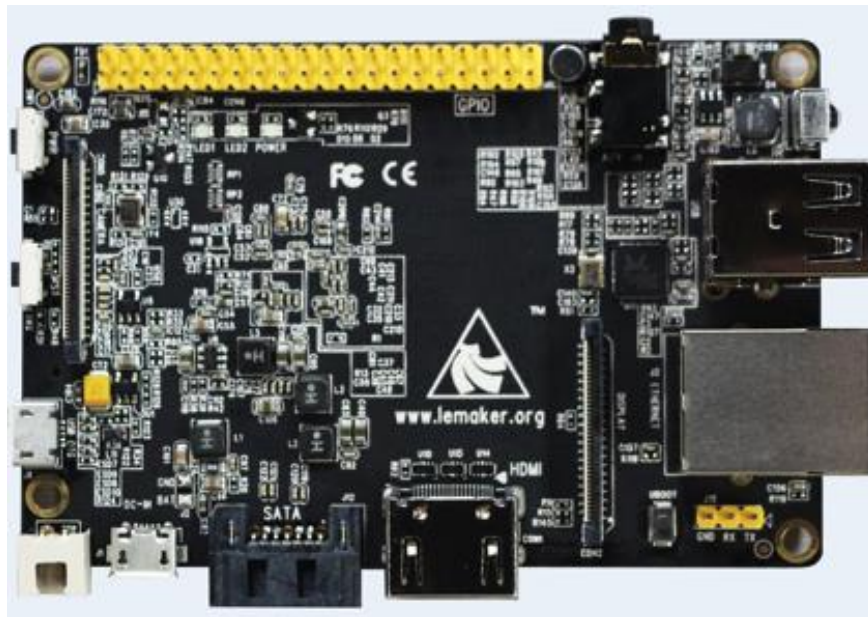


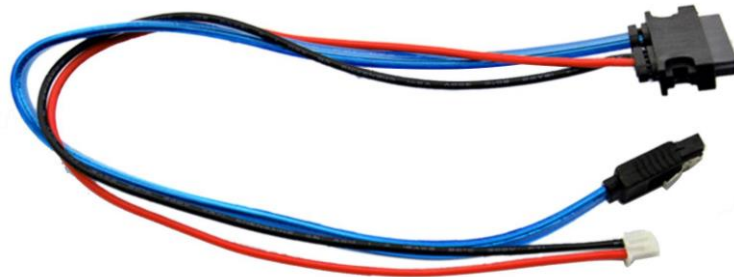
1

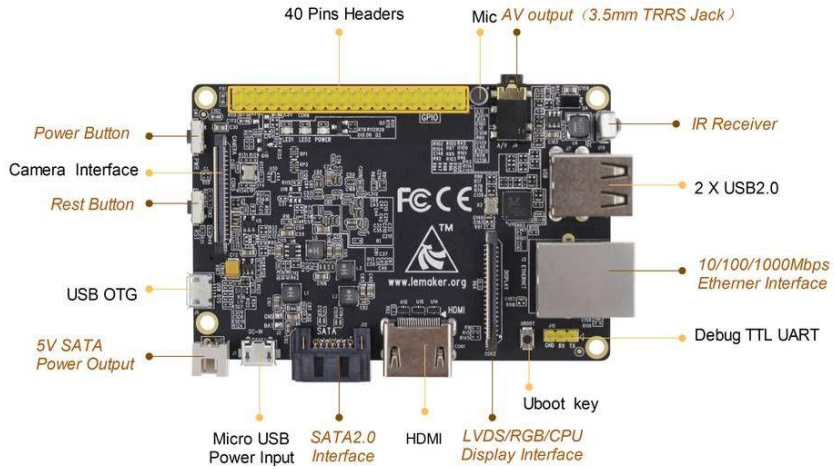
Introduction to Banana Pro

Banana Pro

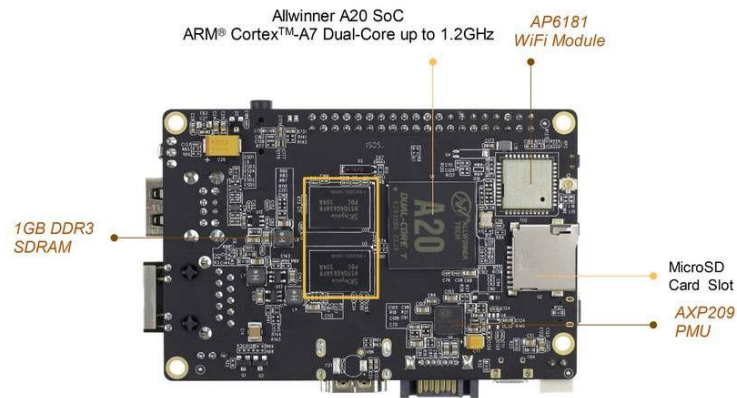


Specifications of Banana Pro



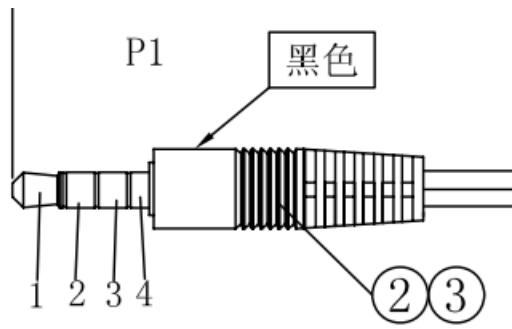


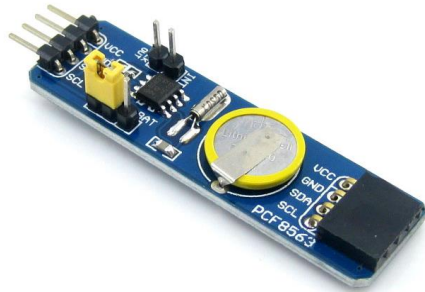
Front side



Back side

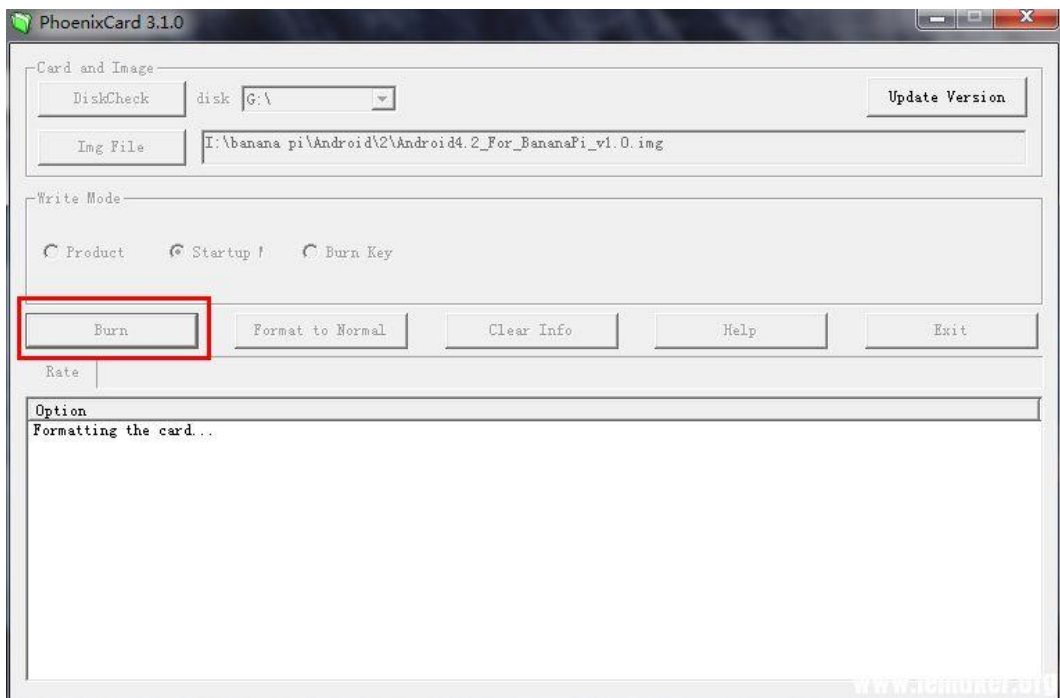
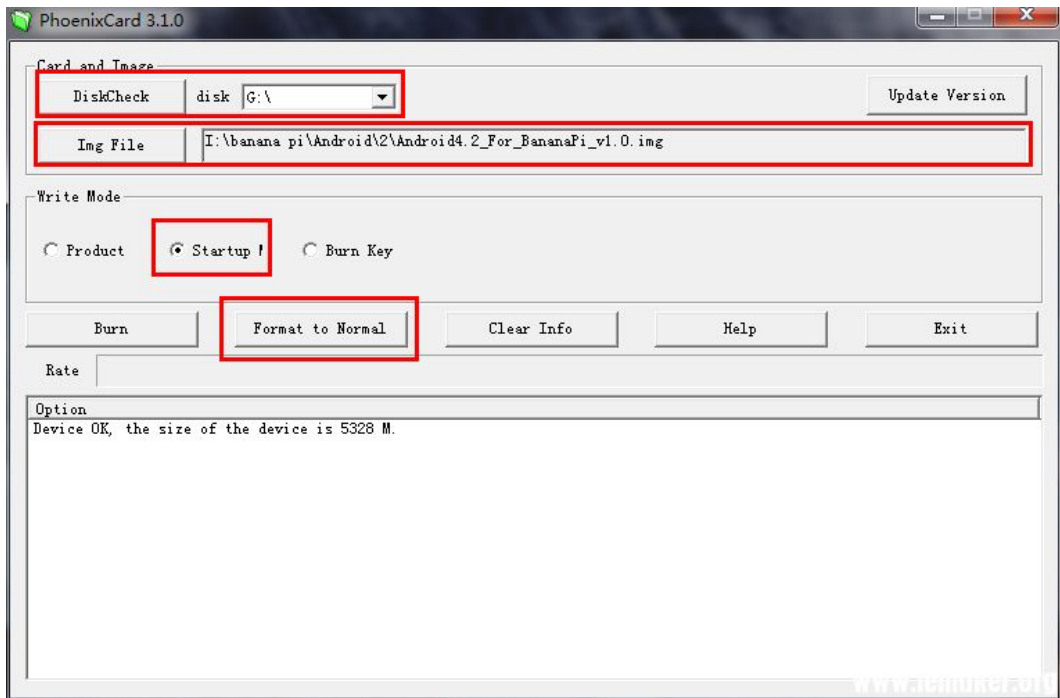




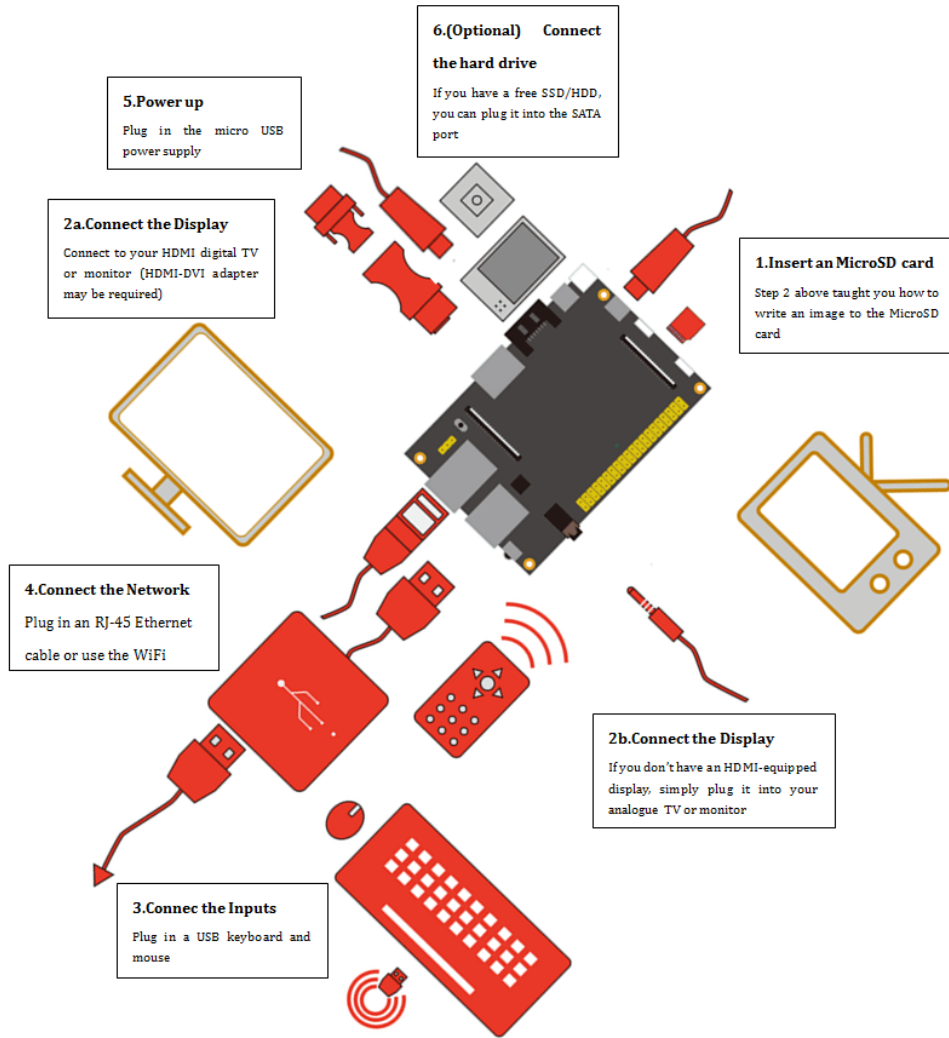


Getting started


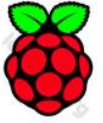
























The first boot



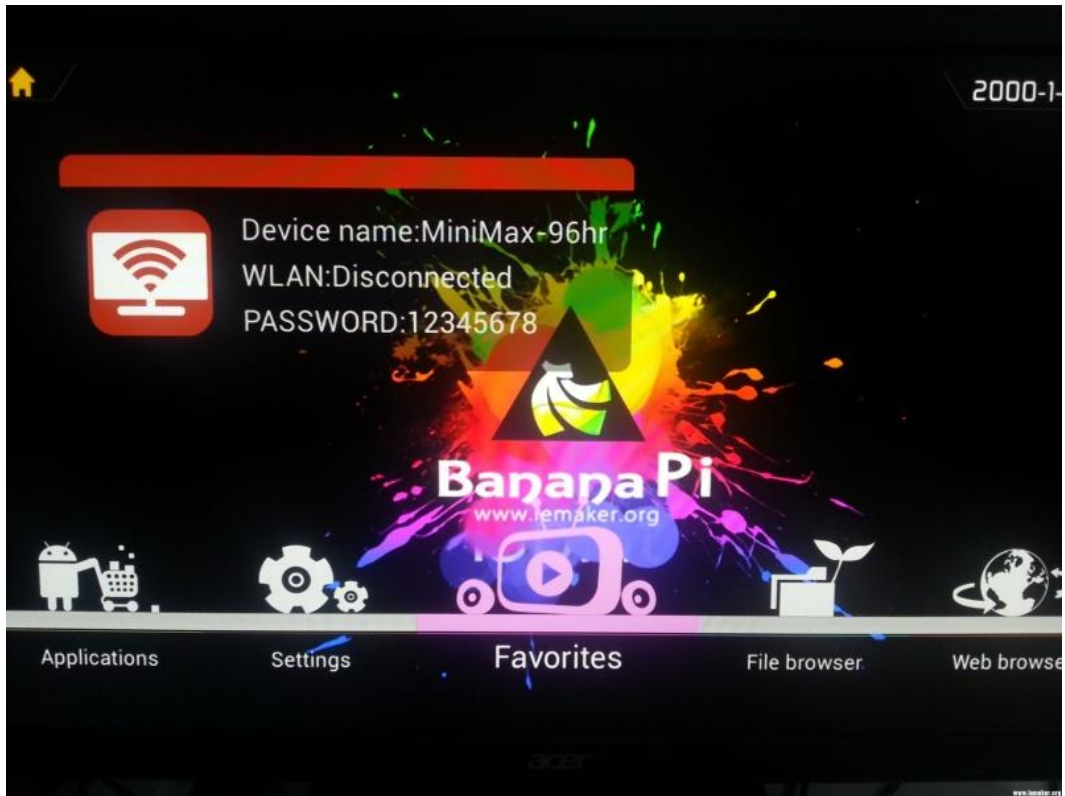
Available operating systems for Banana Pro

 <p>Lubuntu Updated : 2014-12-26 Download Now</p>	 <p>Raspbian Updated : 2014-12-26 Download Now</p>	 <p>Android Updated : 2014-12-25 Download Now</p>
 <p>Bananian Updated : 2015-01-11 Download Now</p>	 <p>Berryboot Updated : 2014-09-10 Download Now</p>	 <p>LeMedia Updated : 2014-11-17 Download Now</p>
 <p>OpenSuse Updated : 2014-12-26 Download Now</p>	 <p>Fedora Updated : 2014-12-26 Download Now</p>	 <p>Gentoo Updated : 2014-12-26 Download Now</p>
 <p>Scratch Updated : 2014-05-20 Download Now</p>	 <p>ArchLinux Updated : 2014-12-26 Download Now</p>	 <p>Open MediaVault Updated : 2014-09-12 Download Now</p>
 <p>OpenWrt Updated : 2014-09-29 Download Now</p>		

Banana Pro Images

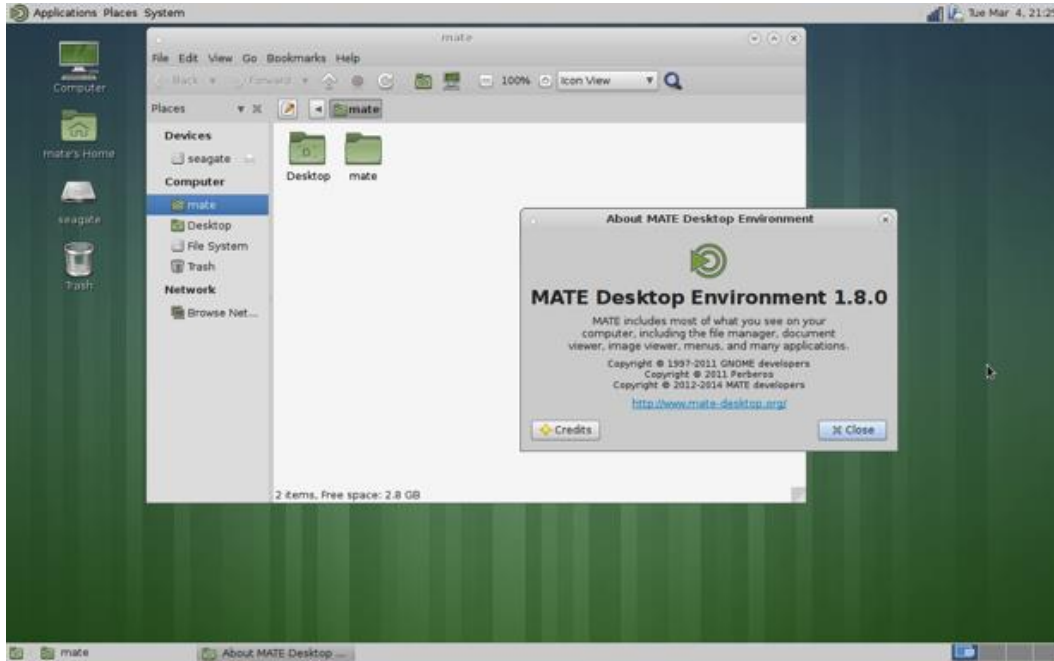
 <p>Open Media Vault For BananaPro Download</p>	 <p>ArchLinux For BananaPro Download</p>	 <p>Gentoo For BananaPro Download</p>
 <p>Fedora For BananaPro Download</p>	 <p>OpenSuse For BananaPro Download</p>	 <p>Android For BananaPro Download</p>
 <p>Raspbian For BananaPro Download</p>	 <p>Lubuntu For BananaPro Download</p>	 <p>Bananian For BananaPro Download</p>

Android

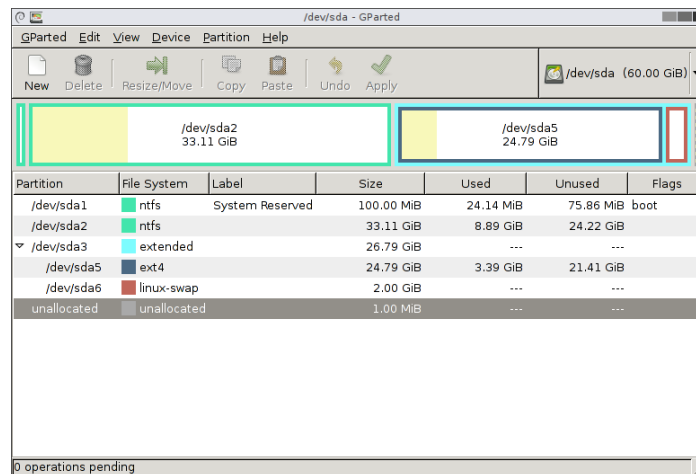




Linux



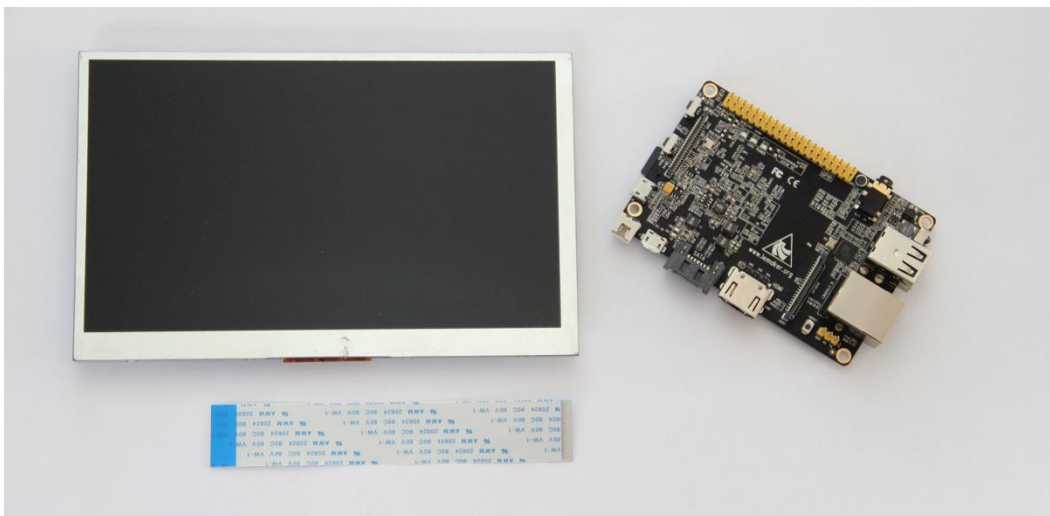
Transferring an OS to a hard disk

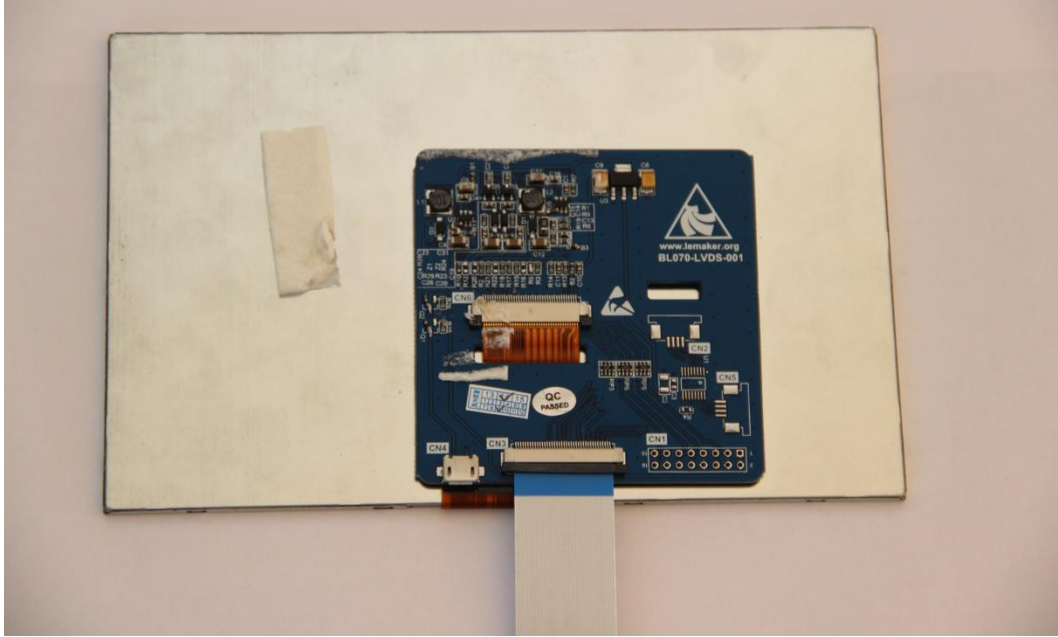


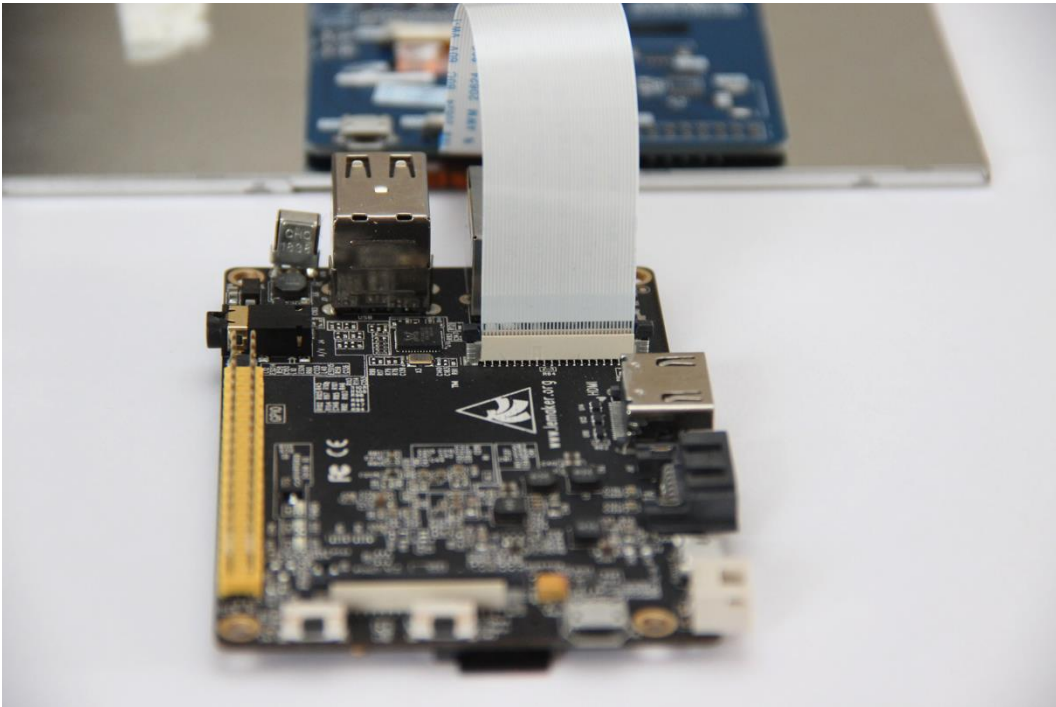
The 7-inch LCD step-by-step guide

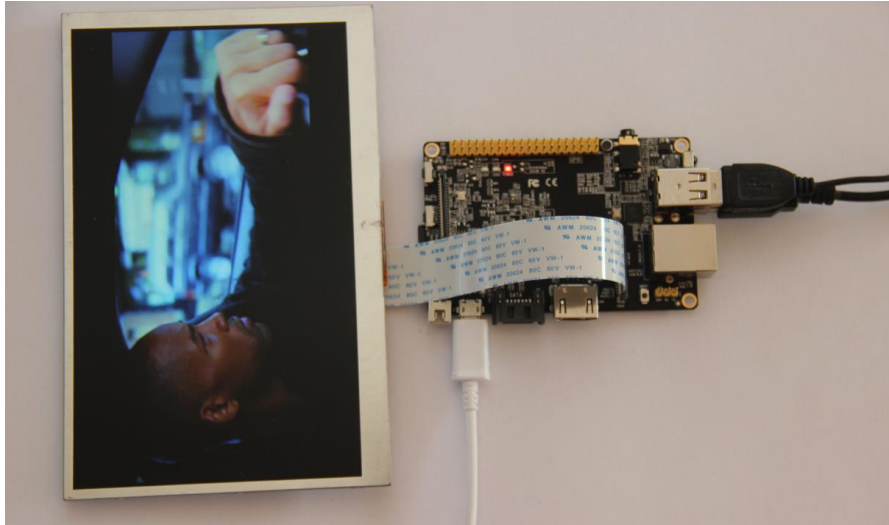
```
pi@bananapi: ~
GNU nano 2.2.6 File: /etc/modules Modified
ump
mali
mali_drm
hci_uart
gpio_sunxi
rfcomm
hidp
#sunxi-ir
sunxi-lirc
bonding
spi_sun7i
sunxi_cedar_mod
#ap6210
ap6210 op_mode=2
lcd
#ov5640
#sun4i_csi0

^G Get Help ^O WriteOut ^R Read File ^Y Prev Page ^K Cut Text ^C Cur Pos
^X Exit ^J Justify ^W Where Is ^V Next Page ^U UnCut Text ^T To Spell
```





