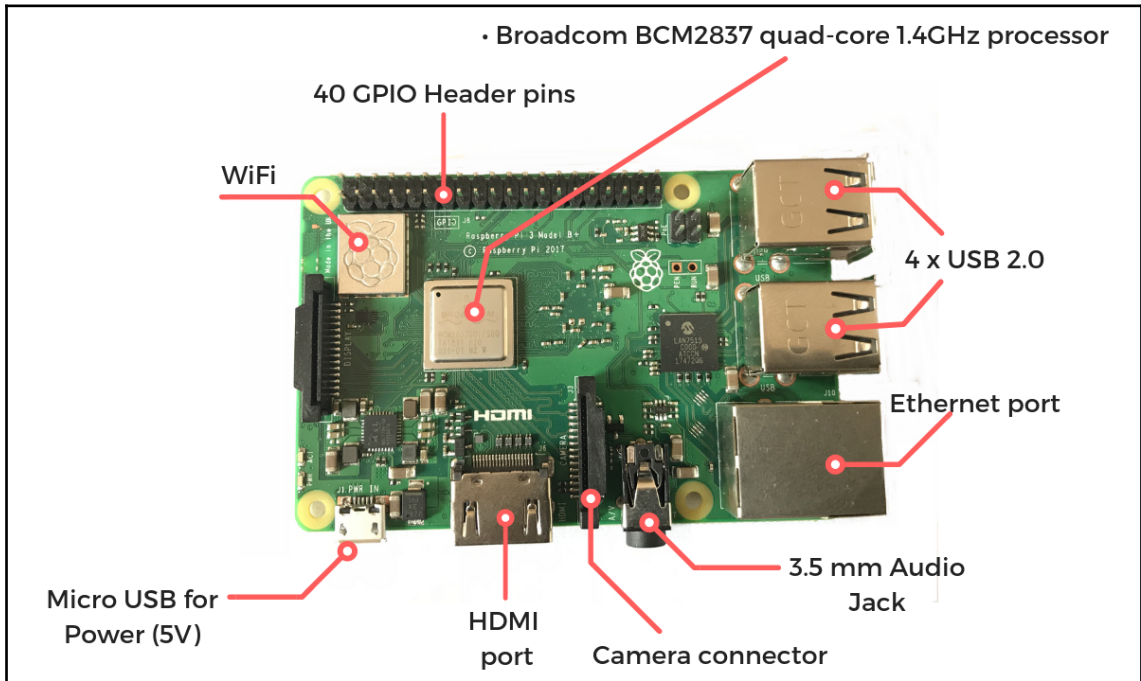
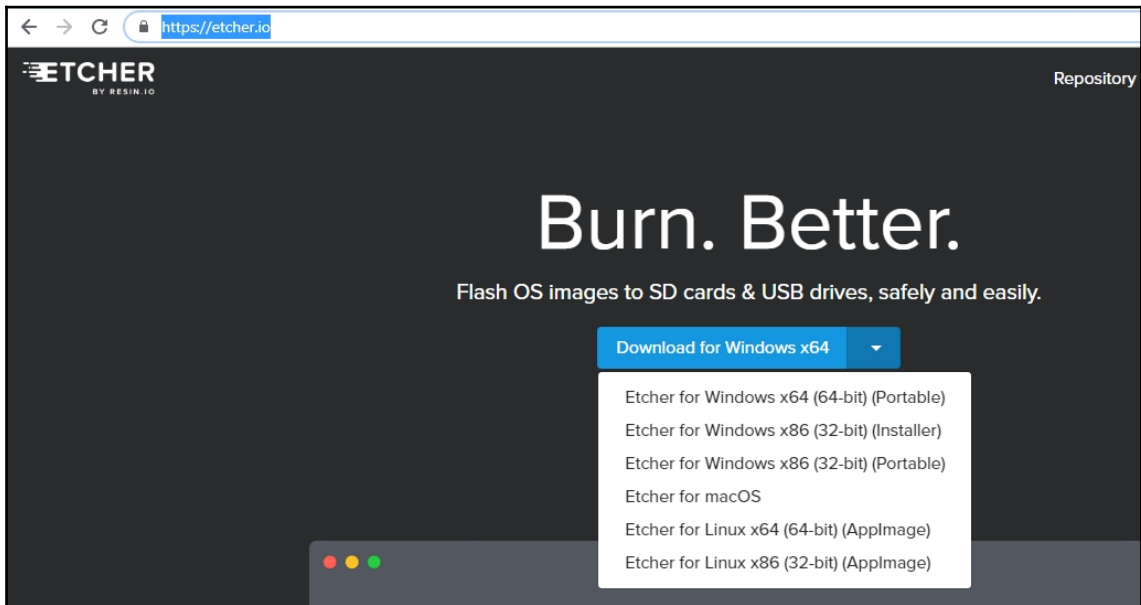
