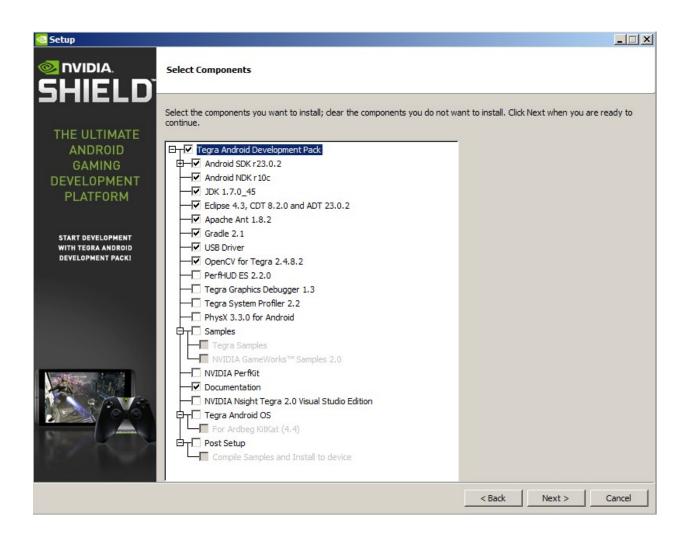
Chapter 1: Getting Yourself Ready



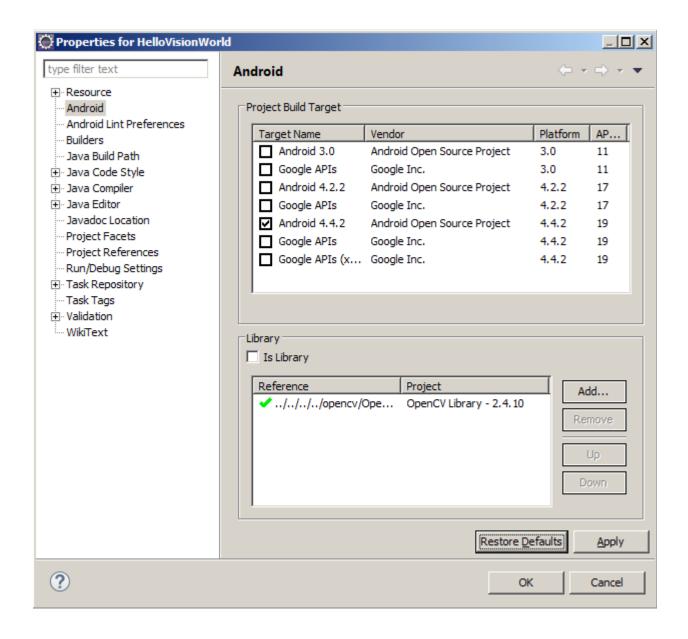


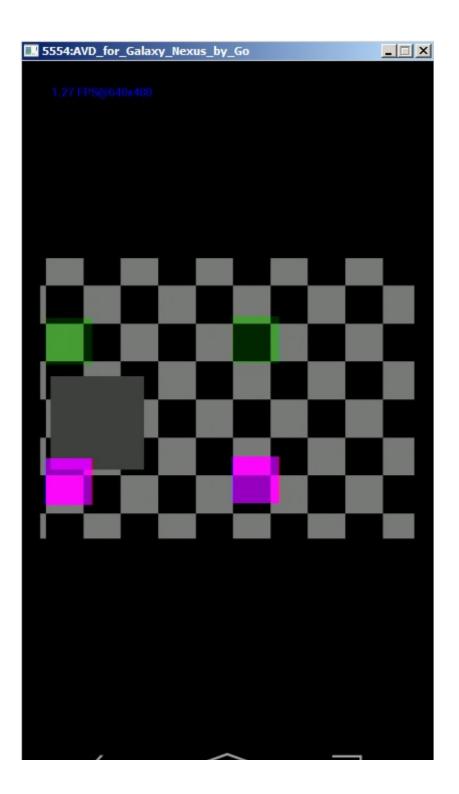
kages		,		
Name	API	Rev.	Status	
	19	4	蒙 Installed	
	19	6	Not installed	
🛛 🖬 ARM EABI v7a System Image	19	2	Not installed	
🗹 💵 Intel x86 Atom System Image	19	2	Not installed	
🛛 🛱 Google APIs (x86 System Image)	19	10	Not installed	
	19	10	Not installed	
	19	11	Not installed	
Sources for Android SDK	19	2	Not installed	
- 🗖 🔂 Android 4.3.1 (API 18)				
	18	3	😿 Installed	
	18	1	Not installed	
	18	2	Not installed	
✓ III Intel x86 Atom System Image	18	1	Not installed	
	18	3	Not installed	
Sources for Android SDK	18	1	Not installed	
- Android 4.2.2 (API 17)				
□ 🛒 SDK Platform	17	3	😿 Installed	
Samples for SDK	17	1	Not installed	
ARM EABI v7a System Image	17	2	Not installed	
✓ III Intel x86 Atom System Image	17	1	Not installed	
MIPS System Image	17	1	Not installed	
Google APIs	17	3	Not installed	