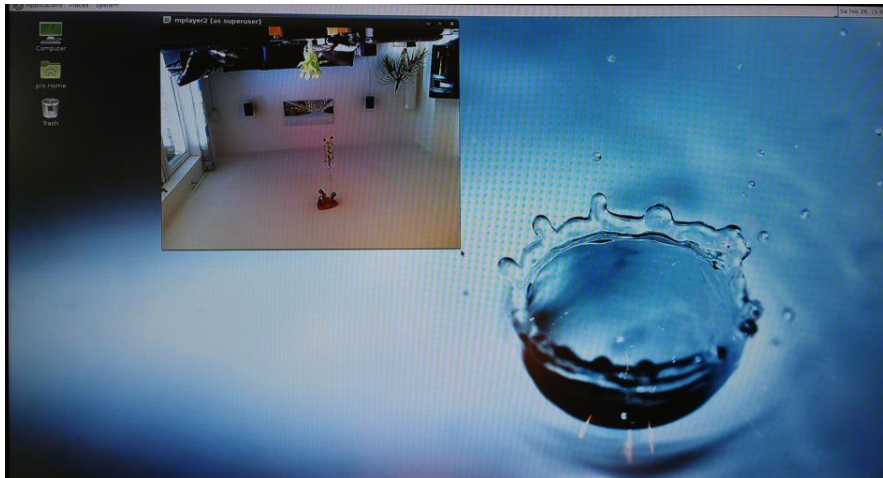




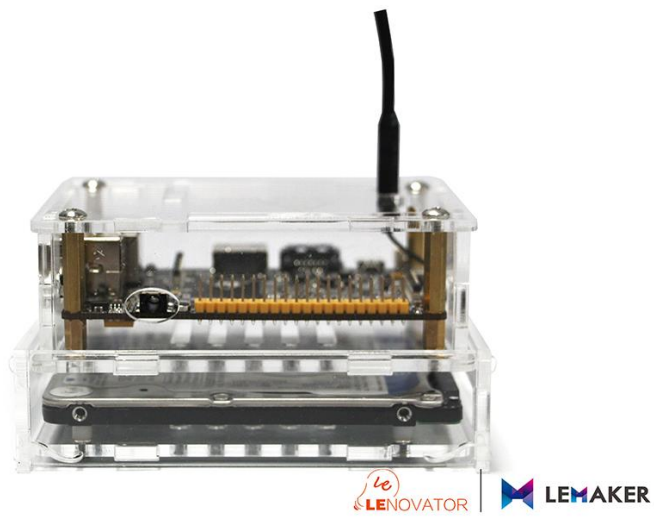
The camera module

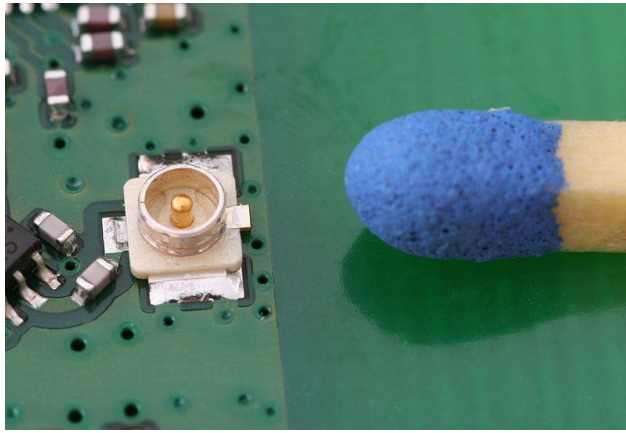


The camera module step-by-step guide

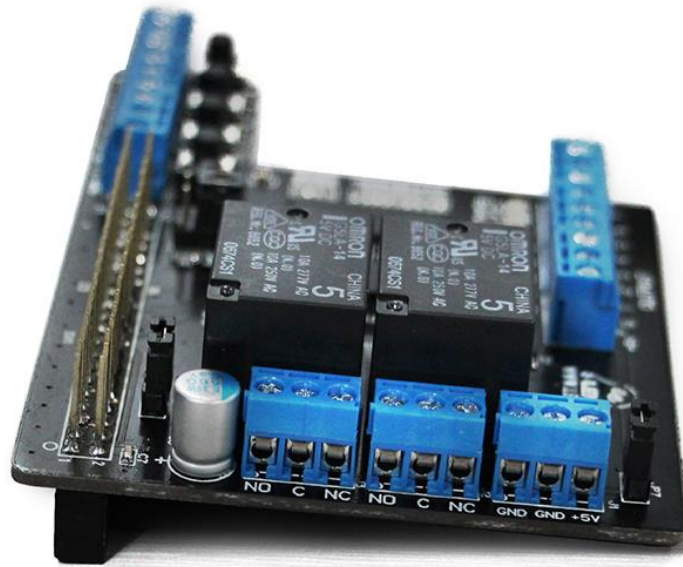


Cases

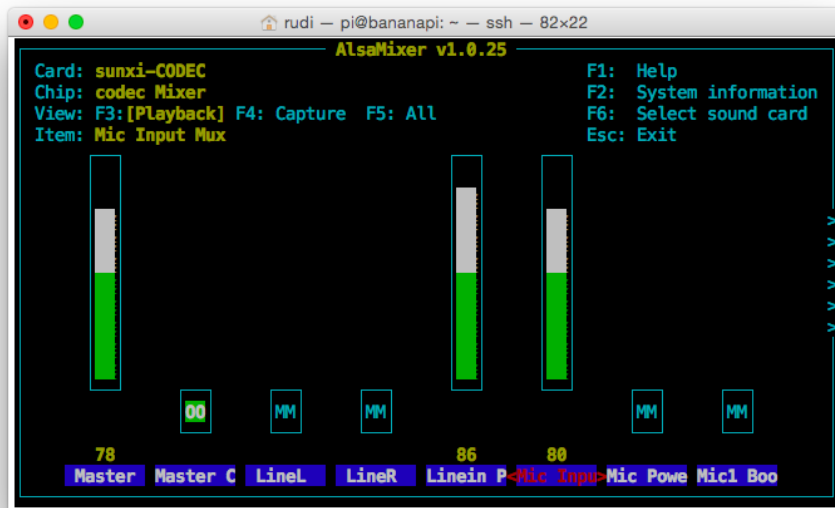




GPIO add-ons



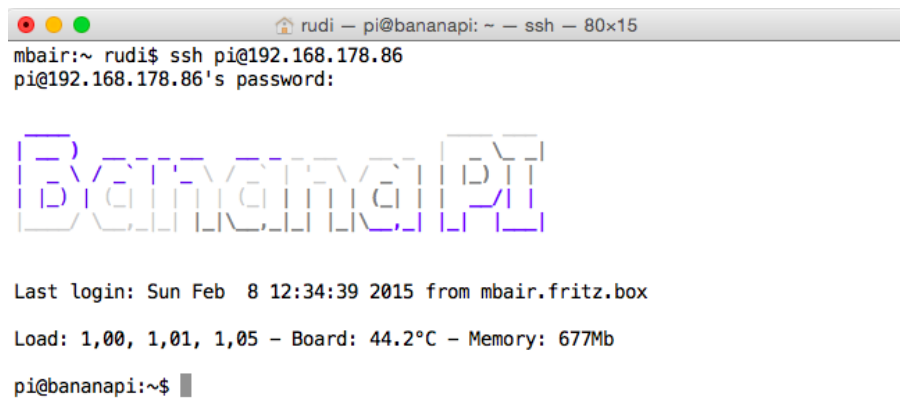
An onboard microphone



2

Programming Languages

Secure Shell

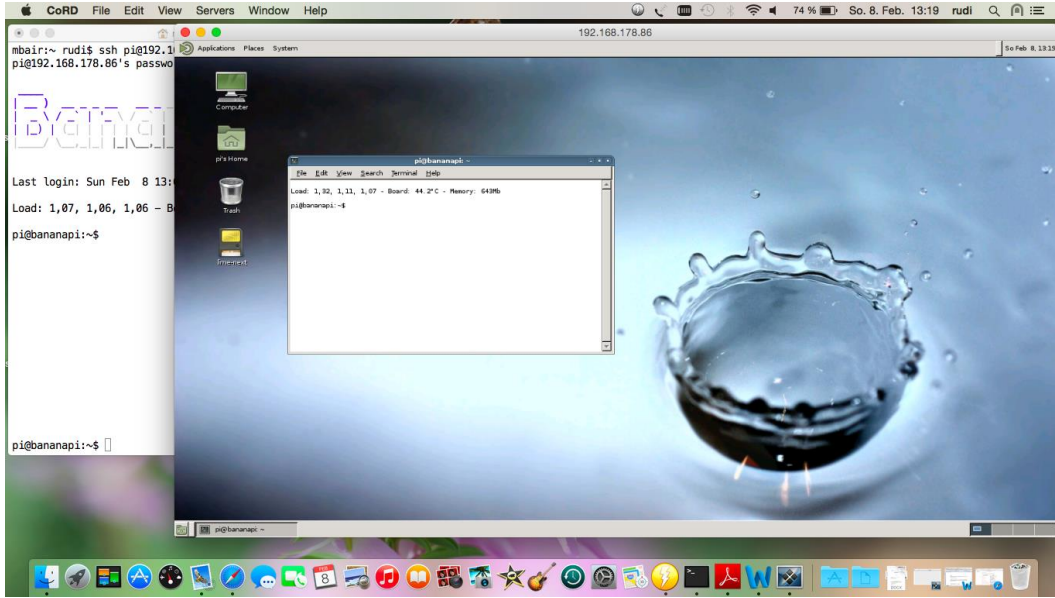


```
rudi - pi@bananapi: ~ - ssh - 80x15
mbair:~ rudi$ ssh pi@192.168.178.86
pi@192.168.178.86's password:

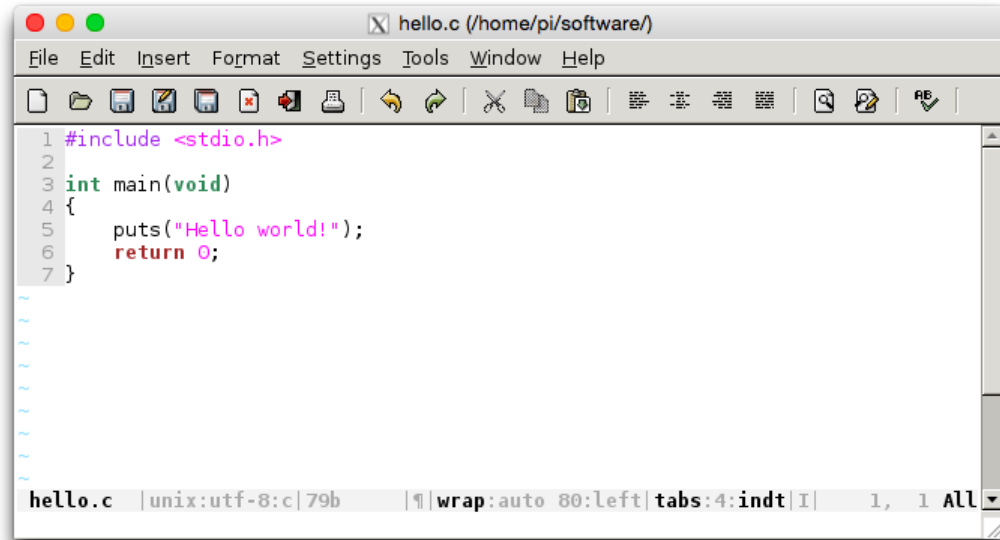
BananaPi

Last login: Sun Feb 8 12:34:39 2015 from mbair.fritz.box
Load: 1,00, 1,01, 1,05 - Board: 44.2°C - Memory: 677Mb
pi@bananapi:~$
```

xrdp



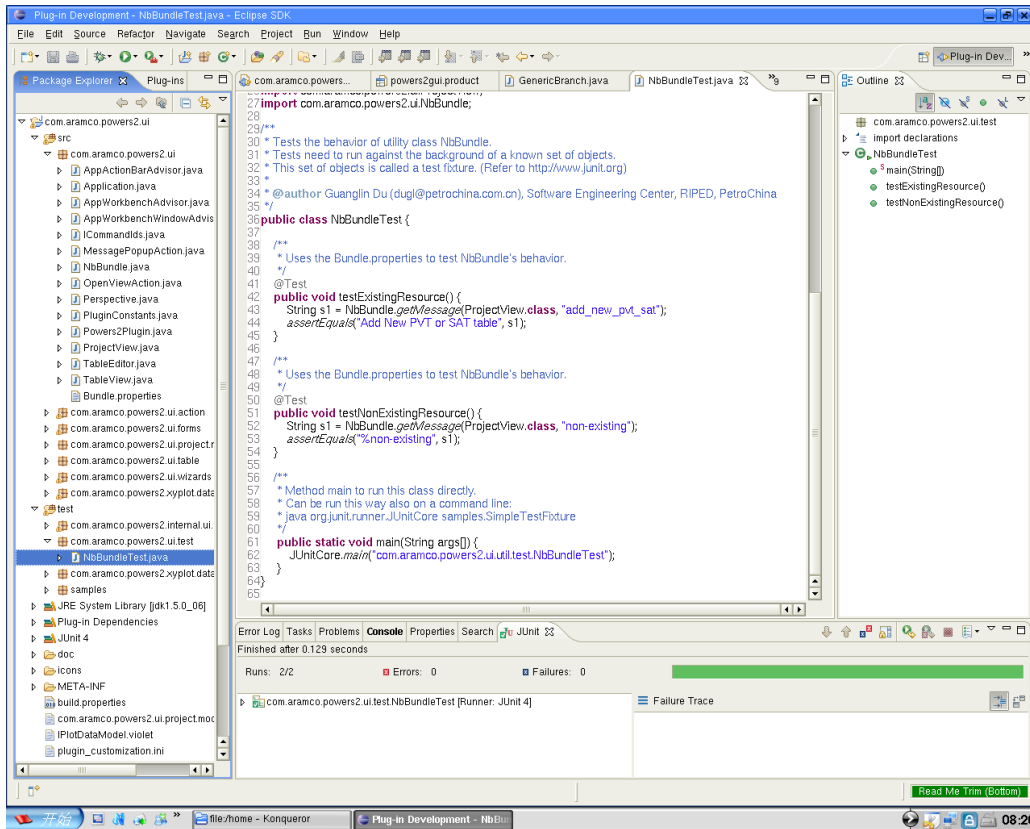
Editors



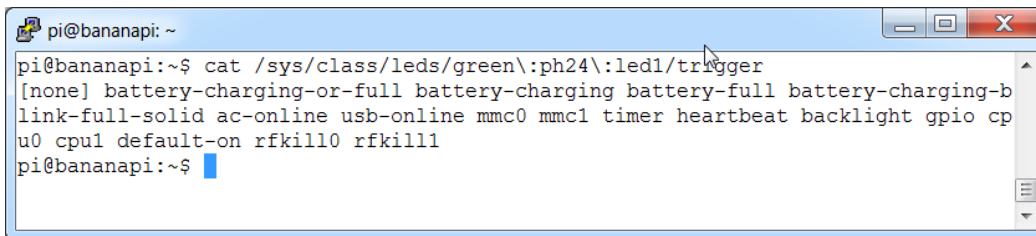
The image shows a screenshot of a code editor window titled "hello.c (/home/pi/software/)". The window has a menu bar with "File", "Edit", "Insert", "Format", "Settings", "Tools", "Window", and "Help". Below the menu bar is a toolbar with various icons for file operations and editing. The main text area contains the following C code:

```
1 #include <stdio.h>
2
3 int main(void)
4 {
5     puts("Hello world!");
6     return 0;
7 }
```

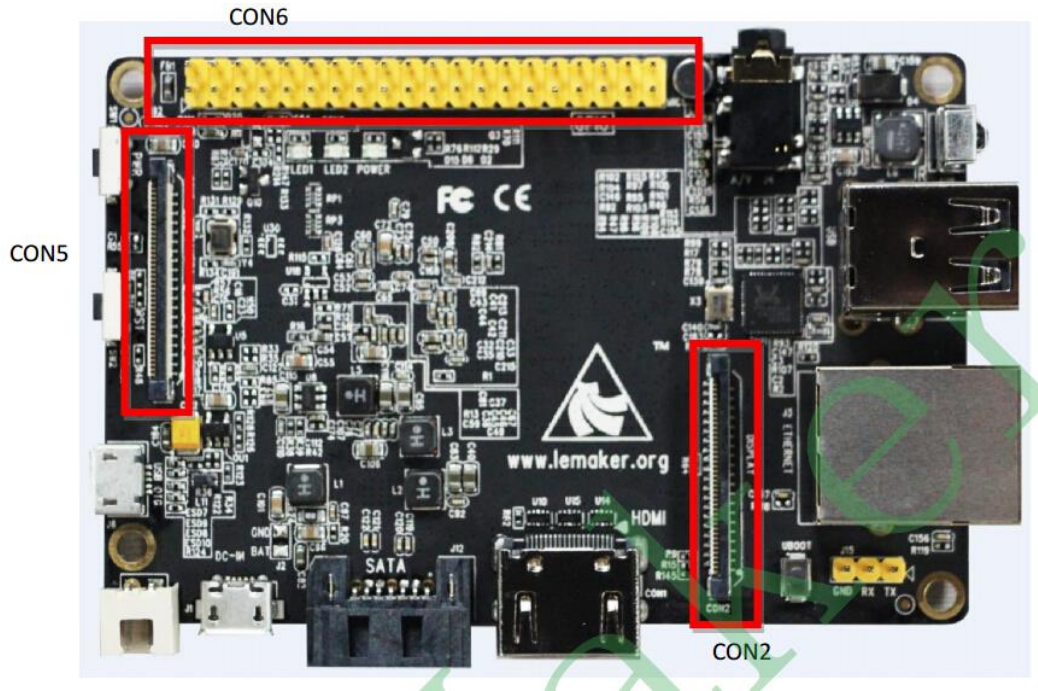
At the bottom of the window, there is a status bar showing "hello.c | unix:utf-8:c|79b | | wrap:auto 80:left| tabs:4:indt|I| 1, 1 ALL".



Controlling Banana Pro's LEDs from SSH



Programming GPIOs from shell



Banana Pro CON6

Pin#	NAME		NAME	Pin#
1	VCC-3.3V	■ ○	VCC-5V	2
3	TWI2-SDA	○ ○	VCC-5V	4
5	TWI2-SCK	○ ●	GND	6
7	IO-1	○ ●	UART4_TX	8
9	GND	○ ●	UART4_RX	10
11	IO-0 (UART2_RX)	● ●	PWM1	12
13	IO-2 (UART2_TX)	● ●	GND	14
15	IO-3 (UART2_CTS)	● ●	IO-4(CAN_TX)	16
17	VCC-3.3V	● ●	IO-5(CAN_RX)	18
19	SPI0_MOSI	○ ●	GND	20
21	SPI0_MISO	○ ●	IO-6(UART2_RTS)	22
23	SPI0_CLK	○ ○	SPI0_CS0	24
25	GND	○ ○	SPI0_CS1	26
27	TWI3-SDA	○ ○	TWI3-SCK	28
29	IO-7(IRO_TX/SPDIF_MCLK)	○ ●	GND	30
31	UART7_RX	○ ●	UART7_TX	32
33	IO-8(SPDIF_DO)	○ ●	GND	34
35	I2S0_LRCK	● ●	I2S0_BCLK	36
37	I2S0_MCLK	● ●	I2S0_DI	38
39	GND	○ ●	I2S0_DO0	40

WiringBP

```

rudi — pi@bananapro: ~/WiringBP/gpio — ssh — 85x28
pi@bananapro:~/WiringBP/gpio$ sudo ./gpio readall
-----Banana Pro-----
| BCM | wPi | Name | Mode | V | Physical | V | Mode | Name | wPi | BCM | |
|---|---|---|---|---|---|---|---|---|---|---|---|
| 2 | 8 | 3.3v | | | 1 | 2 | | | 5v | | |
| 2 | 8 | SDA.1 | ALT5 | 1 | 3 | 4 | | | 5V | | |
| 3 | 9 | SCL.1 | ALT5 | 1 | 5 | 6 | | | 0v | | |
| 4 | 7 | GPIO. 7 | IN | 0 | 7 | 8 | 0 | ALT0 | TxD | 15 | 14 |
| | | 0v | | | 9 | 10 | 0 | ALT0 | RxD | 16 | 15 |
| 17 | 0 | GPIO. 0 | ALT4 | 0 | 11 | 12 | 0 | IN | GPIO. 1 | 1 | 18 |
| 27 | 2 | GPIO. 2 | ALT4 | 0 | 13 | 14 | | | 0v | | |
| 22 | 3 | GPIO. 3 | ALT4 | 0 | 15 | 16 | 0 | IN | GPIO. 4 | 4 | 23 |
| | | 3.3v | | | 17 | 18 | 0 | IN | GPIO. 5 | 5 | 24 |
| 10 | 12 | MOSI | ALT5 | 0 | 19 | 20 | | | 0v | | |
| 9 | 13 | MISO | ALT5 | 0 | 21 | 22 | 0 | ALT4 | GPIO. 6 | 6 | 25 |
| 11 | 14 | SCLK | ALT5 | 0 | 23 | 24 | 0 | ALT5 | CE0 | 10 | 8 |
| | | 0v | | | 25 | 26 | 0 | ALT5 | CE1 | 11 | 7 |
| 0 | 30 | SDA.0 | ALT4 | 0 | 27 | 28 | 0 | ALT4 | SCL.0 | 31 | 1 |
| 5 | 21 | GPIO.21 | IN | 0 | 29 | 30 | | | 0v | | |
| 6 | 22 | GPIO.22 | ALT4 | 0 | 31 | 32 | 0 | ALT4 | GPIO.26 | 26 | 12 |
| 13 | 23 | GPIO.23 | ALT0 | 0 | 33 | 34 | | | 0v | | |
| 19 | 24 | GPIO.24 | ALT5 | 0 | 35 | 36 | 0 | ALT5 | GPIO.27 | 27 | 16 |
| 26 | 25 | GPIO.25 | ALT5 | 0 | 37 | 38 | 0 | ALT5 | GPIO.28 | 28 | 20 |
| | | 0v | | | 39 | 40 | 0 | ALT5 | GPIO.29 | 29 | 21 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| BCM | wPi | Name | Mode | V | Physical | V | Mode | Name | wPi | BCM |
-----Banana Pro-----
pi@bananapro:~/WiringBP/gpio$

```

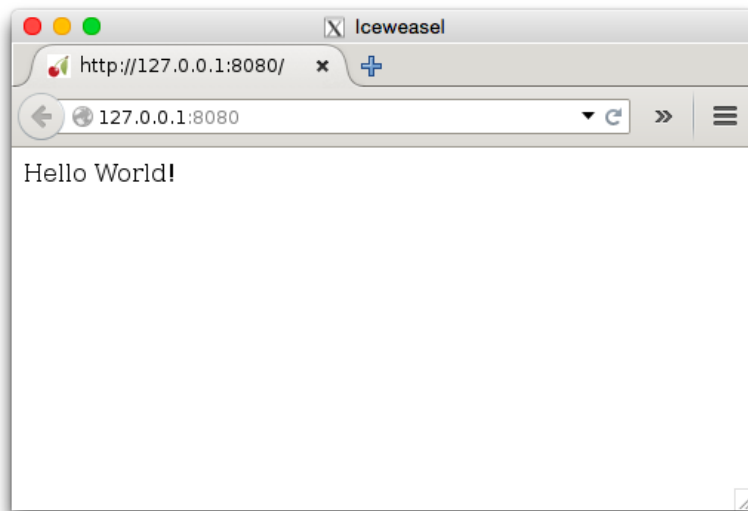
```

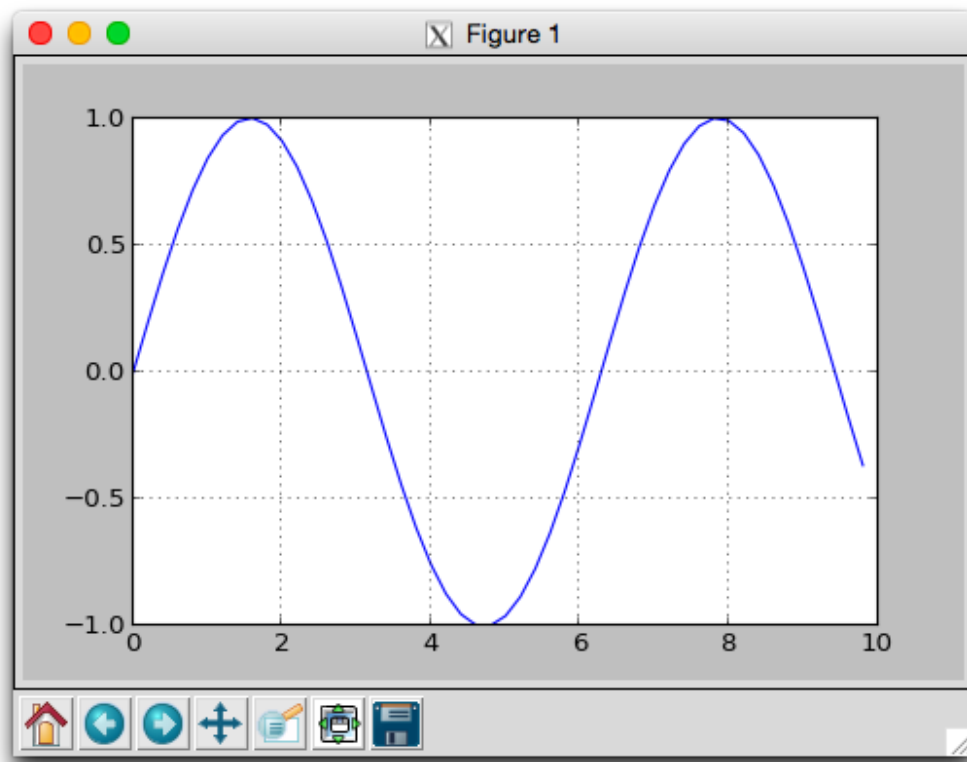
rudi — pi@bananapro: ~/WiringBP/gpio — ssh — 85x6
| 26 | 25 | GPIO.25 | OUT | 0 | 37 | 38 | 0 | ALT5 | GPIO.28 | 28 | 20 |
| | | 0v | | | 39 | 40 | 0 | ALT5 | GPIO.29 | 29 | 21 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| BCM | wPi | Name | Mode | V | Physical | V | Mode | Name | wPi | BCM |
-----Banana Pro-----
pi@bananapro:~/WiringBP/gpio$

```

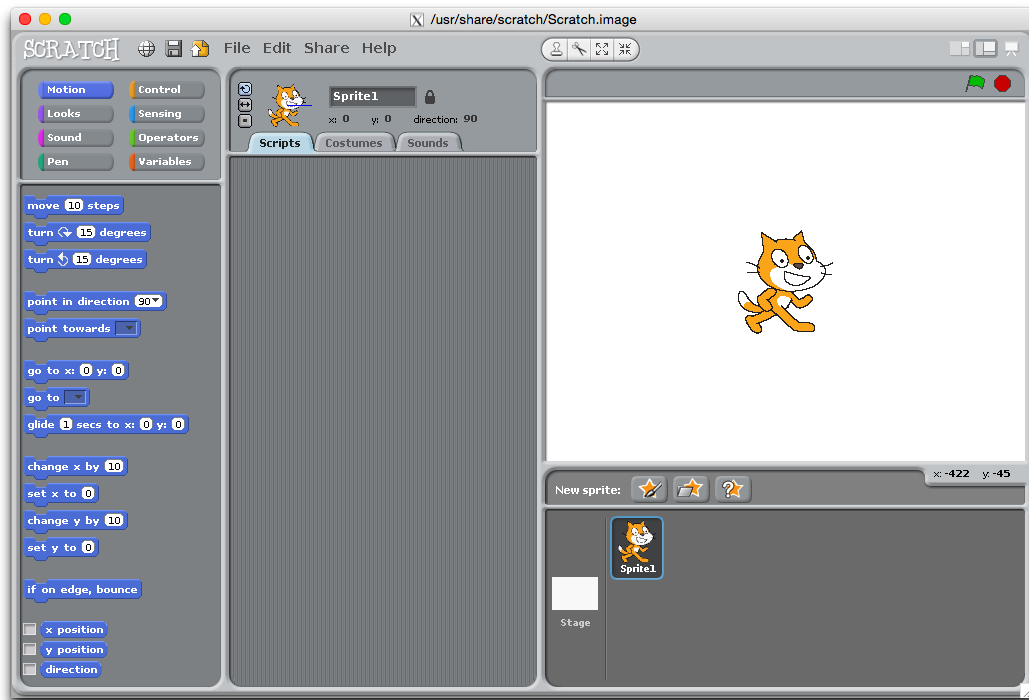
```
rudi — pi@bananapro: ~/WiringBP/gpio — ssh — 85x7
| 19 | 24 | GPIO.24 | ALT5 | 0 | 35 | 36 | 0 | ALT5 | GPIO.27 | 27 | 16 |
| 26 | 25 | GPIO.25 | OUT  | 1 | 37 | 38 | 0 | ALT5 | GPIO.28 | 28 | 20 |
|   |   | 0v       |   |   | 39 | 40 | 0 | ALT5 | GPIO.29 | 29 | 21 |
+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+
| BCM | wPi | Name  | Mode | V | Physical | V | Mode | Name  | wPi | BCM |
+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+
|                                           | Banana Pro |
pi@bananapro:~/WiringBP/gpio$
```

A simple web server





Scratch



Hello Scratch

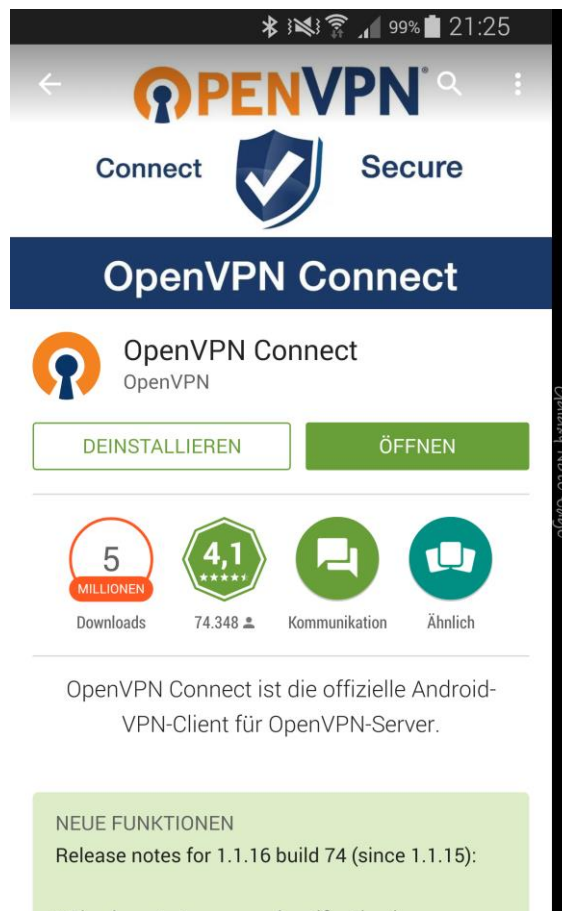


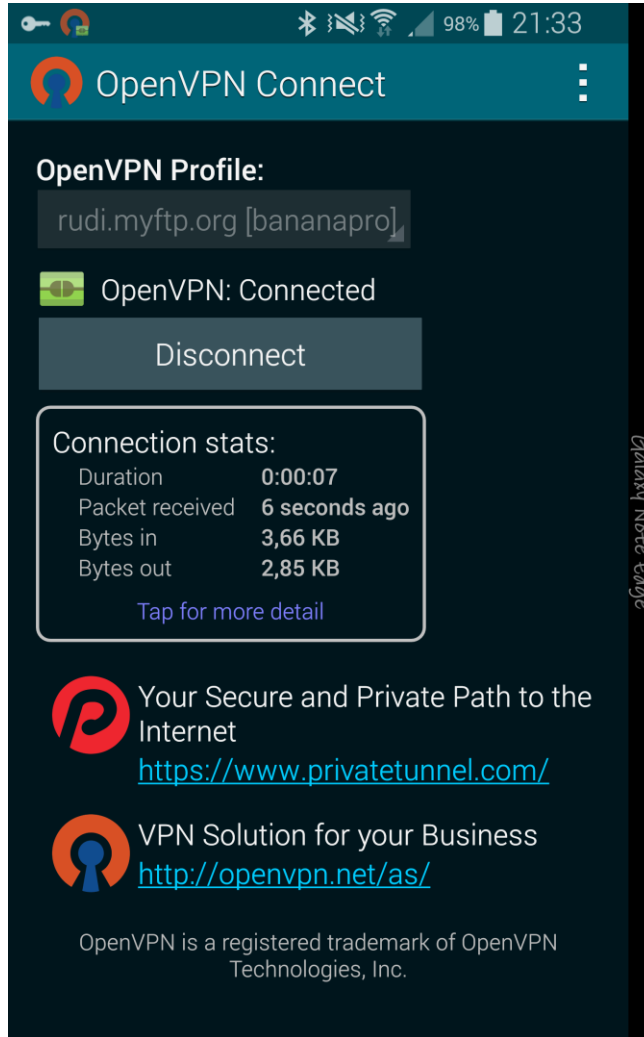


3

Wireless Projects

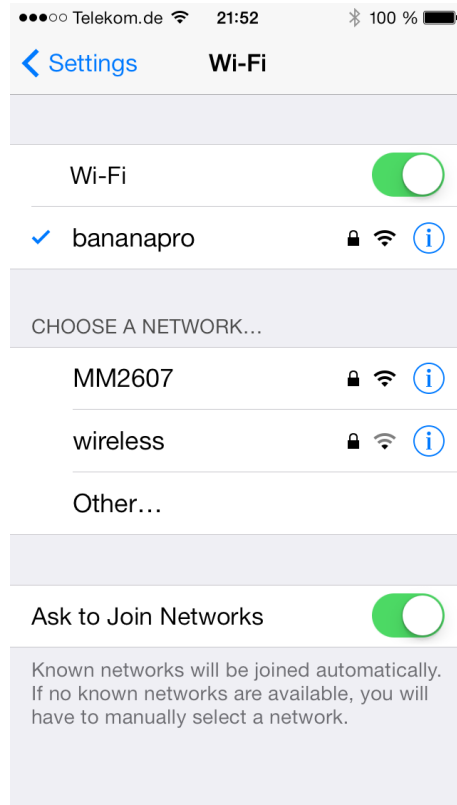
Connecting from Android



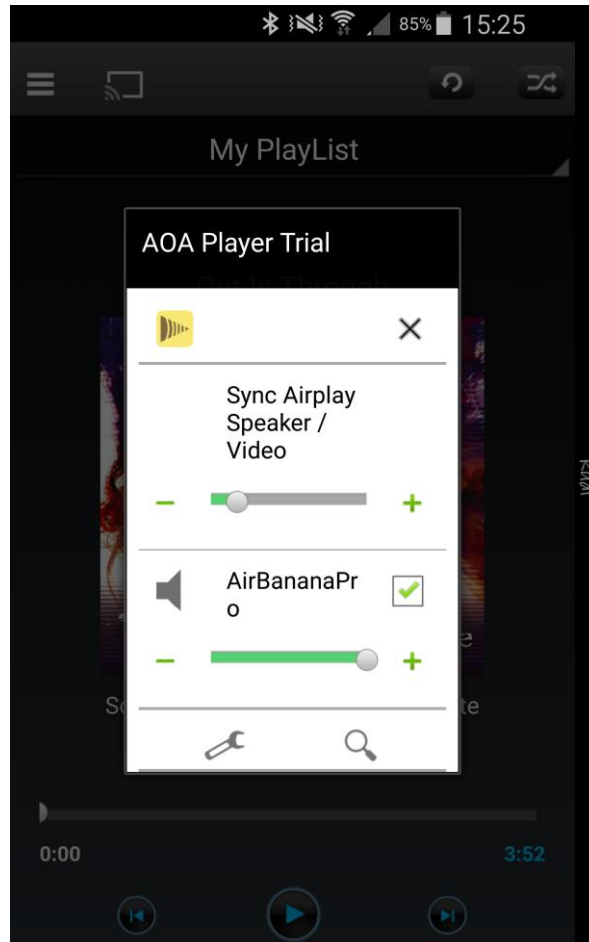


Galaxy Note Edge

Setting up an access point mode



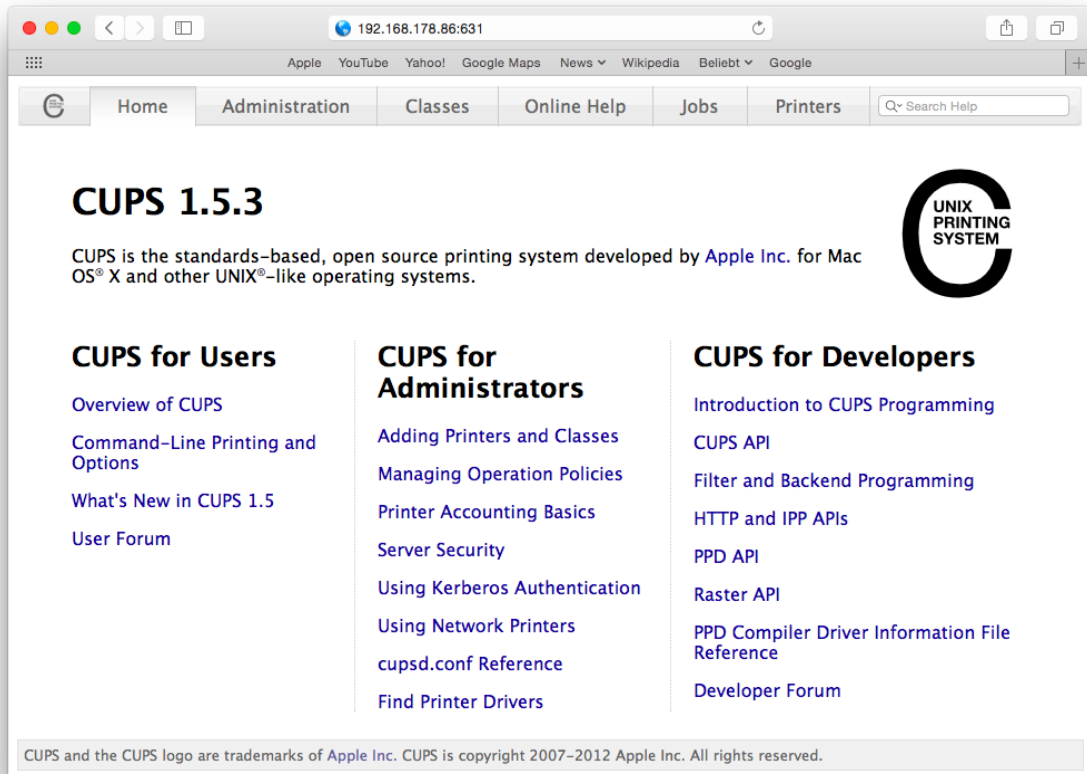
The AirPlay protocol



Using an external USB SPDIF soundcard



Configuring CUPS



192.168.178.66

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Home Administration **Classes** Online Help Jobs Printers Q Search Help

