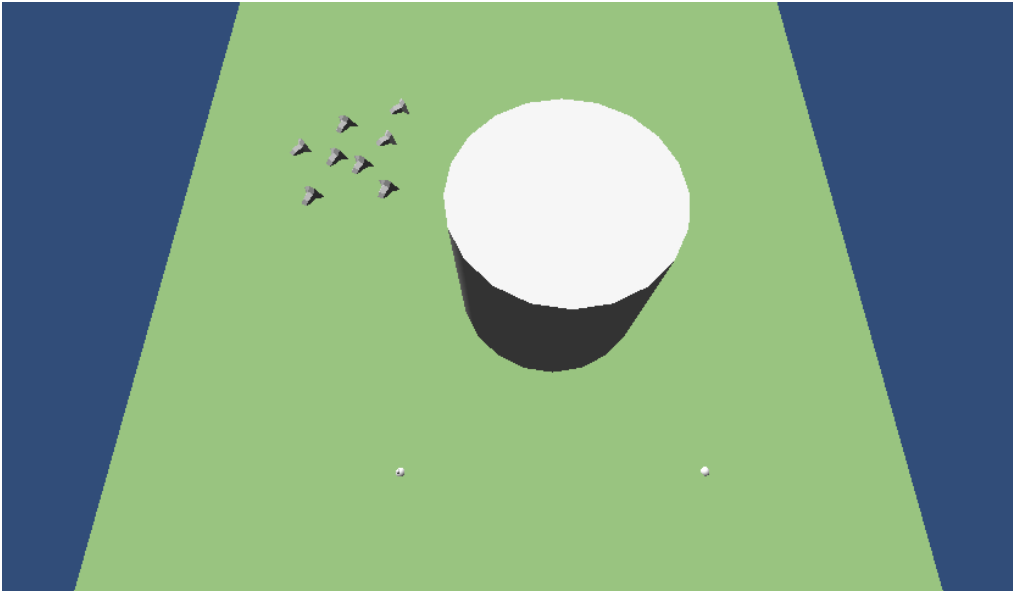










A 2D top-down view of the same ant colony simulation. The nest is a red square with a white arrow pointing down. Numerous orange lines radiate from the nest, representing pheromone trails. Several orange circles are scattered across the black background, representing food sources. On the right side, there is a control panel with various sliders and buttons.

hide gui

food pheromones
life-span in seconds: 39

strength in meters: 8

priority: 23

nest pheromones
life-span in seconds: 36

strength in meters: 10

priority: 24

ant speed: 150

change direction rate: 3

number of ants: 250
food source: 200

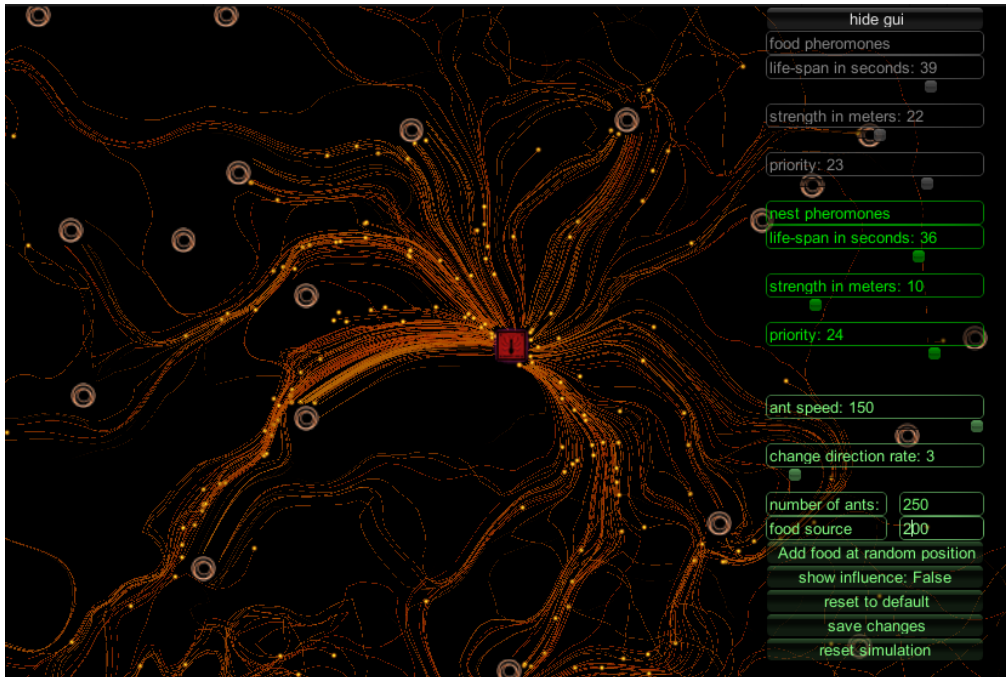
Add food at random position

show influence: False

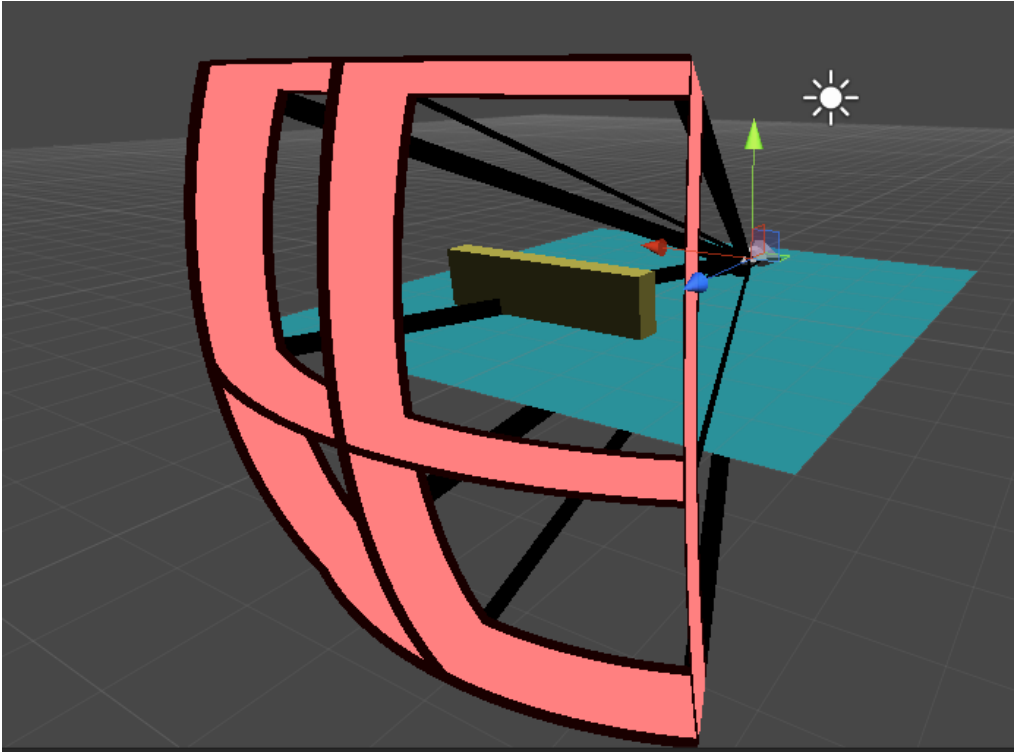
reset to default

save changes

reset simulation



Chapter 6: Sensors and Activities



RAIN

AI



Use Unity Messages

Use Fixed Update

Body



Senses

Deselect All

Remove Selected

Add Sensor

Visual Sensors

Visual Sensor

Show Visual

Sensor Color

Is Active

Sensor Name

Mount Point

Position Offset X 0 Y 0 Z 0

Angle Offset X 0 Y 0 Z 0

Can Detect Self

Horizontal Angle 360

Vertical Angle 360

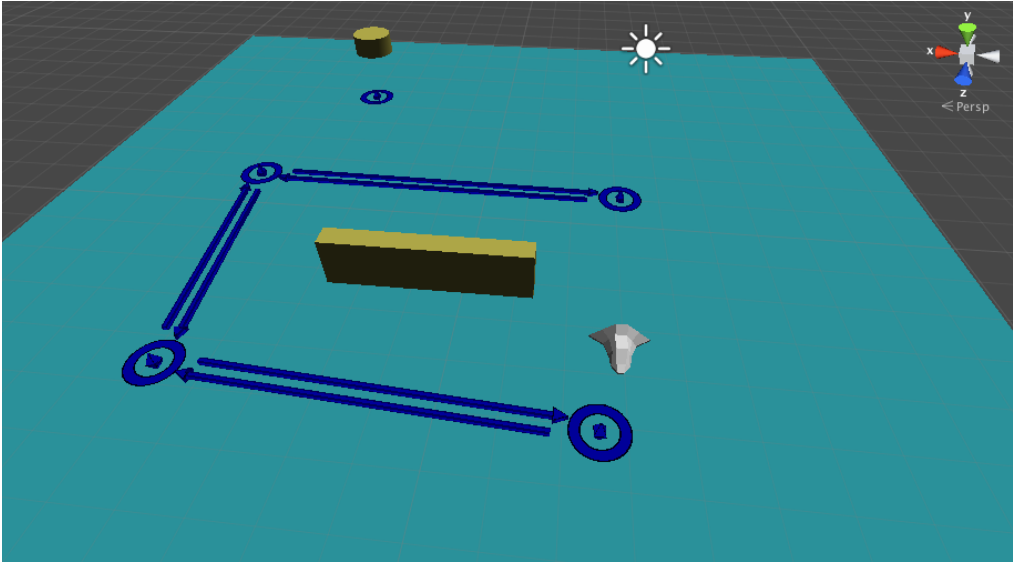
Range 10

Require Line of Sight

Line of Sight Mask

Line of Sight Ignores Self

+ Filters



Behavior Editor

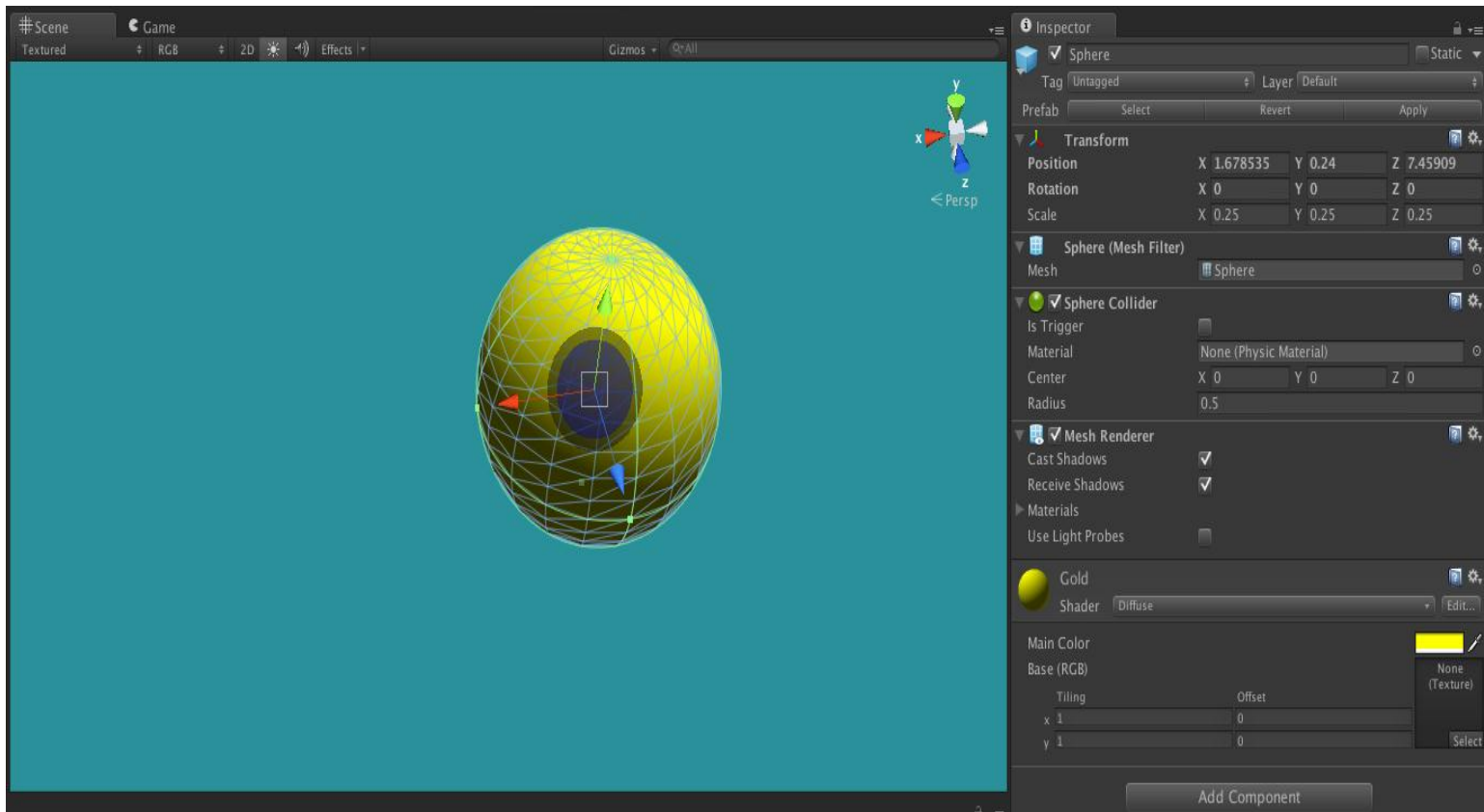
ship

- root
 - waypointpatrol
 - move

RAIN

Behavior Tree: Current AI (ship)

Node Type:	Move
Name:	move
Repeat:	Never
Pause When Hit:	<input type="checkbox"/>
Move Target:	<i>e</i> moveTarget
Move Speed:	<i>e</i> 5
Face Target:	<i>e</i>
Turn Speed:	<i>e</i>
Close Enough Distance:	<i>e</i>
Close Enough Angle:	<i>e</i>



The starting point of our object (Sphere)