C:\windows\system32\cmd.exe	_ 🗆 🗙
<pre>C:\C\windows\system32\cmd.exe C:\android\android-ndk-r10d\samples\hello-jni>ndk-build Android NDK: WARNING: APP_PLATFORM android-15 is larger than android:minSdkUersion 3 in ./AndroidManifest.xml [arm64-v8a] Gdbserver : [aarch64-linux-android-4.9] libs/arm64-v8a/gdbserver [arm64-v8a] Gdbserver : [bb/arm64-v8a/gdb.setup [hips64] Gdbserver : [bibs/arm64-v8a/gdbserver [hips64] Gdbserver : [mips64gd1.setup [armeabi-v7a] Gdbserver : [libs/armeabi-v7a/gdbserver [armeabi] Gdbserver : [larm-linux-androideabi-4.6] libs/armeabi/gdbserver [armeabi] Gdbserver : [libs/armeabi/gdb.setup [armeabi] Gdbserver : [libs/armeabi/gdb.setup] [armeabi] Gdbserver : [libs/armeabi/gdb.setup] [armeabi] Gdbserver : [libs/armeabi/gdb.setup]</pre>	
[X86] Gdbsetup : libs/x86/gdb.setup [nips] Gdbsetup : lips/nips/gdb.setup [nips] Gdbsetup : libs/nips/gdb.setup [arm64-v8a] Install : libhello-jni.so => libs/arm64-v8a/libhello-jni.so [x86_64] Install : libhello-jni.so => libs/x86_64/libhello-jni.so [arm64-v8a] Install : libhello-jni.so => libs/x86_64/libhello-jni.so [armeabi-v7a] Install : libhello-jni.so => libs/armeabi-v7a/libhello-jni.so [x86] Install : libhello-jni.so => libs/armeabi-libhello-jni.so [x86] Install : libhello-jni.so => libs/armeabi-libhello-jni.so [x86] Install : libhello-jni.so => libs/armeabi-libhello-jni.so [nips] Install : libhello-jni.so => libs/x86/libhello-jni.so [nips] Install : libhello-jni.so => libs/mips/libhello-jni.so [mips] Install : libhello-jni.so => libs/mips/libhello-jni.so	
C:\android\android-ndk-r10d\samples\hello-jni>	-

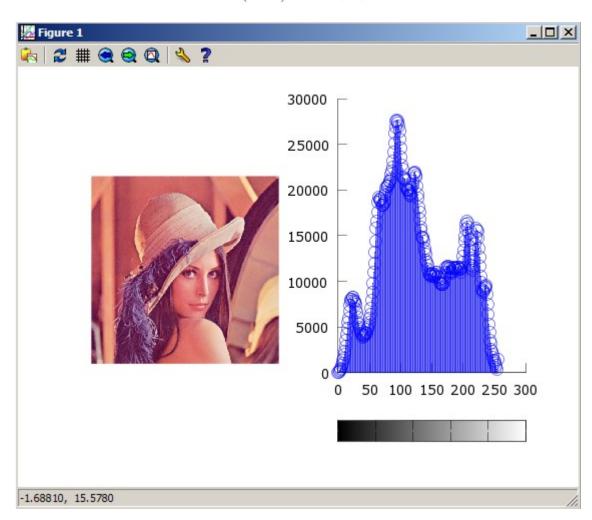
0			<u>_ 🗆 ×</u>
Import Projects Select a directory to search for existing A	Android projects		0
Root Directory: C:\opencv\OpenCV-2.4 Projects:	. 10-android-sdk		Browse
Project to Import	New Project Name		Select All
samples\camera-calibration	OpenCV Sample - camera-calibration OpenCV Sample - color-blob-detection		Deselect All
 samples\face-detection samples\image-manipulations 	OpenCV Sample - face-detection OpenCV Sample - image-manipulations		Refresh
samples native-activity	OpenCV Sample - native-activity		
samples\tutorial-1-camerapreview	OpenCV Tutorial 1 - Camera Preview		
samples\tutorial-2-mixedprocessing	OpenCV Tutorial 2 - Mixed Processing		
samples\tutorial-3-cameracontrol	OpenCV Tutorial 3 - Camera Control		
✓ sdk\java	OpenCV Library - 2.4.10		
Copy projects into workspace Working sets Add project to working sets Working sets:			iglect
?	< <u>B</u> ack <u>N</u> ext > <u>F</u> inish		Cancel