Printers

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Classes

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Jobs

[Manage Jobs](#)

RSS Subscriptions

[Add RSS Subscription](#)

Server

[Edit Configuration File](#) [View Access Log](#) [View Error Log](#) [View Page Log](#)

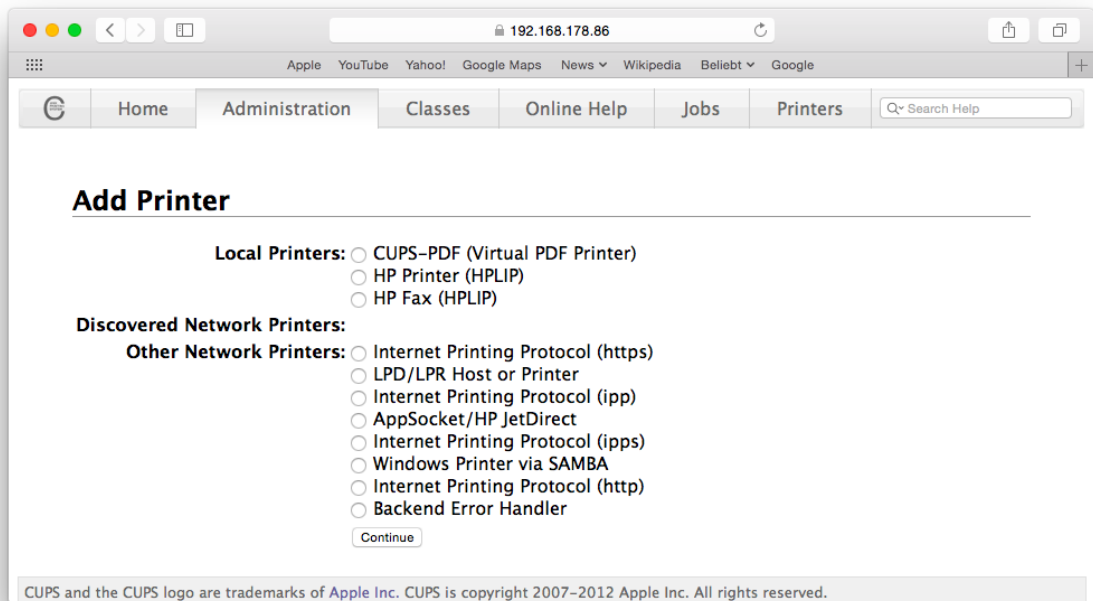
Server Settings:

Advanced ▶

- Show printers shared by other systems
- Share printers connected to this system
 - Allow printing from the Internet
- Allow remote administration
- Use Kerberos authentication ([FAQ](#))
- Allow users to cancel any job (not just their own)
- Save debugging information for troubleshooting

[Change Settings](#)

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Home Administration Classes Online Help Jobs Printers Search Help

Add Printer

Name:
(May contain any printable characters except "/", "#", and space)

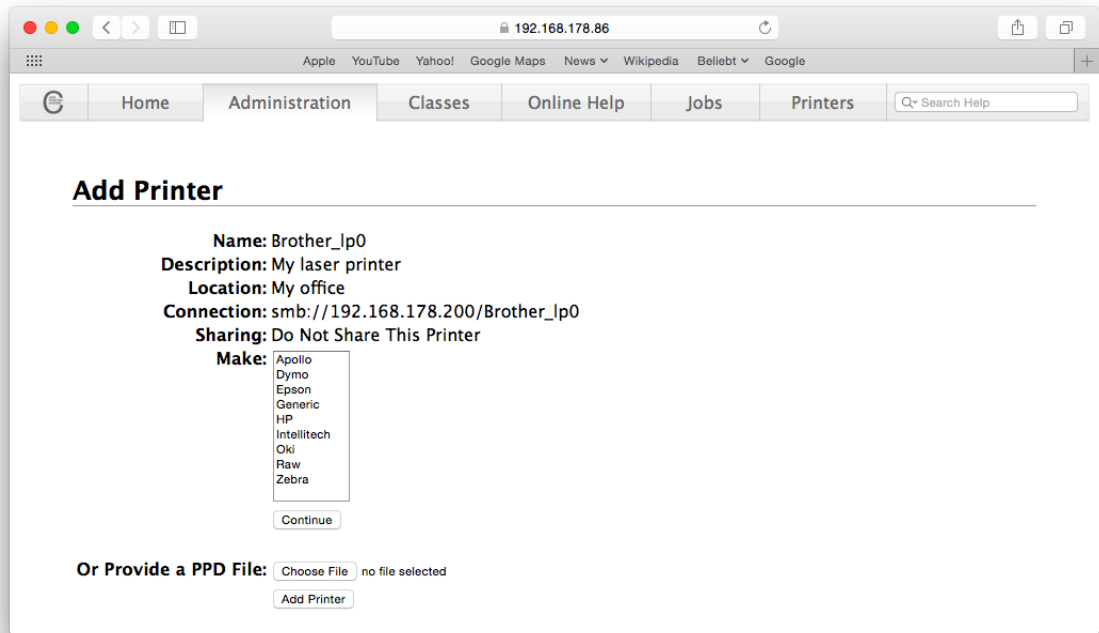
Description:
(Human-readable description such as "HP LaserJet with Duplexer")

Location:
(Human-readable location such as "Lab 1")

Connection:

Sharing: Share This Printer

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Printing from Android and iOS

Let's Print Droid Suite
Cloud Free Printing for Android

Featuring :

- CUPS, LPR/LPD, Samba connectivity
- generic PCL, Postscript, Airprint drivers
- Bonjour mDNS discovery
- on device PDF rendering
- Integration with Android Kitkat Print Framework

Let's Print Droid
BlackSpruce

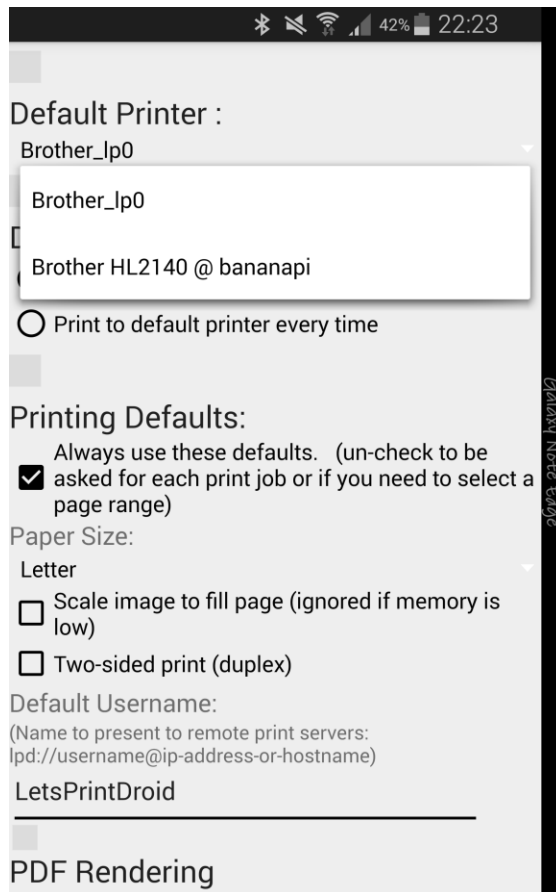
DEINSTALLIEREN ÖFFNEN

100 TAUSEND Downloads 3,8 781 Büro Ähnlich

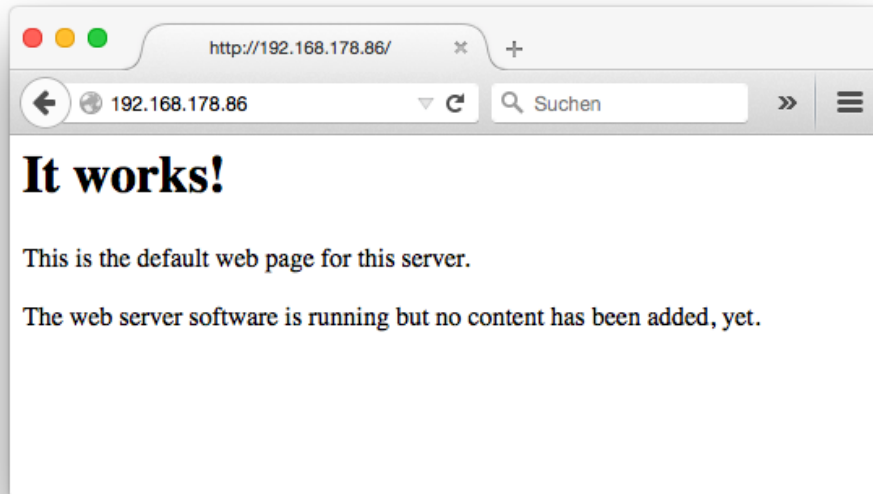
Lassen Sie drucken Droid Suite - Cloud-Druckdienst kostenlos für Android

NEUE FUNKTIONEN
ver 1.48 - Better KitKat Print Service integration.
You can now add printers and change settings

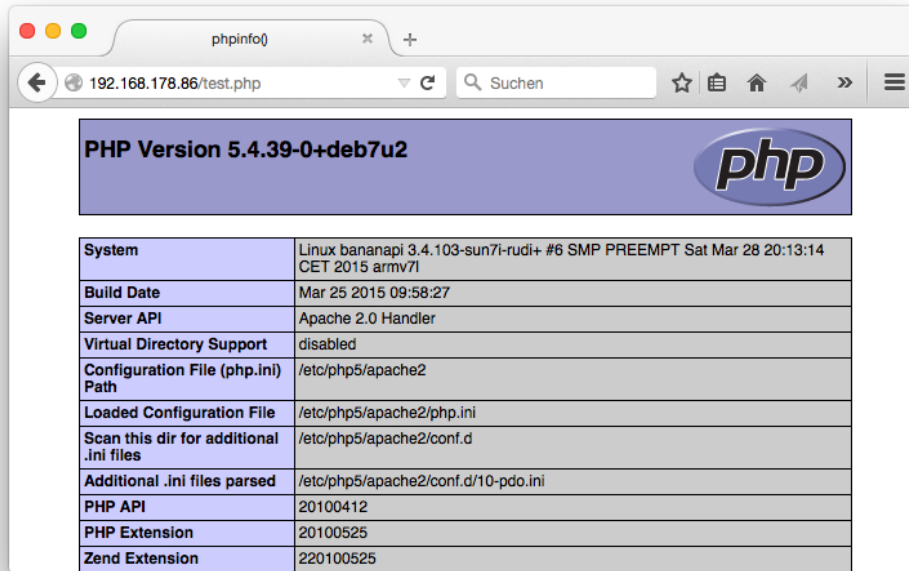
Galaxy Note Edge



Serving web pages

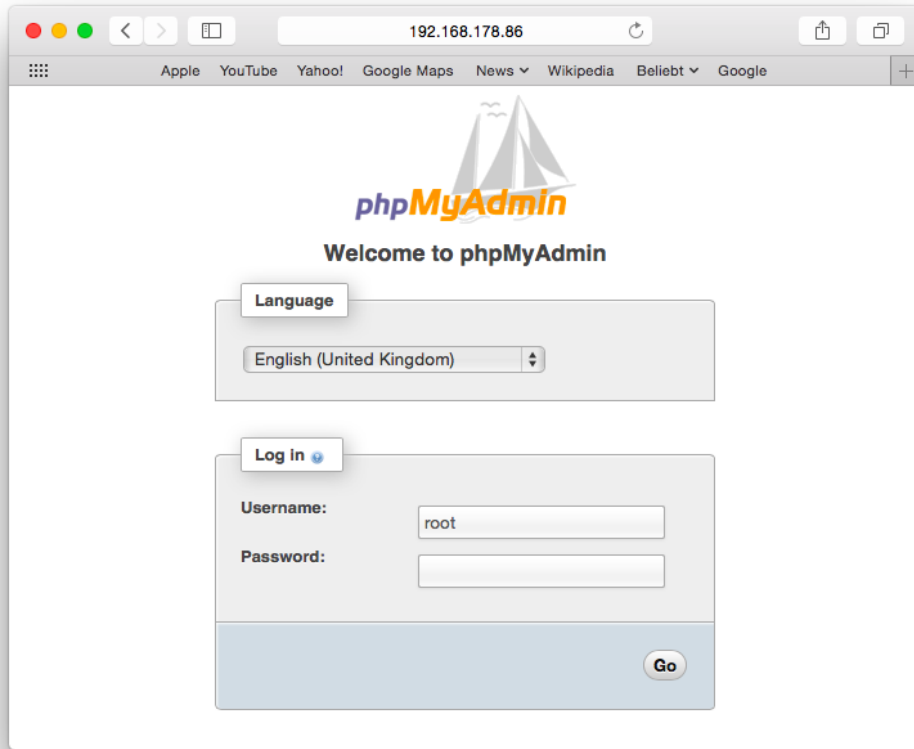


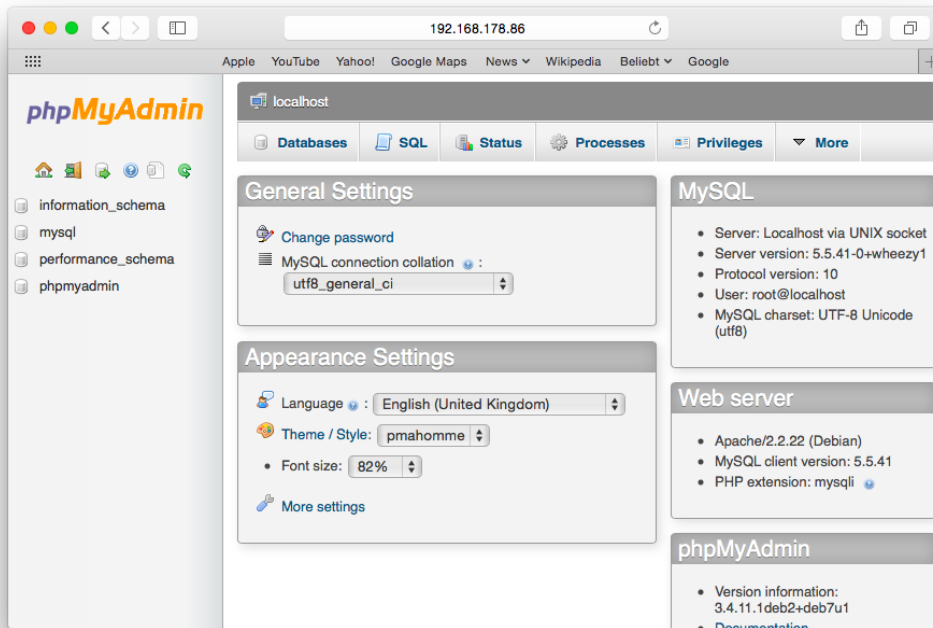
Installing php and mysql



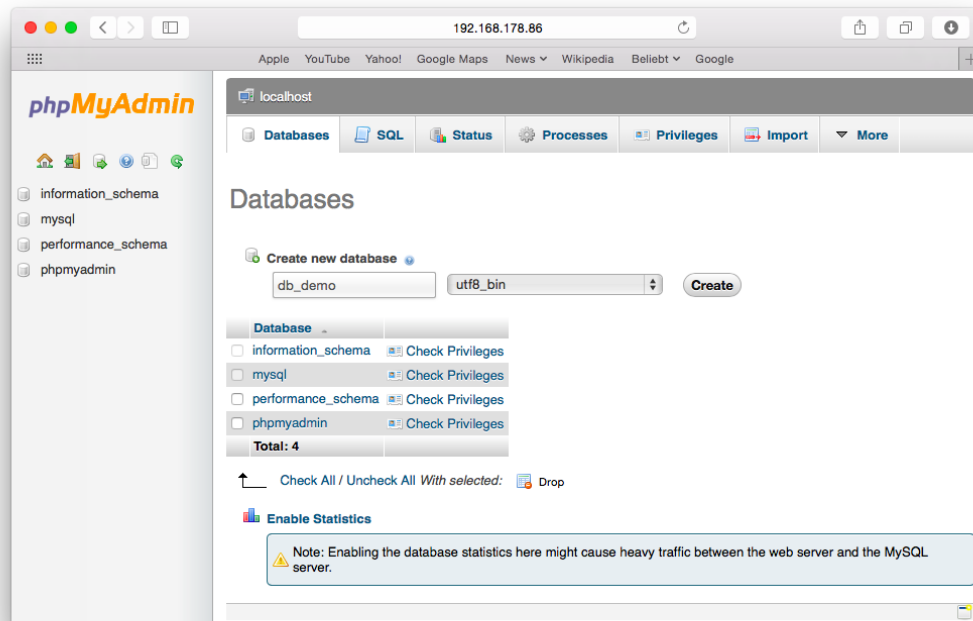
The screenshot shows a web browser window with the address bar displaying '192.168.178.86/test.php'. The page content includes the PHP logo and the text 'PHP Version 5.4.39-0+deb7u2'. Below this is a table with system and configuration details.

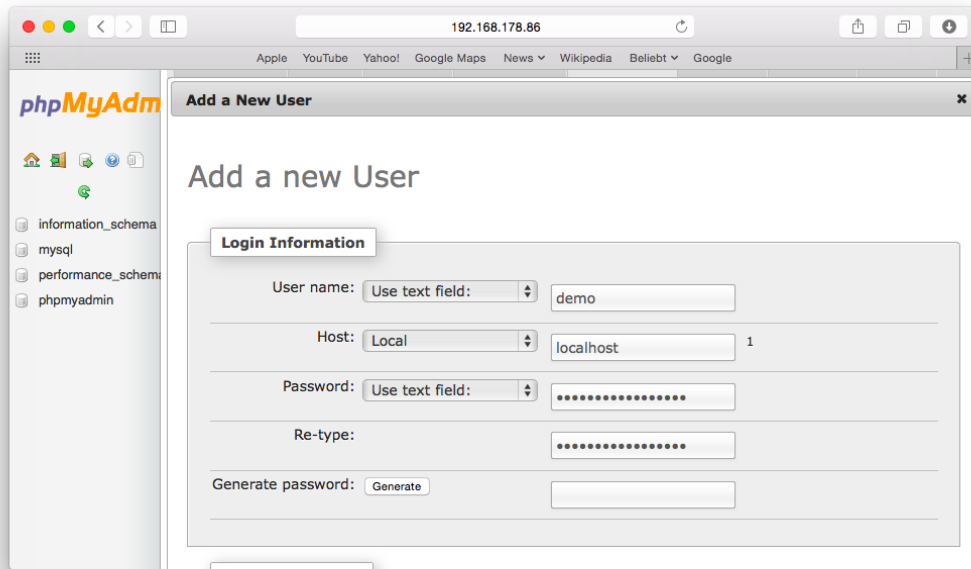
PHP Version 5.4.39-0+deb7u2	
System	Linux bananapi 3.4.103-sun7i-rudi+ #6 SMP PREEMPT Sat Mar 28 20:13:14 CET 2015 armv7l
Build Date	Mar 25 2015 09:58:27
Server API	Apache 2.0 Handler
Virtual Directory Support	disabled
Configuration File (php.ini) Path	/etc/php5/apache2
Loaded Configuration File	/etc/php5/apache2/php.ini
Scan this dir for additional .ini files	/etc/php5/apache2/conf.d
Additional .ini files parsed	/etc/php5/apache2/conf.d/10-pdo.ini
PHP API	20100412
PHP Extension	20100525
Zend Extension	220100525

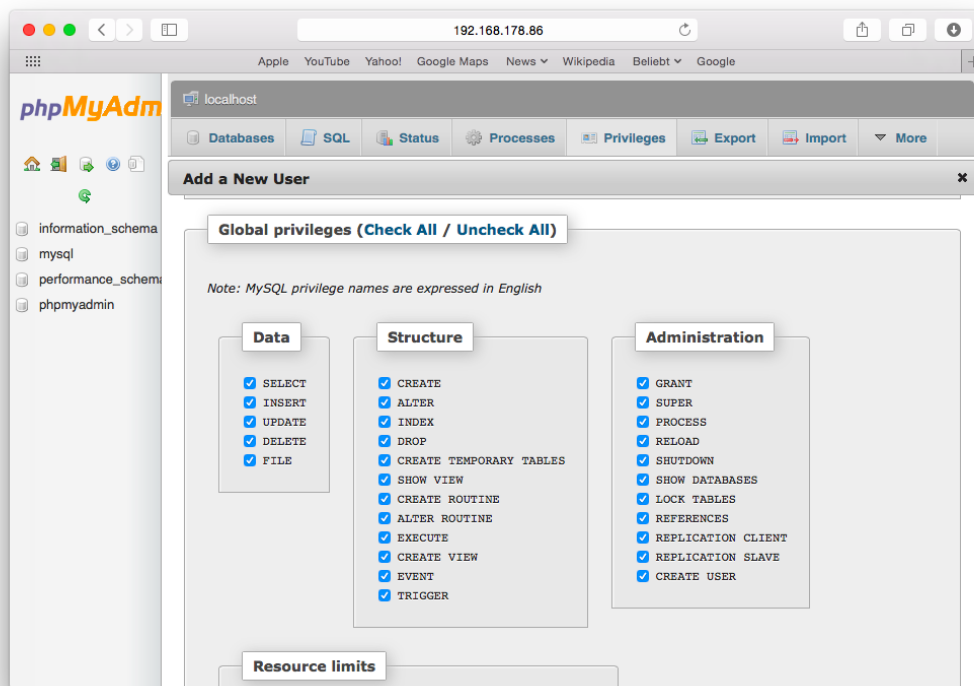


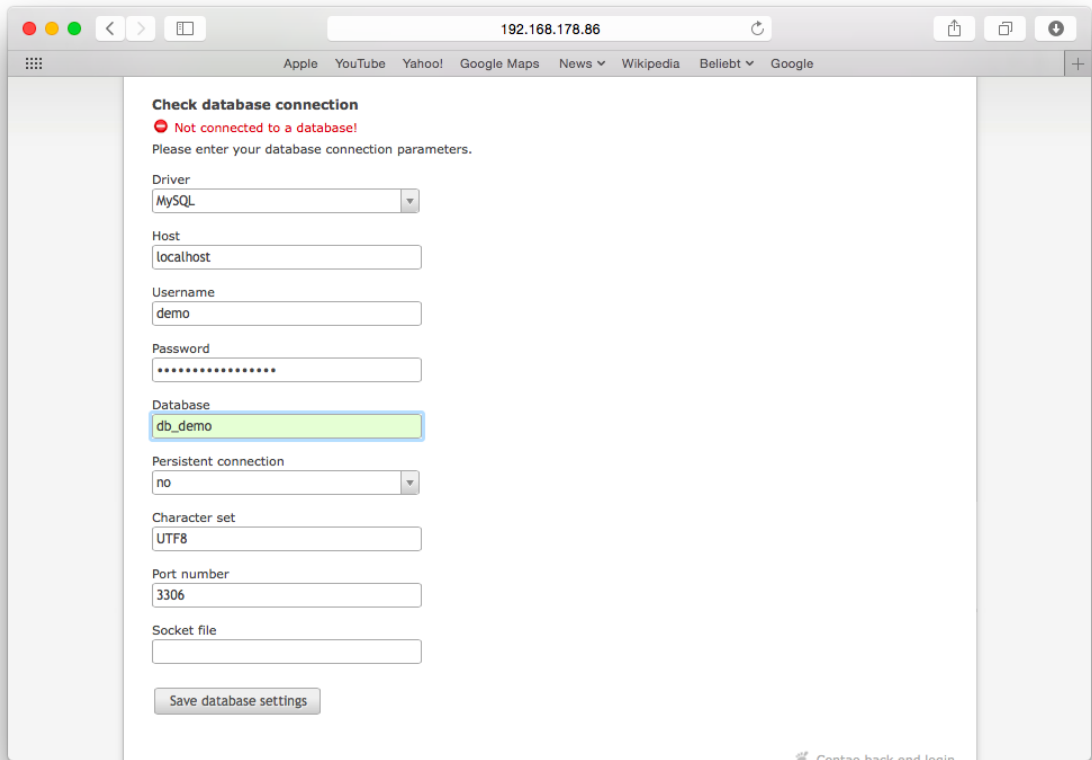


Installing contao









192.168.178.86

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Update database tables

The database is not up to date!

Please note that the update assistant has only been tested with MySQL and MySQLi drivers. If you are using a different database (e.g. Oracle), you might have to install or update your database manually.

Create new tables

Select all

CREATE TABLE `tl_article` (
 `id` int(10) unsigned NOT NULL auto_increment,
 `pid` int(10) unsigned NOT NULL default '0',
 `sorting` int(10) unsigned NOT NULL default '0',
 `tstamp` int(10) unsigned NOT NULL default '0',
 `title` varchar(255) NOT NULL default '',
 `alias` varchar(128) COLLATE utf8_bin NOT NULL default '',
 `author` int(10) unsigned NOT NULL default '0',
 `inColumn` varchar(32) NOT NULL default '',
 `keywords` text NULL,
 `showTeaser` char(1) NOT NULL default '',
 `teaserCssID` varchar(255) NOT NULL default '',
 `teaser` text NULL,
 `printable` varchar(255) NOT NULL default '',
 `customTpl` varchar(64) NOT NULL default '',
 `protected` char(1) NOT NULL default '',
 `groups` blob NULL,
 `guests` char(1) NOT NULL default '',
 `cssID` varchar(255) NOT NULL default '',
 `...