RAIN

ENTITY



Use Unity Messages

Entity Name Gold

Entity Marker

Form Sphere

Aspect Color

+ Custom Elements

Deselect All

Remove Selected

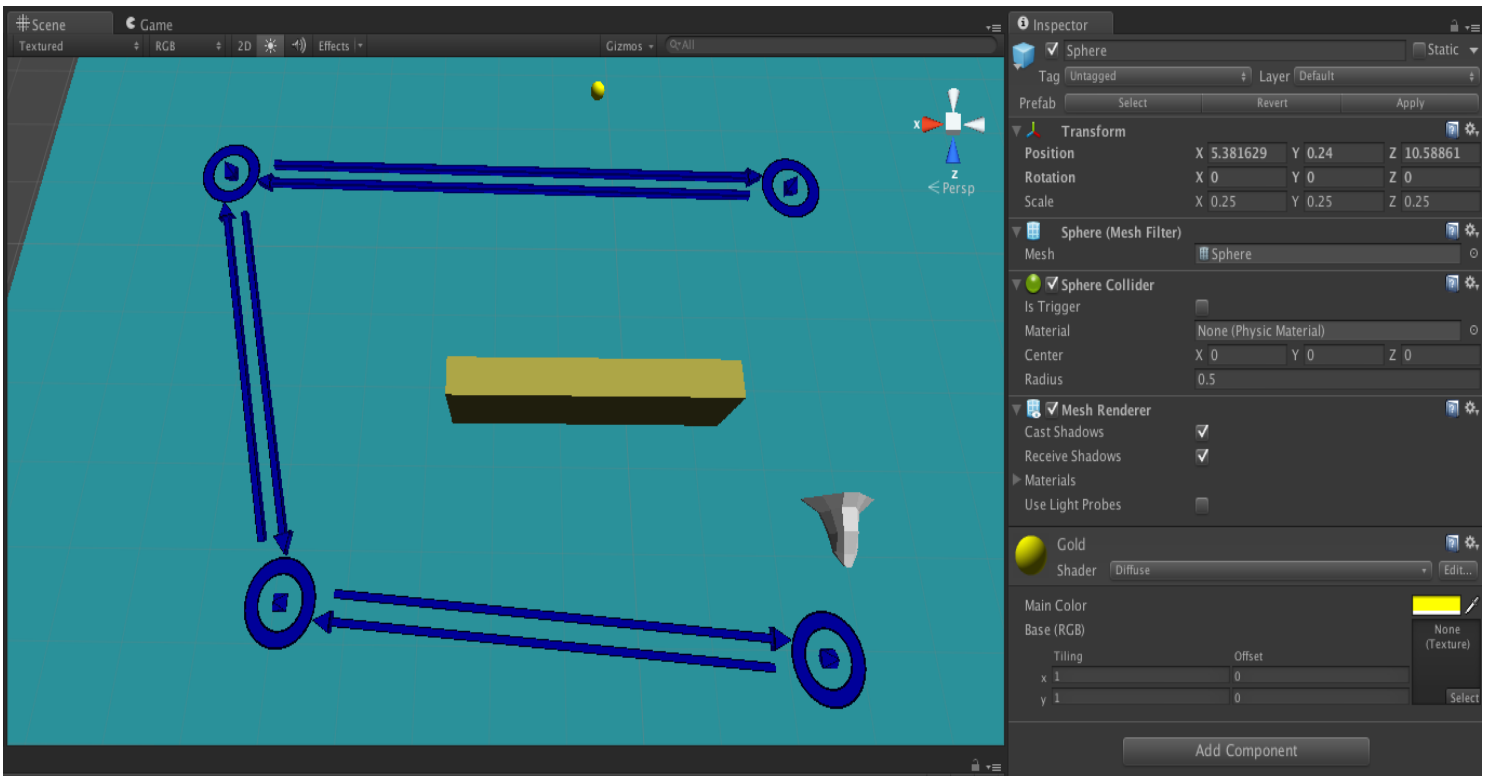
Add Aspect Select a Type

Visual Aspects

Gold

Aspect Name Gold

Mount Point



A sensor demo with gold

RAIN

AI



Use Unity Messages

Use Fixed Update

Body



Senses

Select All

Remove Selected

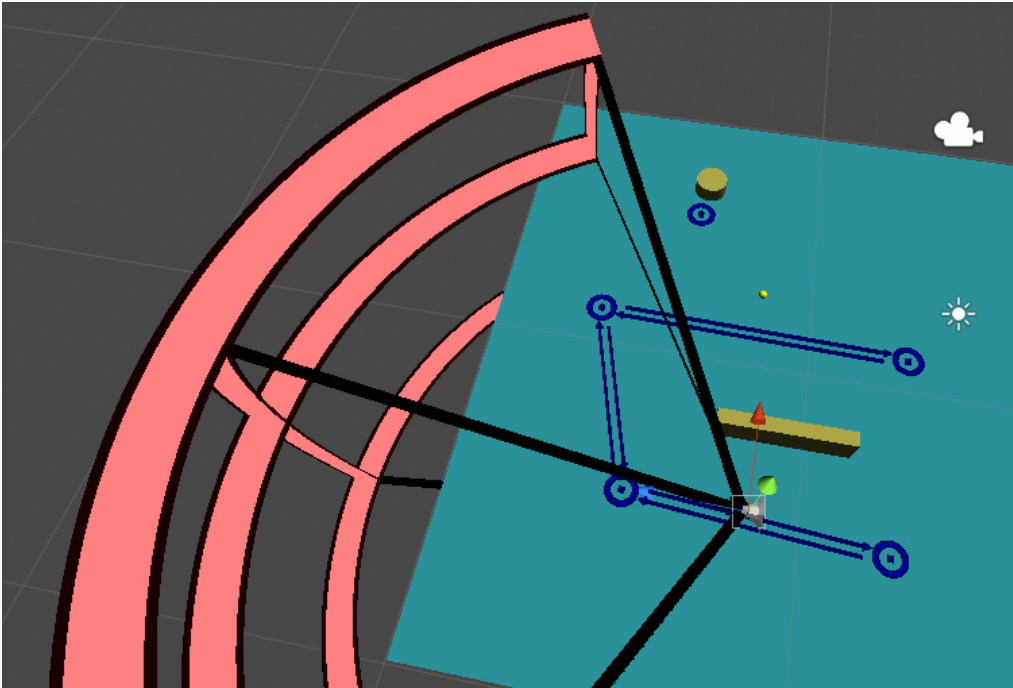
Add Sensor

Visual Sensors

Visual Sensor

- Show Visual
- Sensor Color
- Is Active
- Sensor Name
- Mount Point
- Position Offset X 0 Y 0 Z 0
- Angle Offset X 90 Y 0 Z 0
- Can Detect Self
- Horizontal Angle 120
- Vertical Angle 45
- Range 15
- Require Line of Sight
- Line of Sight Mask
- Line of Sight Ignores Self

+ Filters



Behavior Editor

ET ship

- PAR root
 - detect
 - WAY waypointpatrol
 - move

RAIN

Behavior Tree: Current AI (ship)

Node Type: Detect
Name: detect
Repeat: Forever
Pause When Hit:

Sensor: e "Visual Sensor"
Aspect: e "Gold"
Aspect Variable:
Mount Point Variable:
Form Variable: gold

Detect ?
Use Sensors to detect an Aspect. Store the result in an AI Memory variable.

Behavior Editor

BT ship

- PAR root
 - detect
 - SEL selector
 - CON constraint
 - WAY waypointpatrol
 - move

RAIN

Behavior Tree: Current AI (ship)

Node Type: Constraint
 Name: constraint
 Repeat: Never
 Pause When Hit:
 Constraint: e gold == null

Constraint
 Process child nodes as long as the constraint condition is true.

Behavior Editor

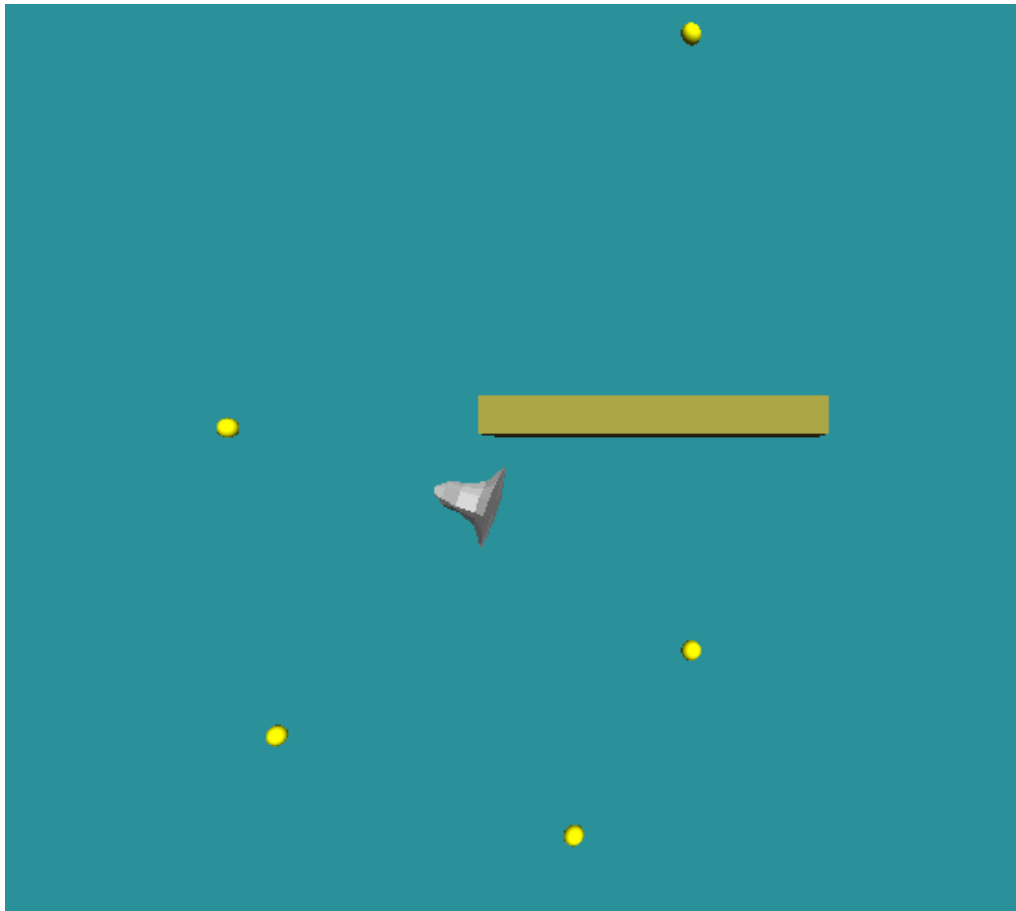
BT ship

- PAR root
 - detect
 - SEL selector
 - CON constraint
 - WAY waypointpatrol
 - move
 - CON constraint
 - move

RAIN

Behavior Tree: Current AI (ship)

Node Type: Move
 Name: move
 Repeat: Never
 Pause When Hit:
 Move Target: e gold
 Move Speed: e 5
 Face Target: e
 Turn Speed: e
 Close Enough Distance: e
 Close Enough Angle: e



RAIN

AI



Use Unity Messages

Use Fixed Update

Body



Senses

Deselect All

Remove Selected

Add Sensor

Visual Sensors

Visual Sensor

Show Visual

Sensor Color

Is Active

Sensor Name

Mount Point

Position Offset X 0 Y 0 Z 0

Angle Offset X 90 Y 0 Z 0

Can Detect Self

Horizontal Angle 120

Vertical Angle 45

Range 15

Require Line of Sight

Line of Sight Mask

Line of Sight Ignores Self

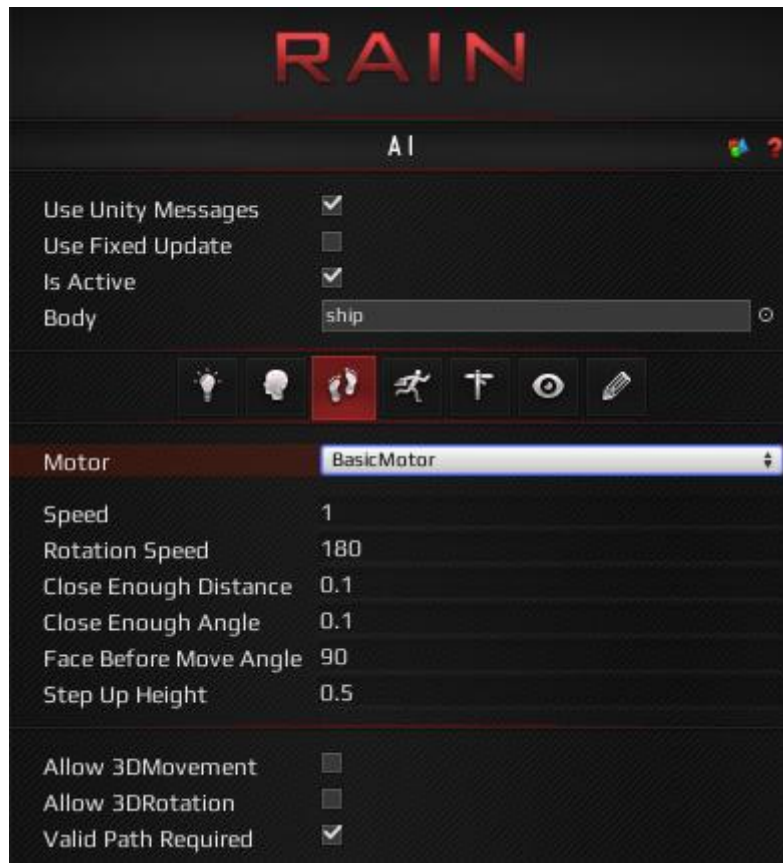
- Filters

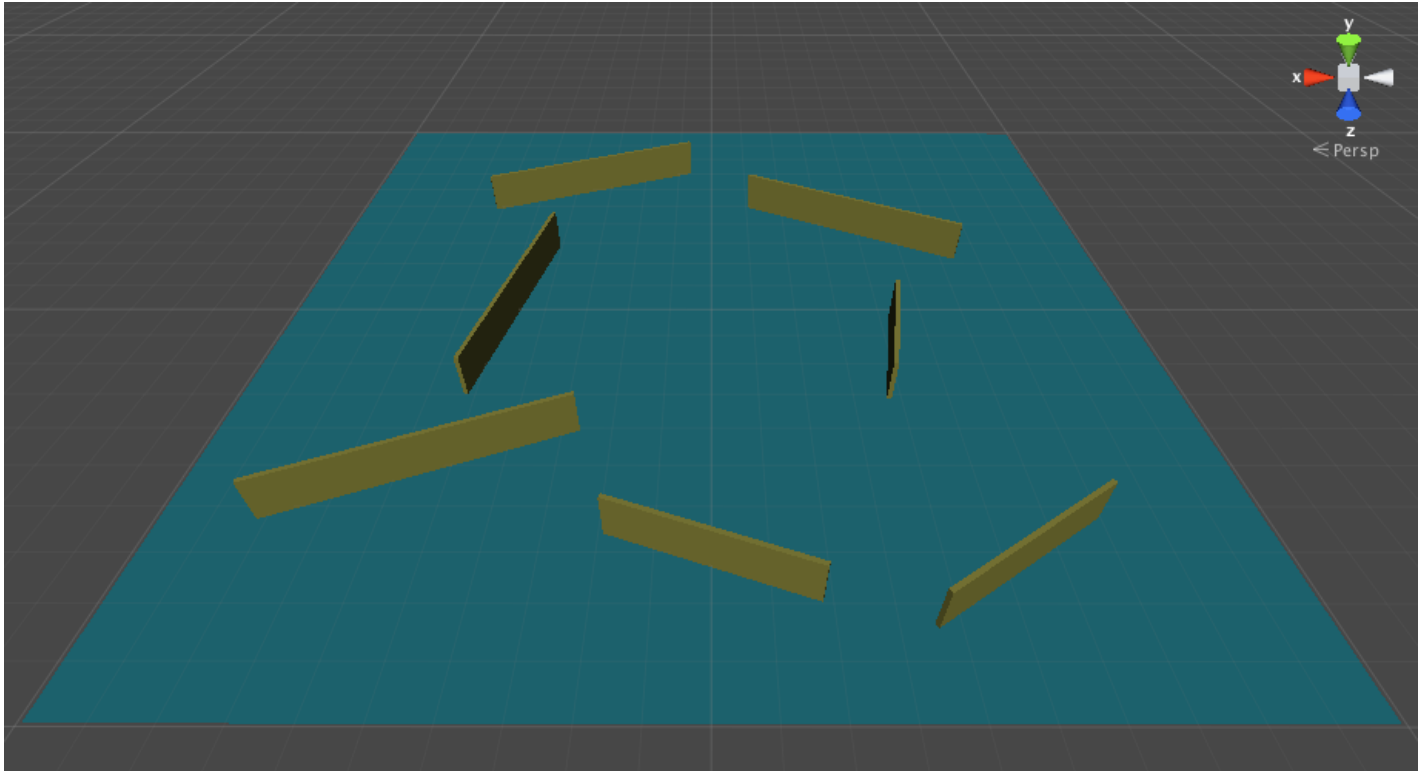
Size 1

Element 0 Create Instance

NearestXFilter

Chapter 7: Adaptation





The basic starting point of our demo

```

1 using UnityEngine;
2 using System.Collections;
3 using RAIN.Core;
4
5 public class Ground : MonoBehaviour {
6
7     private static Vector3 min, max;
8
9     private const float LevelHeight = 0.5f;
10
11     public static Vector3 randomLevelPosition() {
12         Vector3 position = new Vector3();
13         position.x = Random.Range(min.x, max.x);
14         position.y = LevelHeight;
15         position.z = Random.Range(min.z, max.z);
16         return position;
17     }
18
19     void Start () {
20         const float innerEdge = 0.9f;
21         min = renderers.bounds.min * innerEdge;
22         max = renderers.bounds.max * innerEdge;
23     }
24
25     void Update () {
26
27     }
28 }
29