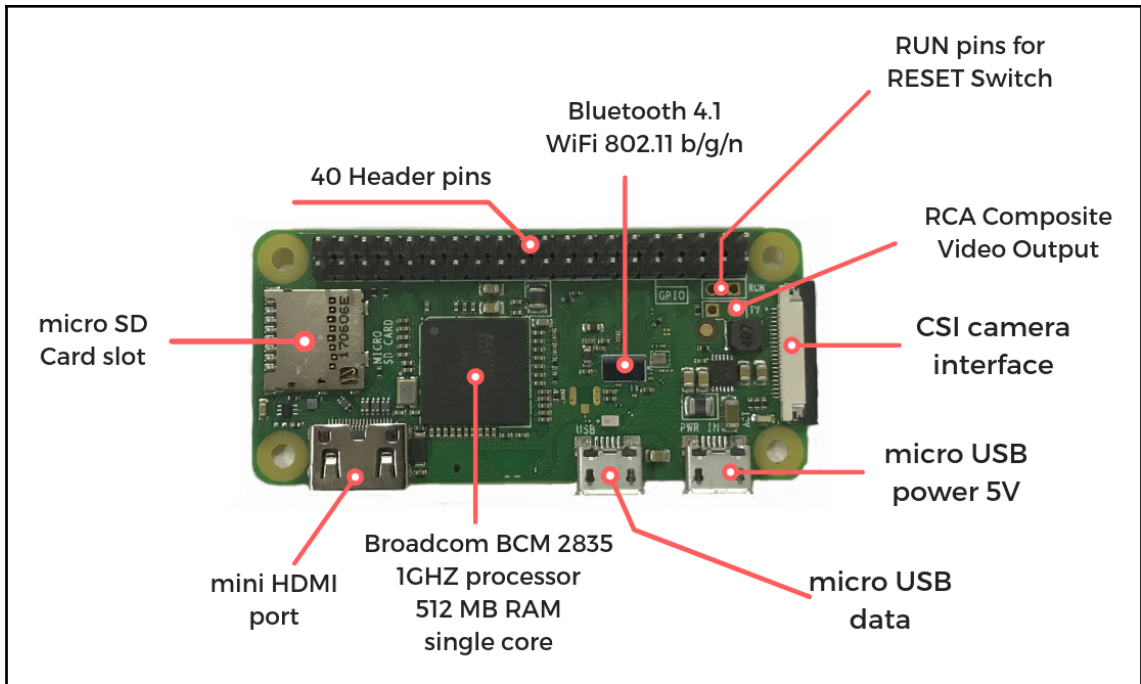