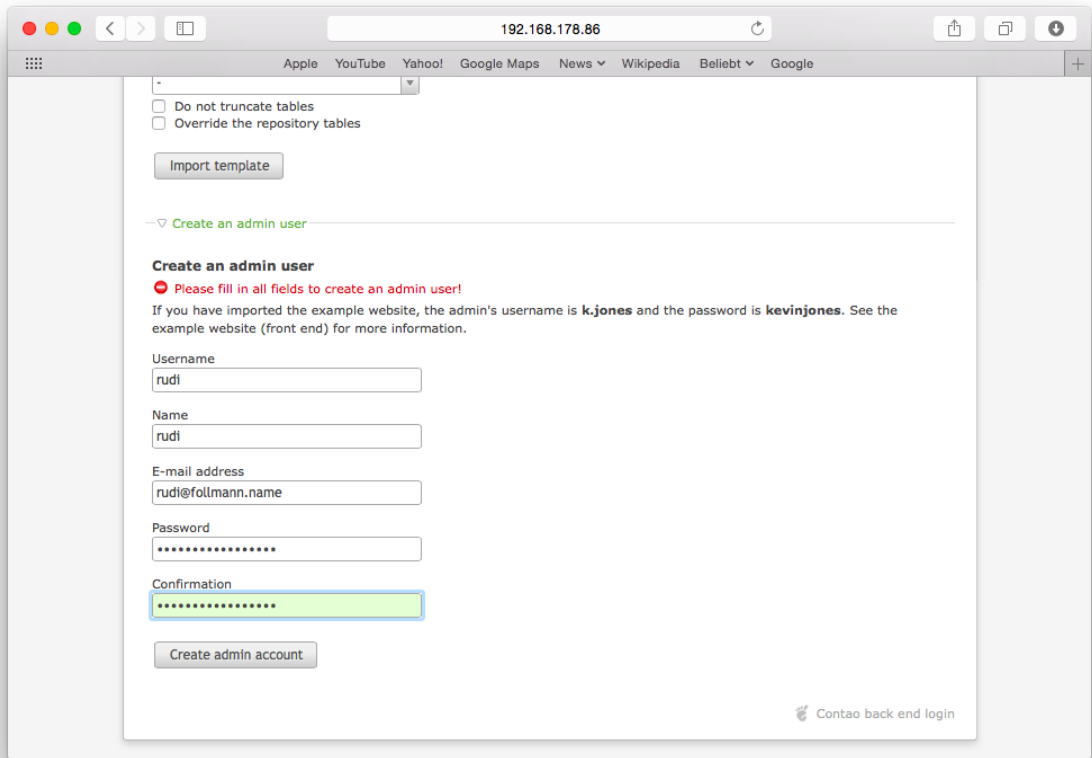
Update database

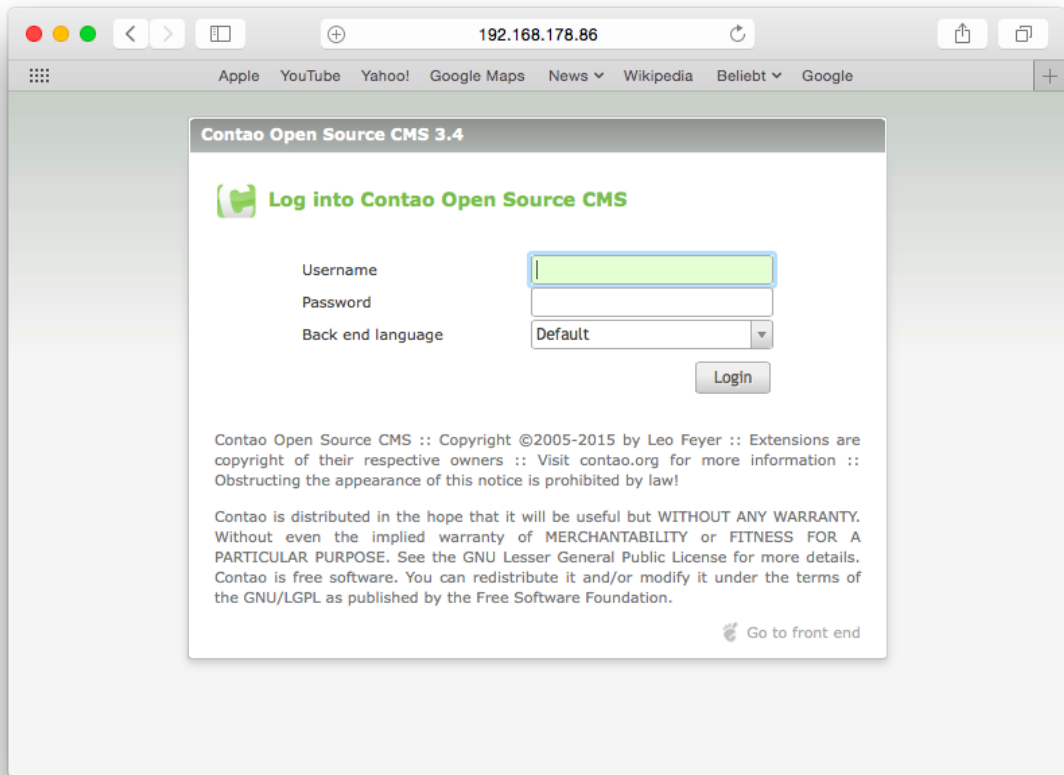
Import a template

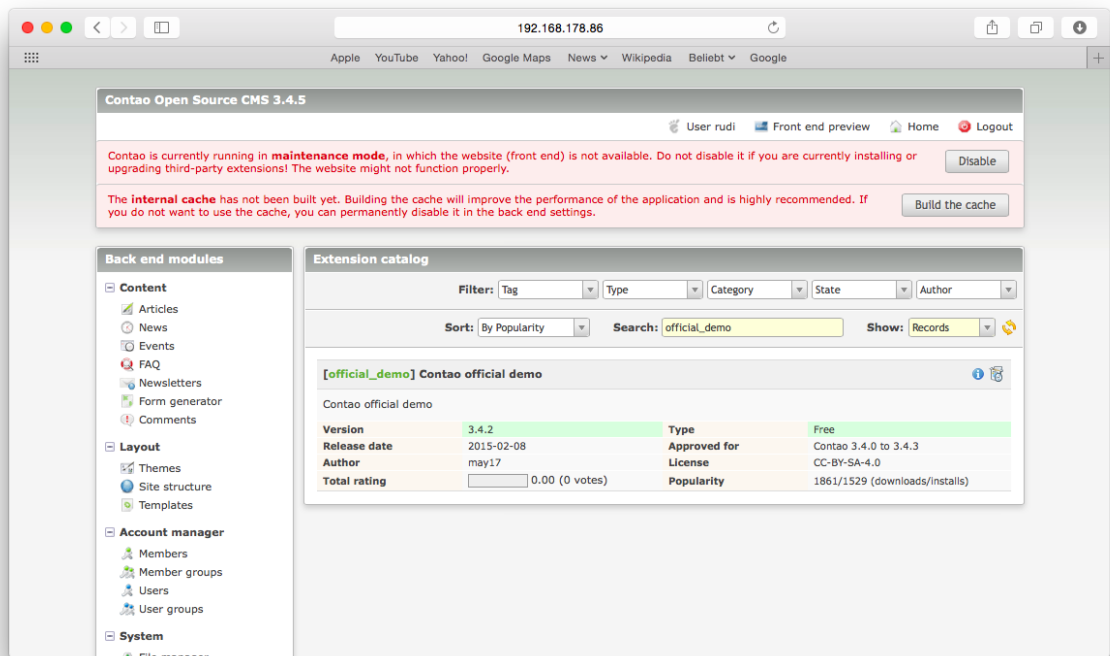
Import a template

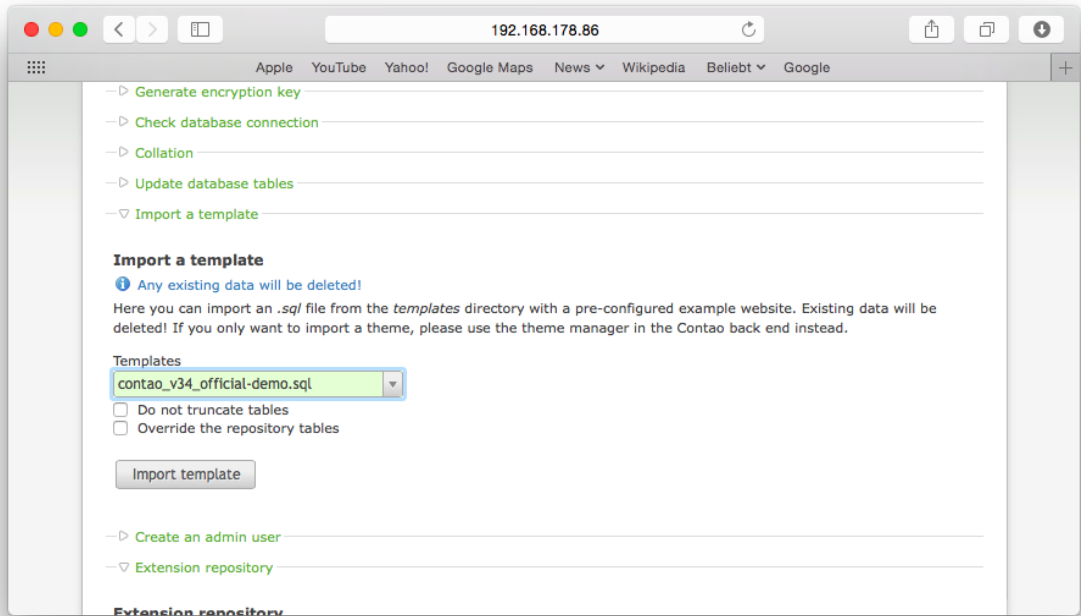
Any existing data will be deleted!

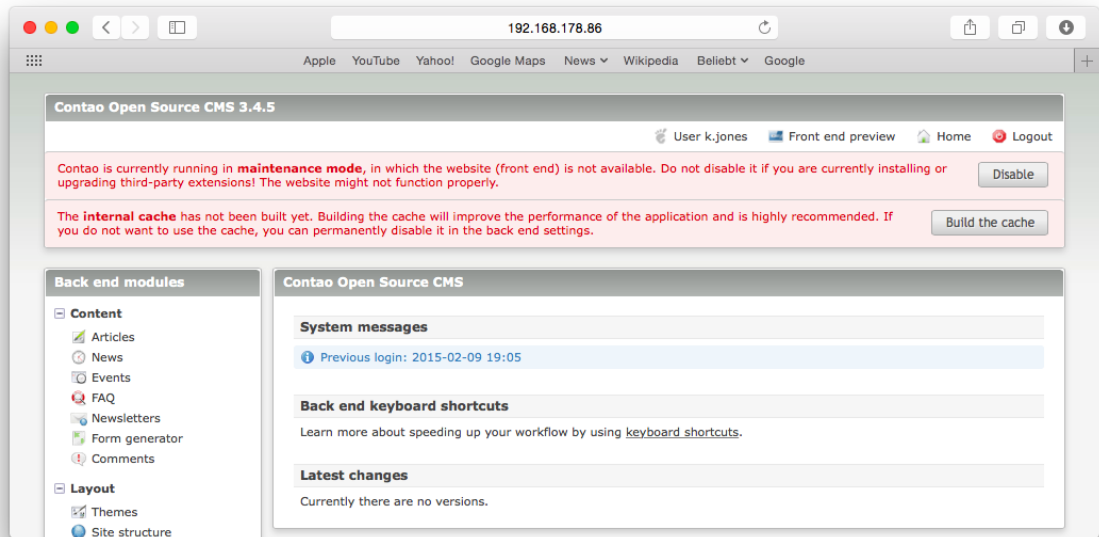
Here you can import an `.sql` file from the `templates` directory with a pre-configured example website. Existing data will be deleted! If you only want to import a theme, please use the theme manager in the Contao back end instead.





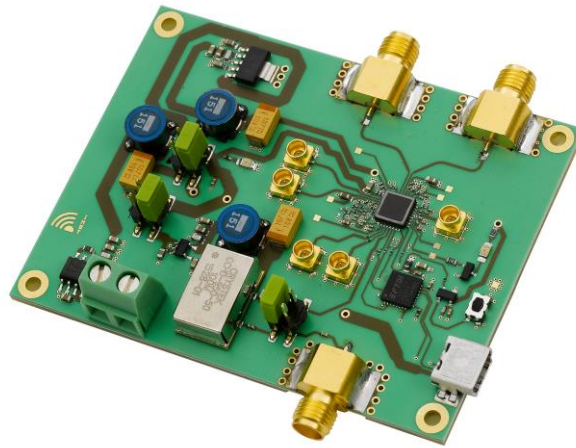




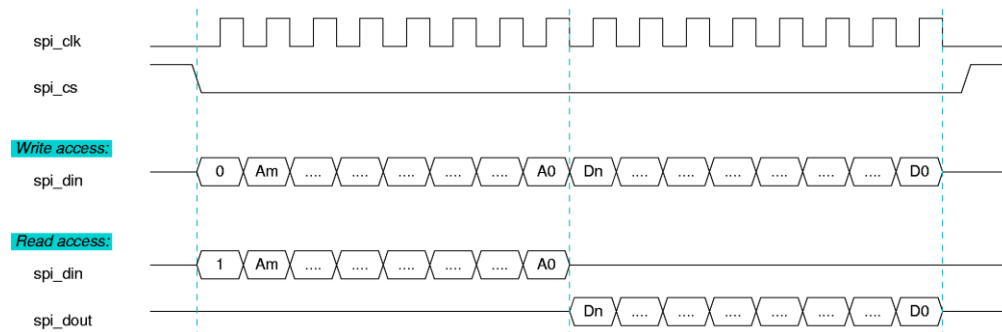




A measurement server




The FTDI/SPI control of devices



A web server

```
pi@bananapi:~/novelo$ ls -l
total 196
-rw-r--r-- 1 pi pi 1147 Mai  9 17:43 convert.cpp
-rw-r--r-- 1 pi pi  326 Mai  9 17:43 convert.h
drwxr-xr-x 2 pi pi 4096 Mai  9 17:43 data
-rw-r--r-- 1 pi pi 3254 Mai  9 17:43 FTDI_Basic_IO.cpp
-rw-r--r-- 1 pi pi  306 Mai  9 17:43 FTDI_Basic_IO.h
-rw-r--r-- 1 pi pi 9615 Mai  9 17:43 FTDI.cpp
-rw-r--r-- 1 pi pi 1075 Mai  9 17:43 FTDI.h
-rw-r--r-- 1 pi pi 11655 Mai  9 17:43 lo9.cc
-rw-r--r-- 1 pi pi 2213 Mai  9 17:43 L09_FTDI.h
-rw-r--r-- 1 pi pi  923 Mai  9 17:43 L09.h
-rw-r--r-- 1 pi pi 3265 Mai  9 17:43 lo.py
-rw-r--r-- 1 pi pi  465 Mai  9 17:43 Makefile
-rw-r--r-- 1 pi pi 10612 Mai  9 17:43 novelo.cc
-rw-r--r-- 1 pi pi  827 Mai  9 17:43 novelo.h
-rw-r--r-- 1 pi pi 12822 Mai  9 17:43 novelo_main.cpp
-rw-r--r-- 1 pi pi 20542 Mai  9 17:43 novelo_sub.cpp
-rw-r--r-- 1 pi pi  616 Mai  9 17:43 novelo_sub.h
-rw-r--r-- 1 pi pi  159 Mai  9 17:43 server.ini
-rw-r--r-- 1 pi pi 21574 Mai  9 17:43 server.py
-rw-r--r-- 1 pi pi  902 Mai  9 17:43 setup.py
-rw-r--r-- 1 pi pi 1009 Mai  9 17:43 simple.c
drwxr-xr-x 2 pi pi 4096 Mai  9 17:43 styles
-rw-r--r-- 1 pi pi 6323 Mai  9 17:43 test.cpp
-rw-r--r-- 1 pi pi 22635 Mai  9 17:43 Write_Read_L09_Regs.cpp
pi@bananapi:~/novelo$
```

 To view this page, you must log in to this area on 192.168.178.86:1000:

Banana Pro web server

Your login information will be sent securely.


Name:

Password:

Remember this password in my keychain

Raspberry Pi Web NOVELO x +

192.168.179.1:1000 Suchen

NOVELO web programming interface 

LO version 0 subversion 1
Lock detect: 0, error counter: 0

Read out values:
Divider: 45.00000000, Ref divider: 0,
CP fine: 8, Off fine: 1 Off coarse: 1,
VCO sel: 0, VCO band: 3,
SDM reset: 0, SDM mux: 1,
Preload: 0000000000000000,
GPO: 1111111100000000

N/f: Reference divider: Ref f:

CP fine: Offset fine: Offset coarse:

VCO sel 11G 9G 7G VCO band:

Reset SDM SDM order:

Preload: GPO:

File:

Please use div f [GHz] for programming a frequency instead of a divider ratio.
© 2014 by IMST NOVELO team. For more information please visit [IMST](#).

4

Arcade Cabinet

Installing modules

```
mali_drm          2608    1
drm               209226  2 mali_drm
mali              111427  0
ump               52415   4 mali,disp_ump
```

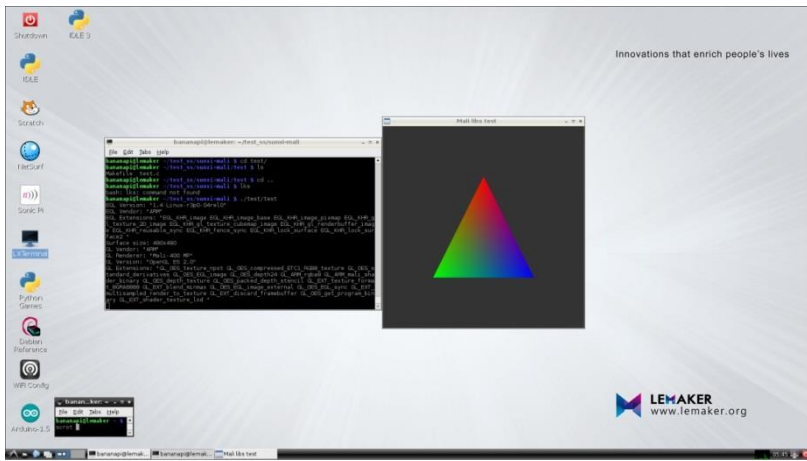
```
# /etc/modules: kernel modules to load at boot time.
#
# This file contains the names of kernel modules that should be loaded
# at boot time, one per line. Lines beginning with "#" are ignored.
ump
mali
mali_drm
```

Installing libump

```
bananapi@lemaker ~ $ sudo find /usr/include/ -name ump*
/usr/include/ump
/usr/include/ump/ump_platform.h
/usr/include/ump/ump_ref_drv.h
/usr/include/ump/ump.h
```

```
bananapi@lemaker ~ $ sudo find / -name *UMP*
/usr/lib/arm-linux-gnueabi/libUMP.a
/usr/lib/arm-linux-gnueabi/libUMP.so.3
/usr/lib/arm-linux-gnueabi/libUMP.so.3.0.0
/usr/lib/arm-linux-gnueabi/libUMP.so
```

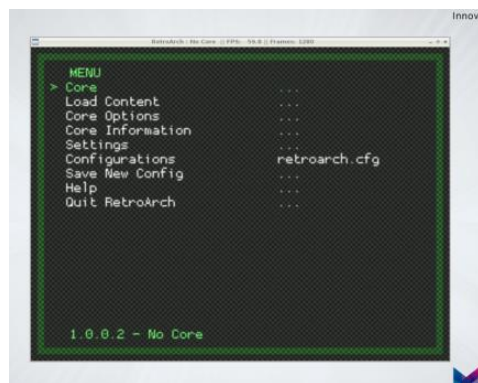
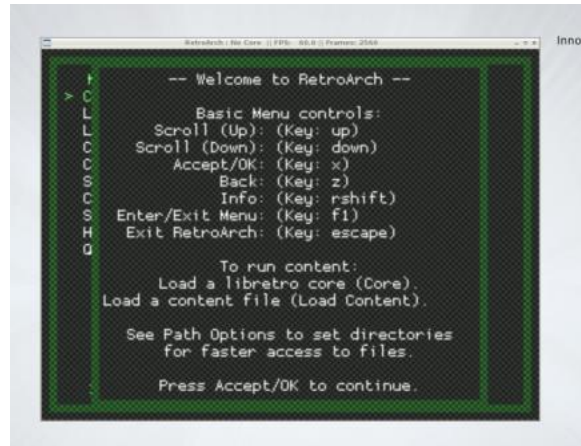
Testing hardware acceleration



Framebuffer version RetroArch

```
bananapi@lemaker ~/RetroArch $ ls /opt/retroarch/bin/retroarch
/opt/retroarch/bin/retroarch
```


Playing a game from RetroArch menu interface



```
RetrosArch - No Core - 0 FPS - 64.1 | Frames: 119/60
CORE SELECTION /usr/lib/libretro/
> libretro-ime4all.so (CORE)
libretro-pocketsnes.so (CORE)

1.0.0.2 - No Core
```

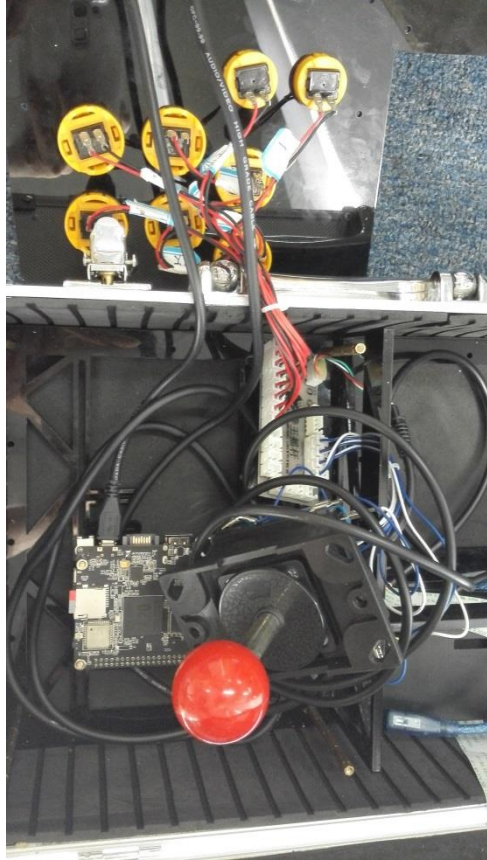
```
RetrosArch - No Core - 0 FPS - 54.9 | Frames: 122/60
NTENT (IME4a11) /opt/retroarch/roms/mame037
> 1942.zip (FILE)
1943.zip (FILE)
bublbob1.zip (FILE)
driftout.zip (FILE)
goldnaxe.zip (FILE)
mk.zip (FILE)
mk2.zip (FILE)
mslug.zip (FILE)
mslug2.zip (FILE)
neobombe.zip (FILE)
neogeo.zip (FILE)
outrun.zip (FILE)
pacman.zip (FILE)
pacmanb1.zip (FILE)
pacmania.zip (FILE)
pacmanj.zip (FILE)
pacmanjp.zip (FILE)
1.0.0.2 - IMAME4a11 0.37 BETA 5 (Apr 28 2015)
```

Suitcase



Joystick





A micro USB extended line



A USB hub



An LCD display



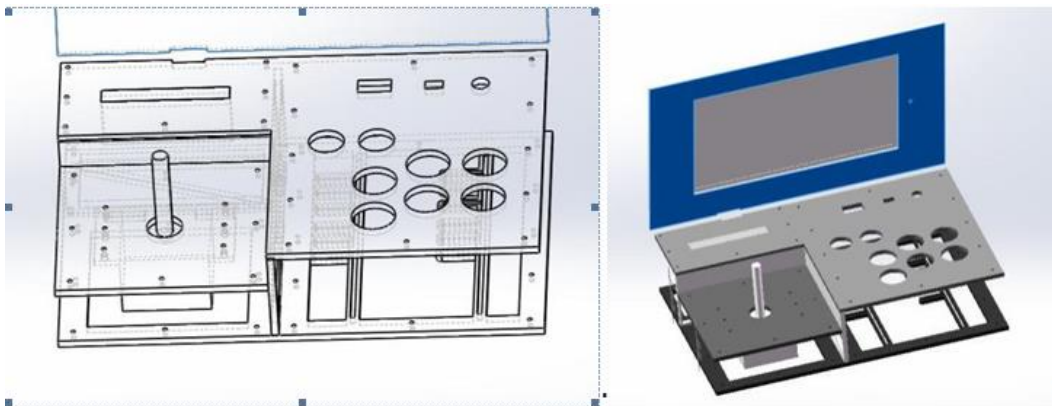
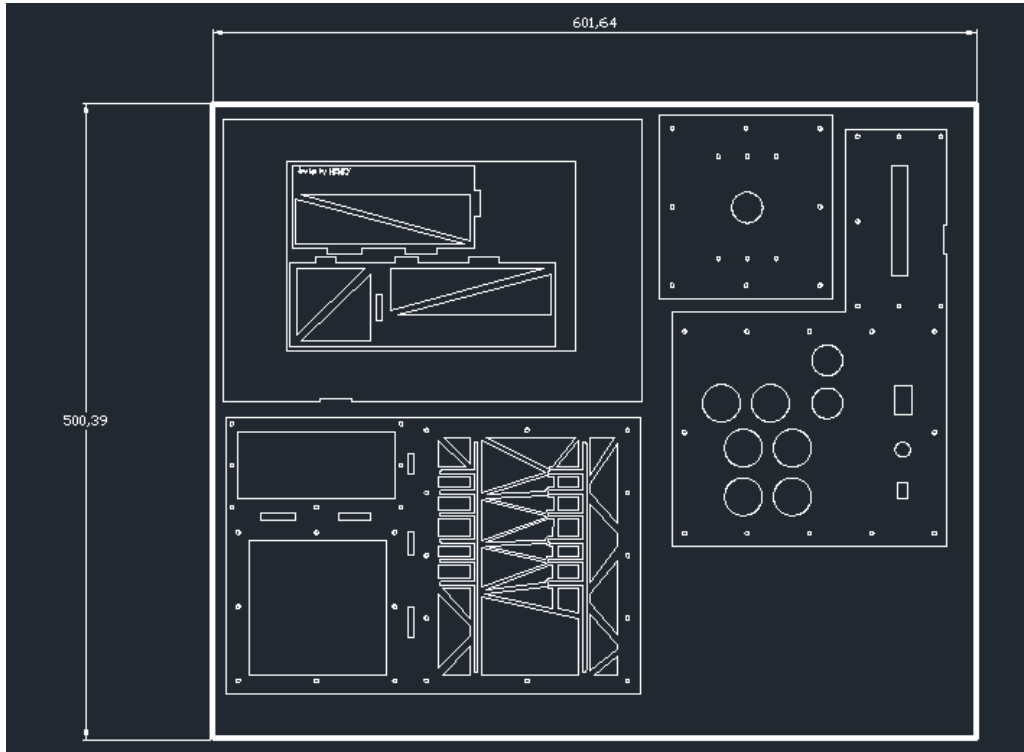
An audio extended line



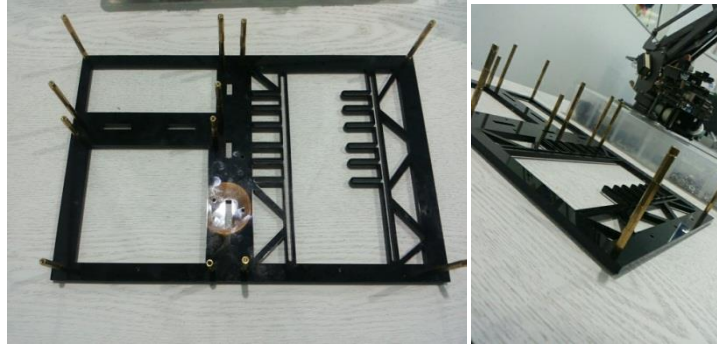
A mini keyboard



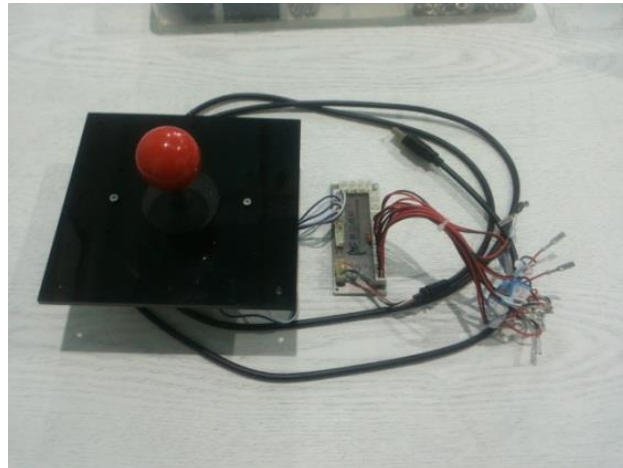
Designing a frame

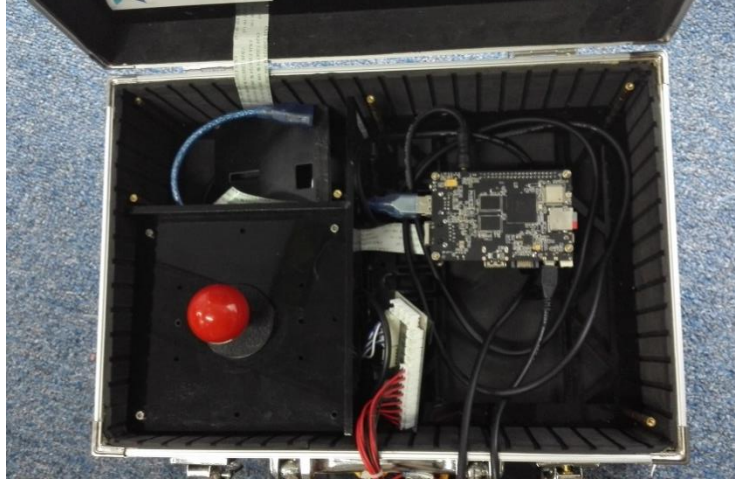


Assembling a base frame



Assembling Banana Pro and a joystick

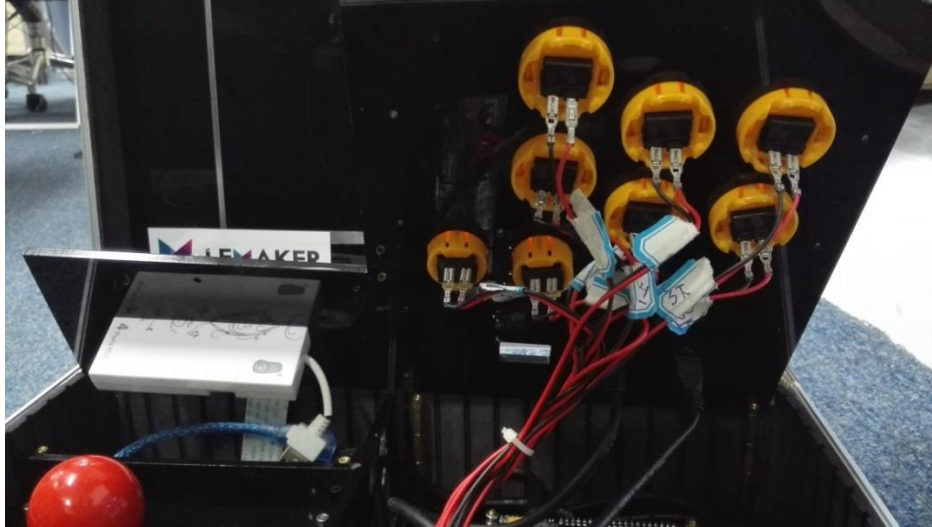




Mounting an LCD



Assembling a top frame



Configuring output to an LCD



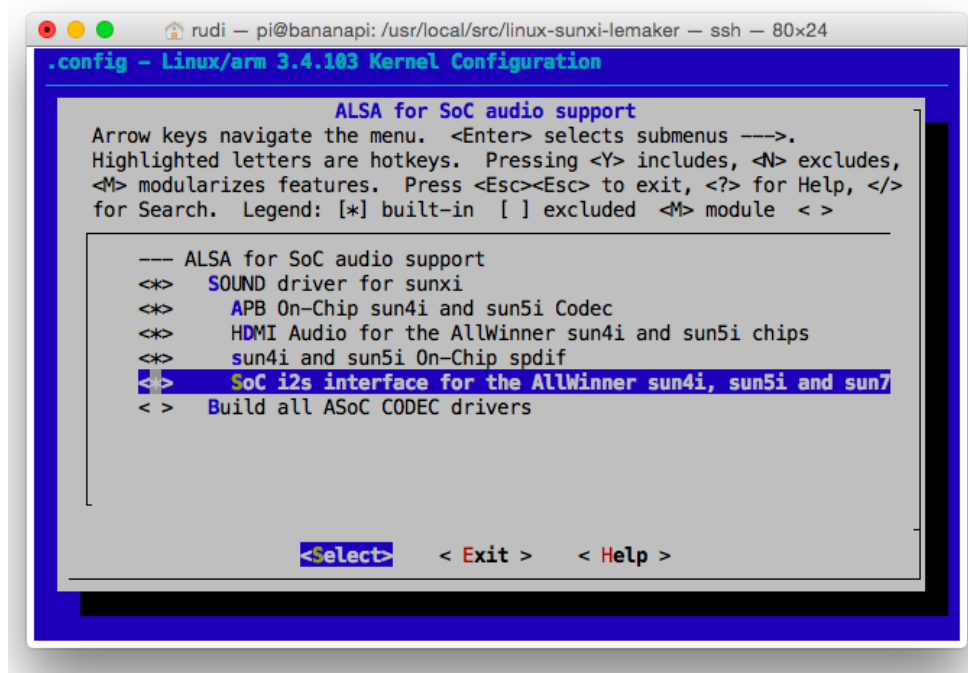
Playing the game on the arcade cabinet



5

A Multimedia Centre

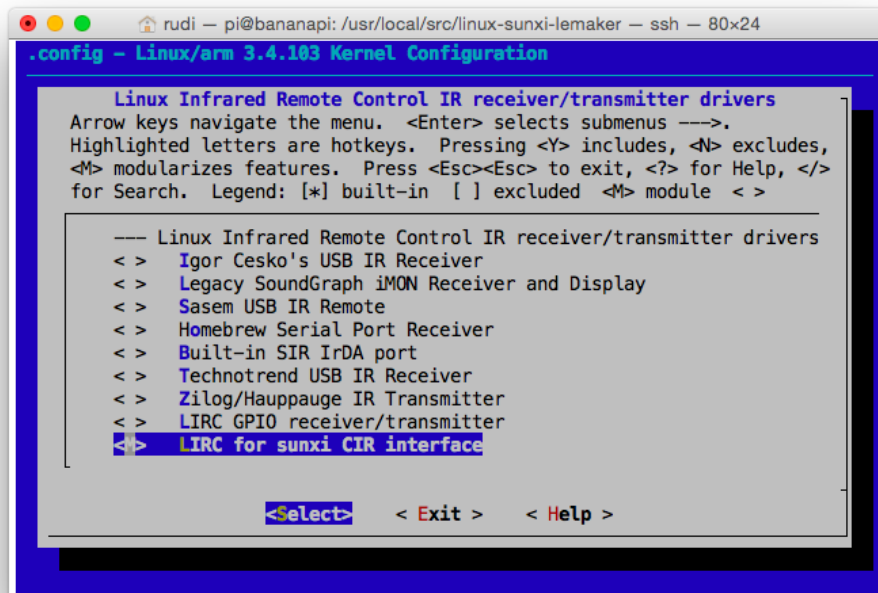
Adding the I2S audio device



```
rudi — pi@bananapi: /usr/local/src/linux-sunxi-lemaker — ssh — 80x15
pi@bananapi:/usr/local/src/linux-sunxi-lemaker$ aplay -l
*** List of PLAYBACK Hardware Devices ***
card 0: sunxicodec [sunxi-CODEC], device 0: M1 PCM [sunxi PCM]
  Subdevices: 1/1
    Subdevice #0: subdevice #0
card 1: sunxisndspdif [sunxi-sndspdif], device 0: SUNXI-SPDIF sndspdif-0 []
  Subdevices: 1/1
    Subdevice #0: subdevice #0
card 2: sunxisndi2s [sunxi-sndi2s], device 0: SUNXI-I2S sndi2s-0 []
  Subdevices: 1/1
    Subdevice #0: subdevice #0
card 3: sunxisndhdm1 [sunxi-sndhdm1], device 0: SUNXI-HDMIAUDIO sndhdm1-0 []
  Subdevices: 1/1
    Subdevice #0: subdevice #0
pi@bananapi:/usr/local/src/linux-sunxi-lemaker$ █
```