```

```

7     public Transform gold;
8     private float goldTimer = 0.0f;
9     private const float goldCreateTime = 2.0f;
10
11     void Update () {
12
13         goldTimer += Time.deltaTime;
14         if(goldTimer >= goldCreateTime) {
15             Instantiate(gold, randomLevelPosition(), Quaternion.identity);
16             goldTimer = 0.0f;
17         }
18     }

```

```
1 using UnityEngine;
2 using System.Collections;
3 using System.Collections.Generic;
4 using RAIN.Core;
5 using RAIN.Action;
6
7 [RAINAction]
8 public class ChooseRandomSpot : RAINAction
9 {
10     public ChooseRandomSpot()
11     {
12         actionName = "ChooseRandomSpot";
13     }
14
15     public override void Start(AI ai)
16     {
17         Vector3 moveTarget = Ground.randomLevelPosition();
18         ai.WorkingMemory.SetItem("moveTarget", moveTarget);
19         base.Start(ai);
20     }
21
22     public override ActionResult Execute(AI ai)
23     {
24         return ActionResult.SUCCESS;
25     }
26
27     public override void Stop(AI ai)
28     {
29         base.Stop(ai);
30     }
31 }
```

Behavior Editor

ship

```

    graph TD
      root[PAR root] --> detect[detect]
      root --> selector[SEL selector]
      selector --> constraint1[CON constraint]
      selector --> move1[move]
      selector --> constraint2[CON constraint]
      constraint1 --> action1[action]
      constraint2 --> move2[move]
      constraint2 --> action2[action]
  
```

RAIN

Behavior Tree: Current AI (SearchShip)

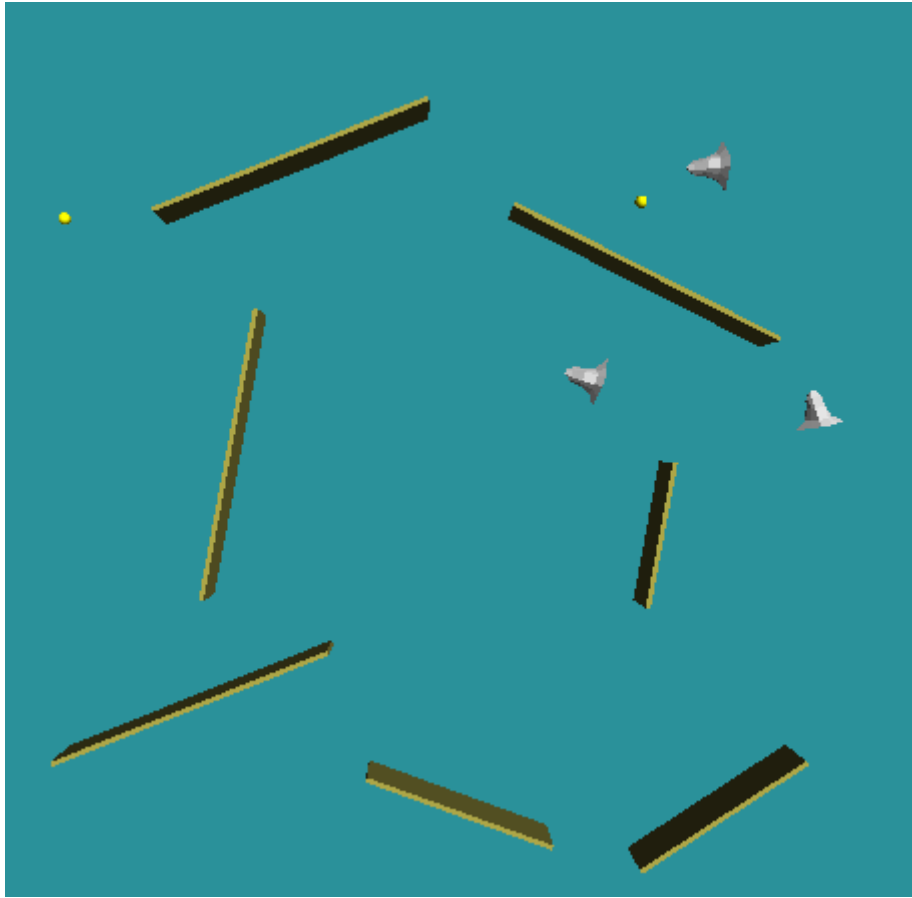
Node Type: Move
 Name: move
 Repeat: Never
 Pause When Hit:

Move Target: *e* moveTarget
 Move Speed: *e* 2
 Face Target: *e*
 Turn Speed: *e*
 Close Enough Distance: *e* 0.5
 Close Enough Angle: *e*

Move

Move to a target location and/or turn to face a target. Target can be the name of a Navigation Target (in quotes), a vector, or a variable expression representing an object or location.

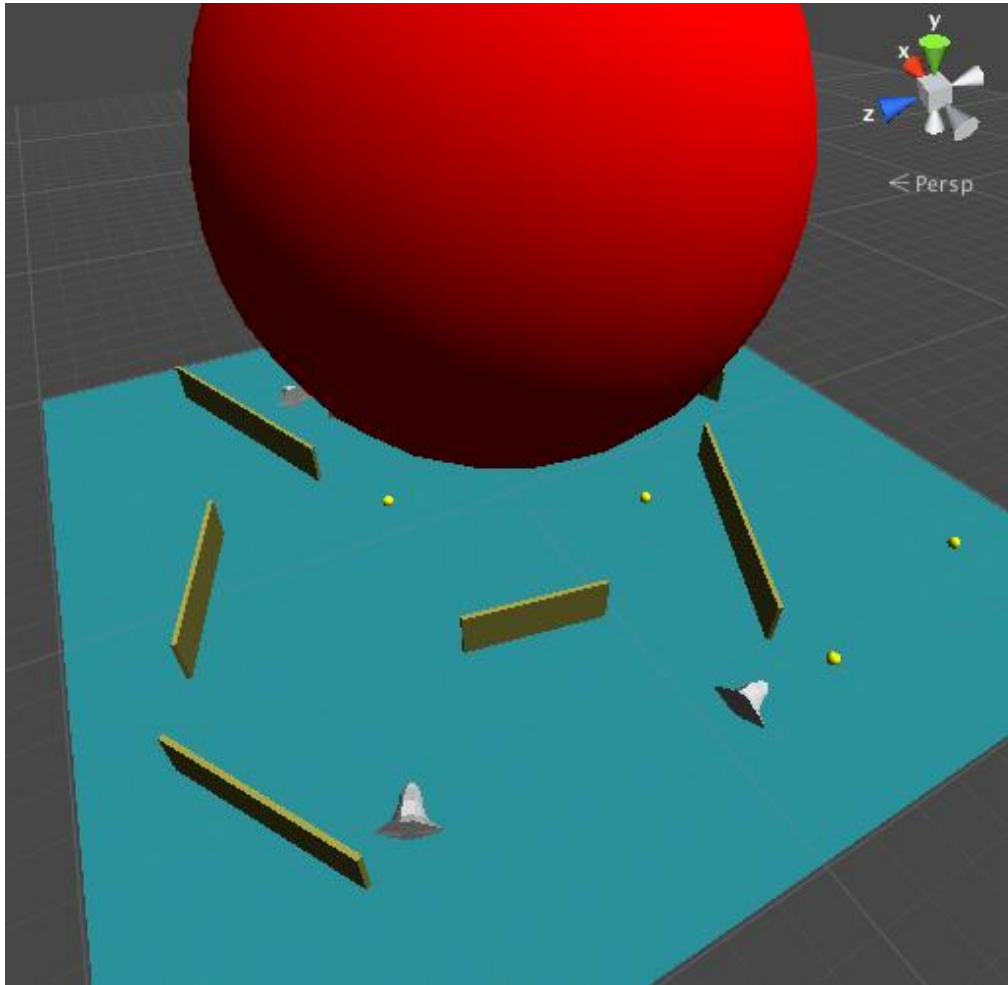
```
1 using UnityEngine;
2 using System.Collections;
3 using System.Collections.Generic;
4 using RAIN.Core;
5 using RAIN.Action;
6
7 [RAINAction]
8 public class ChooseRandomSpot : RAINAction
9 {
10     public ChooseRandomSpot()
11     {
12         actionName = "ChooseRandomSpot";
13     }
14
15     public override void Start(AI ai)
16     {
17         Vector3 moveTarget = Ground.randomLevelPosition();
18         ai.WorkingMemory.SetItem("moveTarget", moveTarget);
19         base.Start(ai);
20     }
21
22     public override ActionResult Execute(AI ai)
23     {
24         GameObject gold = ai.WorkingMemory.GetItem<GameObject>("gold");
25         if(gold != null) {
26             return ActionResult.FAILURE;
27         }
28
29         Vector3 moveTarget = ai.WorkingMemory.GetItem<Vector3>("moveTarget");
30         if(Vector3.Distance(moveTarget, ai.Body.transform.position) < 1.0f) {
31             return ActionResult.SUCCESS;
32         }
33
34         ai.Motor.MoveTo(moveTarget);
35
36         return ActionResult.RUNNING;
37     }
38
39     public override void Stop(AI ai)
40     {
41         base.Stop(ai);
42     }
43 }
```



```

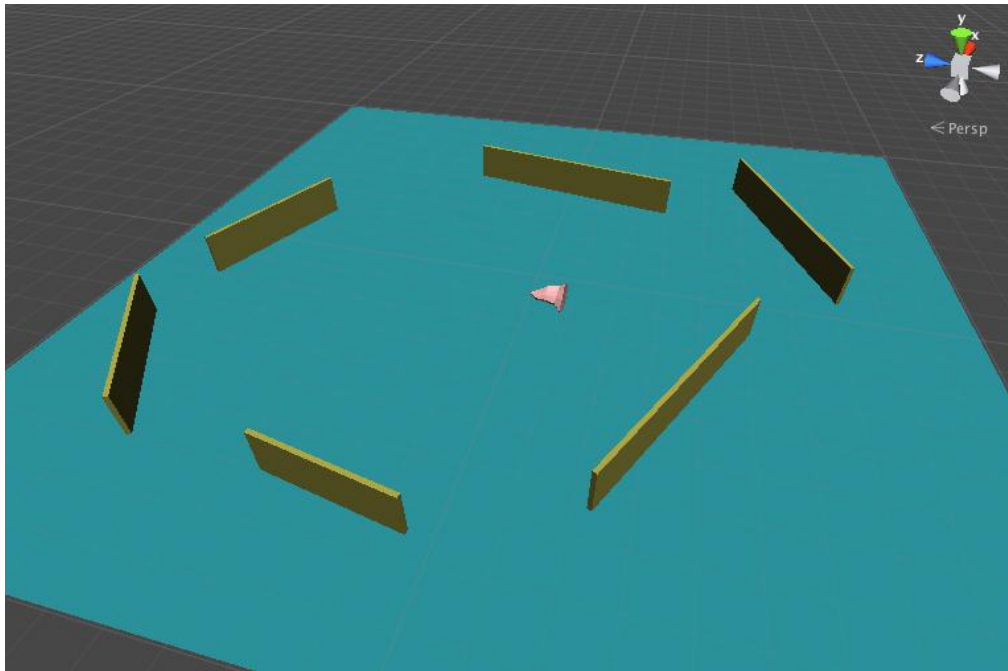
1 using UnityEngine;
2 using System.Collections;
3 using RAIN.Core;
4
5 public class Ground : MonoBehaviour {
6
7     *.*
8     public Transform bomb;
9     public float BombTime = 30.0f;
10
11     *.*
12
13     void Update () {
14
15         if(BombTime < 0.0f) {
16             return;
17         }
18
19         goldTimer += Time.deltaTime;
20         if(goldTimer >= goldCreateTime) {
21             Instantiate(gold, randomLevelPosition(), Quaternion.identity);
22             goldTimer = 0.0f;
23         }
24
25         BombTime -= Time.deltaTime;
26         if(BombTime <= 0.0f) {
27             GameObject.Instantiate(bomb);
28
29             AIRig[] AIs = GameObject.FindObjectsOfType(typeof(AIRig)) as AIRig[];
30             for(int i = 0; i < AIs.Length; i++) {
31                 AIs[i].enabled = false;
32             }
33         }
34     }
35 }
36

```

```
7 public bool IsTargetVisible (Transform target)
8 {
9     Vector3 targetDirection = target.position - transform.position;
10    Ray ray = new Ray (transform.position, targetDirection);
11    var inFOV = Vector3.Angle (transform.forward, targetDirection) < 45;
12    if (inFOV) {
13        RaycastHit hit;
14        if (Physics.Raycast (ray, out hit, 1000)) {
15            return hit.collider.transform == target;
16        }
17    }
18    return false;
19 }
```

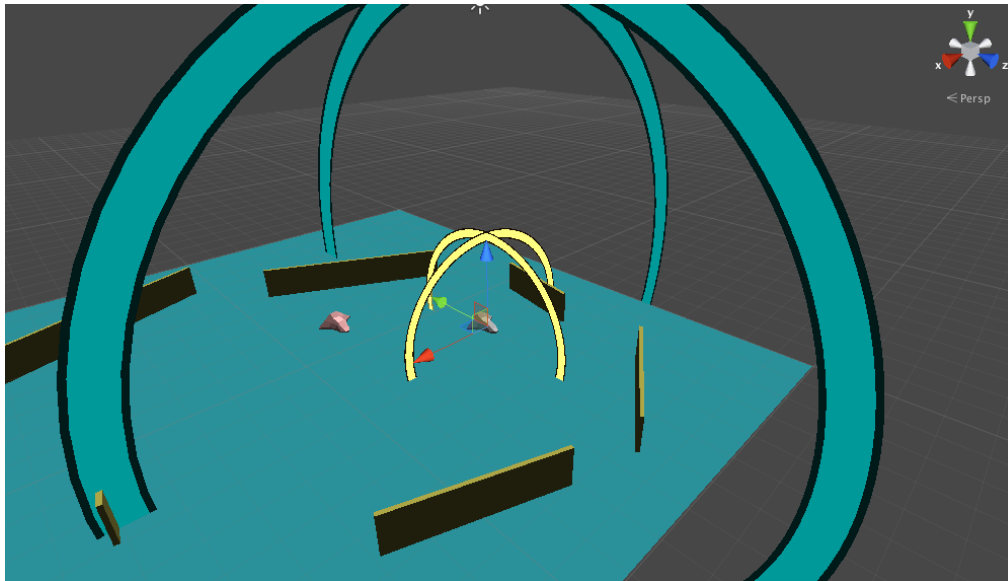
Chapter 8: Attacking



```

1  using UnityEngine;
2  using System.Collections;
3  using RAIN.Core;
4
5  public class Enemy : MonoBehaviour {
6
7      float blinkTime = 0.0f;
8      const float blinkLength = 0.1f;
9
10     AIRig aiRig = null;
11
12     void Start () {
13         aiRig = GetComponentInChildren<AIRig>();
14     }
15
16     void Update () {
17
18         bool isAttacking = aiRig.AI.WorkingMemory.GetItem<bool>("isAttacking");
19
20         if(!isAttacking) {
21             gameObject.renderer.material.color = Color.white;
22             return;
23         }
24
25         blinkTime += Time.deltaTime;
26         if(blinkTime > blinkLength) {
27             blinkTime = -blinkLength;
28         }
29
30         gameObject.renderer.material.color = blinkTime < 0.0f ? Color.green : Color.white;
31     }
32 }
33

```



Behavior Editor

ChaseAndAttack

```

    graph TD
      ET[ET ChaseAndAttack] --> PAR[PAR root]
      PAR --> D1[detect]
      PAR --> D2[detect]
      PAR --> CON[CON constraint]
      CON --> SEL[SEL selector]
  
```

RAIN

Behavior Tree: Current AI (ship)

Node Type: Constraint
 Name: constraint
 Repeat: Never
 Debug Break:

Constraint: `e playerChase != null ||`

Constraint
 Process child nodes as long as the constraint condition is true.