Chapter 1: Introduction to the Raspberry Pi





https://www.raspberrypi.org/downloads/raspbian/ ☆



RASPBIAN STRETCH WITH DESKTOP

Image with desktop based on Debian Stretch

Version: October 2018
Release date: 2018-10-09
Kernel version: 4.14
Release notes: [Link](#)

[Download Torrent](#) [Download ZIP](#)



RASPBIAN STRETCH LITE

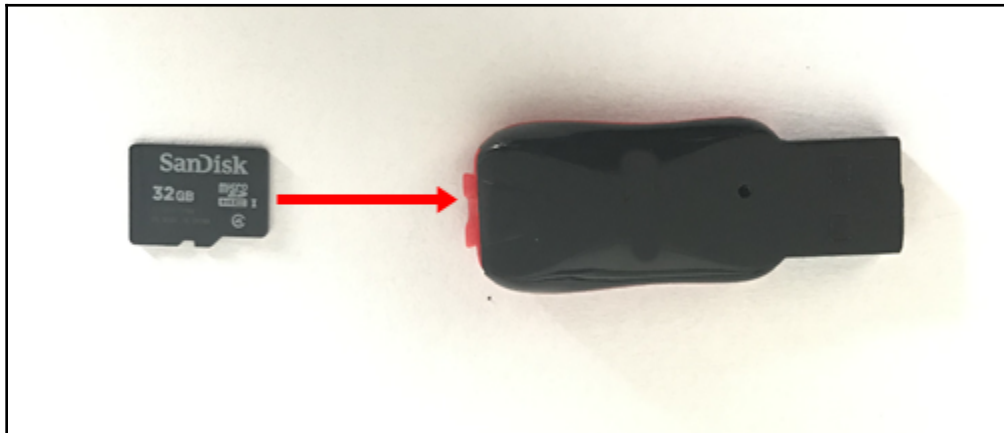
Minimal image based on Debian Stretch

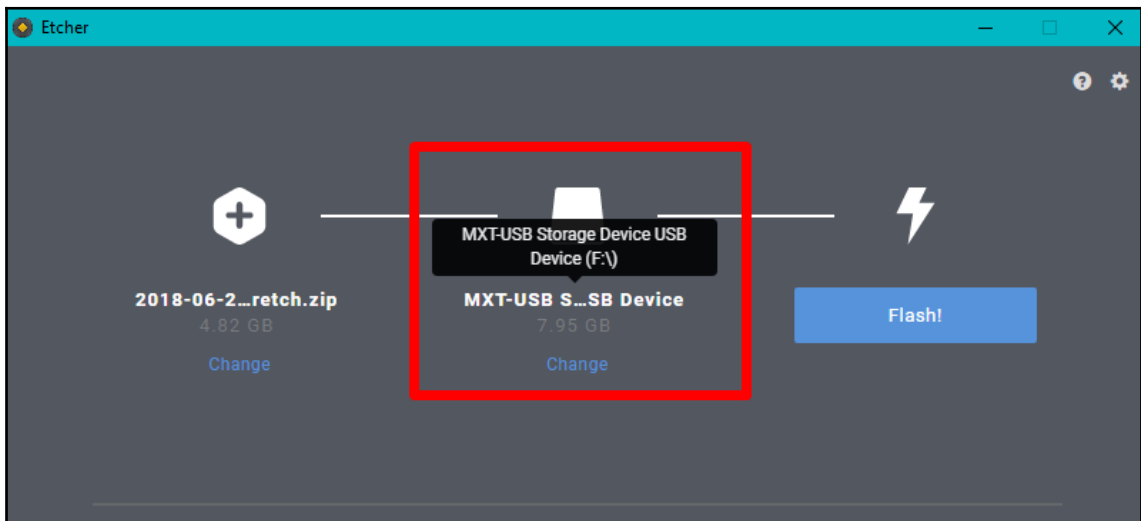
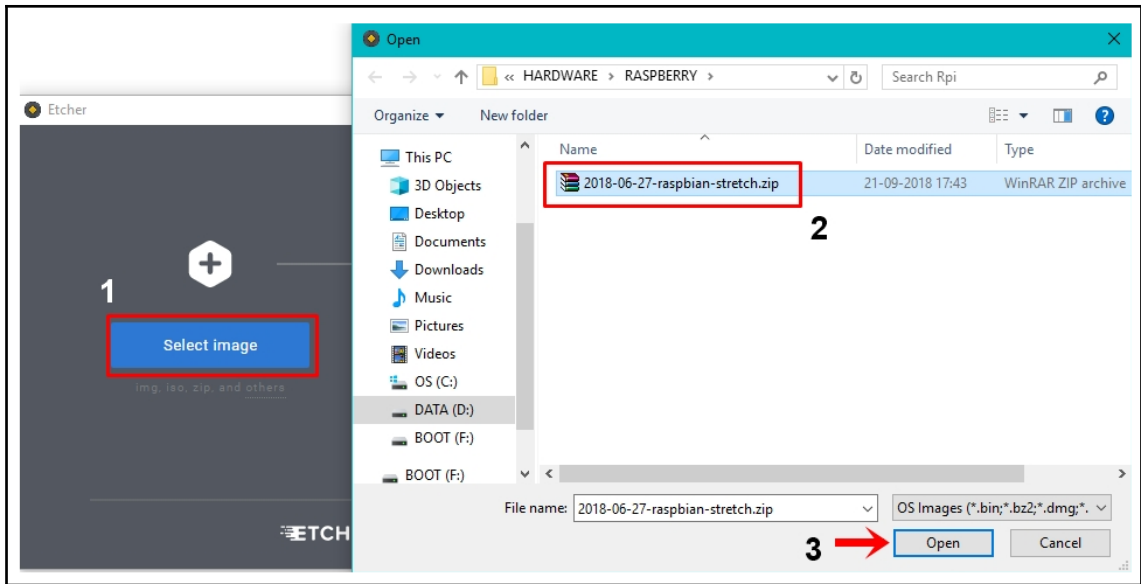
Version: October 2018
Release date: 2018-10-09
Kernel version: 4.14
Release notes: [Link](#)