Deactivating display driver kernel logging

Activating the sunxi lirc driver



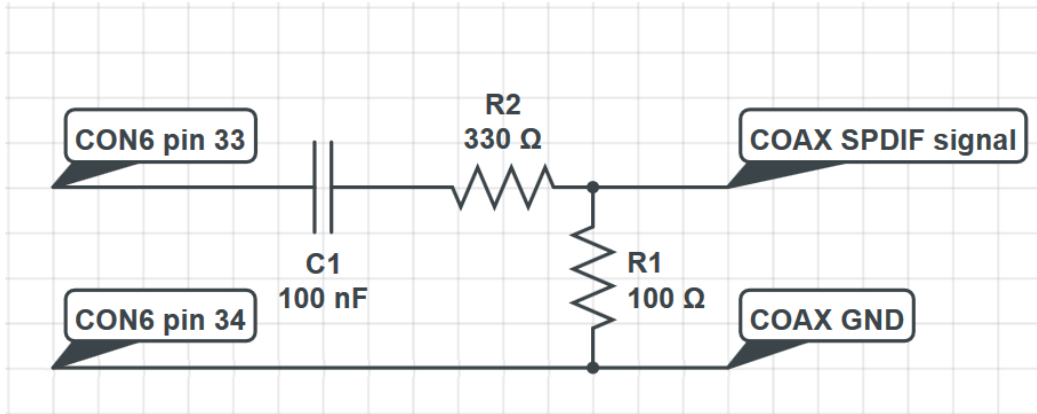
```
.config - Linux/arm 3.4.103 Kernel Configuration

Linux Infrared Remote Control IR receiver/transmitter drivers
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
<M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>
for Search. Legend: [*] built-in [ ] excluded <M> module < >

--- Linux Infrared Remote Control IR receiver/transmitter drivers
< > Igor Cesko's USB IR Receiver
< > Legacy SoundGraph iMON Receiver and Display
< > Sasem USB IR Remote
< > Homebrew Serial Port Receiver
< > Built-in SIR IrDA port
< > Technotrend USB IR Receiver
< > Zilog/Hauppauge IR Transmitter
< > LIRC GPIO receiver/transmitter
< > LIRC for sunxi CIR interface

<Select> < Exit > < Help >
```


Using an electrical SPDIF with Banana Pro



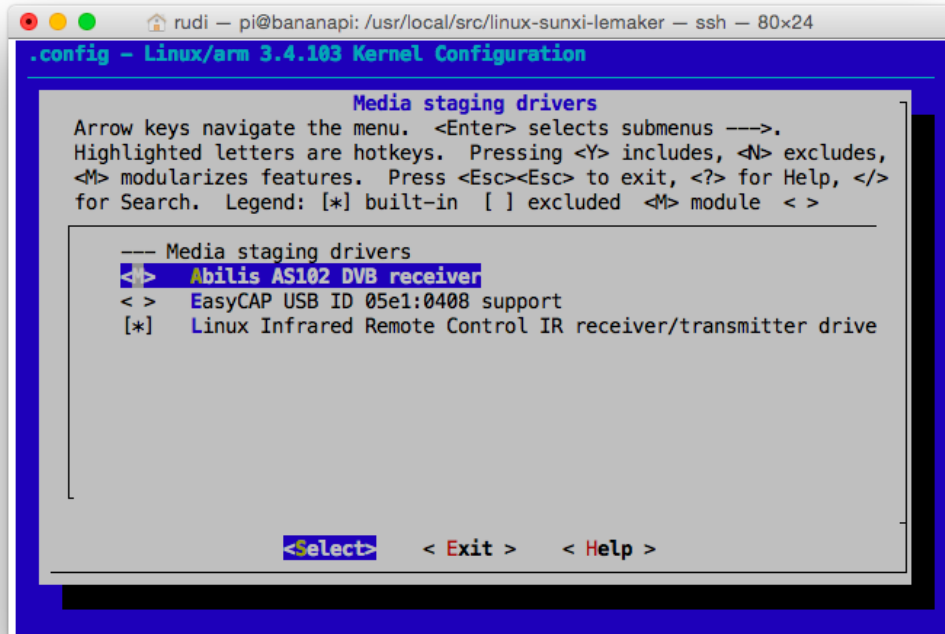
Configuring a remote control



```
pi@bananapi:~$ mode2 -d /dev/lirc0 -m
8724-pulse  4458-space  533-pulse  575-space  469-pulse
1706-space
512 1663 491 575 491 575
469 597 512 618 448 1685
512 1727 448 1706 512 1663
512 1706 469 575 491 1706
469 618 469 554 533 597
469 1685 491 554 533 575
491 575 469 597 491 597
491 575 469 1706 469 618
469 1706 491 1706 491 1685
491 1663 512 1685 491 1706
512 21693 8767 2282 512 16275
8788 2261 491 16275 8788 2218
555 16275 8767 2239 533 16275
8788 2218 533 16275 8767 2239
512 16275 8831 2197 576 16275
8788 2239 469 16275 8788 2282
469 16275 8788 2303 469 16275
8767 2261 491 16275 8810 2218
491 16275 8746 2261 512 16275
8788 2261 491 16275 8788 2261
512 16275 8788 2218 491 16275
```

The DVB kernel driver



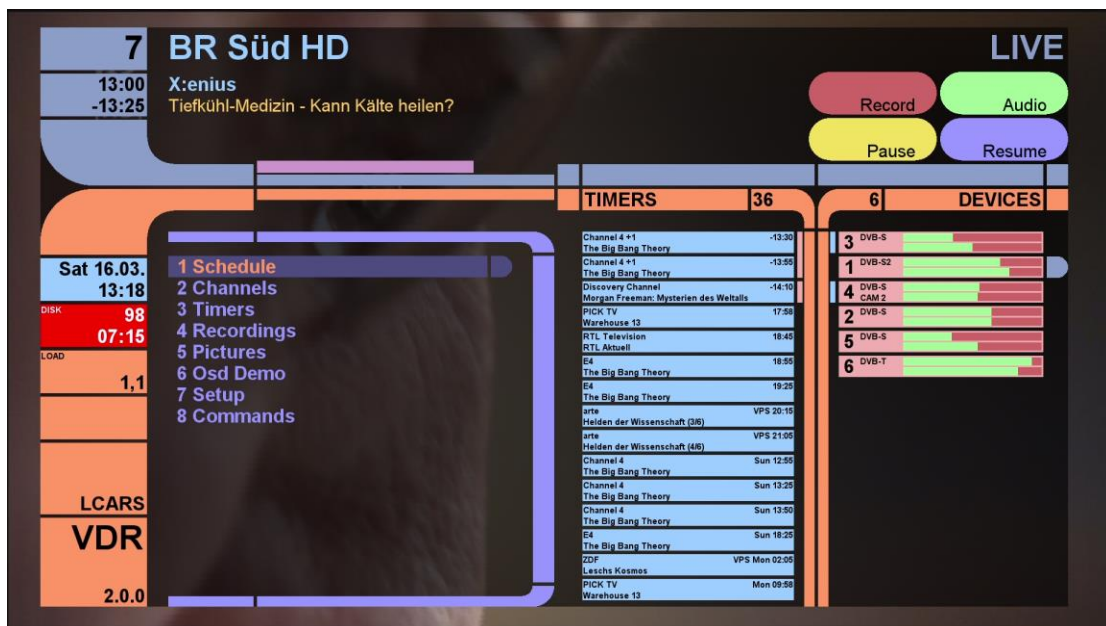




The DVB userspace driver



VDR scripts



7 BR Süd HD **LIVE**

13:00 X:enius
-13:25 Tiefkühl-Medizin - Kann Kälte heilen?

Record Audio
Pause Resume

TIMERS 36 **6 DEVICES**

Sat 16.03. 13:18
DISK 98
LOAD 07:15
1,1

LCARS
VDR
2.0.0

1 Schedule
2 Channels
3 Timers
4 Recordings
5 Pictures
6 Osd Demo
7 Setup
8 Commands

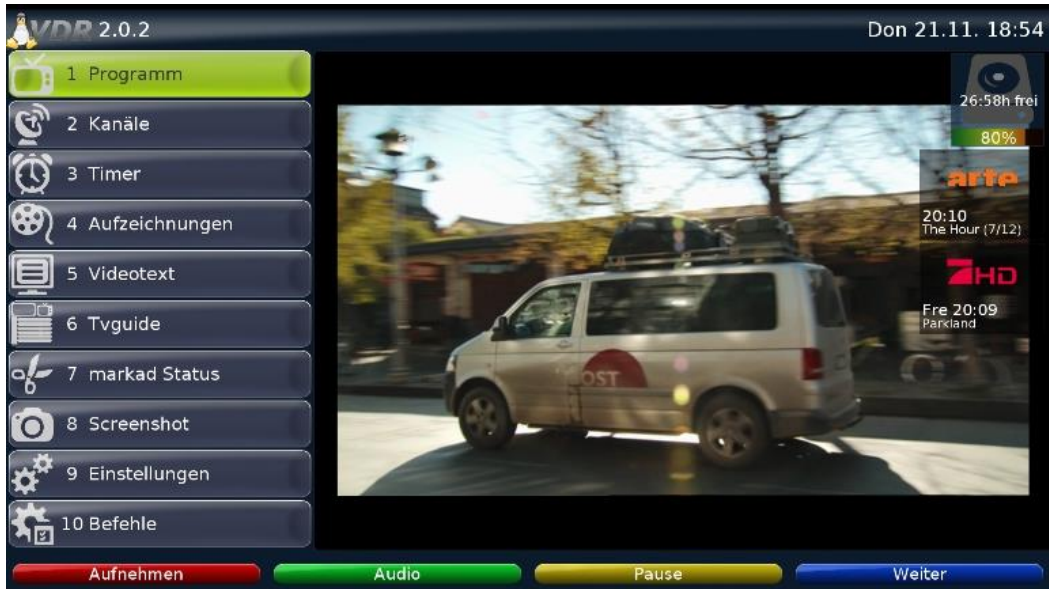
Channel	Program	Start
Channel 4 +1	The Big Bang Theory	-13:30
Channel 4 +1	The Big Bang Theory	-13:50
Discovery Channel	Morgan Freeman: Mysterien des Weltalls	-14:10
PICK TV	Warehouse 13	17:50
RTL Television	RTL Aktuell	18:40
E4	The Big Bang Theory	18:55
E4	The Big Bang Theory	19:20
arte	Heiden der Wissenschaft (3B)	VPS 20:15
arte	Heiden der Wissenschaft (4B)	VPS 21:00
Channel 4	The Big Bang Theory	Sun 12:55
Channel 4	The Big Bang Theory	Sun 13:25
Channel 4	The Big Bang Theory	Sun 13:50
E4	The Big Bang Theory	Sun 18:25
ZDF	Leschs Kosmos	VPS Mon 02:00
PICK TV	Warehouse 13	Mon 09:50

3 DVB-S
1 DVB-S2
4 DVB-S CAM 2
2 DVB-S
5 DVB-S
6 DVB-T

Watching teletext



Changing VDR's skin



Vdradmin-am

The screenshot displays the VDRAdmin-AM 3.4.6 web interface. The browser window title is "VDRAdmin-AM 3.4.6 (localhost) - Mozilla Firefox". The address bar shows "http://localhost:8001/". The main content area is titled "What's on at 08:52 o'clock" and shows a grid of TV channels and their current programs. A sidebar on the left contains navigation options like "What's On Now?", "Playing Today?", "Timeline", "Channels", "Timer", "Auto Timer", "Recordings", "Remote Control", "Watch TV", "Commands", "Configuration", and "About / Help". A search button is located at the bottom of the sidebar.

Channel	Program	Time
Das Erste	ZDF-Morgenmagazin	Tuesday, 07/18/06 05:10-09:00
ZDF	ZDF-Morgenmagazin	Tuesday, 07/18/06 05:10-09:00
ProSieben	Do it Yourself - S.O.S.	Tuesday, 07/18/06 05:05-09:00
SAT.1	Sat.1-Frühstücksfernsehen	Tuesday, 07/18/06 05:05-09:00
KABELL	Unsere kleine Farm	Tuesday, 07/18/06 06:51-08:15
VOX	Titus	Tuesday, 07/18/06 06:30-08:15
Super RTL	SpongeBob Schwammkopf	Tuesday, 07/18/06 06:30-09:00
arte	Lola	Tuesday, 07/18/06 06:30-09:00
DAS VIERTE	Ihr Auftritt, Al Nundy!	Tuesday, 07/18/06 07:00-08:15
TELE 5	Die Traumfrau von Beverly Hills	Tuesday, 07/18/06 06:15-10:30
ORF 1	Dawson's Creek	Tuesday, 07/18/06 08:22-10:13
ORF 2	Wetter-Panorama	Tuesday, 07/18/06 07:30-08:59
PREMIERE START	HIT24 clip rotation	Tuesday, 07/18/06 08:30-10:00
PREMIERE 1	Die Ex-Freundinnen meines Fr	Tuesday, 07/18/06 08:30-10:30

A pop-up window titled "ZDF-Morgenmagazin" is open, showing details for the program "Komplott 52 plus" and "Festschraubt: Deutsches Inpostkontrollsystem kämpft zur Sicherung der Wahlen". It also lists video and audio tracks.

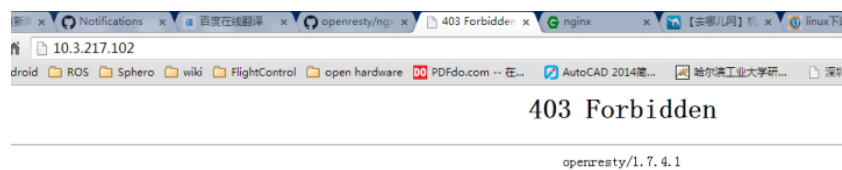
6

Remote Controlling a Smart Monitor Car

Starting the nginx server

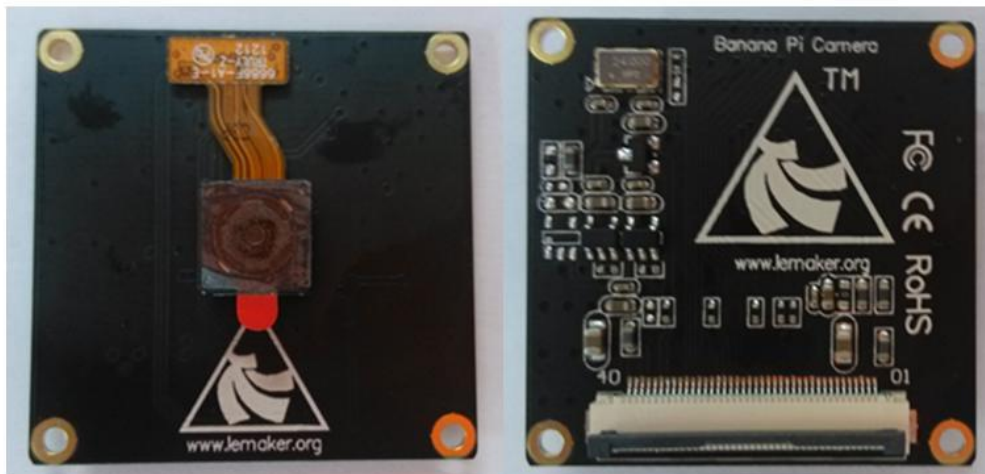
```
bananapi@lemaker ~/remote_monitor_car/bananapro_ipcamera $ sudo /usr/local/live/nginx/sbin/nginx  
nginx: [emerg] open() "/home/logs/nginx-rtmp/1936.error.log" failed (2: No such file or directory)
```

Accessing the nginx server



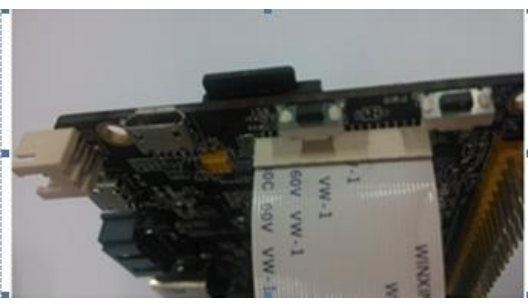
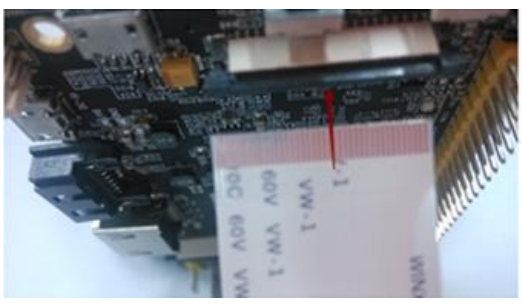


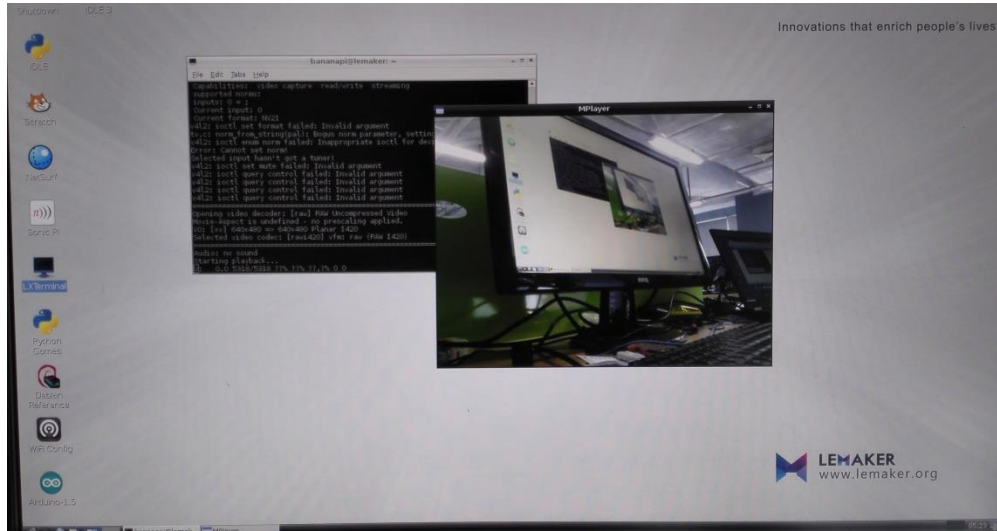
Setting up a camera



Connecting the camera module







```
frame=13056 fps= 15 q=24.8 size= 102470kB time=00:14:29.66 bitrate= 965.2kbits/
frame=13064 fps= 15 q=24.8 size= 102532kB time=00:14:30.20 bitrate= 965.2kbits/
frame=13072 fps= 15 q=24.8 size= 102594kB time=00:14:30.73 bitrate= 965.2kbits/
frame=13080 fps= 15 q=24.8 size= 102657kB time=00:14:31.26 bitrate= 965.2kbits/
frame=13088 fps= 15 q=24.8 size= 102719kB time=00:14:31.80 bitrate= 965.2kbits/
frame=13096 fps= 15 q=24.8 size= 102781kB time=00:14:32.30 bitrate= 965.2kbits/
frame=13104 fps= 15 q=24.8 size= 102844kB time=00:14:32.83 bitrate= 965.2kbits/
frame=13112 fps= 15 q=24.8 size= 102906kB time=00:14:33.36 bitrate= 965.2kbits/
frame=13120 fps= 15 q=24.8 size= 102968kB time=00:14:33.90 bitrate= 965.2kbits/
frame=13128 fps= 15 q=24.8 size= 103031kB time=00:14:34.43 bitrate= 965.2kbits/
frame=13136 fps= 15 q=24.8 size= 103093kB time=00:14:34.96 bitrate= 965.2kbits/
frame=13144 fps= 15 q=24.8 size= 103155kB time=00:14:35.50 bitrate= 965.2kbits/
frame=13152 fps= 15 q=24.8 size= 103218kB time=00:14:36.03 bitrate= 965.2kbits/
frame=13160 fps= 15 q=24.8 size= 103280kB time=00:14:36.56 bitrate= 965.2kbits/
frame=13168 fps= 15 q=24.8 size= 103342kB time=00:14:37.10 bitrate= 965.2kbits/
frame=13176 fps= 15 q=24.8 size= 103405kB time=00:14:37.63 bitrate= 965.2kbits/
frame=13184 fps= 15 q=24.8 size= 103467kB time=00:14:38.16 bitrate= 965.2kbits/
frame=13192 fps= 15 q=24.8 size= 103529kB time=00:14:38.70 bitrate= 965.2kbits/
frame=13200 fps= 15 q=24.8 size= 103591kB time=00:14:39.23 bitrate= 965.2kbits/
frame=13208 fps= 15 q=24.8 size= 103654kB time=00:14:39.76 bitrate= 965.2kbits/
frame=13216 fps= 15 q=24.8 size= 103716kB time=00:14:40.30 bitrate= 965.2kbits/
frame=13224 fps= 15 q=24.8 size= 103778kB time=00:14:40.83 bitrate= 965.2kbits/
frame=13232 fps= 15 q=24.8 size= 103841kB time=00:14:41.36 bitrate= 965.2kbits/
frame=13240 fps= 15 q=24.8 size= 103903kB time=00:14:41.90 bitrate= 965.2kbits/
```



Player Type

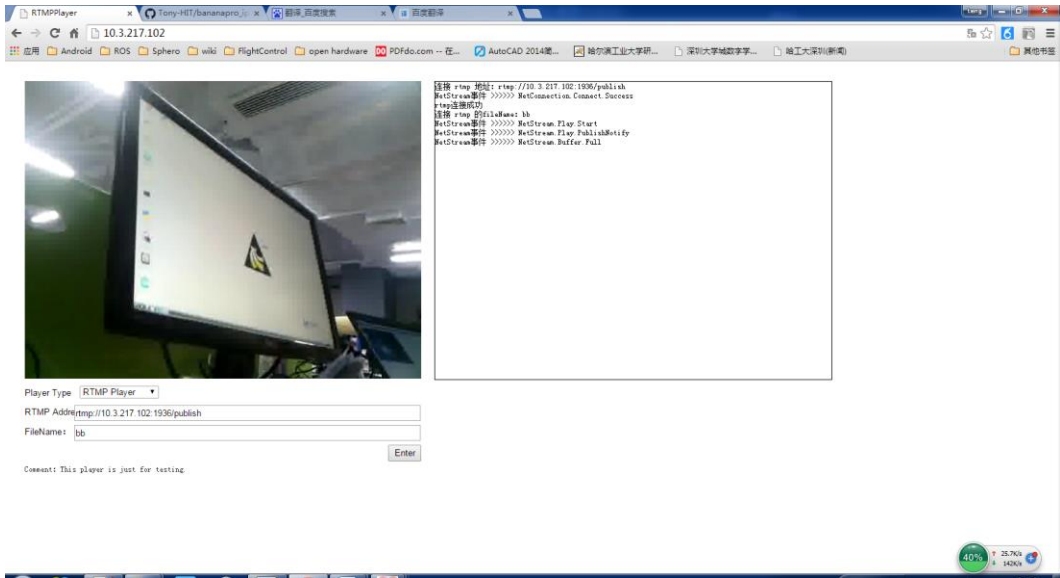
RTMP Address

FileName:

Player Type

RTMP Address

FileName:



A car suite



The L298N motor drive board



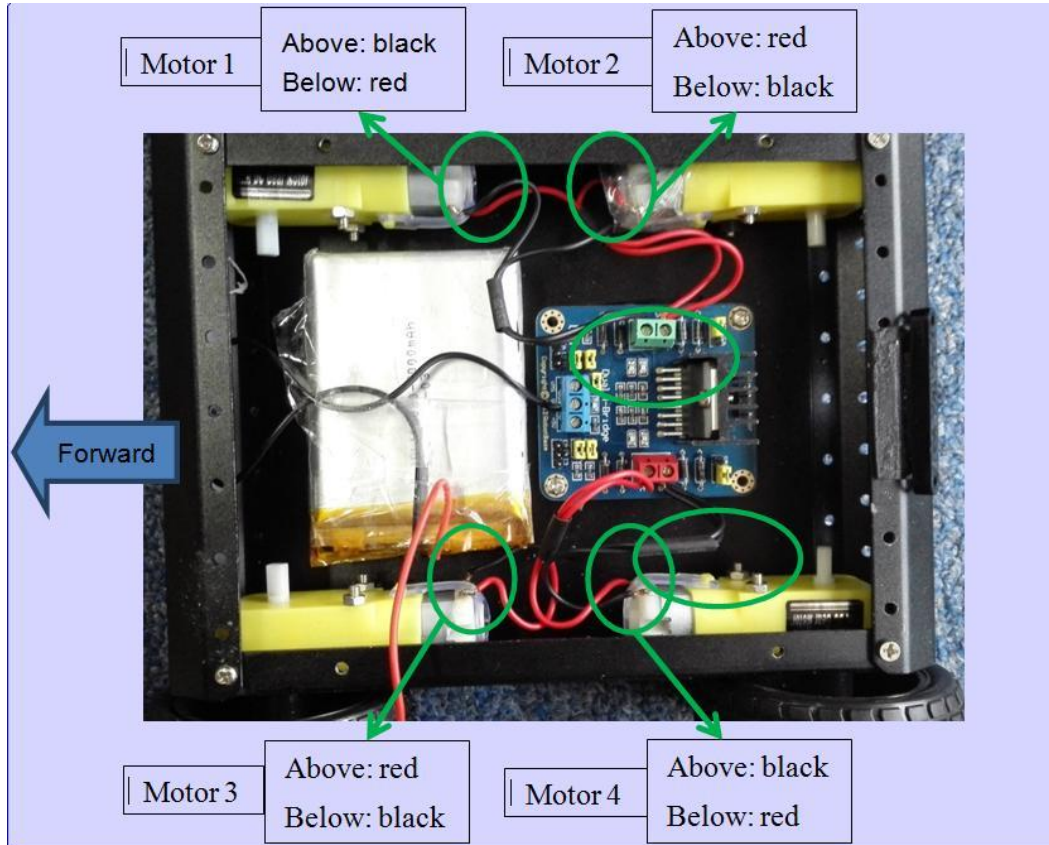
Battery

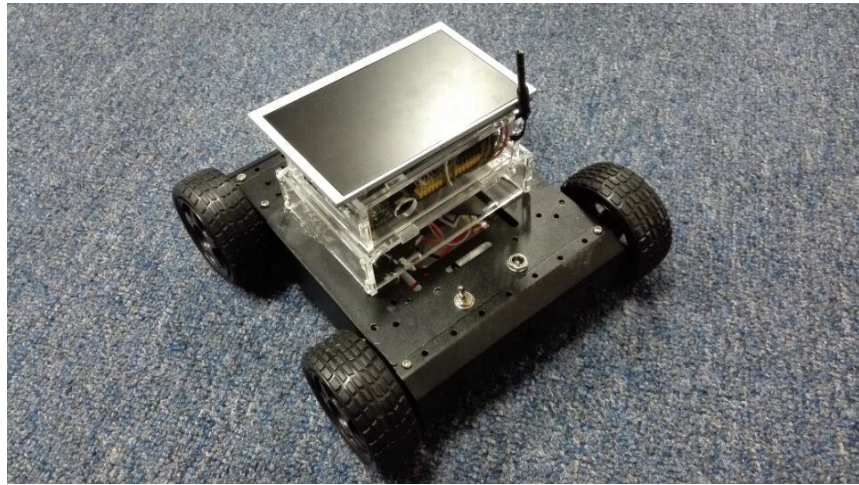


A 5 inch LCD



Assembly

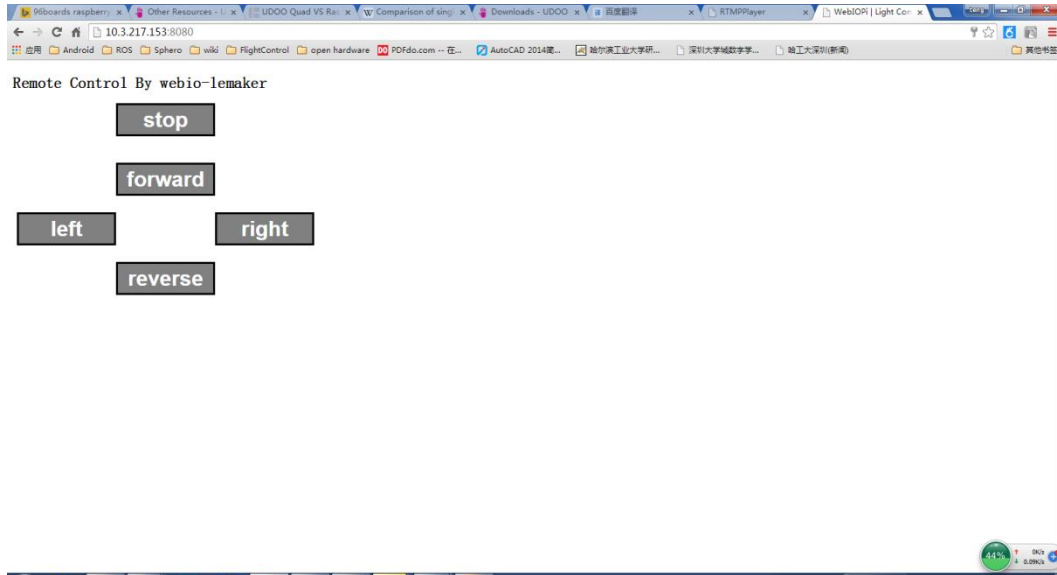




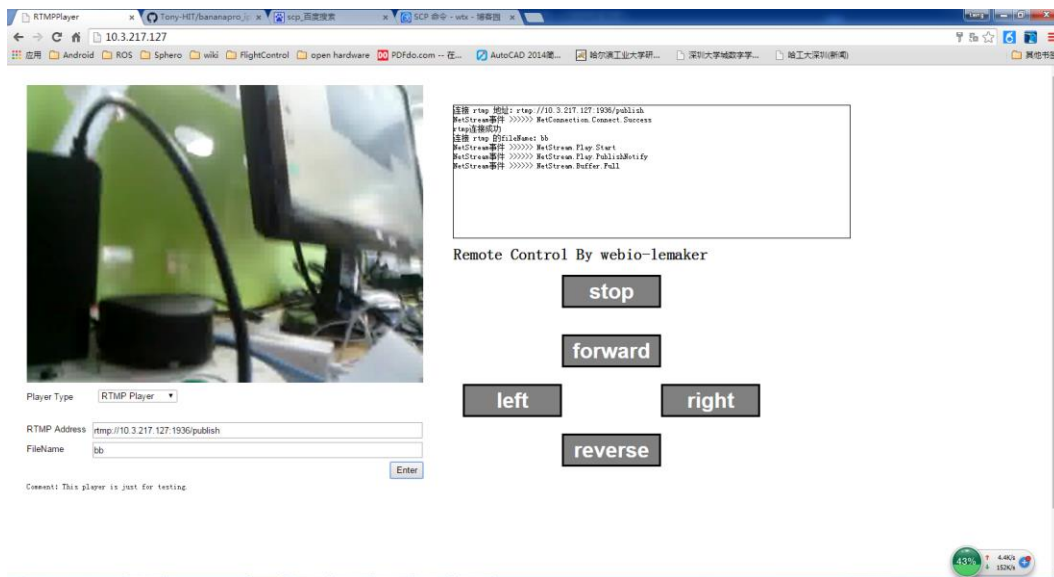
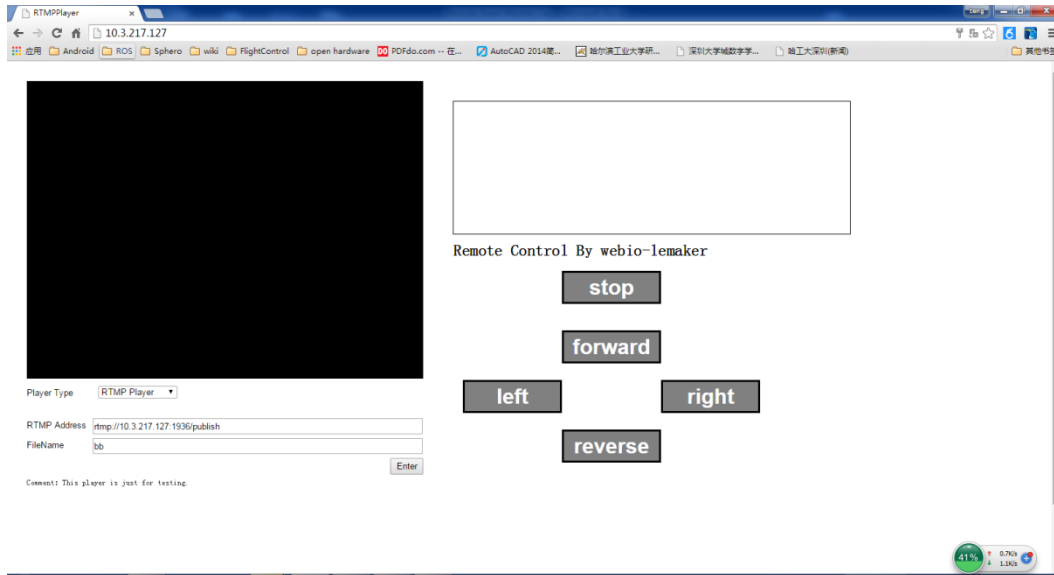
Testing webiopi on Banana Pro