Behavior Editor

ChaseAndAttack

```

    graph TD
      ET[ET ChaseAndAttack] --> PAR[PAR root]
      PAR --> D1[detect]
      PAR --> D2[detect]
      PAR --> CON1[CON constraint]
      CON1 --> SEL[SEL selector]
      SEL --> CON2[CON constraint - attack]
      CON2 --> E1[expression - start attacking]
      CON2 --> E2[expression - don't attack]
      CON2 --> A[action]
      CON1 --> CON3[CON constraint]
      CON3 --> SEQ[SEQ sequencer]
  
```

RAIN

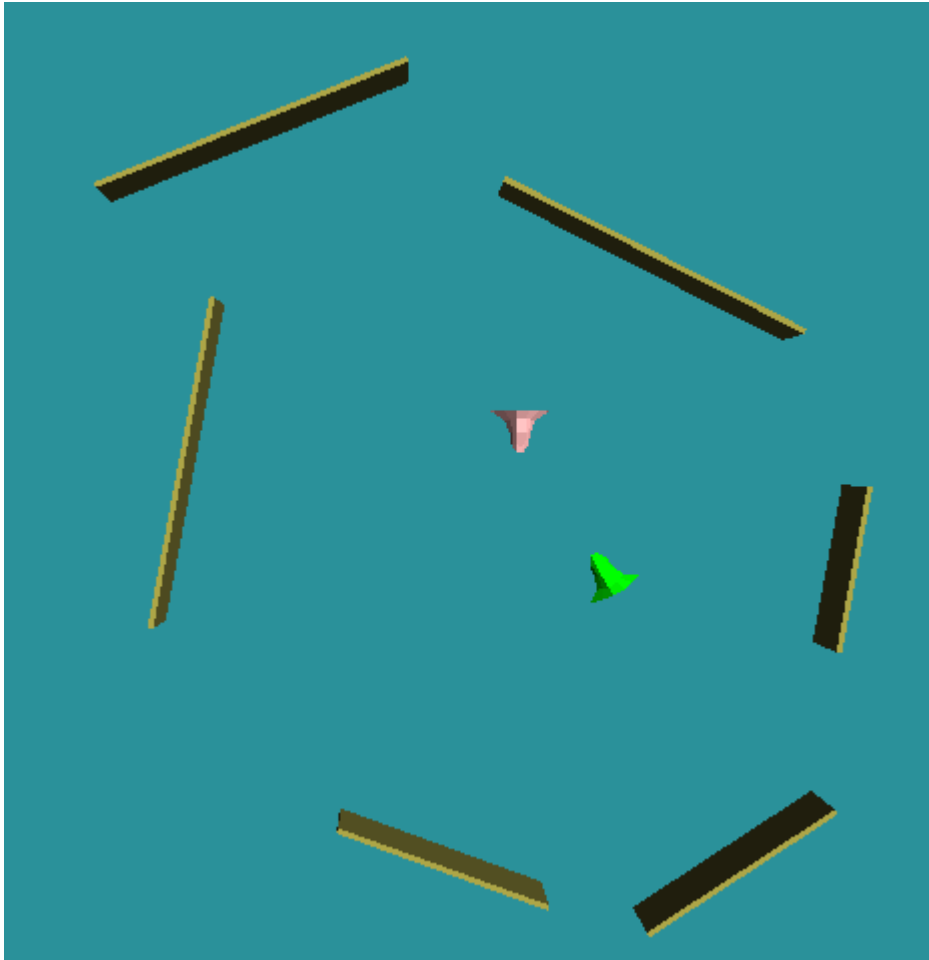
Behavior Tree: Current AI (ship)

Node Type: Constraint
 Name: constraint - attack
 Repeat: Never
 Debug Break:

Constraint: `e playerAttack != null`

Constraint
 Process child nodes as long as the constraint condition is true.

```
1 using UnityEngine;
2 using System.Collections;
3 using System.Collections.Generic;
4 using RAIN.Core;
5 using RAIN.Action;
6
7 [RAINAction]
8 public class Chase : RAINAction
9 {
10     public GameObject player;
11
12     public override void Start(AI ai)
13     {
14         base.Start(ai);
15
16         player = GameObject.Find("player");
17     }
18
19     public override ActionResult Execute(AI ai)
20     {
21         if(player == null) {
22             return ActionResult.FAILURE;
23         }
24
25         ai.Motor.MoveTo(player.transform.position);
26
27         return ActionResult.RUNNING;
28     }
29
30     public override void Stop(AI ai)
31     {
32         base.Stop(ai);
33     }
34 }
```



Behavior Editor

ChaseAndAttack

Behavior Tree

Current AI (ship)

Node Type: Constraint

Name: constraint

Repeat: Never

Debug Break:

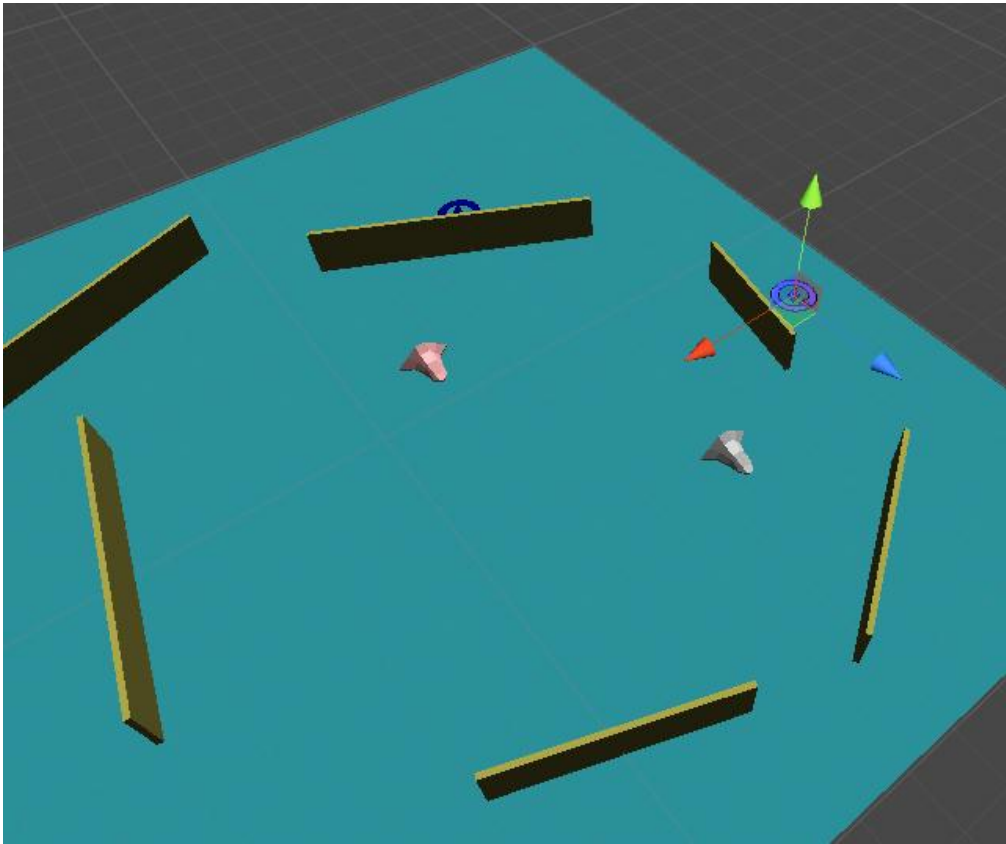
Constraint: e playerAttack != null &&

Constraint

Process child nodes as long as the constraint condition is true.

Behavior Tree Structure:

- ChaseAndAttack (BT)
 - root (PAR)
 - detect
 - detect
 - constraint (CON)
 - selector (SET)
 - constraint - attack (CON)
 - expression - start attacking
 - expression - don't attack
 - action
 - constraint (CON) (highlighted)
 - sequencer (SEQ)
 - timer
 - expression - don't attack
 - expression - start hiding



Behavior Editor

ET ChaseAndAttack

- PAR** root
 - detect
 - detect
 - CON** constraint
 - SEL** selector
 - CON** constraint - attack
 - expression - start attacking
 - expression - don't attack
 - action
 - SEL** selector
 - CON** constraint
 - SEQ** sequencer
 - timer
 - expression - don't attack
 - expression - start hiding
 - CON** constraint
 - action - choose hiding spot

RAIN

Behavior Tree: Current AI (ship)

Node Type: Custom Action

Name: action - choose hiding spo

Repeat: Never

Debug Break:

Assembly: (global)

Class: ChooseHidingSpot

Custom Action ?

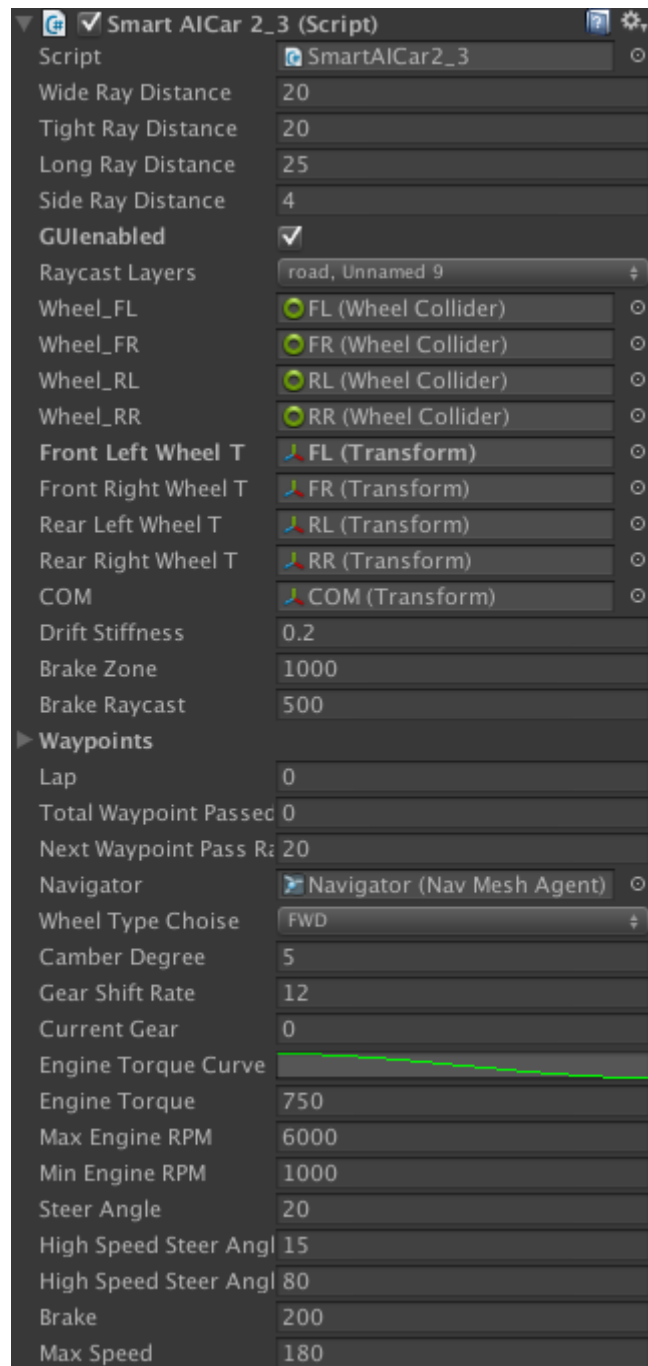
User defined action that calls into custom code. Custom actions are RAINActions marked with the [RAINAction] attribute.

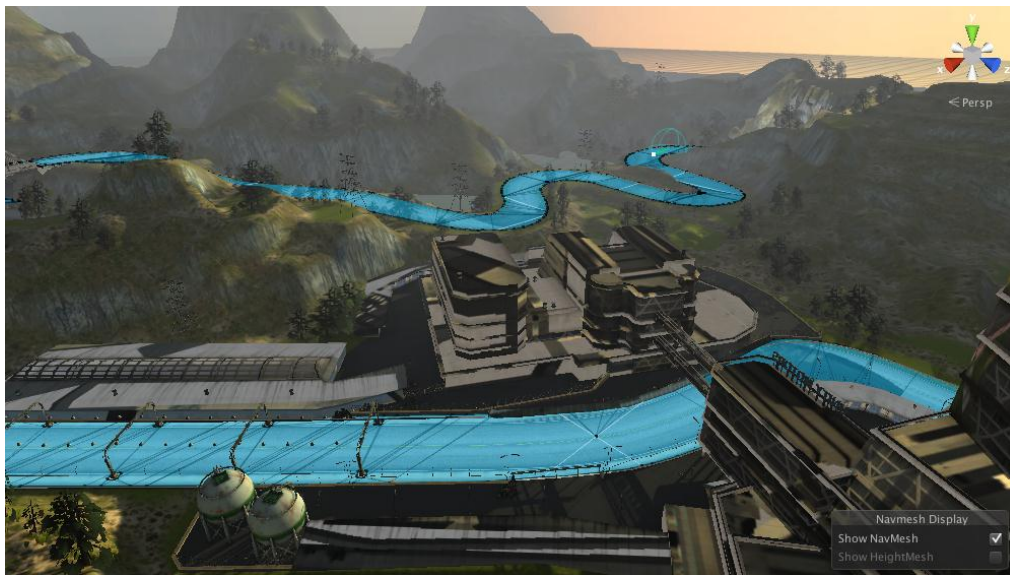
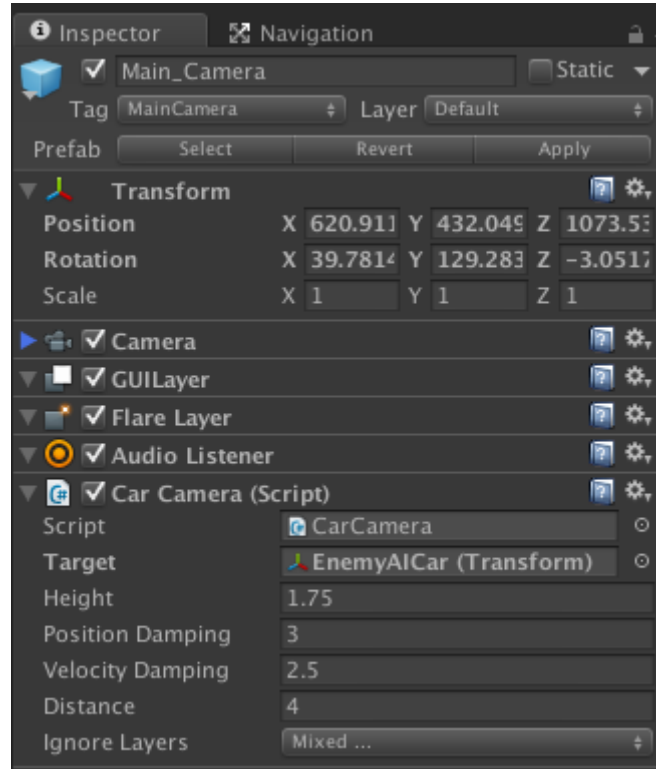
```

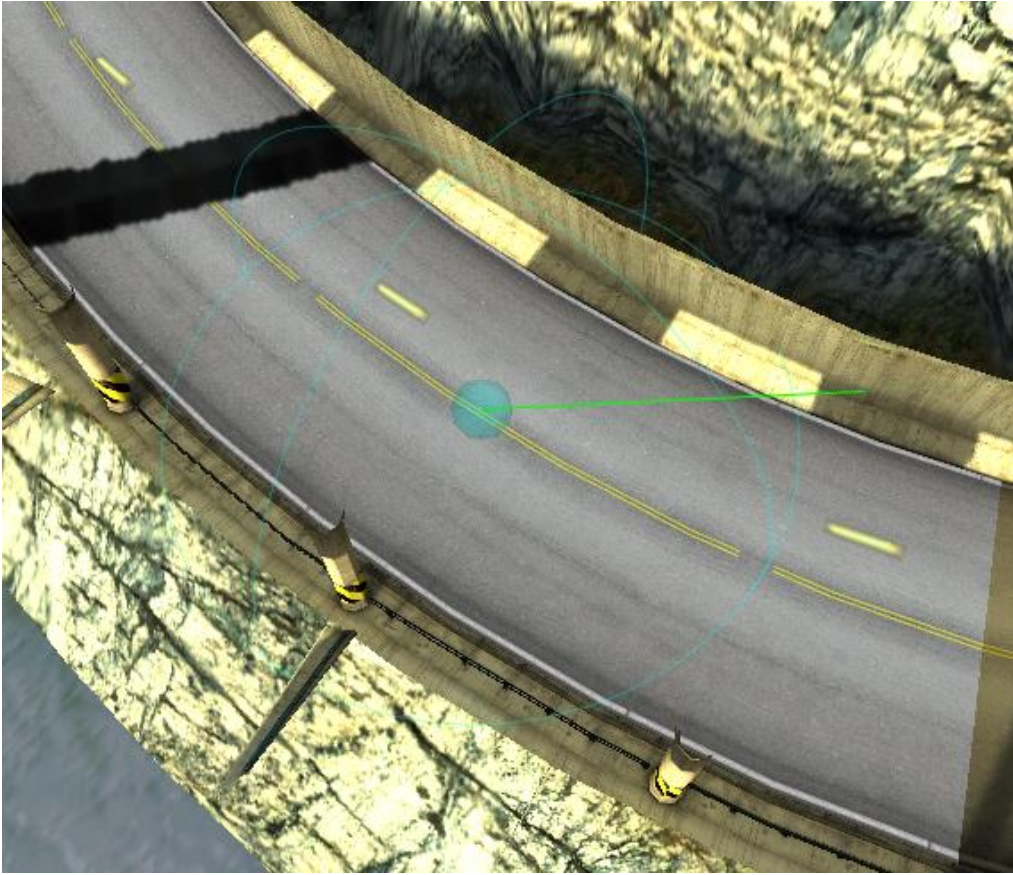
8 [RAINAction]
9 public class ChooseHidingSpot : RAINAction
10 {
11     Vector3 hideTarget;
12
13     public override void Start(AI ai)
14     {
15         NavigationTargetRig[] coverPoints = GameObject.FindObjectsOfType(typeof(NavigationTargetRig)) as NavigationTargetRig[];
16
17         if(coverPoints.Length == 0)
18         {
19             return;
20         }
21
22         float length = float.MaxValue;
23         Vector3 target = Vector3.zero;
24         foreach(NavigationTargetRig obj in coverPoints)
25         {
26             if(Vector3.Distance(ai.Body.transform.position, obj.Target.PositionOffset) < length)
27             {
28                 target = obj.Target.PositionOffset;
29             }
30         }
31
32         hideTarget = target;
33
34         base.Start(ai);
35     }
36
37     public override ActionResult Execute(AI ai)
38     {
39         if(Vector3.Distance(hideTarget, ai.Body.transform.position) < 1.0f) {
40             return ActionResult.SUCCESS;
41         }
42         ai.Motor.MoveTo(hideTarget);
43
44         return ActionResult.RUNNING;
45     }
46
47     public override void Stop(AI ai)
48     {
49         base.Stop(ai);
50     }
51 }
52 }