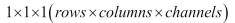


Chapter 2: App 1 - Building Your Own Darkroom

 2^{8}

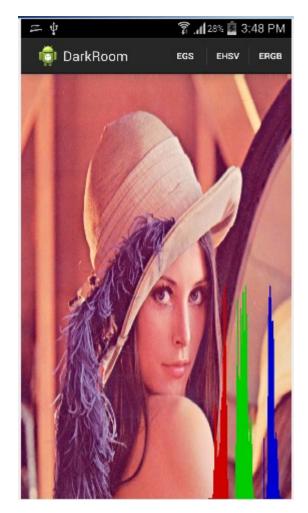


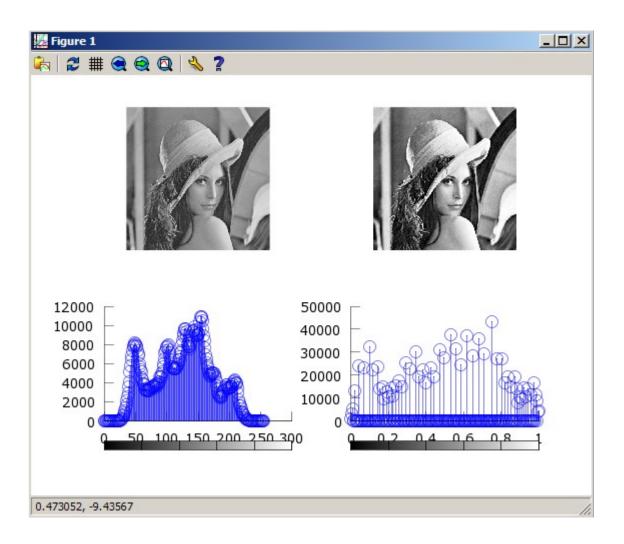
 $8 \times 3(RGB) = 24 megabyte$

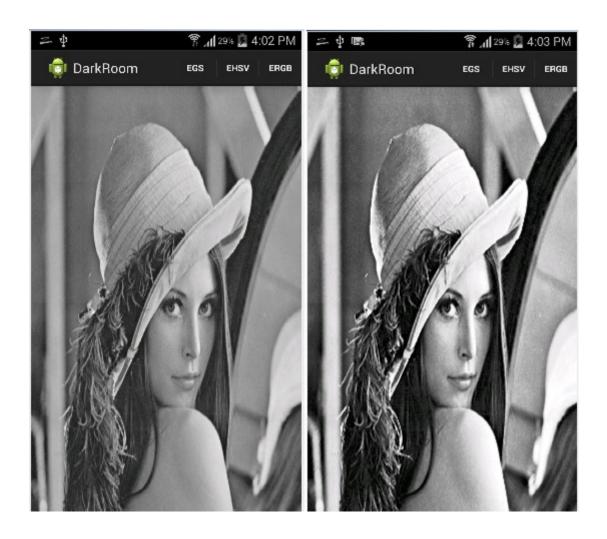


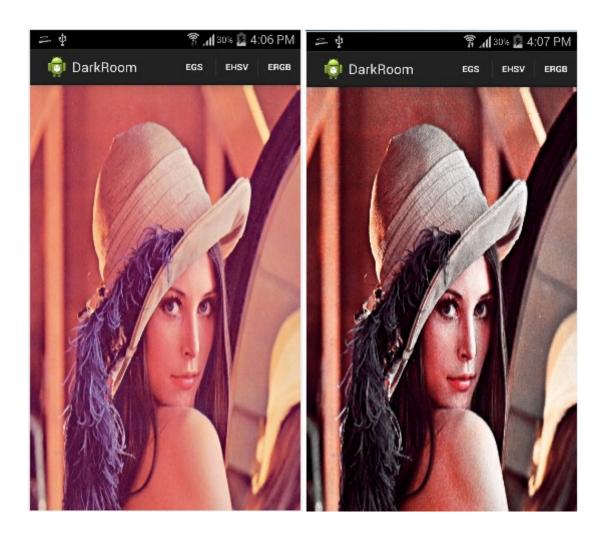
 $1 \times 1 \times number of bins$

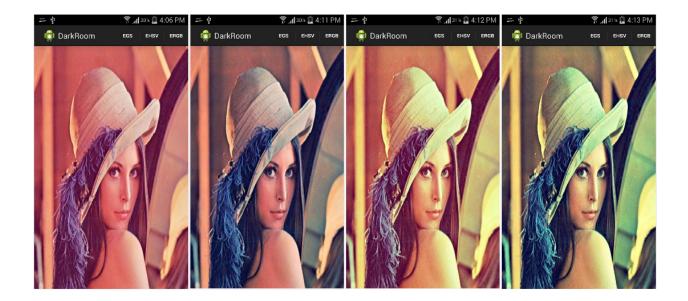
 $2 \times 1 \times 1$



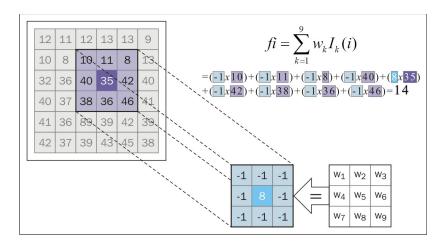




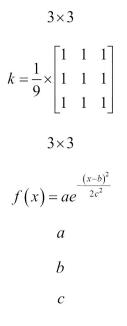




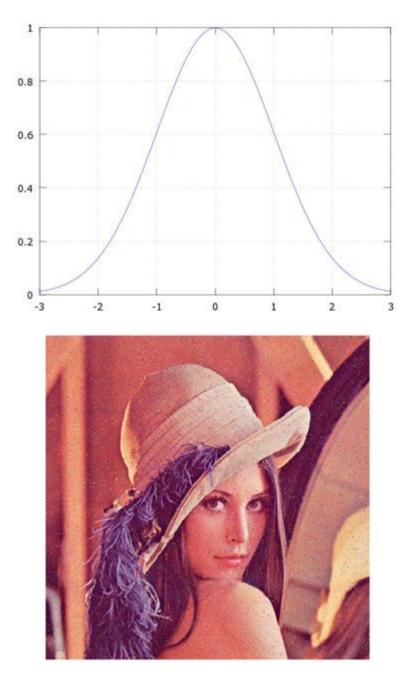