Writing the webiopi controlling code



Adding the car controls to the IP camera web page

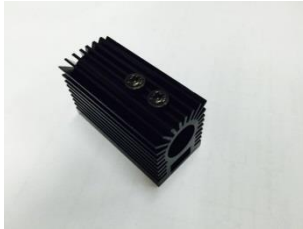
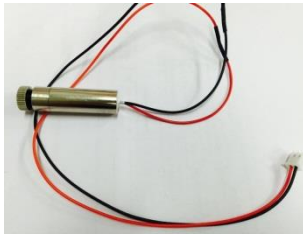


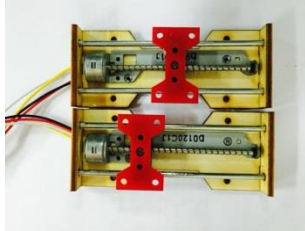
7

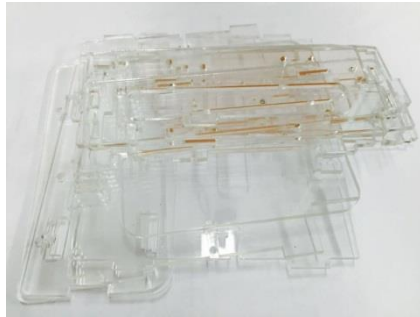
Laser Engraver

Preparing materials

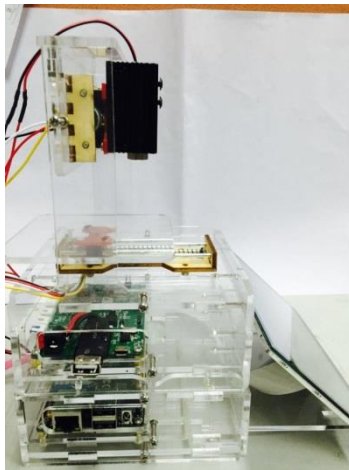
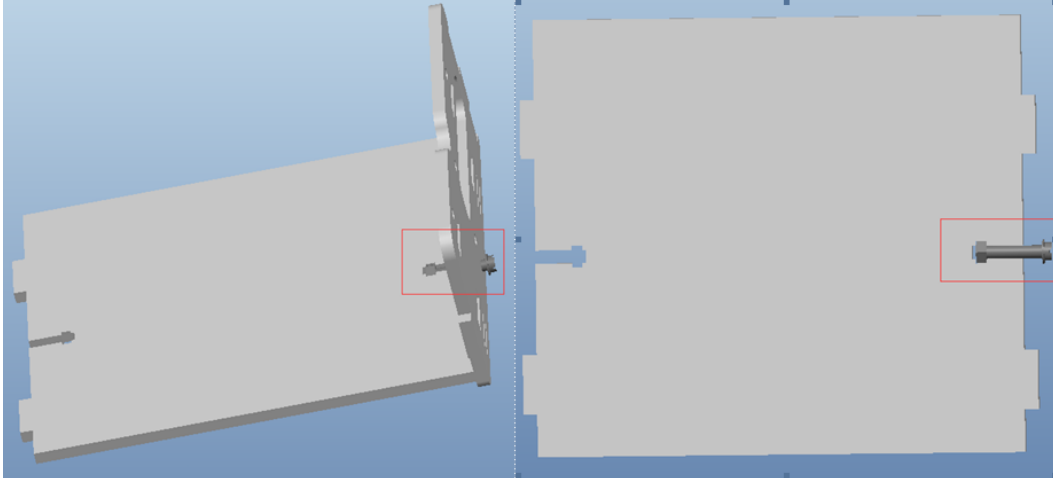








Setting up the laser engraving machine hardware



Installing dependencies

```
bananapi@lemaker: ~  
File Edit Tabs Help  
Ign http://ports.ubuntu.com trusty/main Translation-en_US  
Ign http://ports.ubuntu.com trusty/multiverse Translation-en_US  
Ign http://ports.ubuntu.com trusty/restricted Translation-en_US  
Ign http://ports.ubuntu.com trusty/universe Translation-en_US  
Fetched 2,480 kB in 54s (45.3 kB/s)  
Reading package lists... Done  
bananapi@lemaker:~$
```

Installing the GrblController software

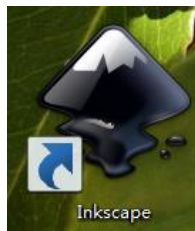
```
bananapi@lemaker: ~/cncWorkspace/GrblHoming-build  
File Edit Tabs Help  
der.o moc_simplelayout.o moc_filter.o moc_ttcclayout.o moc_writerappender.o moc_de  
bugappender.o moc_denyallfilter.o moc_nullappender.o moc_levelmatchfilter.o moc_le  
velrangefilter.o moc_listappender.o moc_stringmatchfilter.o moc_mainwindow.o moc_o  
ptions.o moc_grbldialog.o moc_about.o moc_gcode.o moc_timer.o moc_renderarea.o qrc  
GrblController.o -L/usr/lib/arm-linux-gnueabihf -lQtGui -lQtCore -lpthread  
bananapi@lemaker:~/cncWorkspace/GrblHoming-build$
```

```
bananapi@lemaker: ~/cncWorkspace/GrblHoming-build  
File Edit Tabs Help  
bananapi@lemaker:~/cncWorkspace/GrblHoming-build$ ls GrblController  
GrblController  
bananapi@lemaker:~/cncWorkspace/GrblHoming-build$
```

```
GrblController.desktop (~/Desktop) - gedit
File Edit View Search Tools Documents Help
+ Open Save Undo
GrblController.desktop x
[Desktop Entry]
Type=Application
Name=GrblController
Icon=/home/bananapi/cncWorkspace/GrblHoming/grbl.ico
Exec=/home/bananapi/cncWorkspace/GrblHoming-build/GrblController
.desktop Tab Width: 8 Ln 3, Col 20 INS
```



Installing Inkscape



Installing Arduino

Download the Arduino Software



ARDUINO 1.6.5

The open-source Arduino Software (IDE) makes it easy to write code and upload it to the board. It runs on Windows, Mac OS X, and Linux. The environment is written in Java and based on Processing and other open-source software.

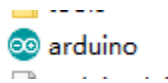
This software can be used with any Arduino board. Refer to the [Getting Started](#) page for installation instructions.

Windows Installer
Windows ZIP file for non admin install

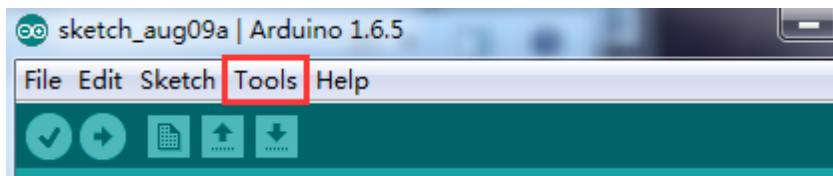
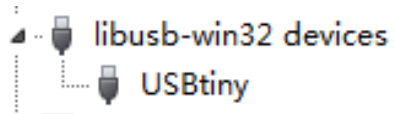
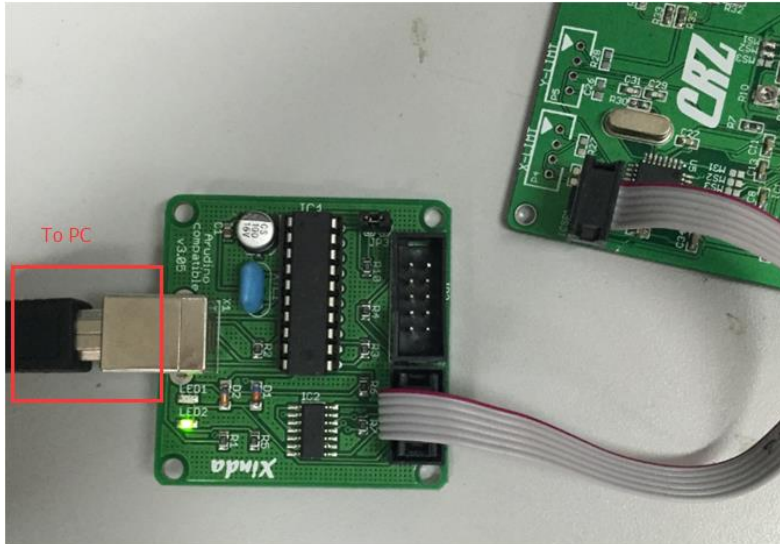
Mac OS X 10.7 Lion or newer

Linux 32 bits
Linux 64 bits

[Release Notes](#)
[Source Code](#)
[Checksums](#)



Loading bootloader

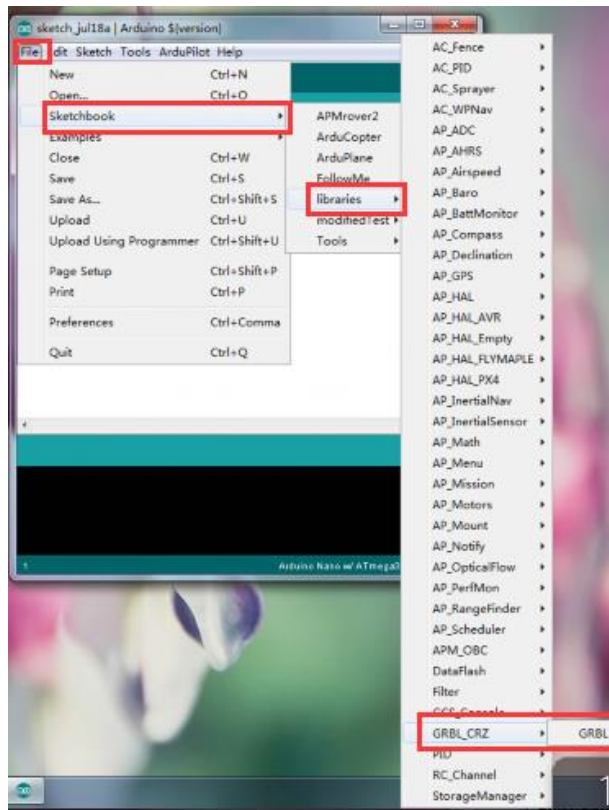
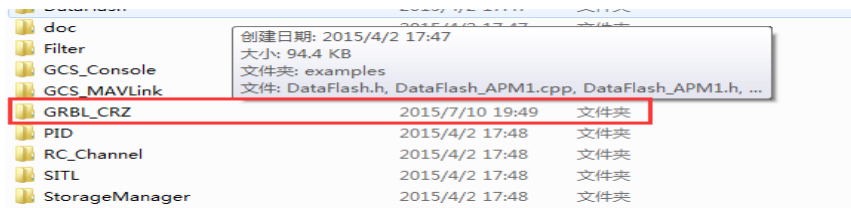


```
Done burning bootloader.  
avrduide done. Thank you.
```

Loading the driving code

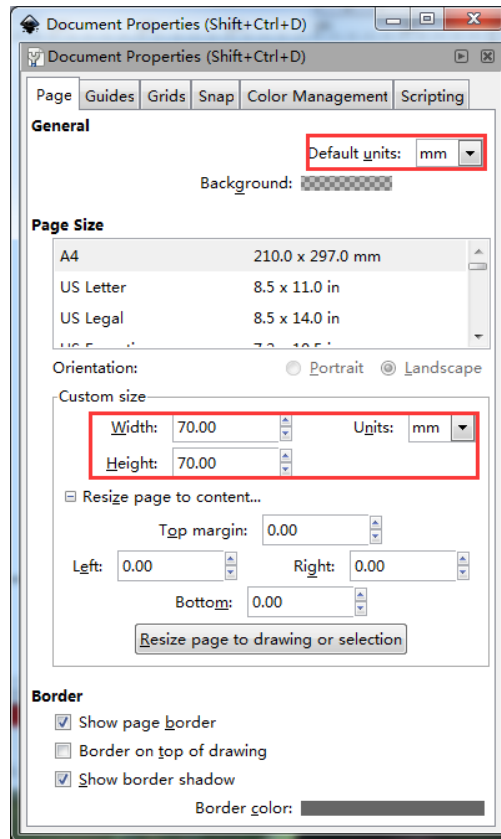


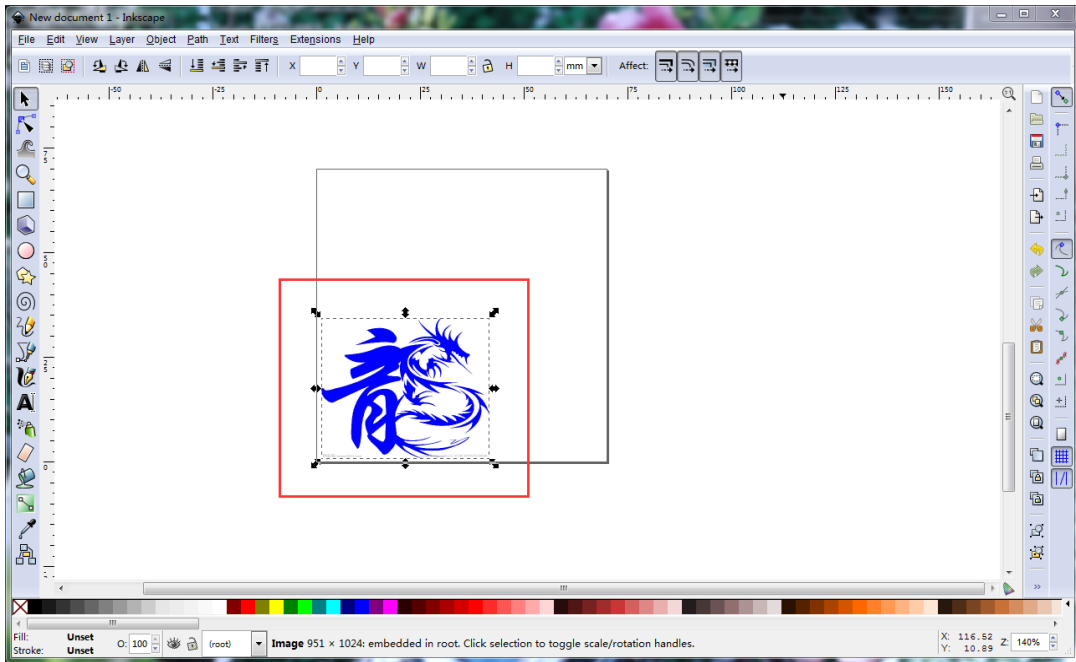
- 端口 (COM 和 LPT)
- USB-SERIAL CH340 (COM9)

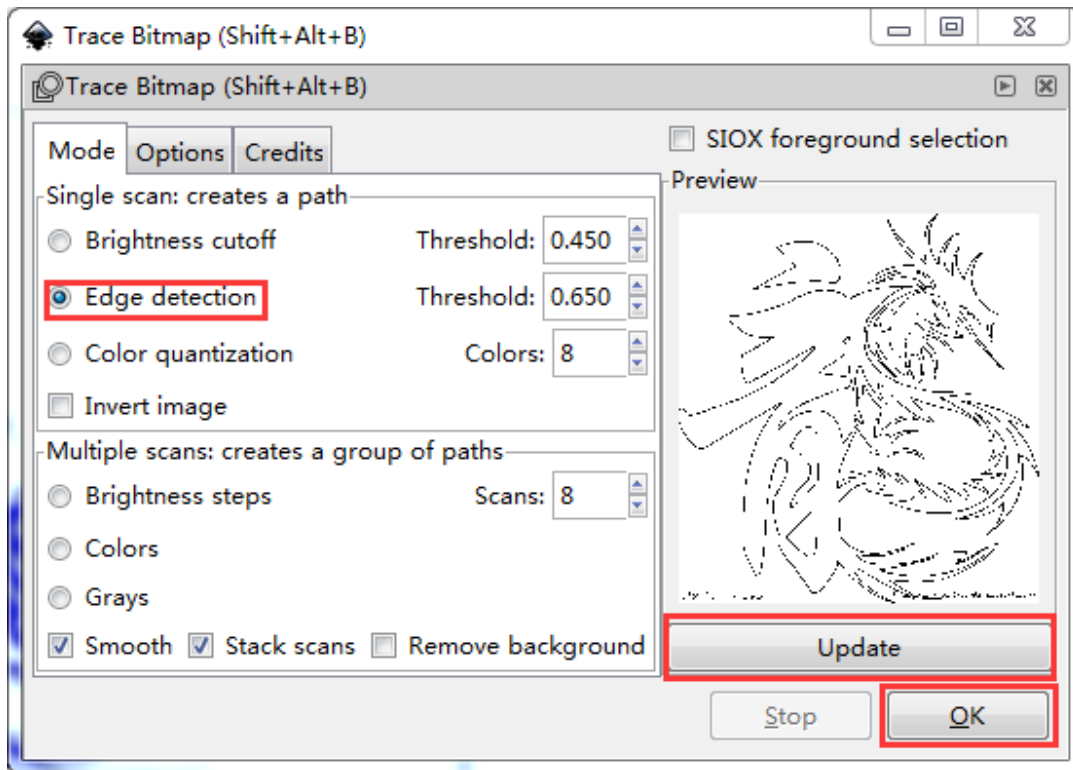


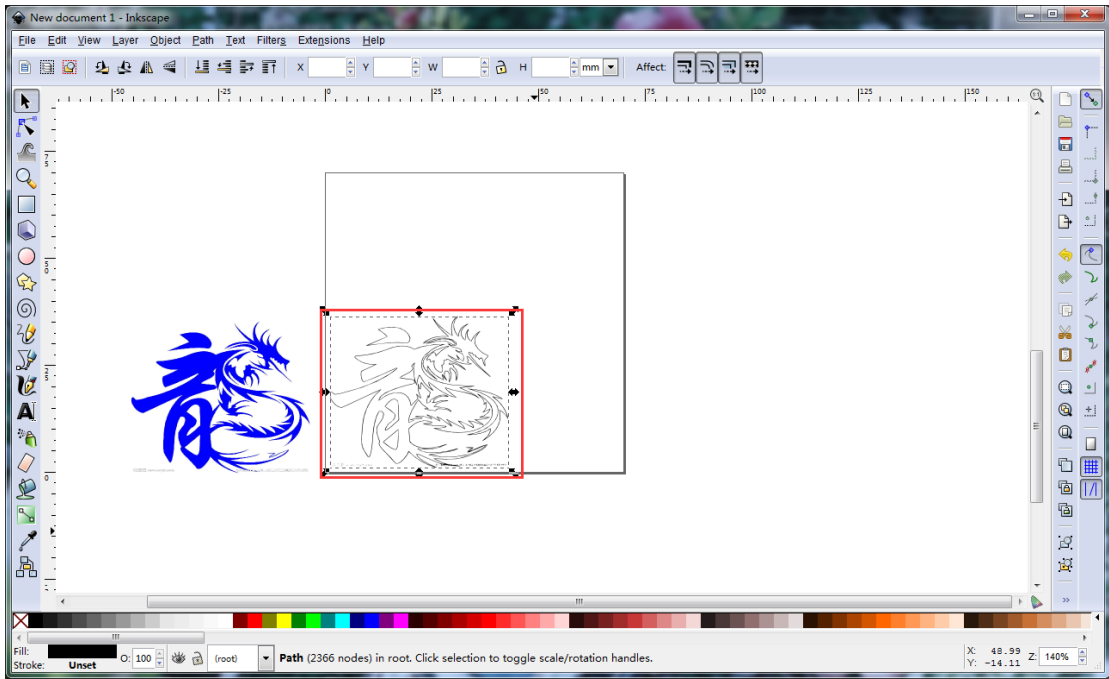
Done compiling.

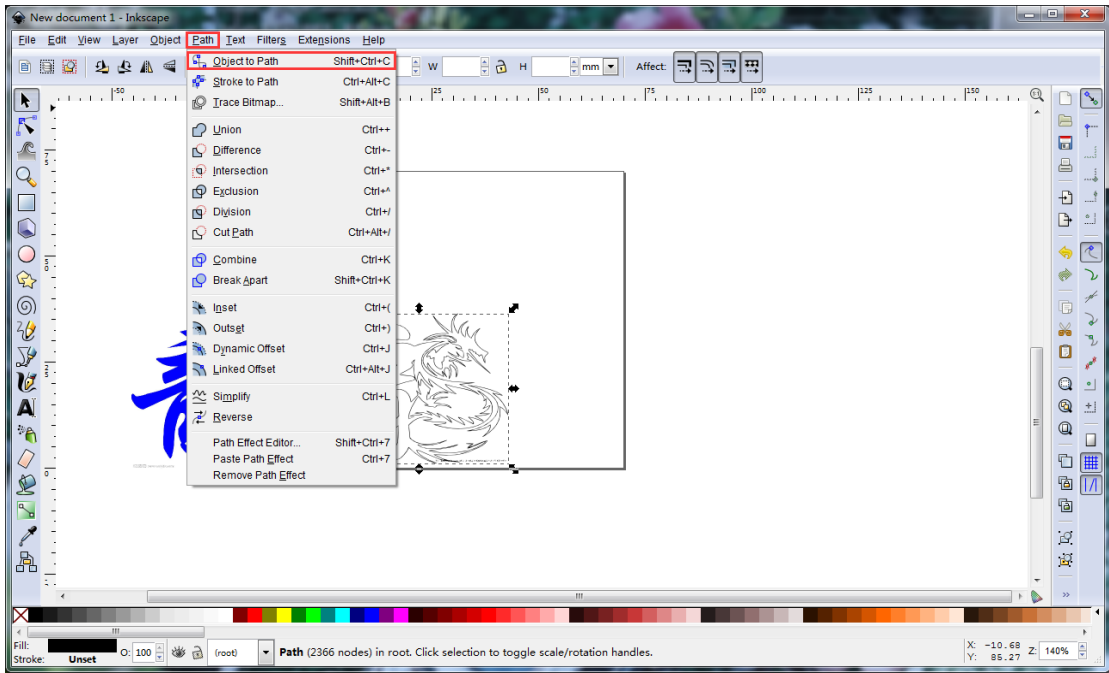
Generate the G code

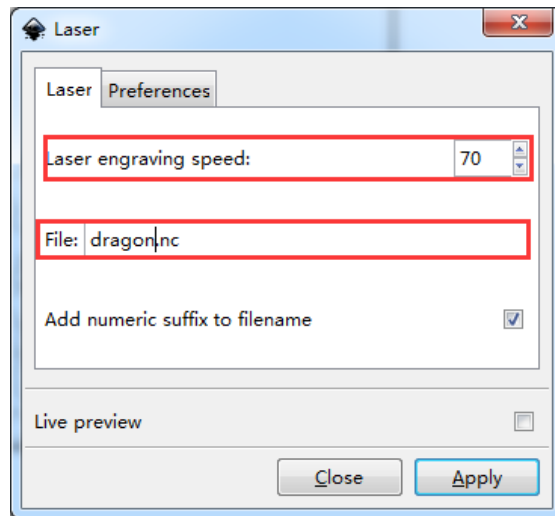
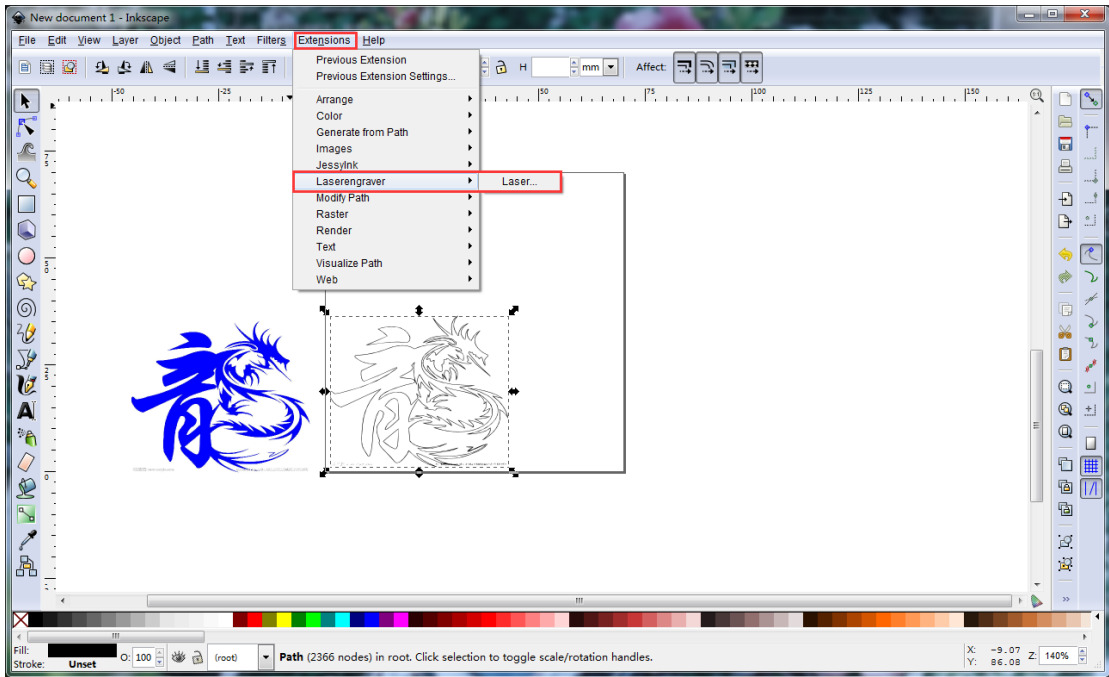


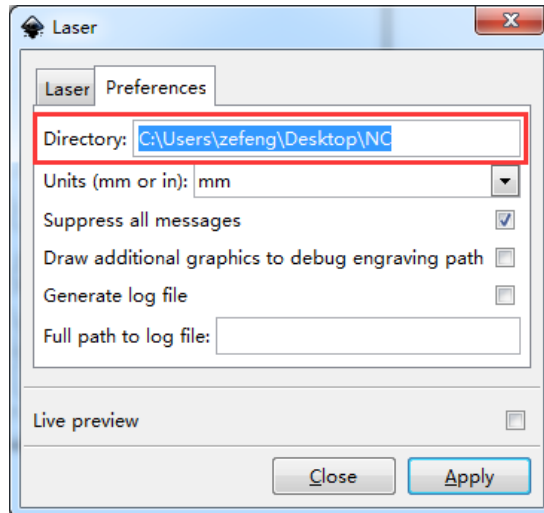












Beginning the engraving process

The screenshot shows the Grbl Controller 3.6.1 interface. The 'Port name' is set to 'ttyUSB0' (step 1). The 'Baud Rate' is set to '9600' (step 2). The 'Send File' field contains the path '/home/bananapi/Desktop/NC/dragon_0001.nc' (step 3). The 'Choose file' button is highlighted (step 4). The 'Begin' button is highlighted (step 7). The 'Zero Position' button is highlighted (step 5). The 'Refresh Pos' button is highlighted (step 6). The 'Machine Coordinates' and 'Work Coordinates' are both at 0.000 mm. The 'Visualizer' tab shows a blue line drawing of a dragon on a yellow background. The 'Command' window shows the following commands: > G1 x0 y0 z0, > G92 x0 y0 z0, > G92 x0 y0 z0, > G92 x0 y0 z0, > G92 x0 y0 z0, Spindle On., Spindle Off., > M03, > M05.

step1:select the Port name ttyUSB0/ttyUSB1

step2:set the Baud Rate be 9600

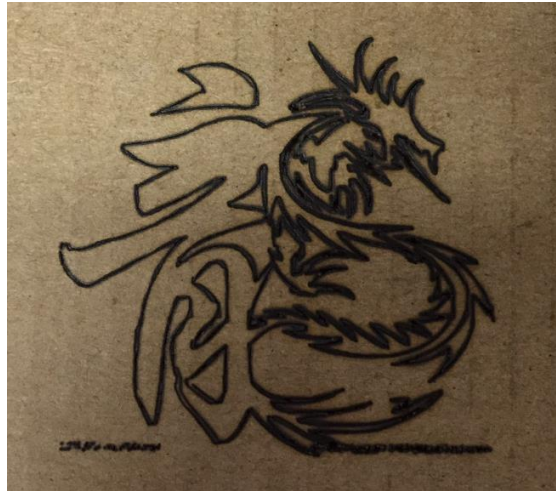
step3:click Open

step4:click Choose file to select the file "dragon_0001.nc"

step5:click Zero Position

step6:click Refresh Pos

step7:click Begin to start engraving.