```


Chapter 9: Driving









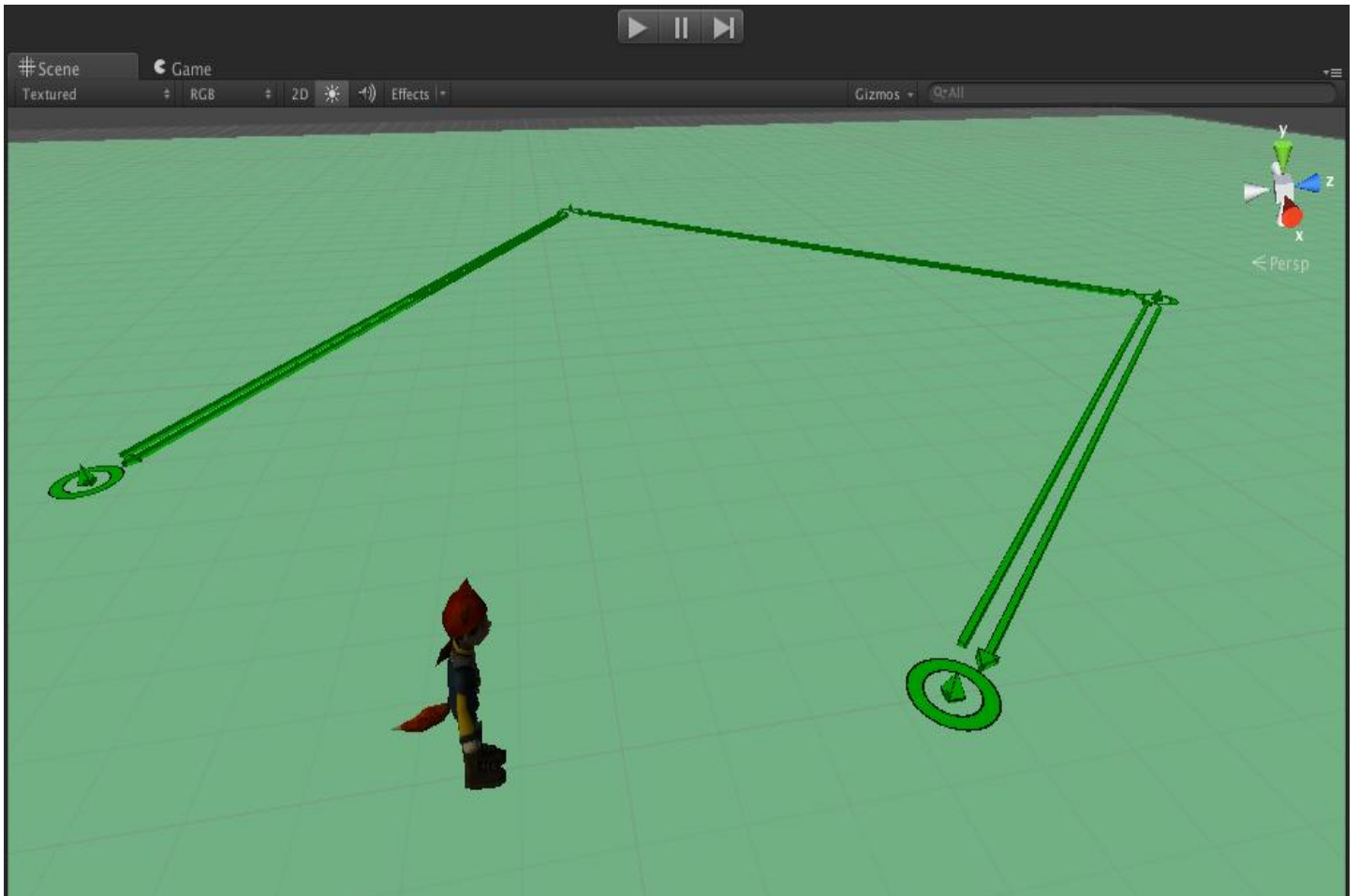
Inspector Navigation

Tags & Layers

- ▶ Tags
- ▶ Sorting Layers
- ▼ Layers

Builtin Layer 0	Default
Builtin Layer 1	TransparentFX
Builtin Layer 2	Ignore Raycast
Builtin Layer 3	
Builtin Layer 4	Water
Builtin Layer 5	UI
Builtin Layer 6	
Builtin Layer 7	
User Layer 8	obstacles
User Layer 9	
User Layer 10	
User Layer 11	
User Layer 12	
User Layer 13	
User Layer 14	
User Layer 15	
User Layer 16	
User Layer 17	
User Layer 18	
User Layer 19	
User Layer 20	
User Layer 21	
User Layer 22	
User Layer 23	
User Layer 24	
User Layer 25	
User Layer 26	
User Layer 27	
User Layer 28	
User Layer 29	
User Layer 30	
User Layer 31	

Chapter 10: Animation and AI



The scene for the AI animation demo

Behavior Editor

BT WalkPenelope

- SEQ root
 - WAY waypointpatrol
 - move

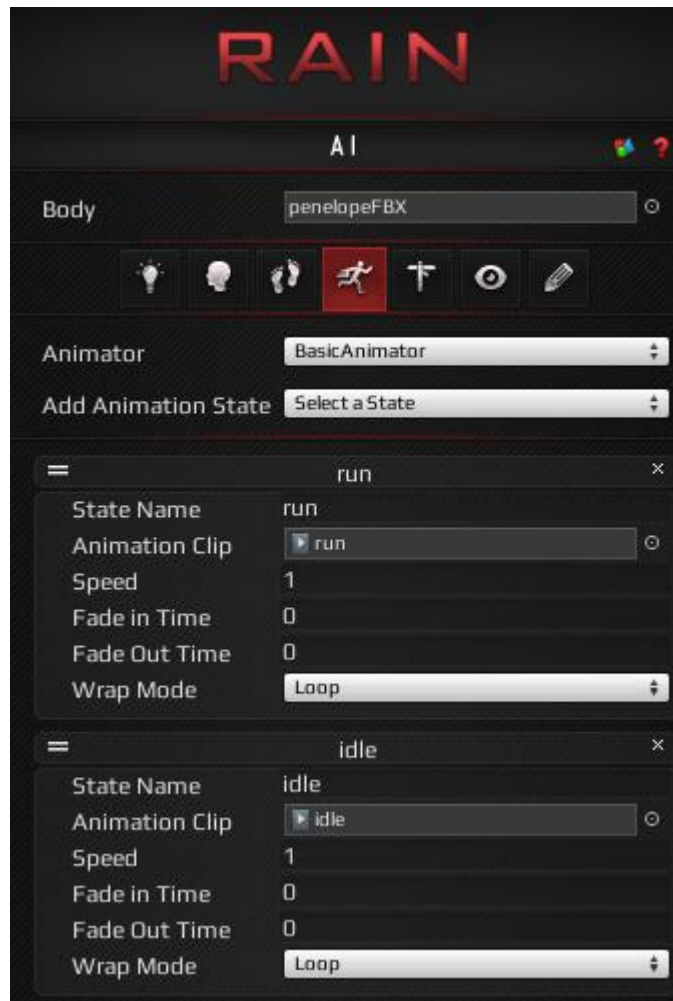
RAIN

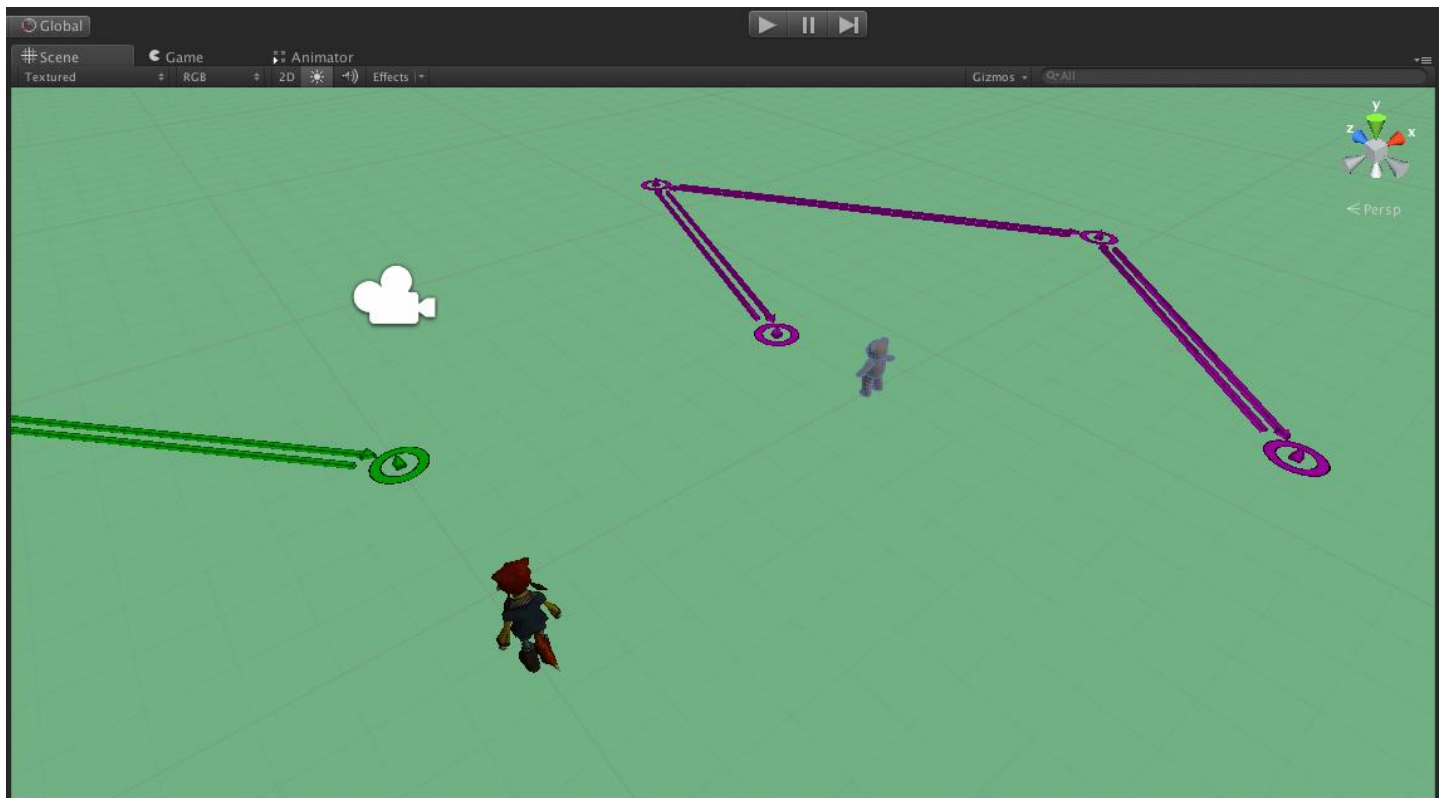
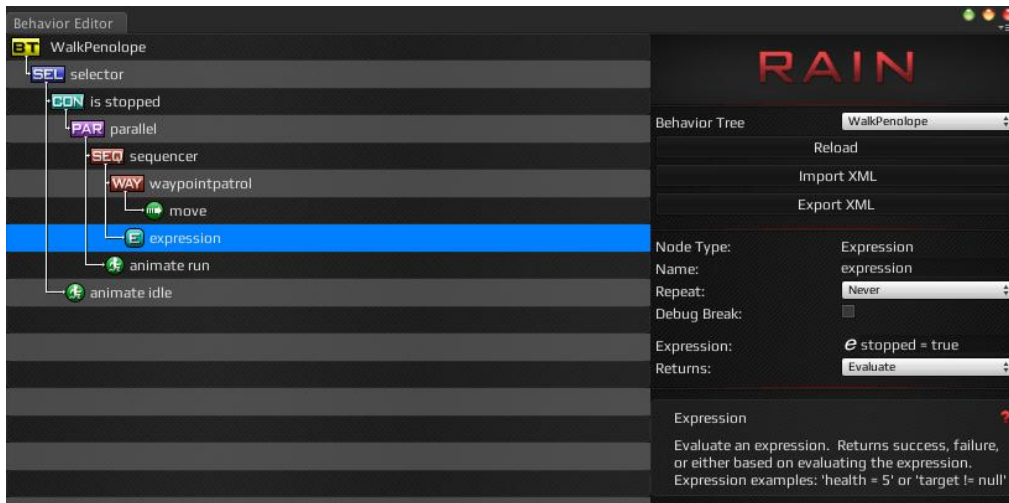
Behavior Tree: Current AI (penelopeFBX)

Node Type: Patrol Route
Name: waypointpatrol
Repeat: Never
Debug Break:
Waypoint Route: e "PenelopeRoute"
Loop Type: One Way
Direction: Forward
Move Target Variable: moveTarget

Patrol Route ?