Chapter 3: App 2 - Software Scanner



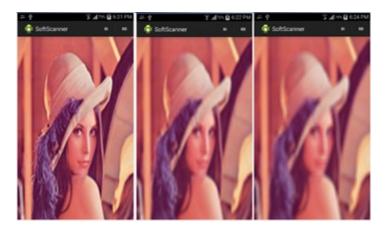


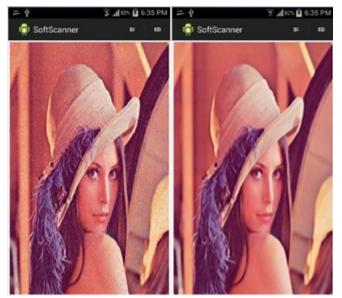


a = 1, b = 0, c = 1



 7×7



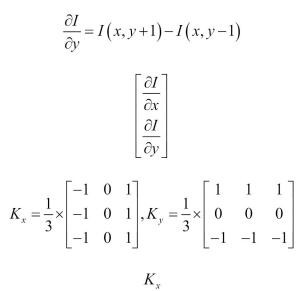


 $n \times n$

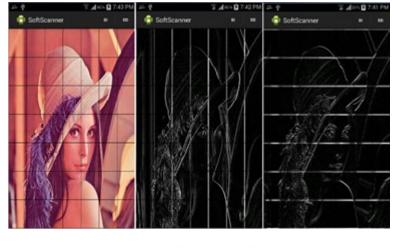
- 1, 2, ..., *n*
- 1, 2, ..., *n*

1.1,1.2,..., and so on

$$\frac{\partial I}{\partial x} = I(x+1, y) - I(x-1, y)$$



 K_y



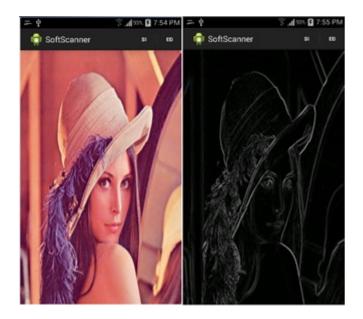
$$K_x = \begin{bmatrix} -1 & 0 & 1 \\ -2 & 0 & 2 \\ -1 & 0 & 1 \end{bmatrix}$$