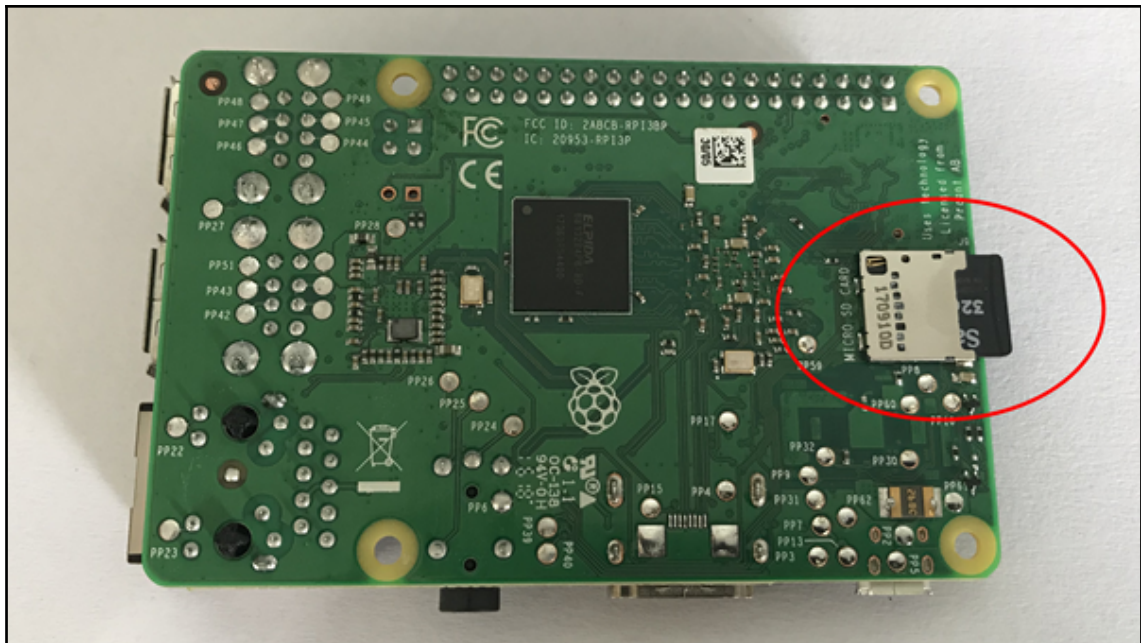
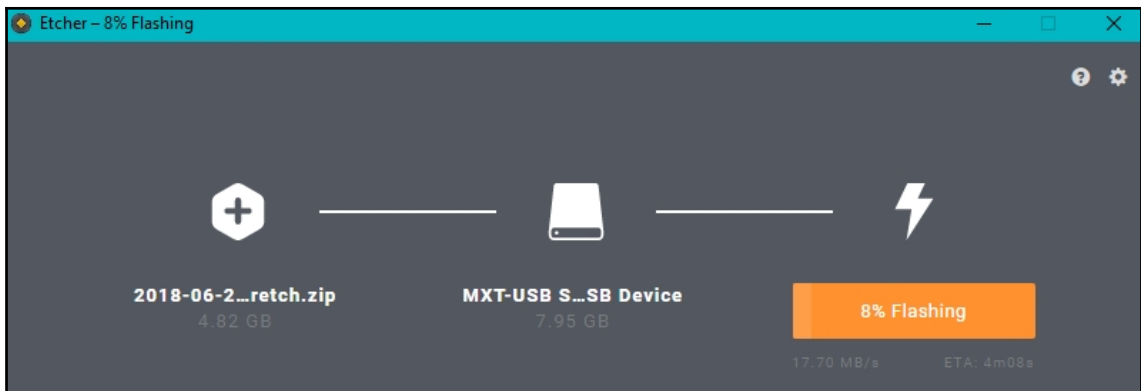
[Download Torrent](#) [Download ZIP](#)