Iterate through a set of Waypoint Route patrol points. Add a child Move action to create a patrol behavior.





RAIN

AI



Body

TeddyBear



Animator

MecanimAnimator



Add Animation State

Select a State



- Base Layer.Run

Mecanim State Base Layer.Run

Layer 0

+ Start Parameter

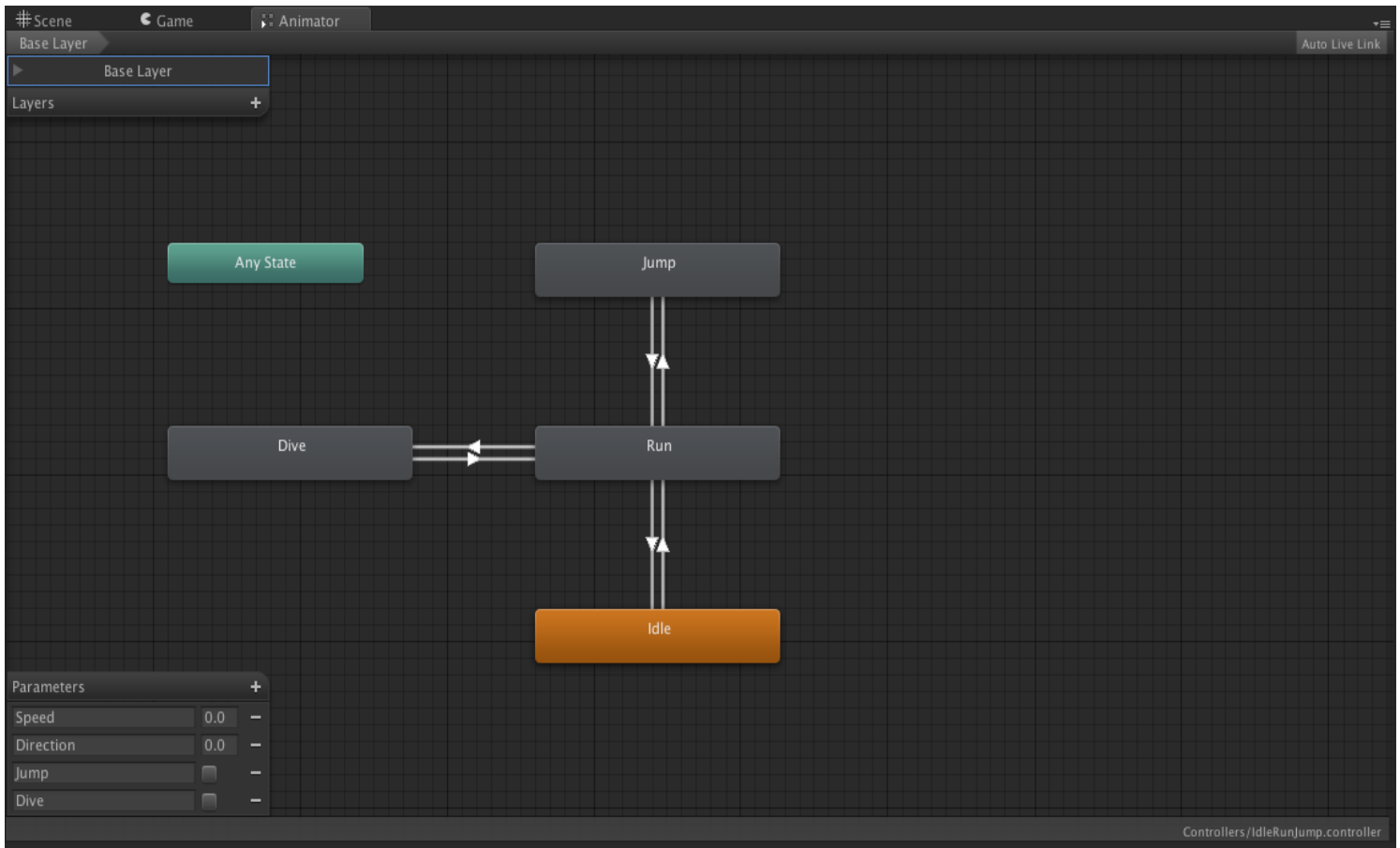
+ Stop Parameter
- Base Layer.Idle

Mecanim State Base Layer.Idle

Layer 0

+ Start Parameter

+ Stop Parameter



RAIN

AI



Body

TeddyBear



Animator

MecanimAnimator

Add Animation State

Select a State

Base Layer.Run

Mecanim State Base Layer.Run

Layer 0

- Start Parameter

Parameter Name Speed

Parameter Type Float

Parameter Value 1

Damp Time 0

+ Stop Parameter

Base Layer.Idle

Mecanim State Base Layer.Idle

Layer 0

- Start Parameter

Parameter Name Speed

Parameter Type Float

Parameter Value 0

Damp Time 0

+ Stop Parameter

Behavior Editor

BT WalkTeddy

- SEQ** root
 - SEL** selector
 - CON** is stopped
 - PAR** parallel
 - SEQ** sequencer
 - WAY** waypointpatrol
 - move
 - E** expression
 - animate run
 - animate idle

RAIN

Behavior Tree: Current AI (TeddyBear)

Node Type: Animate

Name: animate idle

Repeat: Forever

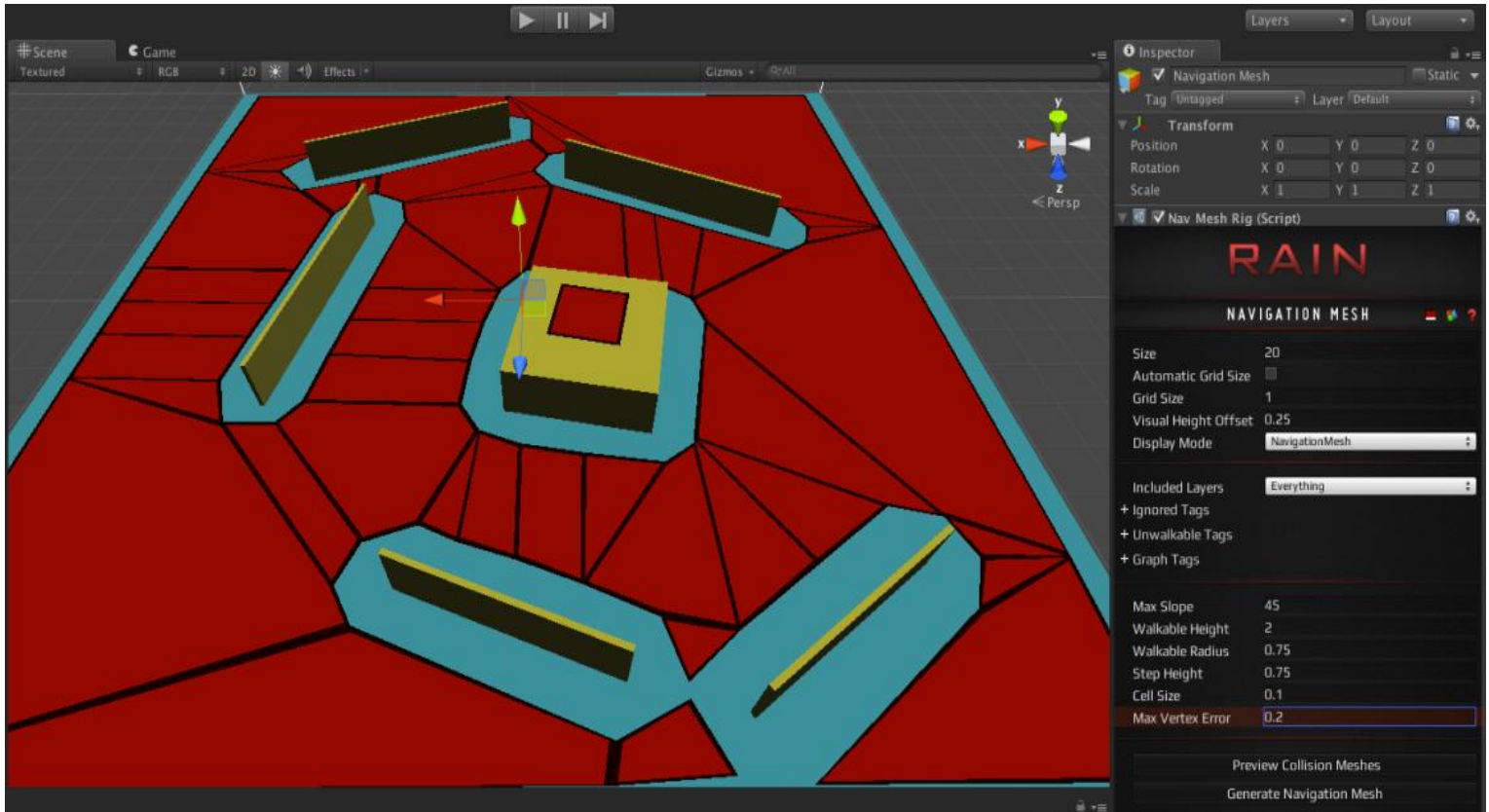
Debug Break:

Animation State: Base Layer.Idle

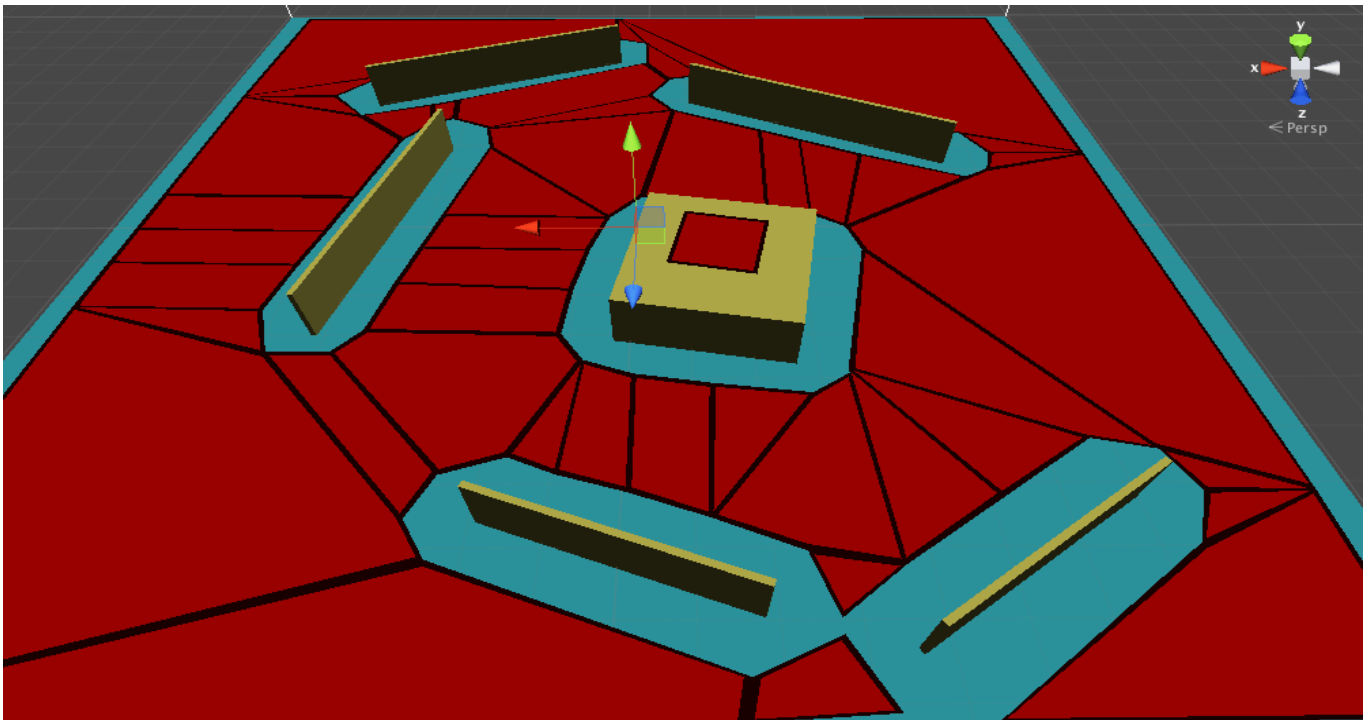
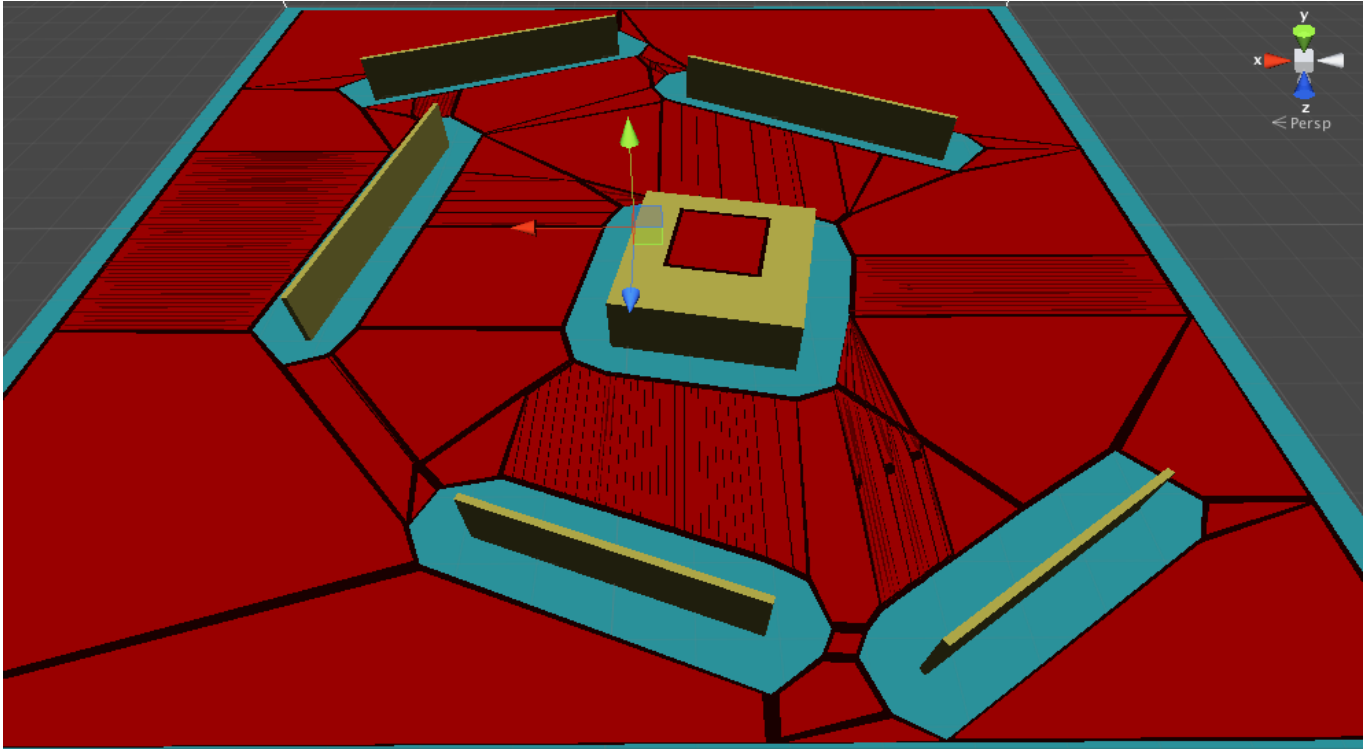
Animate ?