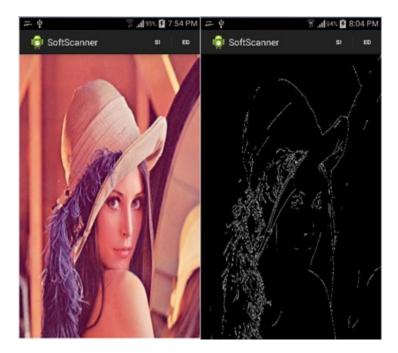
$$K_{y} = \begin{bmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & 1 \end{bmatrix}$$
$$K_{x}$$
$$K_{y}$$
$$7 \times 7$$
ivative = -255 - 0 = -2

derivative = -255 - 0 = -255

gradient magnitude = $\sqrt{f_x^2 + f_y^2}$

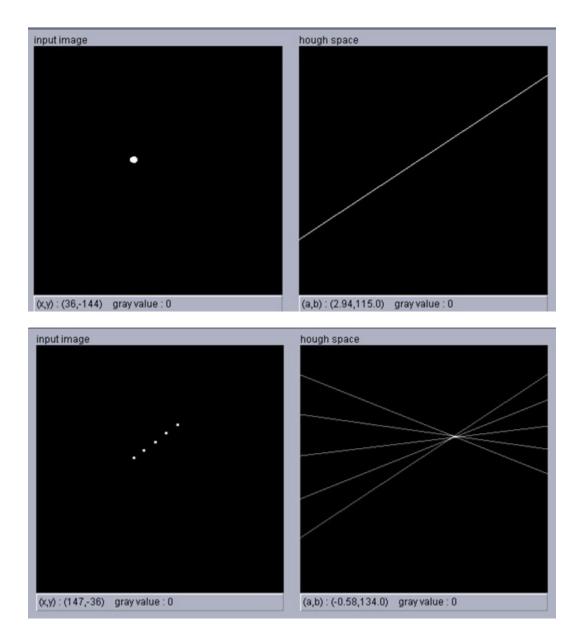
 f_x and f_y

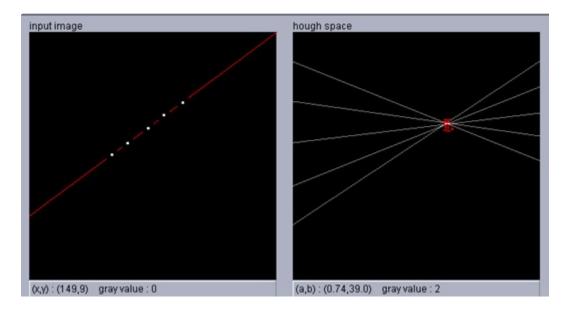






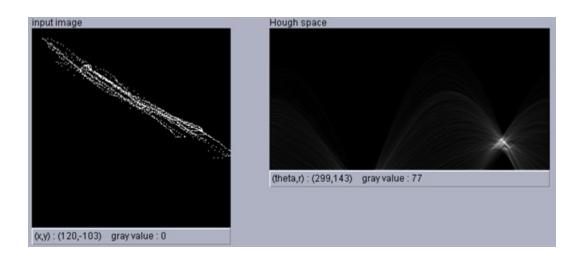
xy = ax + b(a)b = (-x)a + y

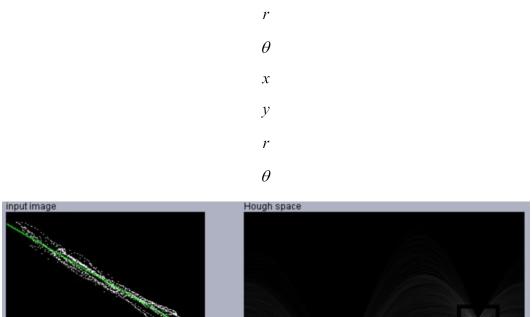




 $r = x\cos\theta + y\sin\theta$

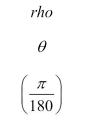
r(rho) θ r θ



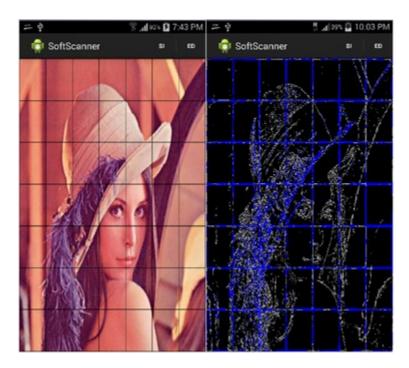




$$\left(x_{\textit{start}}, y_{\textit{start}}, x_{\textit{end}}, y_{\textit{end}}
ight)$$