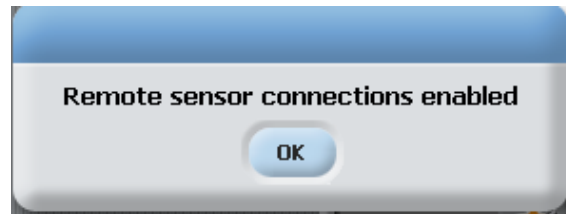
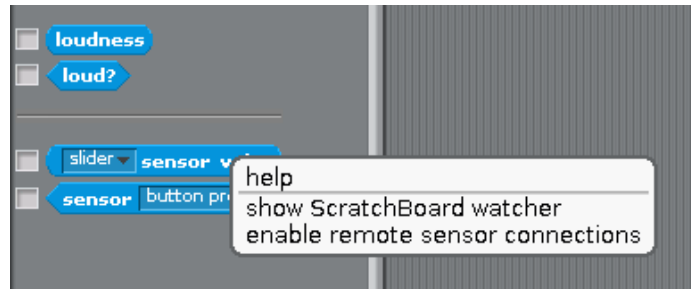
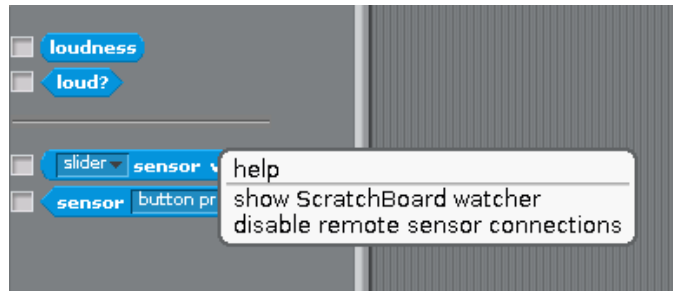
8

Scratch—Building a Smart House

Running LeScratch

```
Connecting..  
Scratch not up. Sleeping for 5 and trying again.  
Connecting..  
Scratch not up. Sleeping for 5 and trying again.  
Connecting..  
Scratch not up. Sleeping for 5 and trying again.  
Connecting..
```

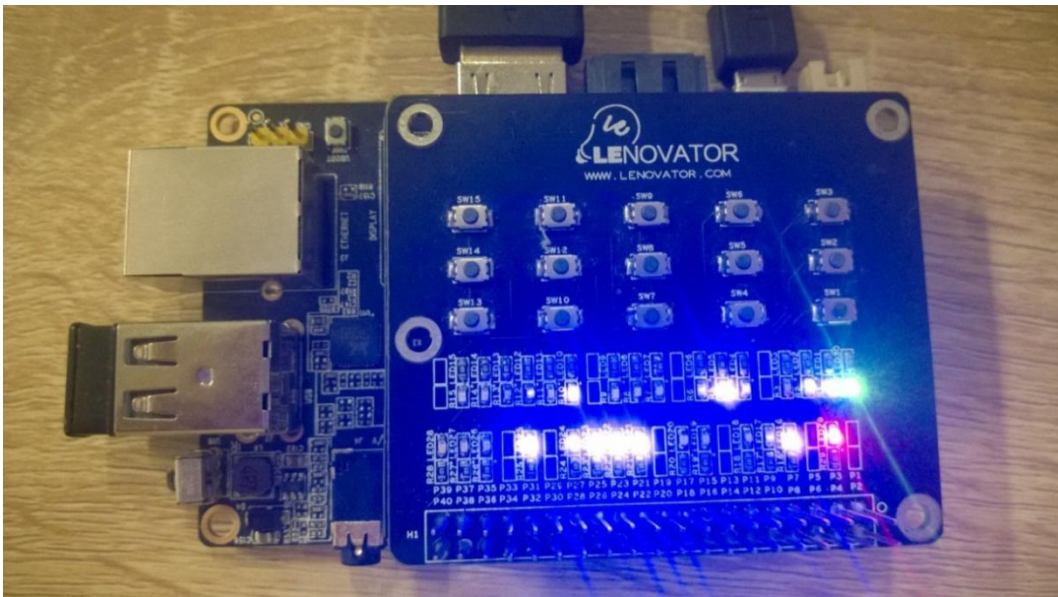




```
Connecting...  
Connected!  
Reconnected.
```

```
Connecting...  
Connected!  
USB_HUB  
I2CButton  
PCF8591  
UltraSonic  
DHTreader  
RTC  
TiltSensor  
LNdigital  
StepMotor  
SoundDetect  
LCD1602  
TouchSensor  
I0board  
LightSensor
```

Example – The GPIO board



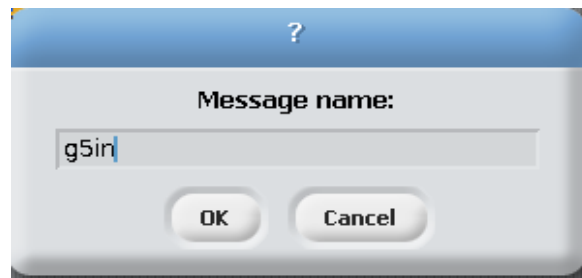
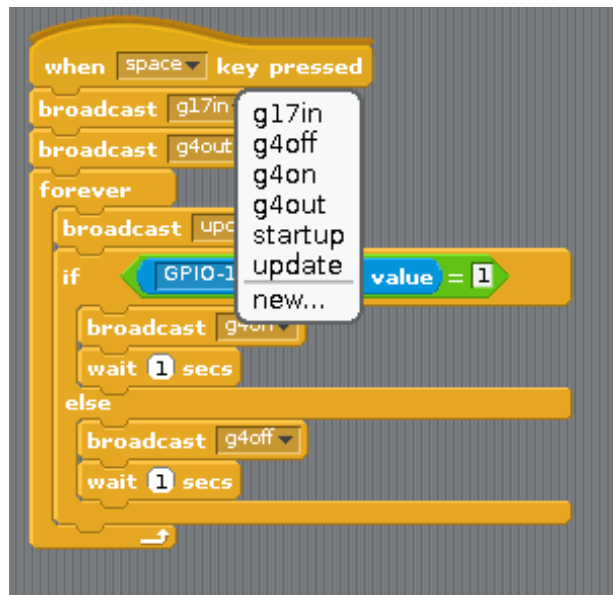
```
when clicked
broadcast g17out
forever
broadcast g17on
wait 1 secs
broadcast g17off
wait 1 secs
```

```
when space key pressed
broadcast g17in
broadcast g4out
forever
broadcast update
if GPIO-17 sensor value = 0
broadcast g4on
wait 1 secs
else
broadcast g4off
wait 1 secs
```

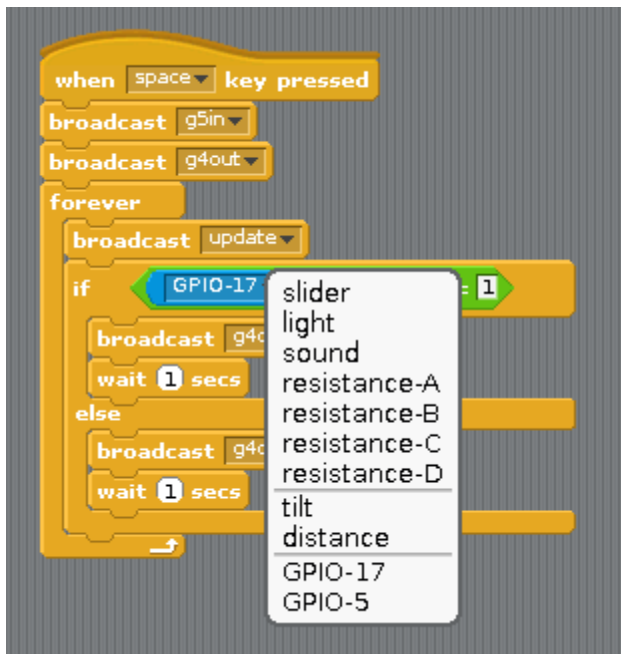
```
when clicked
broadcast g12out g13out g19out g16out g6out
forever
broadcast g12on g13on g19on g16on g6on
wait 1 secs
broadcast g12off g13off g19off g16off g6off
wait 1 secs
```

```
when space key pressed
broadcast g17in
broadcast g4out
forever
broadcast update
if GPIO-17 = 1
broadcast g4o
wait 1 secs
else
broadcast g4o
wait 1 secs
```

- slider
- light
- sound
- resistance-A
- resistance-B
- resistance-C
- resistance-D
- tilt
- distance
- GPIO-17

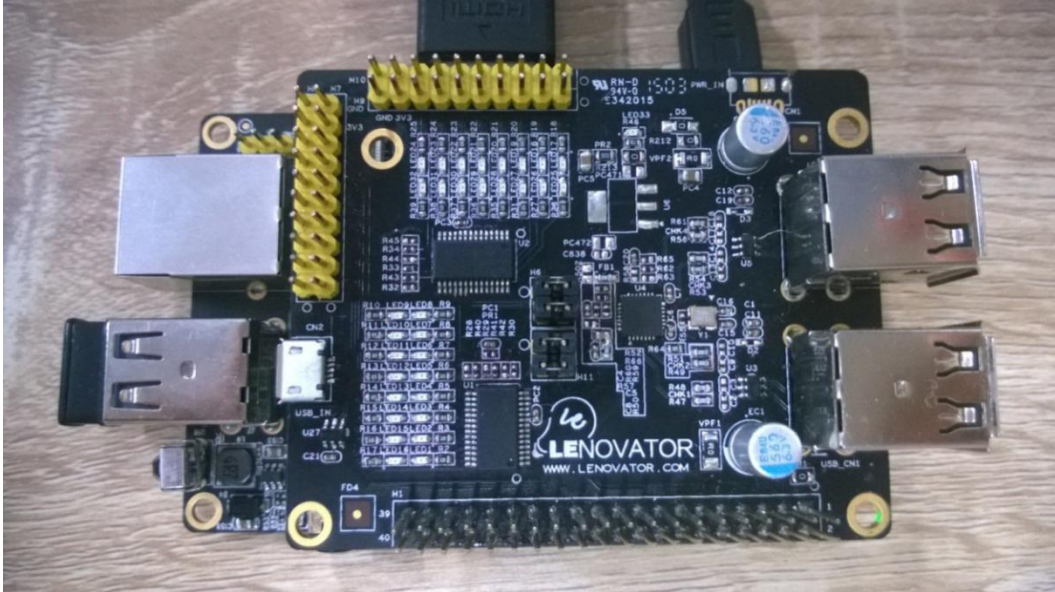


```
pin: 5 -> 1
pin: 17 -> 0
4 set to OFF
pin: 5 -> 1
pin: 17 -> 0
4 set to OFF
pin: 5 -> 1
pin: 17 -> 0
```



The image shows a Scratch script for controlling GPIO pins. It starts with a 'when space key pressed' event block. This is followed by two 'broadcast' blocks: 'g5in' and 'g4out'. A 'forever' loop contains a 'broadcast update' block, an 'if' block, and another 'broadcast update' block. The 'if' block checks 'GPIO-17 = 1'. If true, it broadcasts 'g4c', waits 1 second, and broadcasts 'g4d'. If false, it broadcasts 'g4c' and waits 1 second. A dropdown menu is open over the 'GPIO-17 = 1' block, listing various sensor types: slider, light, sound, resistance-A, resistance-B, resistance-C, resistance-D, tilt, distance, GPIO-17, and GPIO-5.

Example – A USB Hub

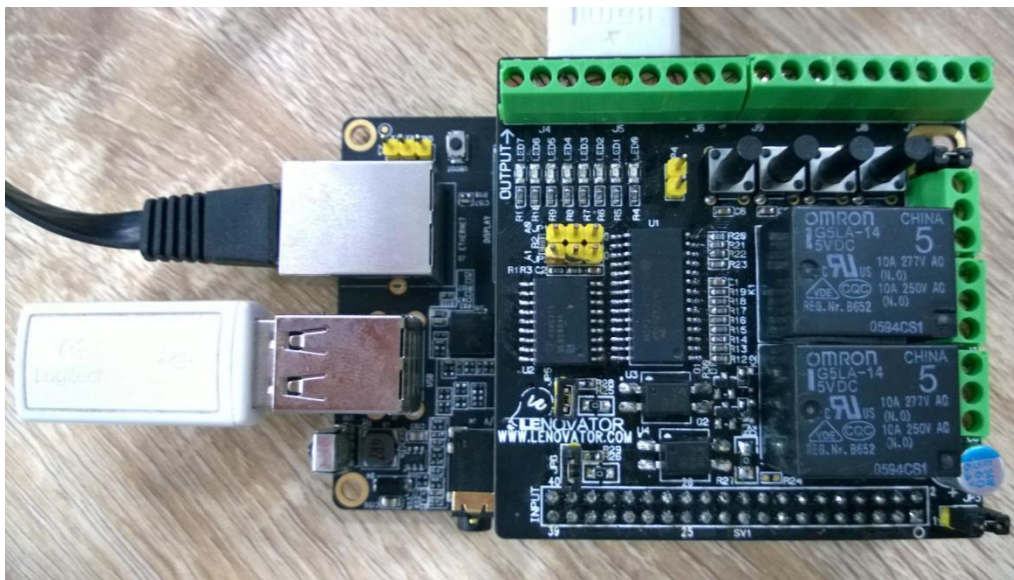


```
when a key pressed
broadcast bit24a00000000
broadcast bit24b00000000
broadcast bit26a00000000
broadcast bit26b00000000
forever
broadcast bit24a10010111
broadcast bit24b01101000
```

```
when down arrow key pressed
broadcast bit24adr bit24bdr
broadcast bit26adr bit26bdr
stop all
```

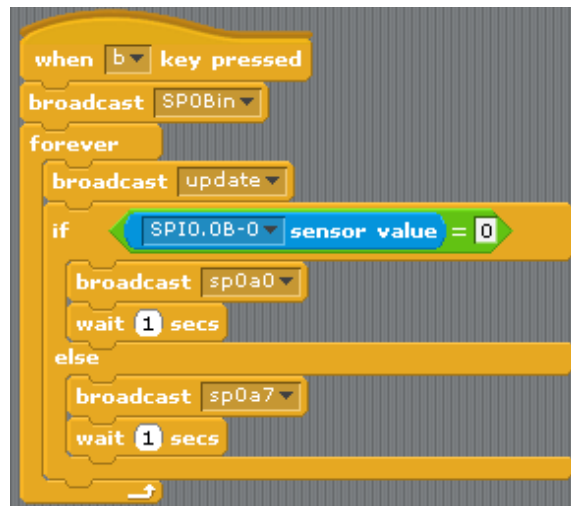
```
when b key pressed
broadcast bit24a00000000
broadcast bit24b00000000
broadcast bit26a00000000
broadcast bit26b00000000
forever
broadcast i224a4 i224a7
wait 1 secs
broadcast i224b1 i224b6
```

Serial Peripheral Interface (SPI)



The image shows two identical Scratch code blocks side-by-side. Each block starts with a 'when clicked' event trigger. This is followed by a 'forever' loop containing four steps: a 'broadcast bits0aon' block, a 'wait 1 secs' block, a 'broadcast bits0aoff' block, and another 'wait 1 secs' block. The right-hand block has a 'broadcast bits0aclr' block instead of 'bits0aoff'.

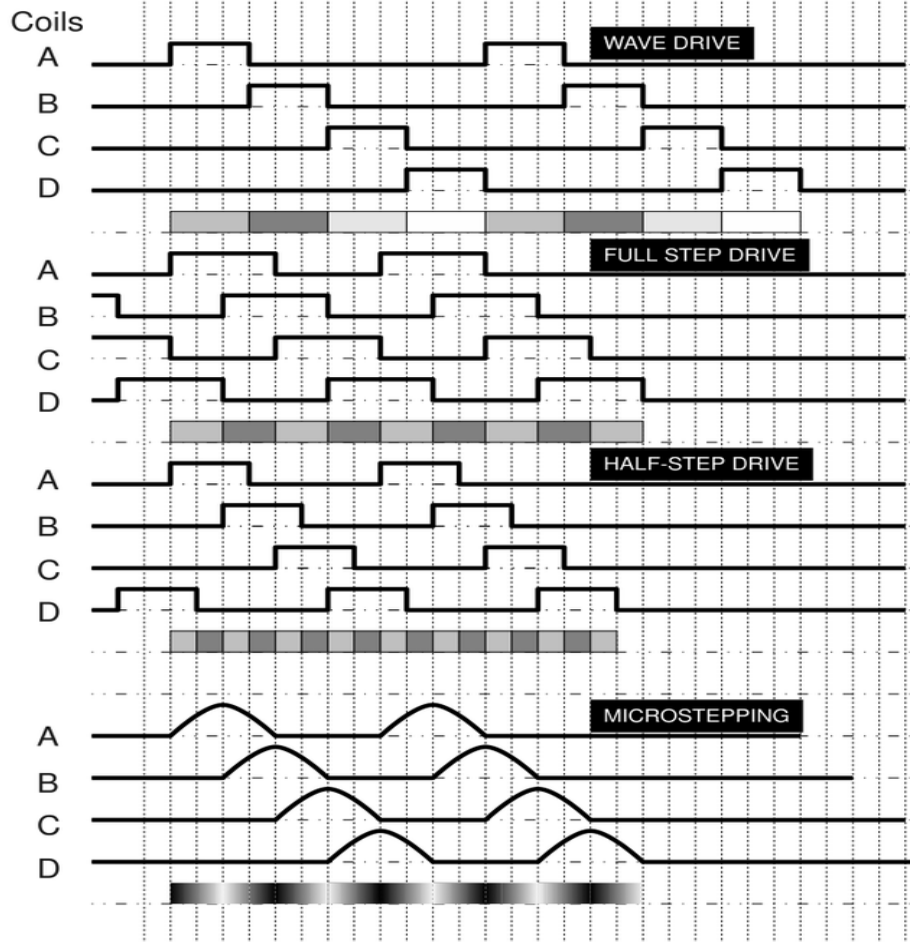
The image shows a single Scratch code block starting with a 'when a key pressed' event trigger. It is followed by a 'broadcast SP0Bin' block. A 'forever' loop contains the following steps: a 'broadcast update' block, an 'if' block with the condition 'SPI0.08-0 sensor value = 0', a 'broadcast bits0a10010110' block, a 'wait 1 secs' block, an 'else' block, a 'broadcast bits0a01101001' block, and another 'wait 1 secs' block.



Example: LN Digital (the LNDI commands)

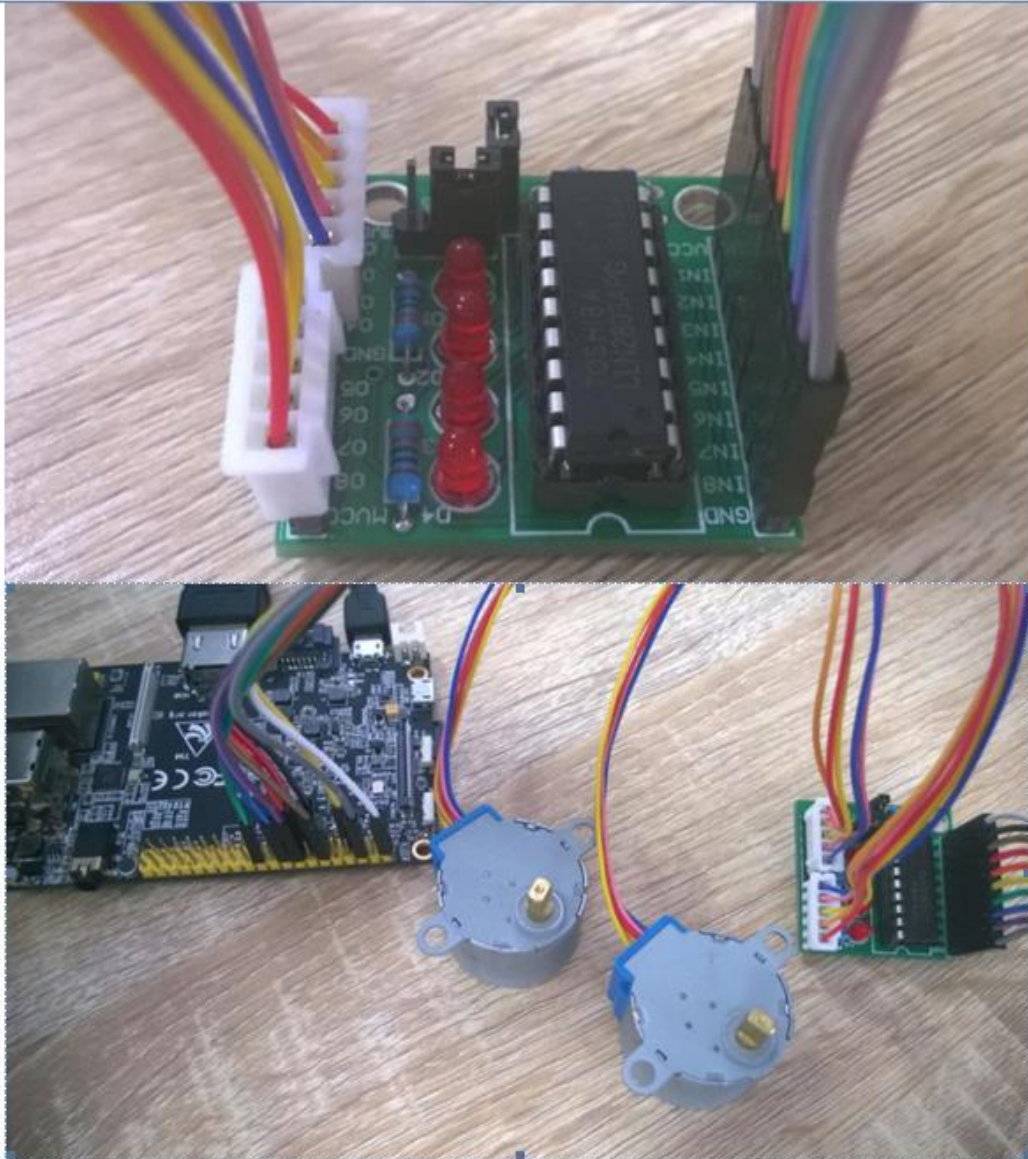


Unipolar motor



Example – the step motor

GND	IN1	IN2	IN3	IN4	IN5	IN6	IN7	IN8	VCC
PIN 6	PIN 23	PIN 26	PIN 36	PIN 37	PIN 7	PIN 22	PIN 18	PIN 16	PIN 2



stepM5A256P ▾

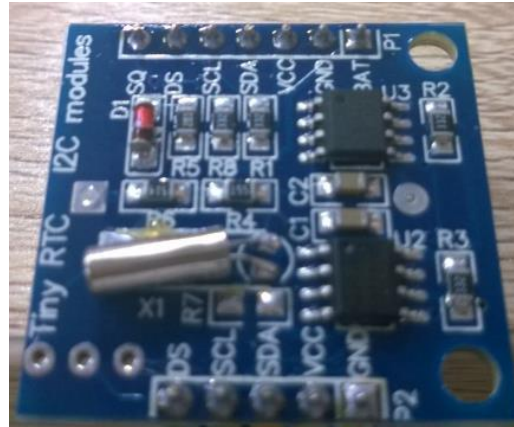


A Scratch script snippet on a grey background. It starts with a yellow 'when clicked' block with a green flag icon. Below it are two 'broadcast' blocks: the first with 'stepMAinit' and the second with 'stepMBinit'. A 'forever' loop block contains four 'broadcast' blocks: 'stepM5A256P', 'stepM5A256N', 'stepM5B256P', and 'stepM5B256N'. A small white arrow points to the right at the bottom of the loop.

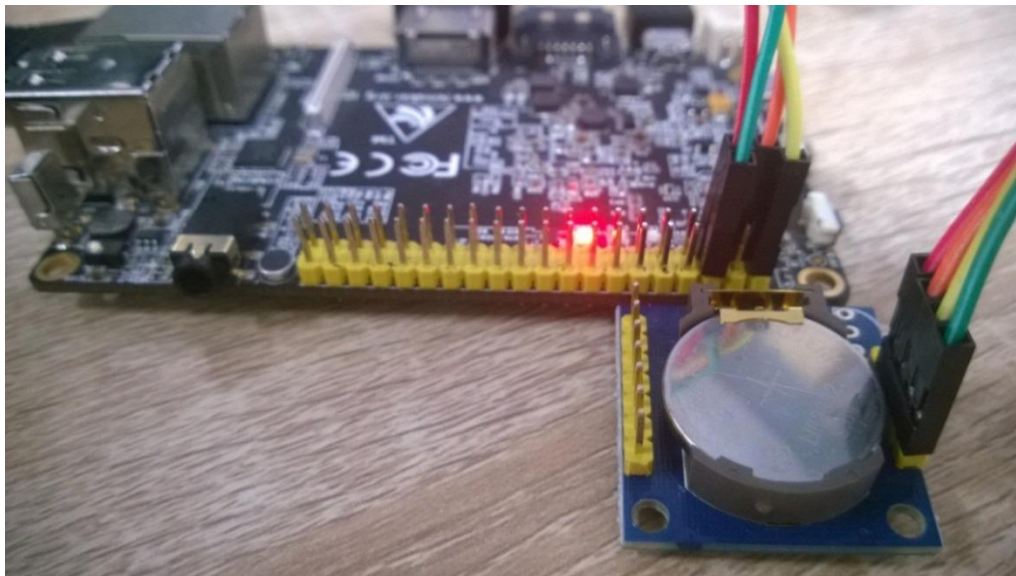


A Scratch script snippet on a grey background. It starts with a yellow 'when clicked' block with a green flag icon. Below it are two 'broadcast' blocks: the first with 'stepMAinit' and the second with 'stepMBinit'. A 'forever' loop block contains two 'broadcast' blocks: 'stepMode1A' and 'stepMode2B'. A small white arrow points to the right at the bottom of the loop.

Technical specifications



Example – RTC



Sprite1

x: 0 y: 0 direction: 90

Costumes Sounds

```

when clicked
broadcast RTC
forever
broadcast update
wait 10 secs

```

RTC

Year sensor value <input type="text" value="15"/>	Hour sensor value <input type="text" value="8"/>
Month sensor value <input type="text" value="5"/>	Minutes sensor value <input type="text" value="55"/>
Date sensor value <input type="text" value="20"/>	Seconds sensor value <input type="text" value="16"/>
Day sensor value <input type="text" value="3"/>	

bananapi@lemaker: ~/LeScratch_test

File Edit Tabs Help

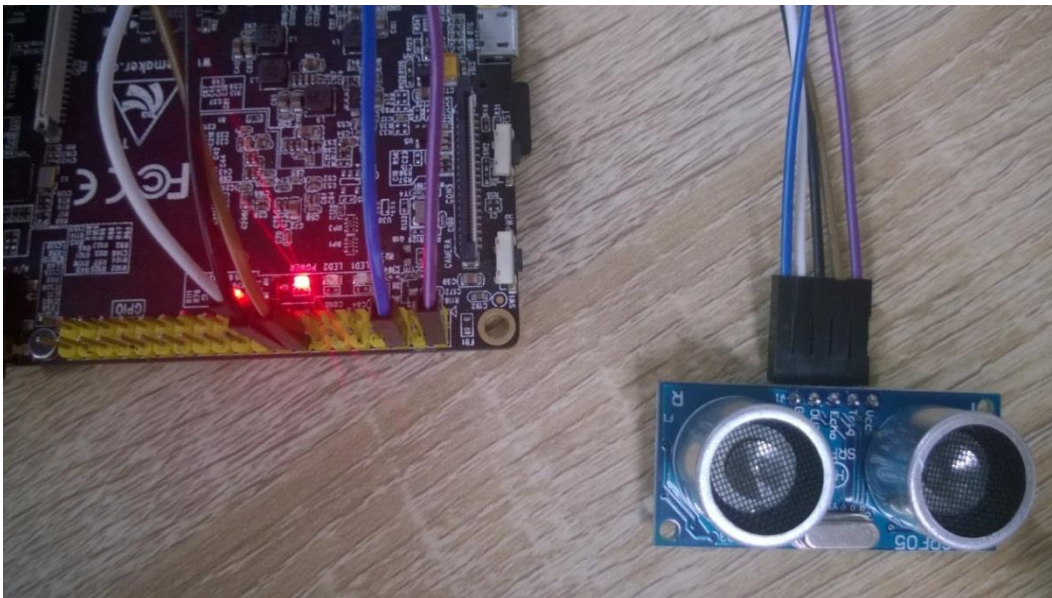
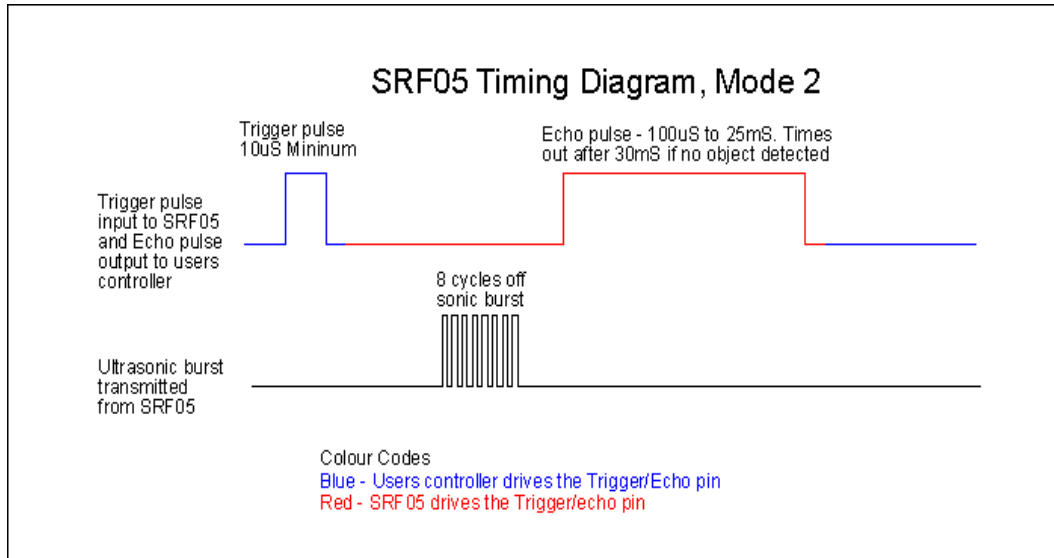
```

Paths match, Continue.
Connecting...
Connected!
StepMotor
DHTreader
IOboard
UltraSonic
SoundDetect
RTC
LNdigital
USB_HUB
PCF8591
I2CButton

DS1307 =                2015-05-20 08:54:46
System Time = 2015-05-20 08:54:46
DS1307 =                2015-05-20 08:54:56
System Time = 2015-05-20 08:54:56
DS1307 =                2015-05-20 08:55:06
System Time = 2015-05-20 08:55:06
DS1307 =                2015-05-20 08:55:16
System Time = 2015-05-20 08:55:16

```

Example – the ultrasonic sensor



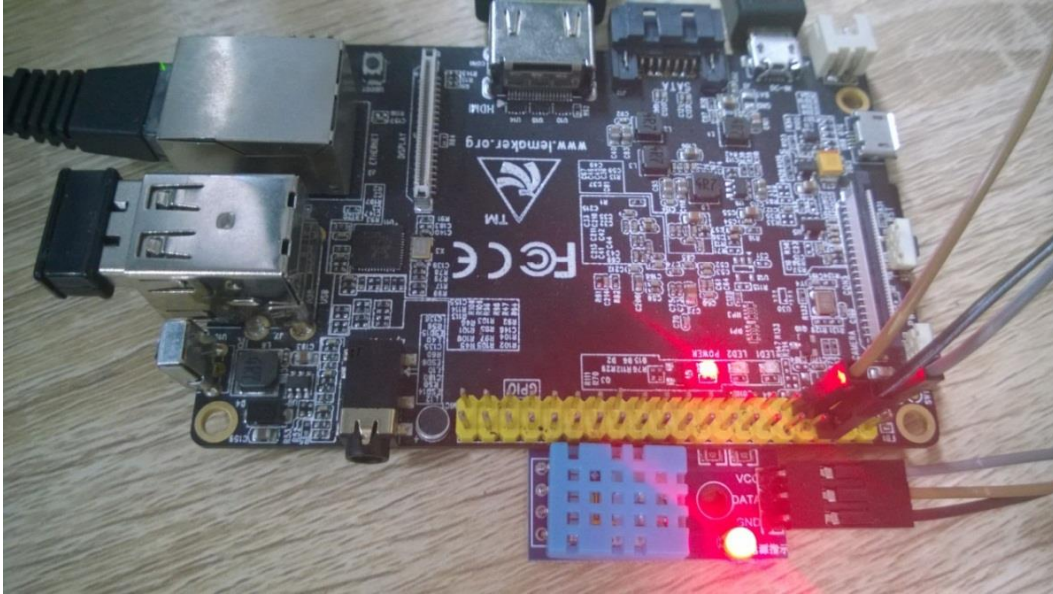
The image shows a Scratch project window on the left and a terminal window on the right. The Scratch window displays the following code for 'Sprite1':

```
when space key pressed
  broadcast Trigger23
  broadcast Echo24
  forever loop
    broadcast update
    broadcast UltraSonic
    wait 1 secs
```

The terminal window, titled 'UltraSonic', shows the output of the program. It displays a series of log messages for each sensor reading, including the distance measurement, the sensor name, and the time taken for the measurement. The current sensor value is shown as 66.3.