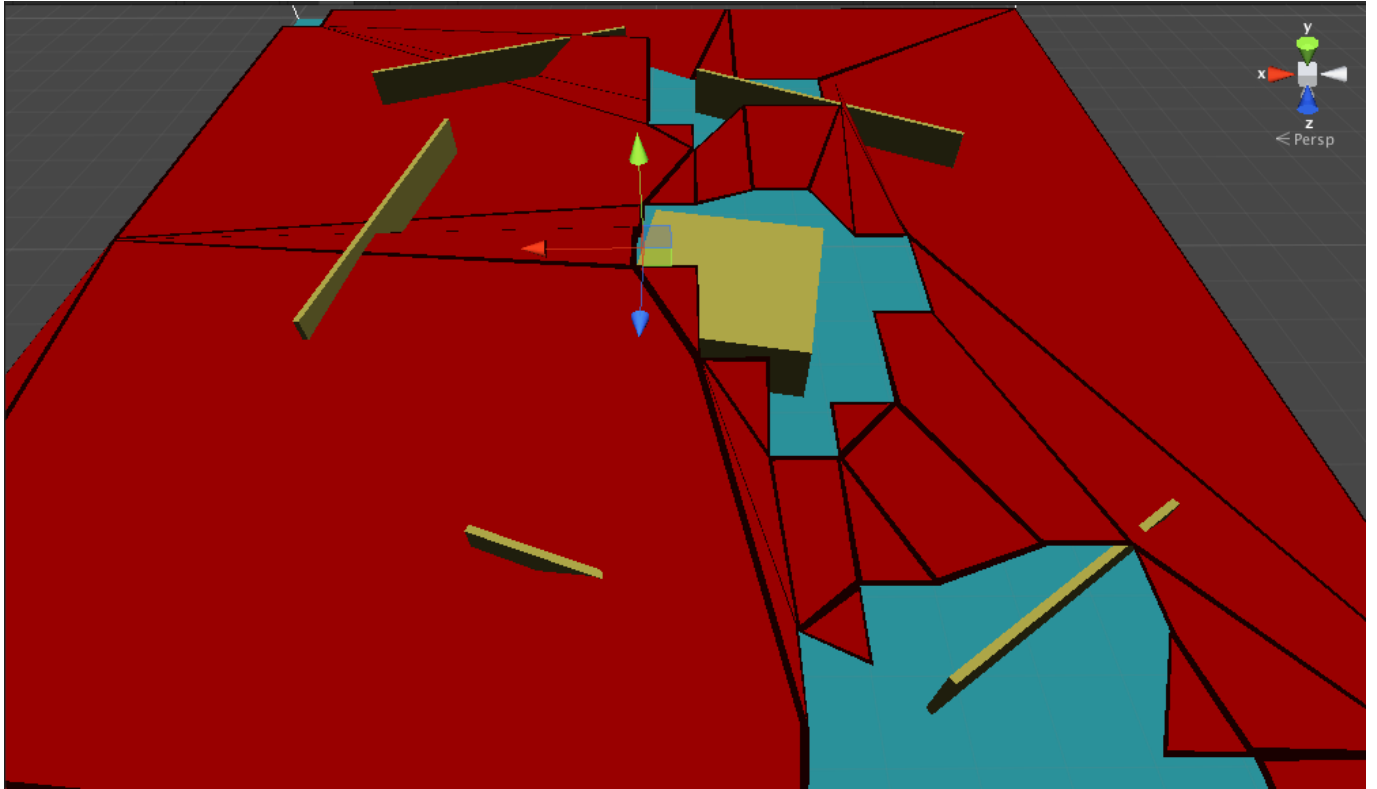
Signal the AI Animator to start an animation state. The node will exit if the state stops playing.

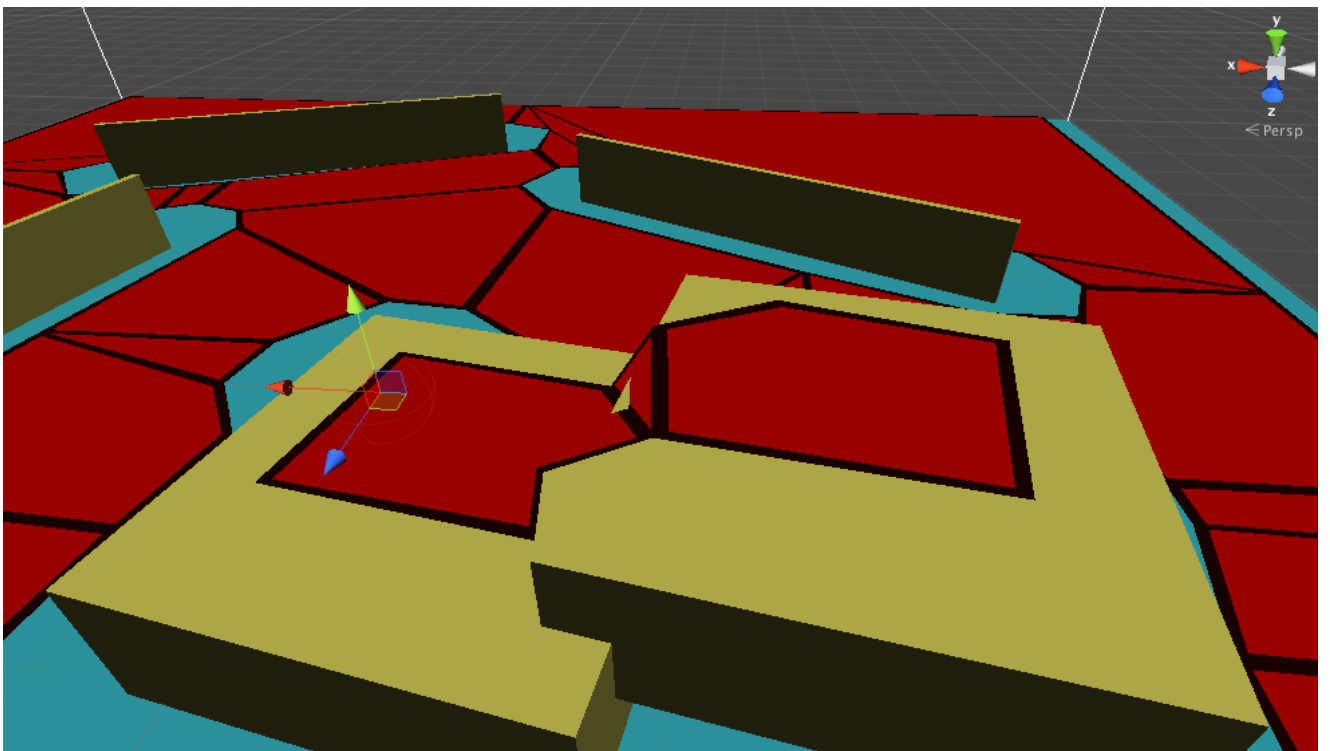
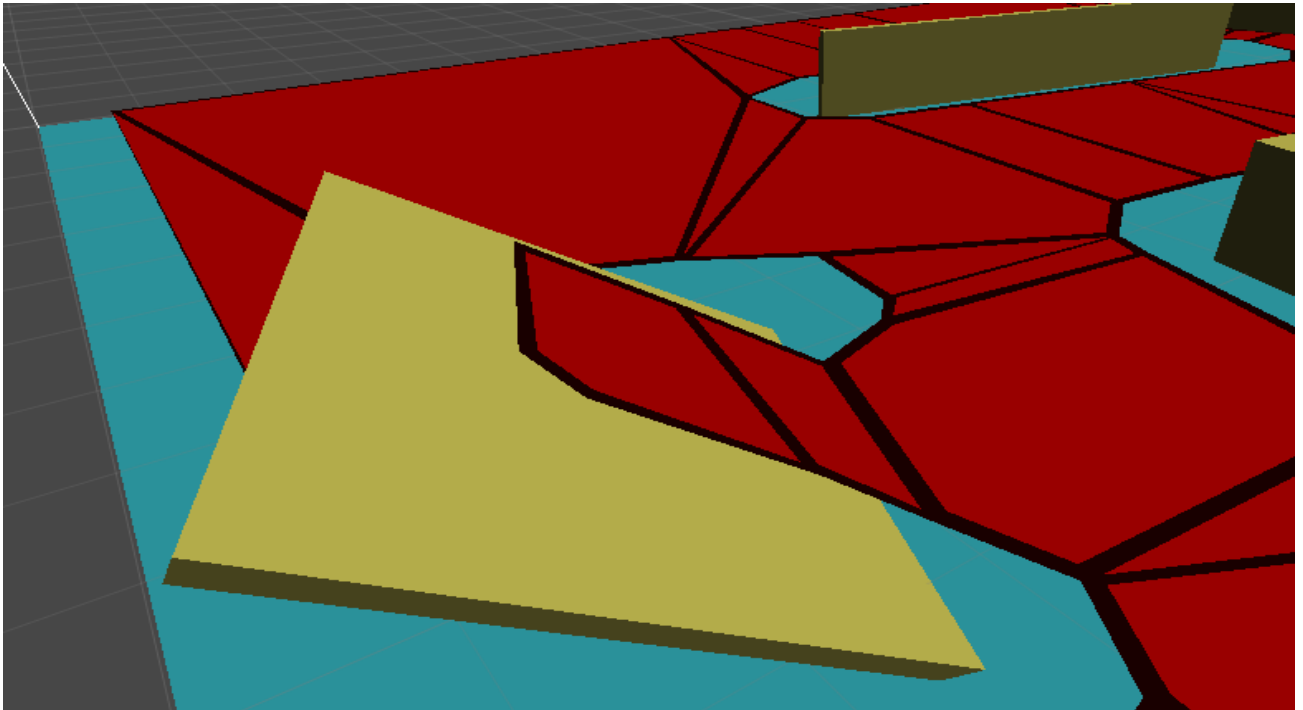
Chapter 11: Advanced NavMesh Generation

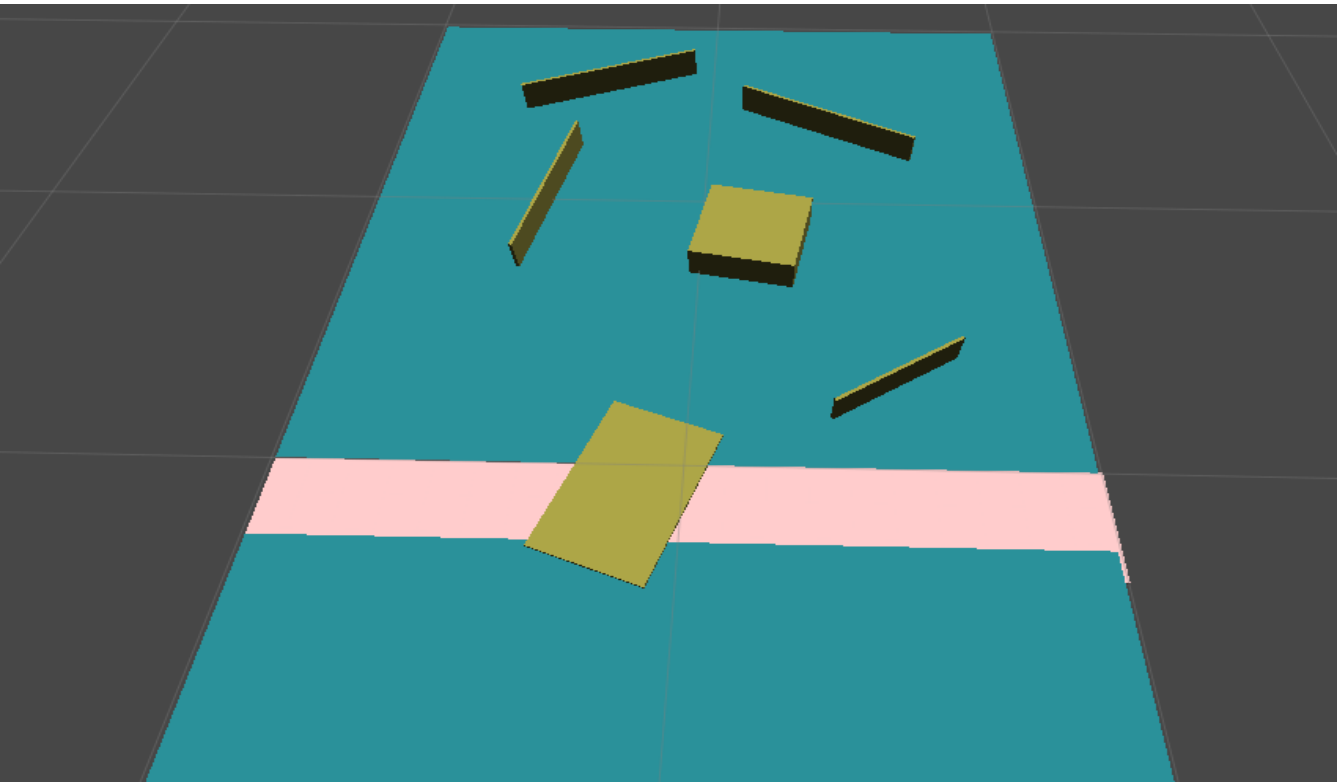
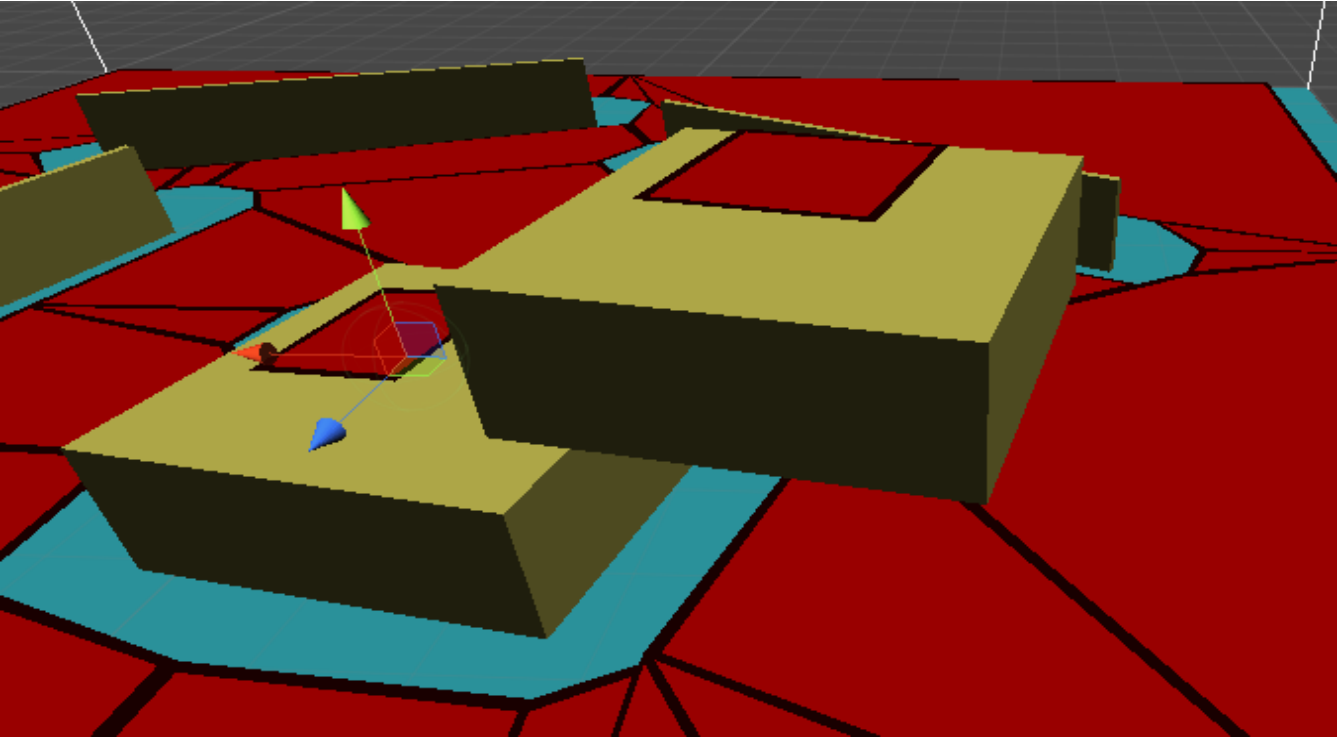