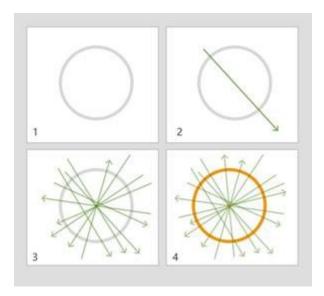
 $(x_{start}, y_{start}, x_{end}, y_{end})$



x, *y*

$$r^{2} = (x-a)^{2} + (y-b)^{2}$$

r, a, and b



(x, y, radius)

Chapter 4: App 2 - Applying Perspective Correction

$$t_{x}$$

$$t_{y}$$

$$p' = p + t$$

$$p' = Rp + t$$

$$R = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$\theta$$

$$s$$

$$p' = sRp + t$$

$$p' = Ap^{-}$$

$$p^{-} = [x, y, 1],$$

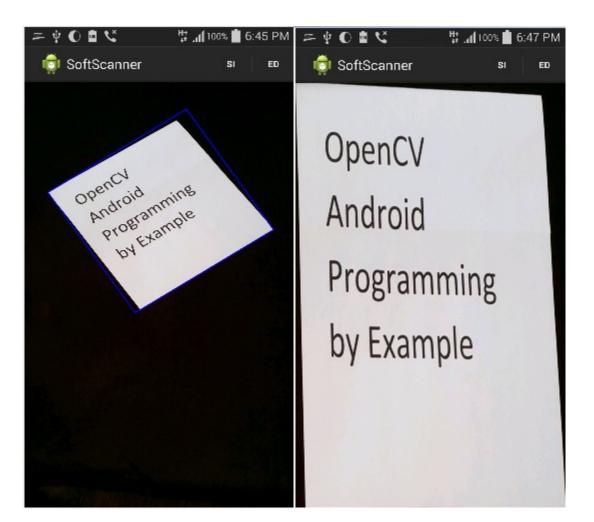
$$\begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix}$$

$$y$$

$$translation$$

$$Euclidean$$

x



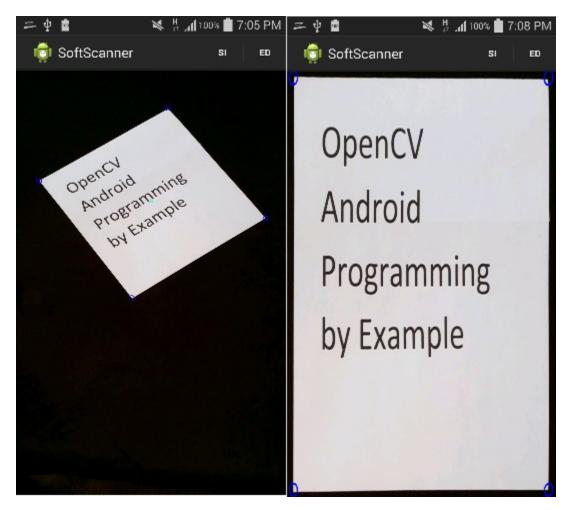
 L_1 $(X_1, Y_1), (X_2, Y_2)$

 L_2

 (X_3, Y_3) and (X_4, Y_4)

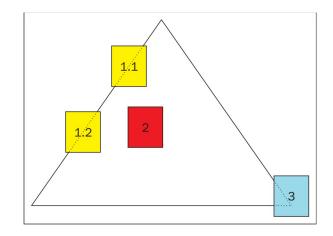
$$IP_{x} = \left(\frac{(x_{1}y_{2} - y_{1}x_{2})(x_{2} - x_{4}) - (x_{1} - x_{2})(x_{2}y_{4} - y_{2}x_{4})}{(x_{1} - x_{2})(y_{2} - y_{4}) - (y_{1} - y_{2})(x_{2} - x_{4})}\right)$$

$$IP_{y} = \left(\frac{(x_{1}y_{2} - y_{1}x_{2})(y_{8} - y_{4}) - (y_{1} - y_{2})(x_{8}y_{4} - y_{8}x_{4})}{(x_{1} - x_{2})(y_{8} - y_{4}) - (y_{1} - y_{2})(x_{8} - x_{4})}\right)$$