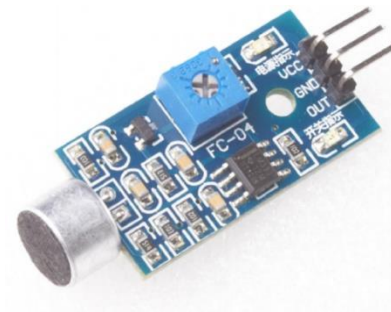
```
UltraSonic sensor value 66.3
bananapi@lemaker: ~/LeScratch_test
File Edit Tabs Help
The distance measurement of UltraSonic: 66.8327212334
UltraSonic time 0.00387192
The distance measurement of UltraSonic: 66.4033889771
UltraSonic time 0.00389385
The distance measurement of UltraSonic: 66.7795658112
UltraSonic time 0.00387001
The distance measurement of UltraSonic: 66.370677948
UltraSonic time 0.00389695
The distance measurement of UltraSonic: 66.8327212334
UltraSonic time 0.00389004
The distance measurement of UltraSonic: 66.7141437531
UltraSonic time 0.00391984
The distance measurement of UltraSonic: 67.225253582
UltraSonic time 0.00392103
The distance measurement of UltraSonic: 67.2456979752
UltraSonic time 0.00389385
The distance measurement of UltraSonic: 66.7795658112
UltraSonic time 0.00389814
The distance measurement of UltraSonic: 66.8531656265
UltraSonic time 0.00392008
The distance measurement of UltraSonic: 67.2293424606
UltraSonic time 0.00386906
The distance measurement of UltraSonic: 66.3543224335
```

Example – the DHT sensor

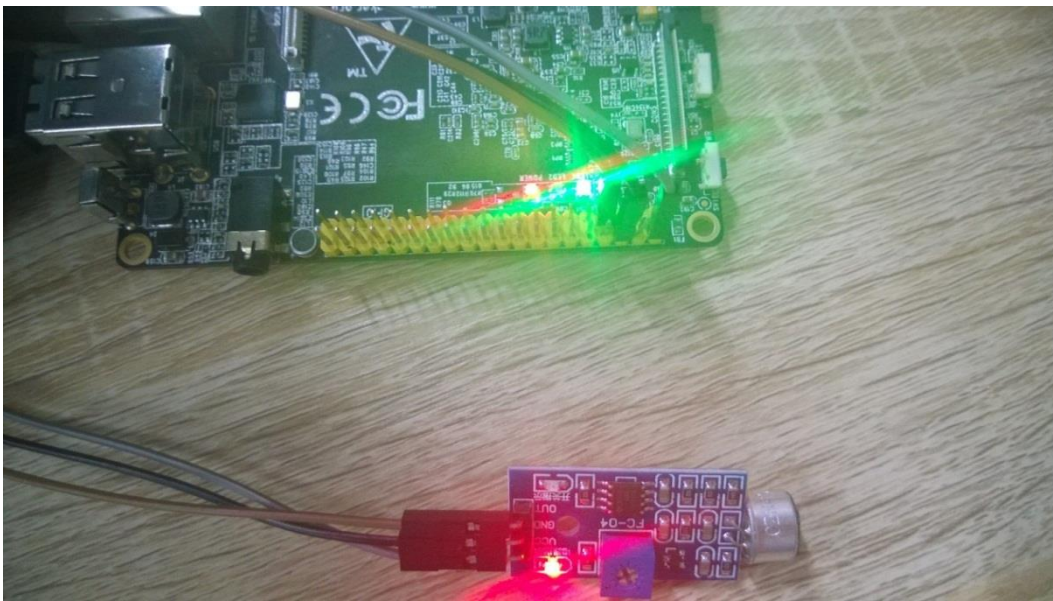


The image shows a Scratch script on the left and a terminal window on the right. The Scratch script is for a sprite named 'Sprite1' and consists of the following blocks: 'when clicked', 'broadcast DHT11pin7', a 'forever' loop containing 'broadcast update' and 'wait 1 secs'. The terminal window, titled 'DHTsensor', shows the output of the script. It displays the temperature and humidity values: 'Temperature sensor value 28.0' and 'Humidity sensor value 57.0'. The terminal also shows a series of log messages: 'Failed to read from sensor, restart.' followed by 'Temperature = 28.0 *C, Humidity = 57.0 %'.

Technical specifications



Example – the sound detect sensor



The image shows a Scratch workspace on the left and a terminal window on the right. The Scratch workspace has a sprite named "Sprite1" with coordinates (0, 0) and a direction of 90 degrees. The script area contains the following code:

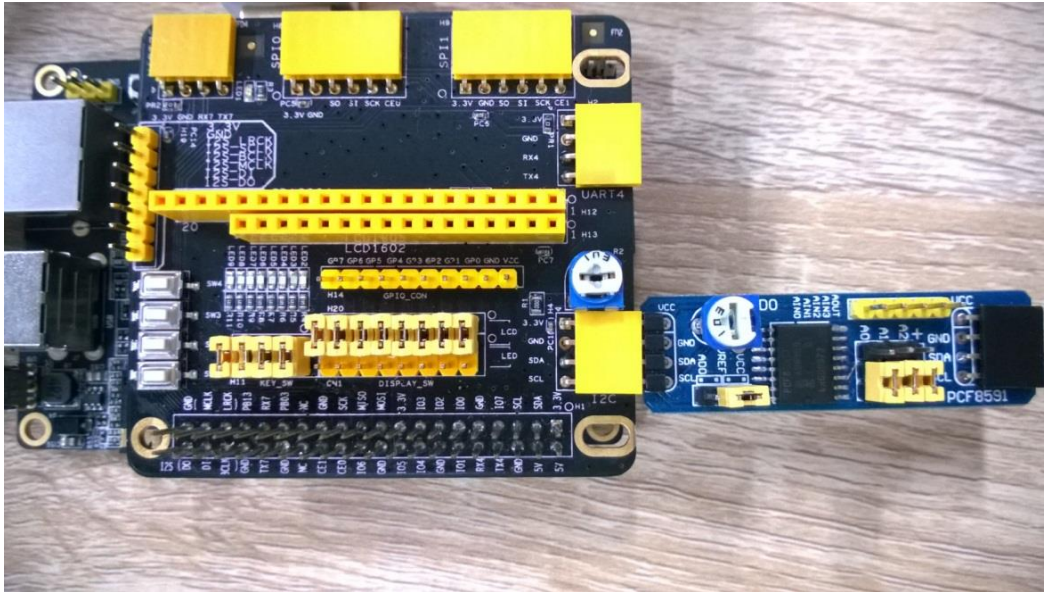
```
when green flag clicked
  broadcast to all soundDetect
  broadcast to all sound4
  forever loop
    broadcast to all update
```

The terminal window, titled "soundDetect", shows the following output:

```
bananapi@lemaker: ~/LeScratch_test
File Edit Tabs Help
Paths match, Continue.
Connecting...
Connected!
StepMotor
DHTreader
IOboard
UltraSonic
SoundDetect
RTC
LNdigital
USB_HUB
PCF8591
I2CButton

SoundDetect device is added.
The value of Pin 4 is 1
Sound is detected on GPIO 4
Sound is detected on GPIO 4
Sound is detected on GPIO 4
Sound is detected on GPIO 4
Sound is detected on GPIO 4
Sound is detected on GPIO 4
Sound is detected on GPIO 4
```

Example – the AD/DA convertor



The screenshot shows the Scratch IDE interface. On the left, there are two scripts for 'Sprite1':

- Script 1: **when green flag clicked** → **broadcast PCF8591** → **forever** loop containing **broadcast AD0read** and **wait 1 secs**.
- Script 2: **when green flag clicked** → **broadcast PCF8591** → **forever** loop containing **broadcast DA255write** and **wait 1 secs**.

On the right, the **IOboard** window shows the following data:

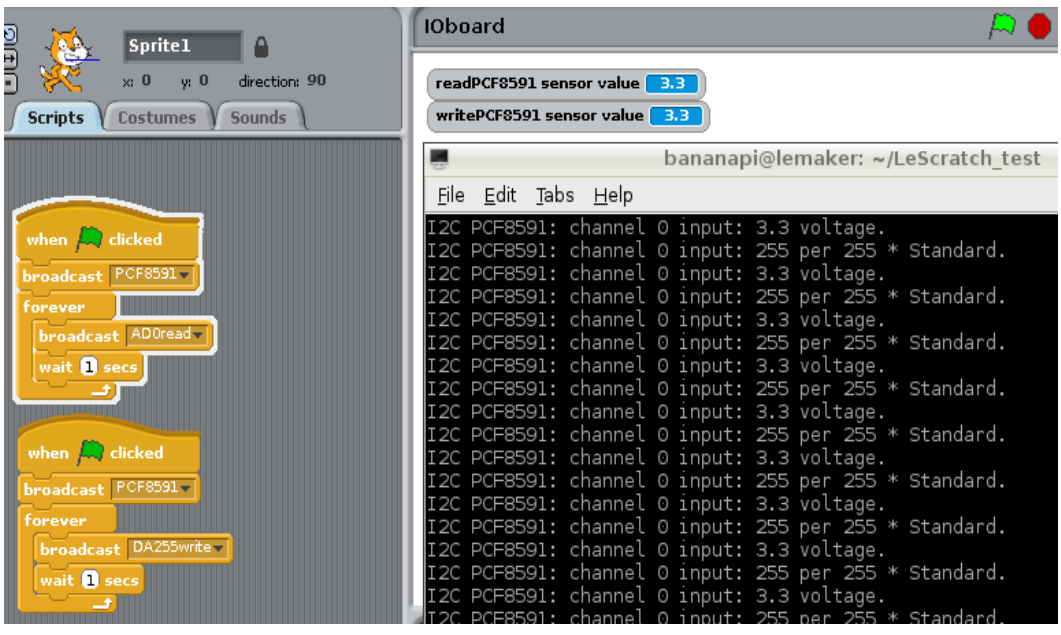
- readPCF8591 sensor value**: 3.3
- writePCF8591 sensor value**: 3.3

Below the IOboard is a terminal window titled **bananapi@lemaker: ~/LeScratch_test**. It displays the following output:

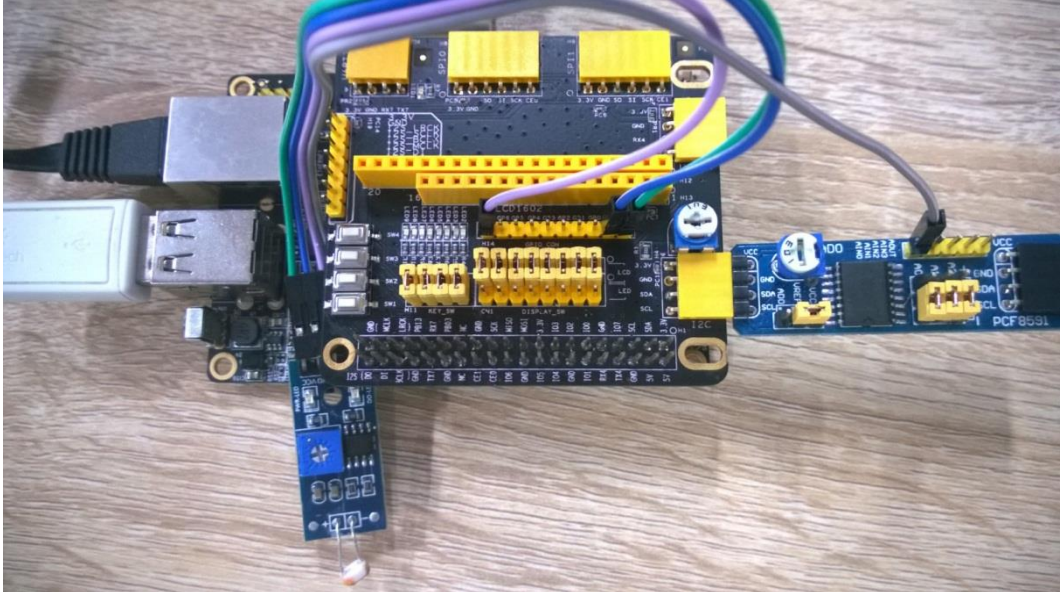
```
File Edit Tabs Help
I2C PCF8591: analog output: 3.3 voltage.
I2C PCF8591: analog output: 255 per 255 * Standard.
I2C PCF8591: analog output: 3.3 voltage.
I2C PCF8591: analog output: 255 per 255 * Standard.
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```

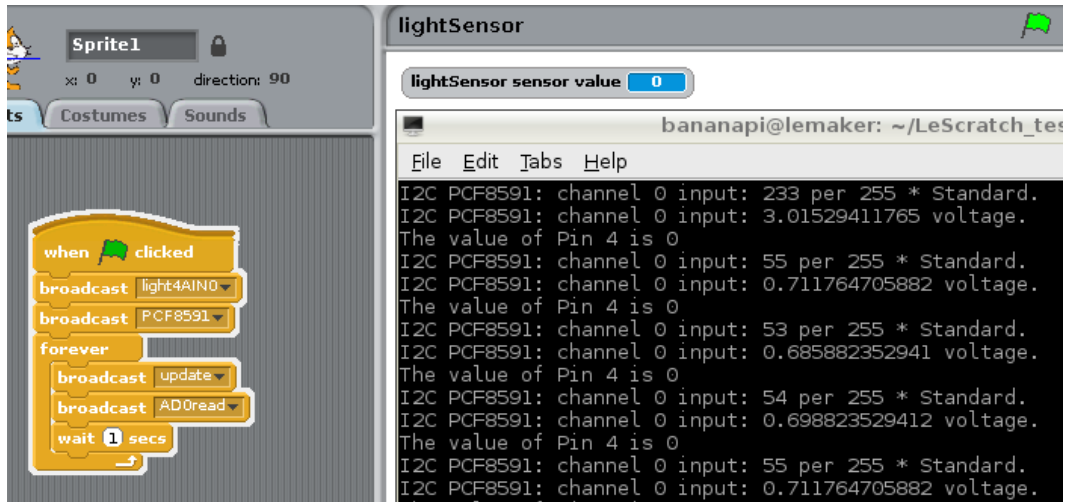
This is a close-up of the first script in the Scratch IDE. It consists of the following blocks:

- when green flag clicked**
- broadcast PCF8591**
- forever** loop containing:
 - broadcast AD0read**
 - wait 1 secs**

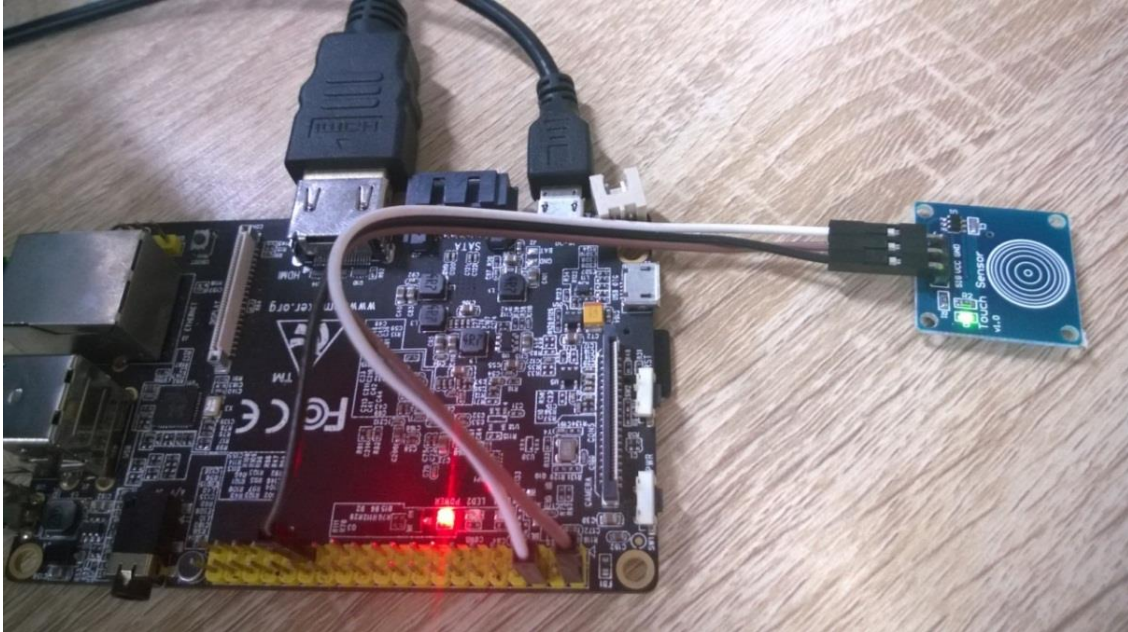


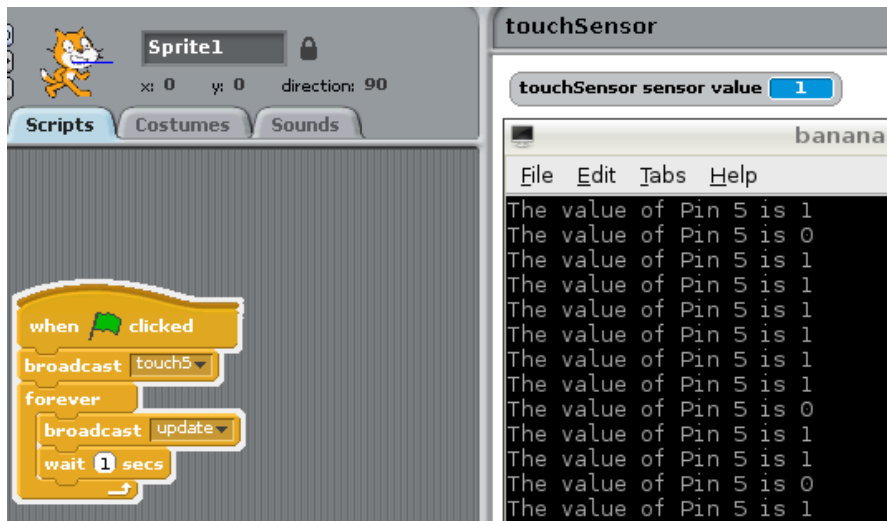
Example – Photoresistor



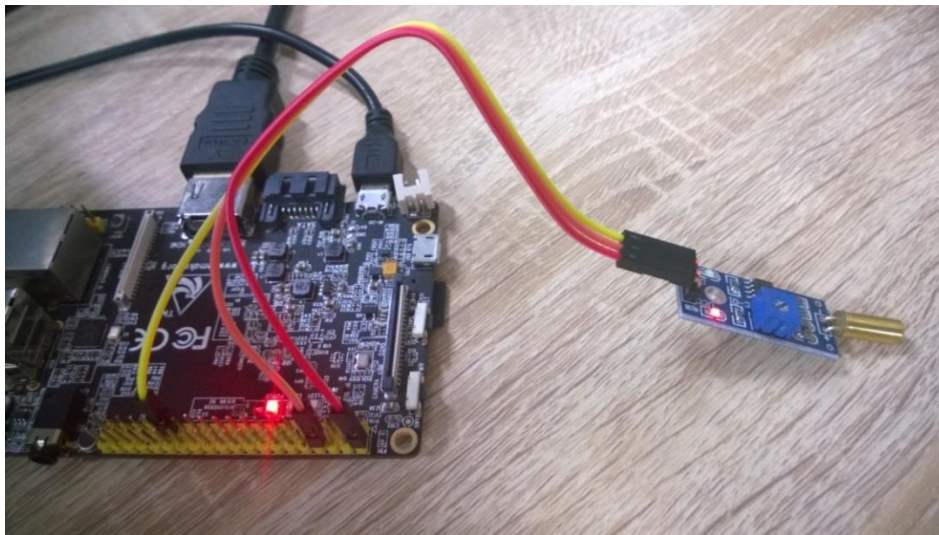


Technical specifications





Example – the tilt sensor





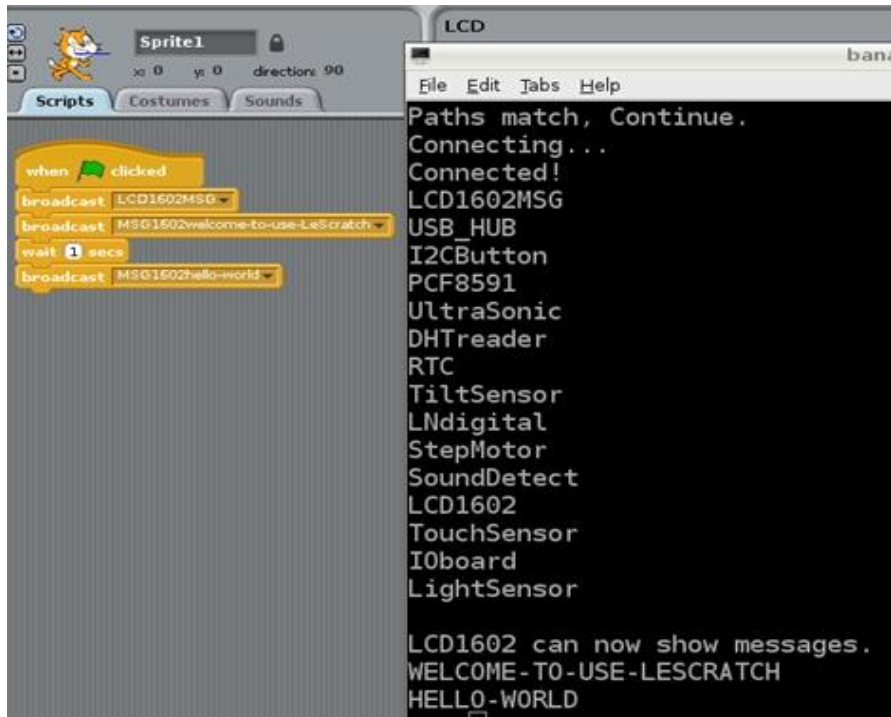
The screenshot shows the Scratch IDE interface. On the left, the "Sprite1" panel shows a green flag icon and coordinates (x: 0, y: 0, direction: 90). The "Scripts" area contains the same code block as shown in the previous image. On the right, a terminal window titled "tiltSensor" is open, displaying the output of a sensor. The terminal shows a series of lines: "tiltSensor sensor value" followed by the number "1" in a blue box. Below that, the terminal output shows "Tilt detect on GPIO 10 is 1" and "Tilt detect on GPIO 10 is 0" alternating.

Technical specifications

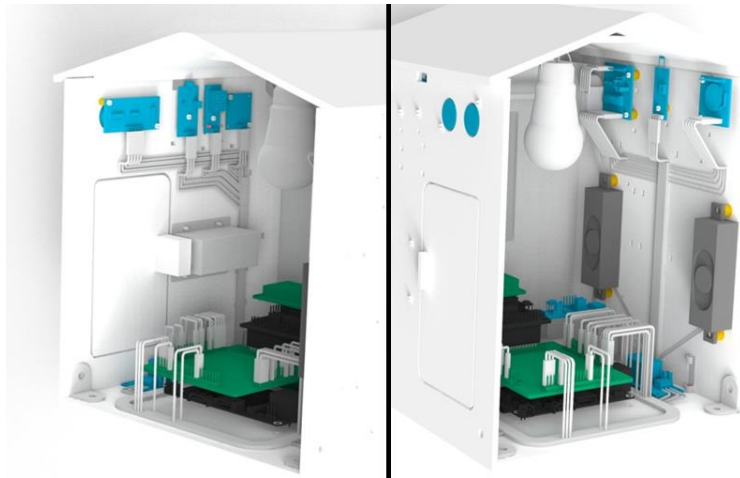
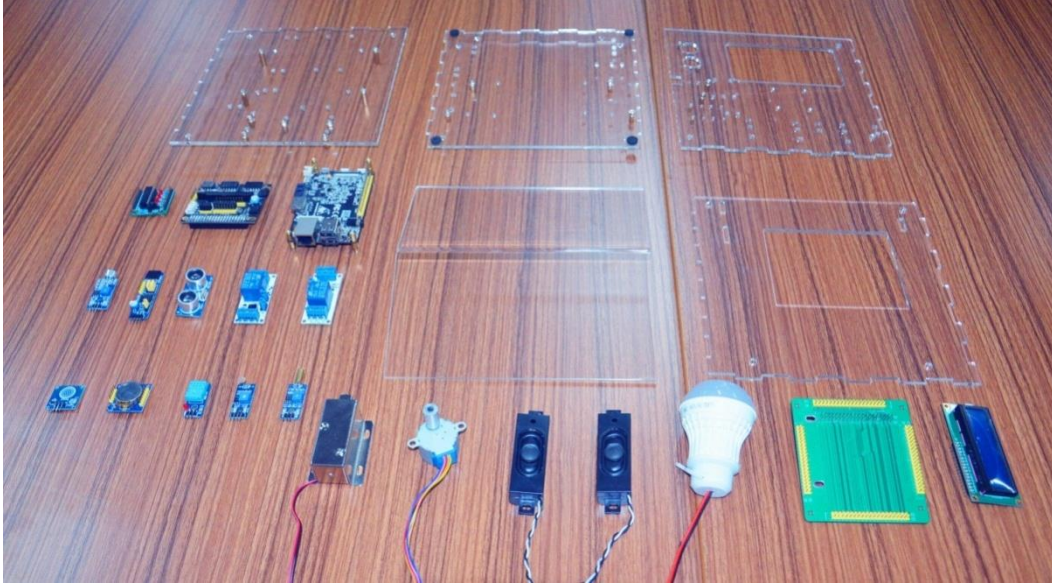
No.	Symbol	Level	Function
1	Vss	--	0V
2	Vdd	--	+5V
3	V0	--	for LCD
4	RS	H/L	Register Select: H:Data Input L:Instruction Input
5	R/W	H/L	H--Read L--Write
6	E	H.H-L	Enable Signal
7	DB0	H/L	Data bus used in 8 bit transfer
8	DB1	H/L	
9	DB2	H/L	
10	DB3	H/L	
11	DB4	H/L	Data bus for both 4 and 8 bit transfer
12	DB5	H/L	
13	DB6	H/L	
14	DB7	H/L	
15	BLA	--	BLACKLIGHT +5V
16	BLK	--	BLACKLIGHT 0V-

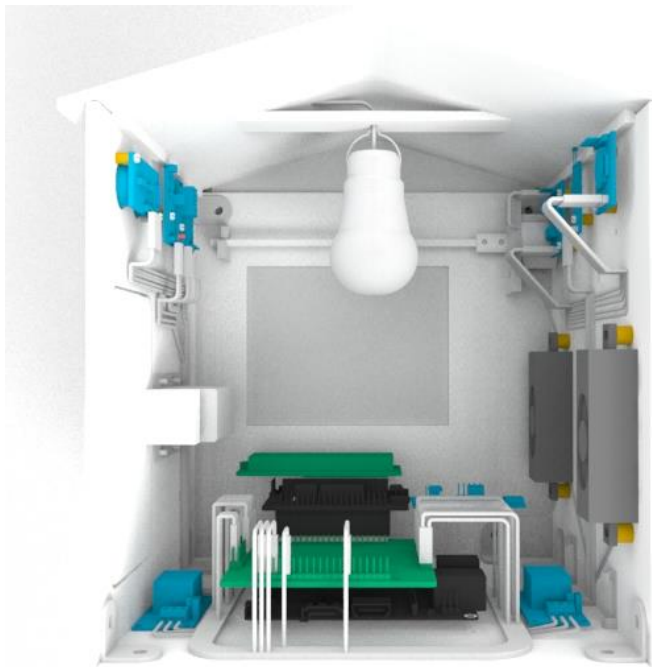
Example – the LCD1602 display

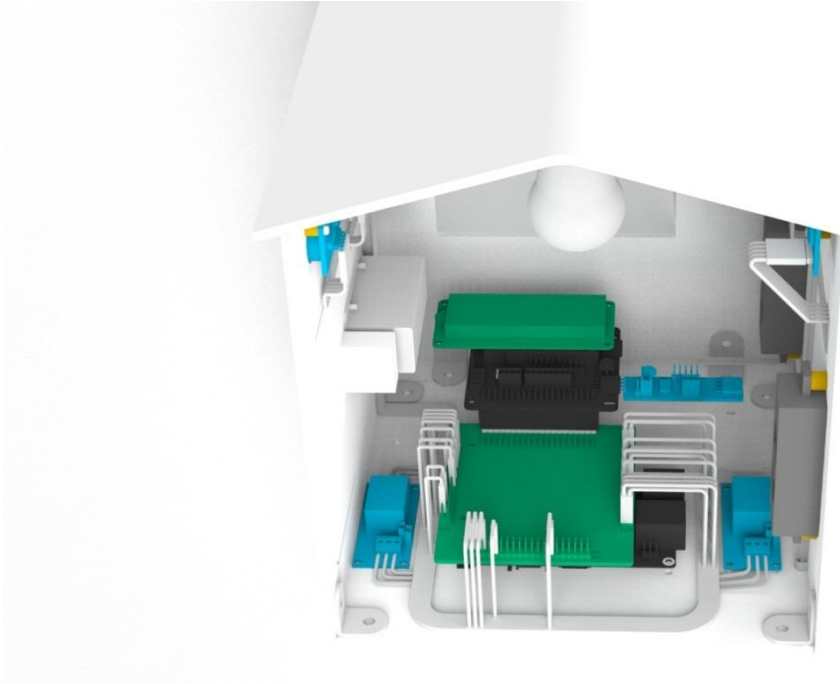


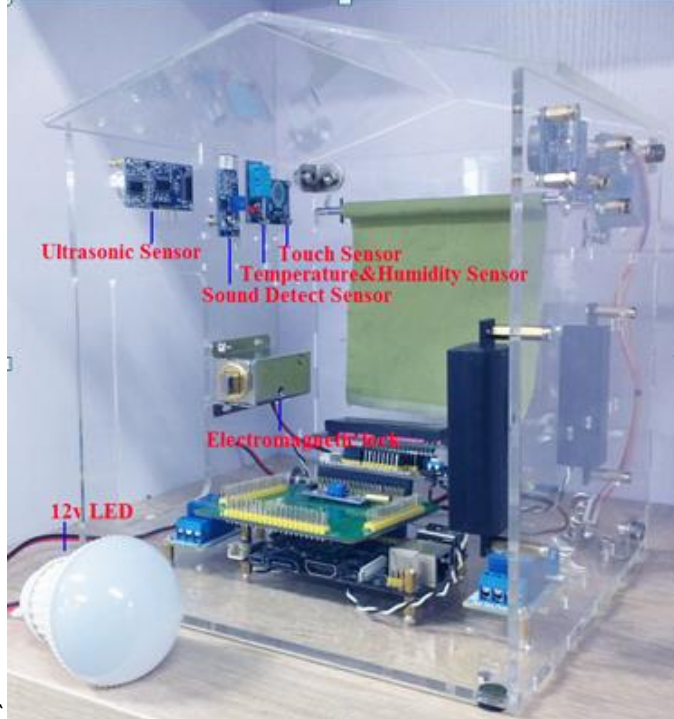
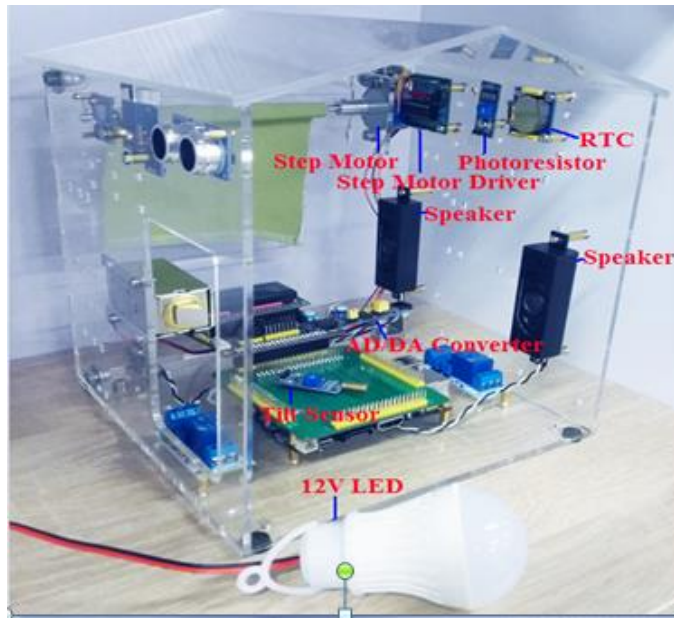


Building the LeScratch smart house











```
when space key pressed
broadcast RTC
broadcast DHT11pin24
broadcast LCD1602
broadcast Trigger14
broadcast Echo15
forever
broadcast update
broadcast UltraSonic
wait 1 secs
```



```
when a key pressed
  set count to 0
  broadcast stepMAinit
  broadcast light21AIN0
  broadcast PCF8591
  repeat until count = 10
    broadcast update
    broadcast AD0read
    if light sensor value < 0.5
      broadcast stepM2A256N
    else
      broadcast stepM2A256P
    change count by 1
```

```
when b key pressed
  broadcast touch6
  forever
    broadcast update
    if touchSensor sensor value = 1
      play sound Cave
```

```
when c key pressed
  broadcast sound8
  forever
    broadcast update
    wait 1 secs
```