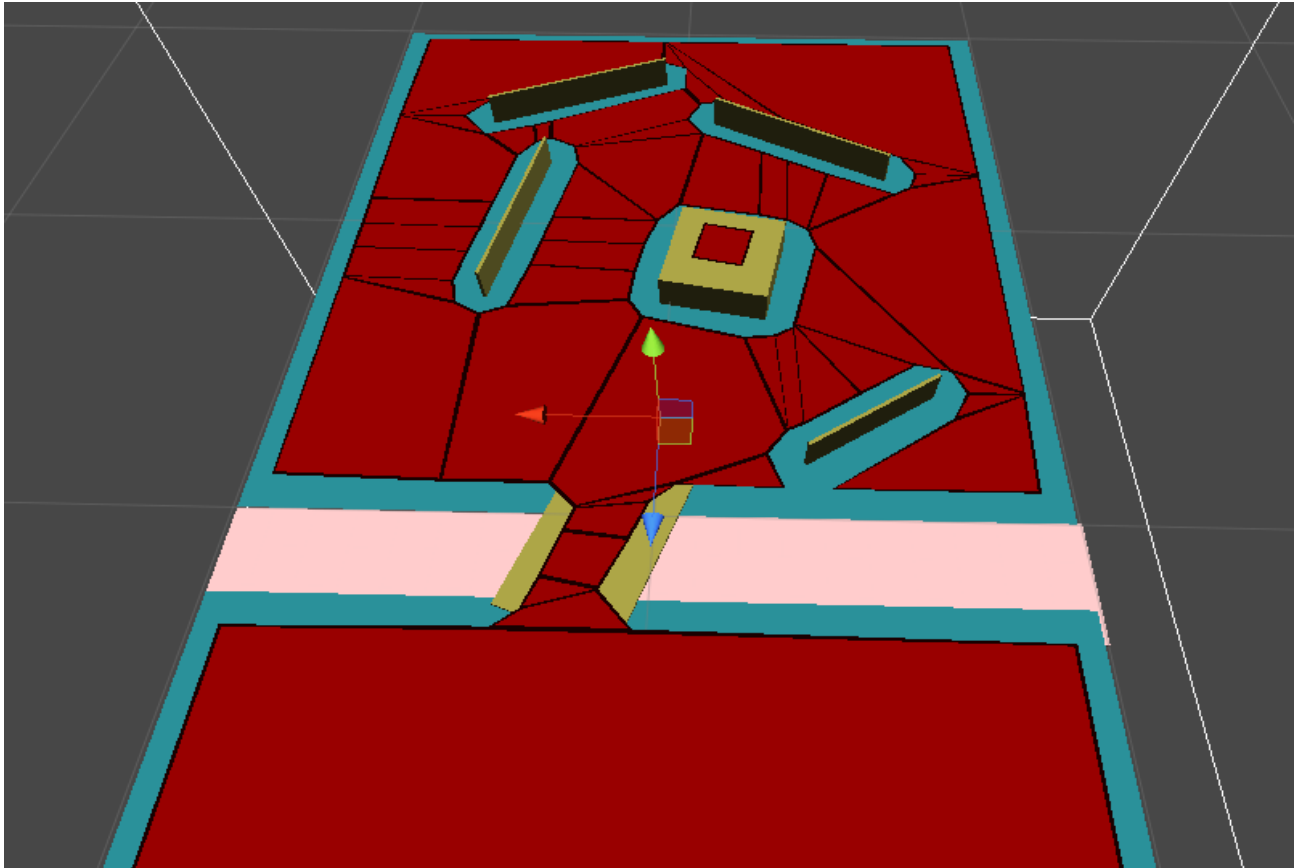
The NavMesh setup











Behavior Editor

shipDemo

- SEQ root
 - move

RAIN

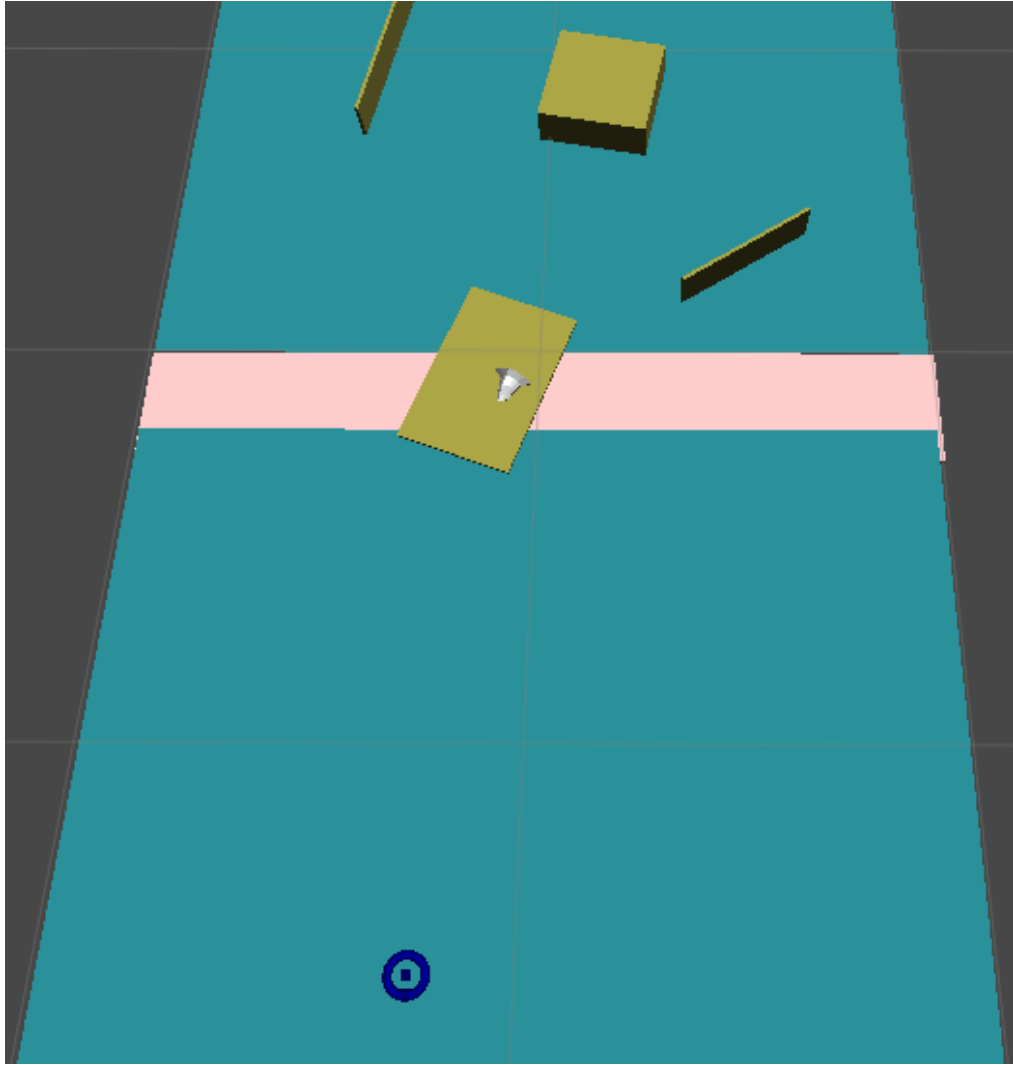
Behavior Tree: Current AI (Enemy)

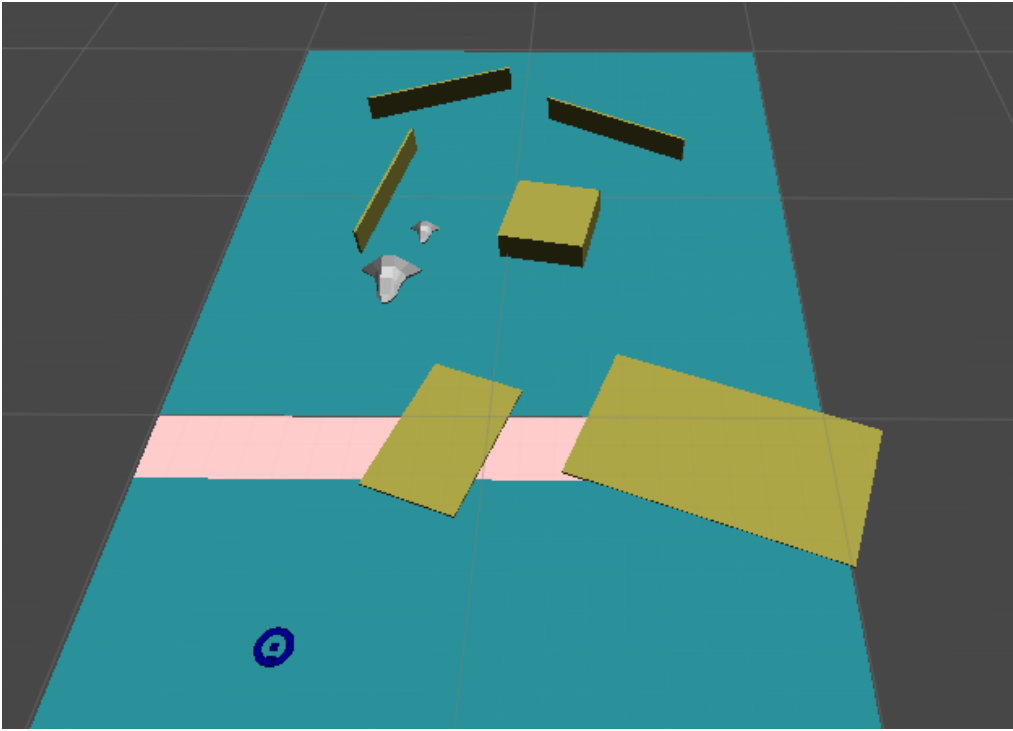
Node Type: Move
Name: move
Repeat: Forever
Debug Break:

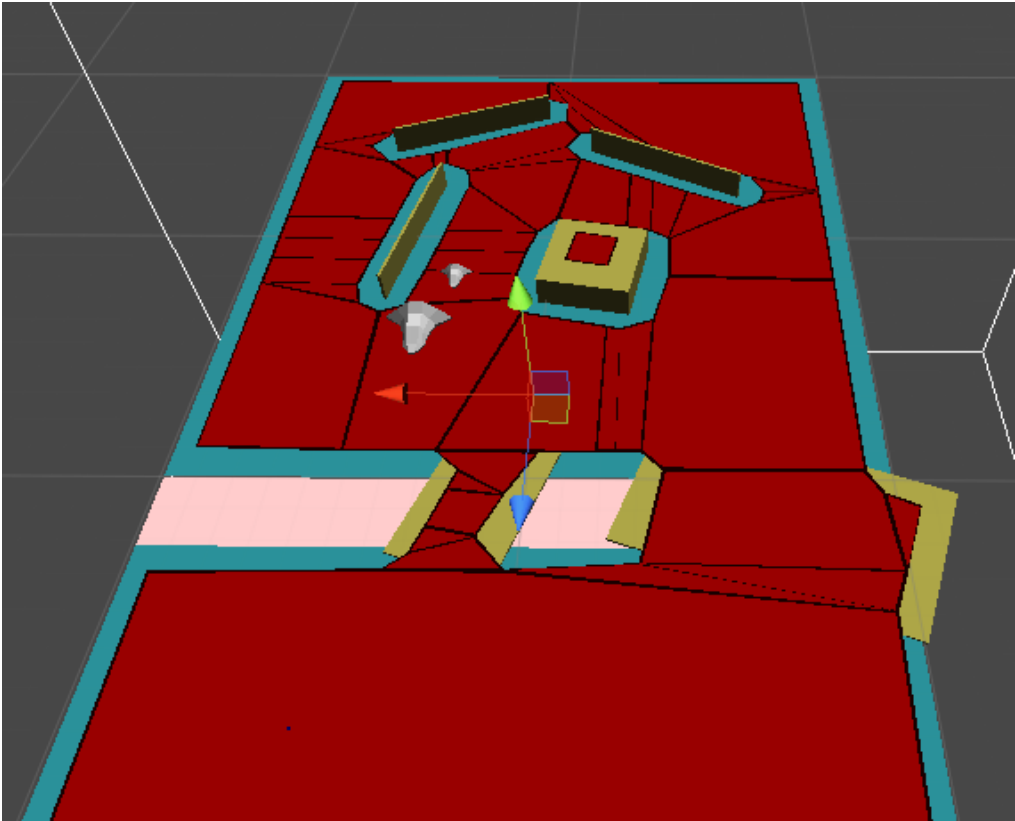
Move Target: e "MoveTarget"
Move Speed: e 10
Face Target: e
Turn Speed: e
Close Enough Distance: e
Close Enough Angle: e

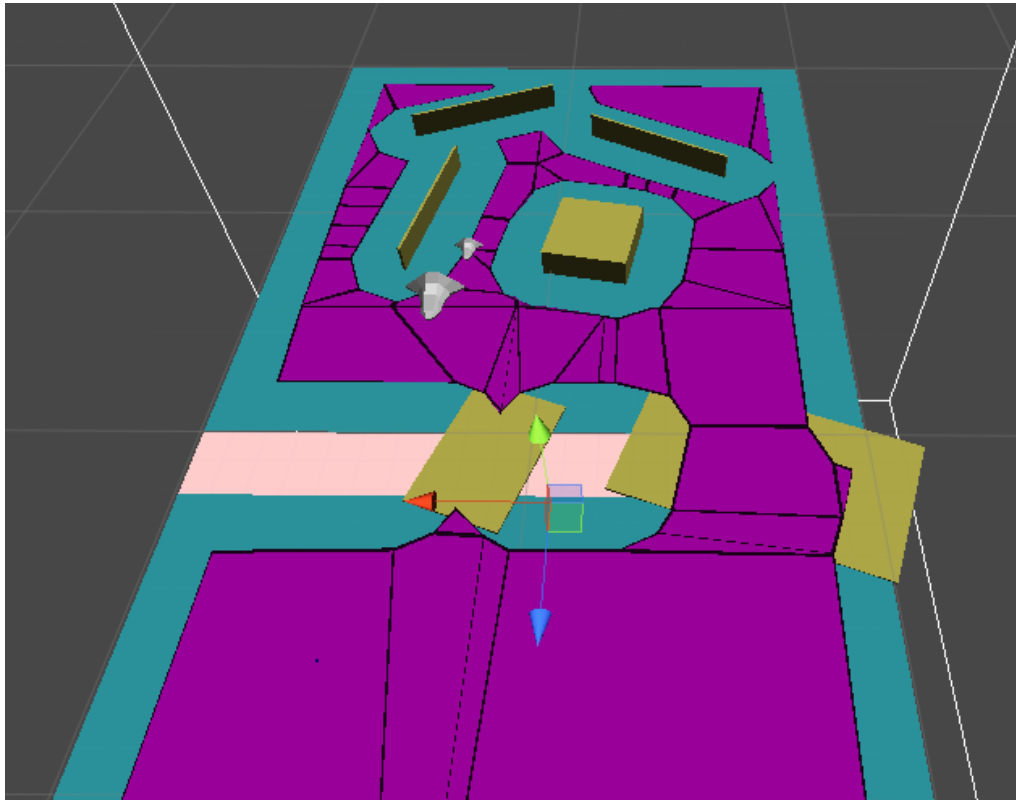
Move ?

Move to a target location and/or turn to face a target. Target can be the name of a Navigation Target (in quotes), a vector, or a variable expression representing an object or location.









RAIN

NAVIGATION MESH



Size	50
Automatic Grid Size	<input type="checkbox"/>
Grid Size	1
Visual Height Offset	0.25
Display Mode	NavigationMesh
Included Layers	Everything
+ Ignored Tags	
+ Unwalkable Tags	
- Graph Tags	
Size	1
Element 0	Small Ship
Max Slope	45
Walkable Height	2
Walkable Radius	0.75
Step Height	0.75
Cell Size	0.1
Max Vertex Error	0.2

Preview Collision Meshes

Generate Navigation Mesh

RAIN

AI



Use Unity Messages

Use Fixed Update

Is Active

Body



Navigator

Draw Paths

Max Pathfinding Step:100

- Graph Tags

Size 1

Element 0 Small Ship