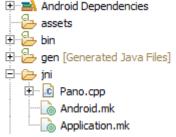
Chapter 5: App 3 - Panoramic Viewer



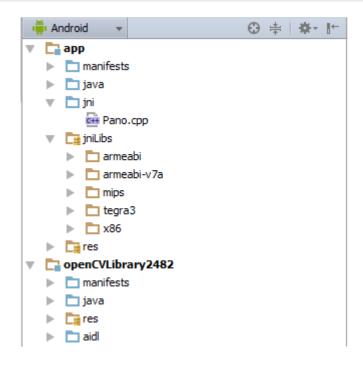


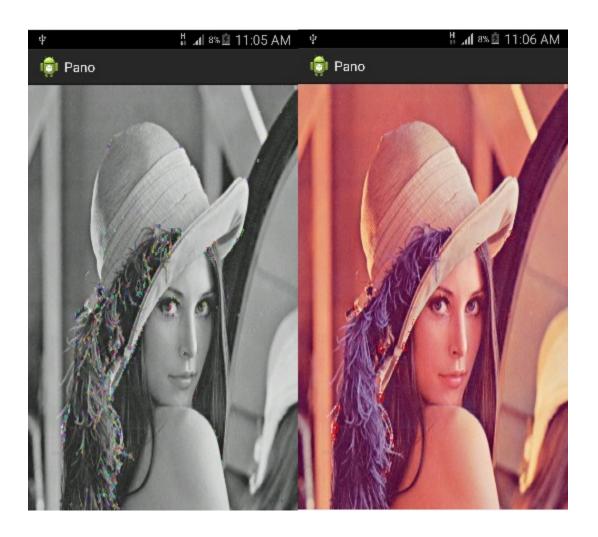
Convert to C or C++	
C Project	C++ Project
Project options Specify project type Project type: Executable Shared Library Static Library Makefile project	Toolchains: Other Toolchain Android GCC Cross GCC Cygwin GCC
Show project types and toolch	ains only if they are supported on the platform
?	< Back Mext > Finish Cancel

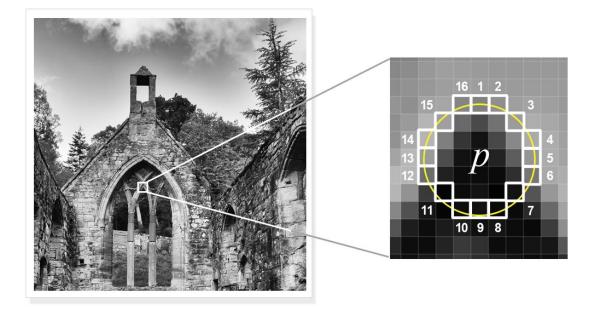
Enable parallel build O Use optimal jobs (4) Use parallel jobs: 4 O Use unlimited jobs	1
Make build target:	
	Variables
, Id preference	
	Variables
dean	Variables
	Use optimal jobs (4) Use parallel jobs: 4 Use unlimited jobs Make build target: ild) ild preference

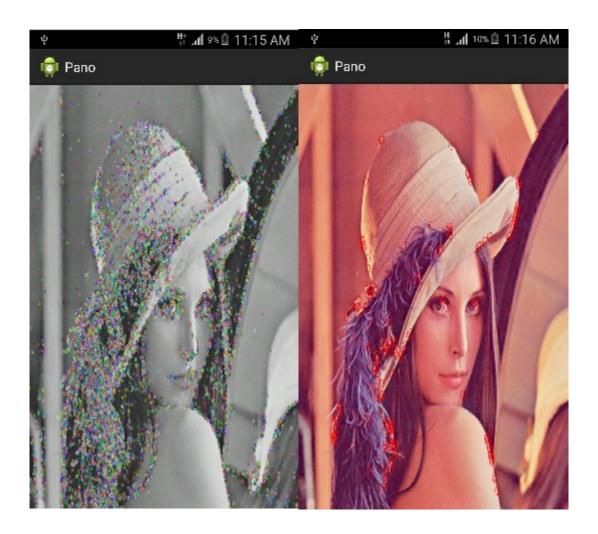


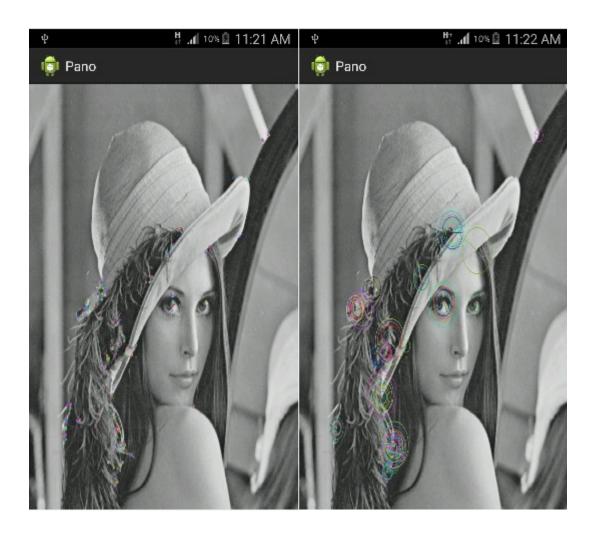
🙊 Project Structure		×
+ -	SDK Location	
SDK Location Project - Developer Services Ads Analytics Authentication Notifications 	Android SDK location: The directory where the Android SDK is located. This location will be used for new projects, and for existing projects that do not have a local.properties file with a sdk.dir property. C:\Users\\enovo\AppData\Local\Android\sdk JDK location: The directory where the Java Development Kit (JDK) is located. C:\Program Files\Java\jdk1.7.0_79 Android NDK location: The directory where the Android NDK is located. This location will be saved as ndk.dir property in the local.properties file.	
	C:\android\android-ndk-r10e	

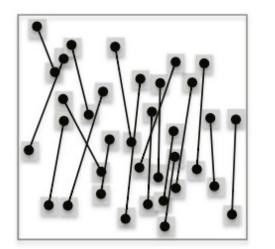


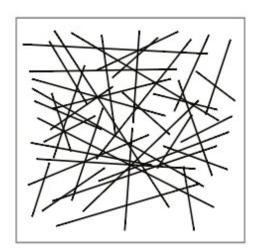


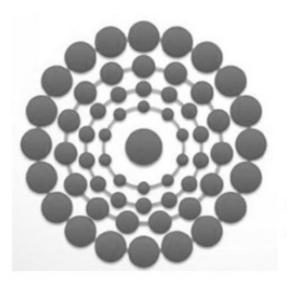


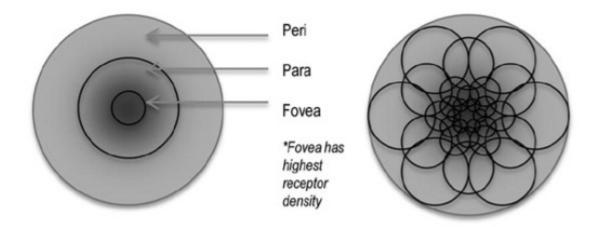


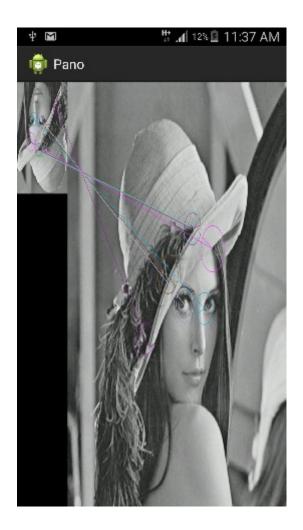


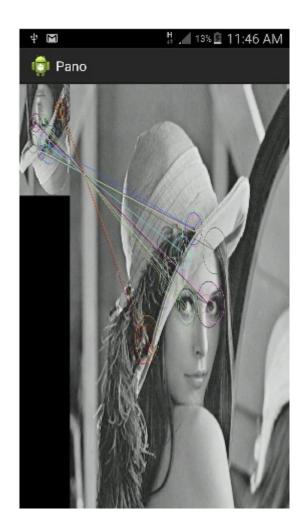




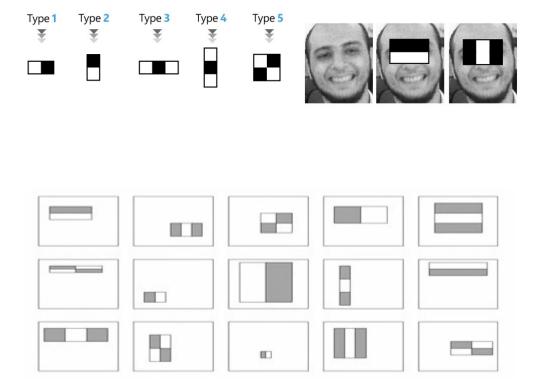


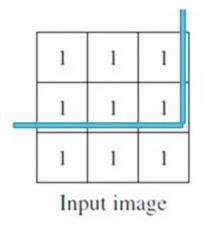


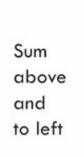




Chapter 6: App 4 - Automatic Selfie

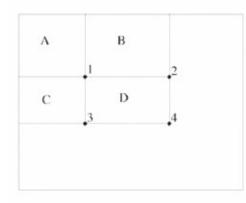




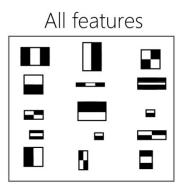


2	3
4	6
6	9
	2 4 6

Integral image



Sum of all pixels in D = 1+4-(2+3) = A+(A+B+C+D)-(A+C+A+B) = D







Irrelevant feature