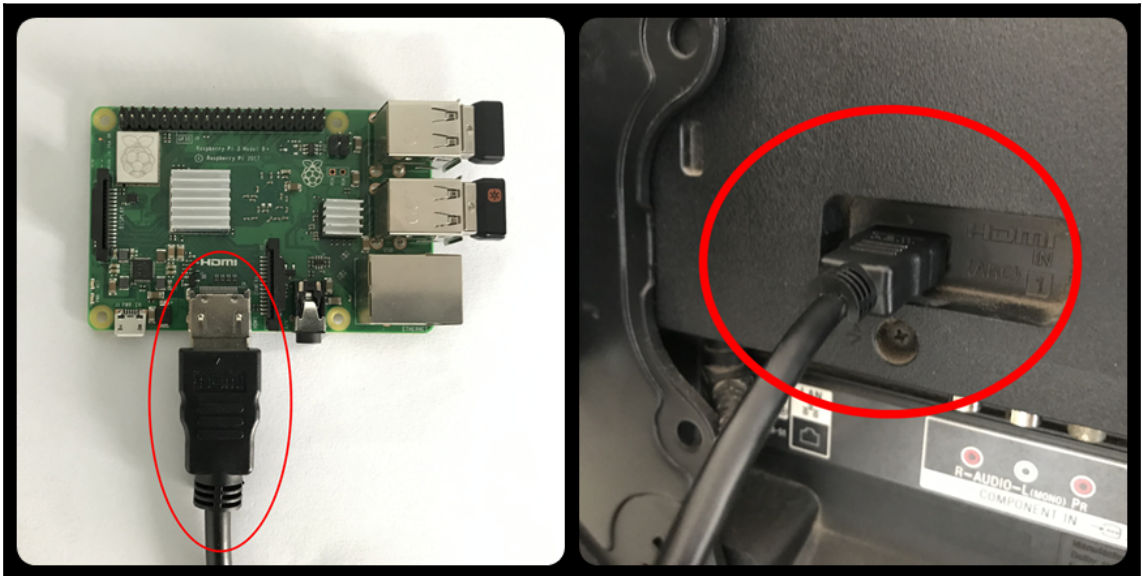
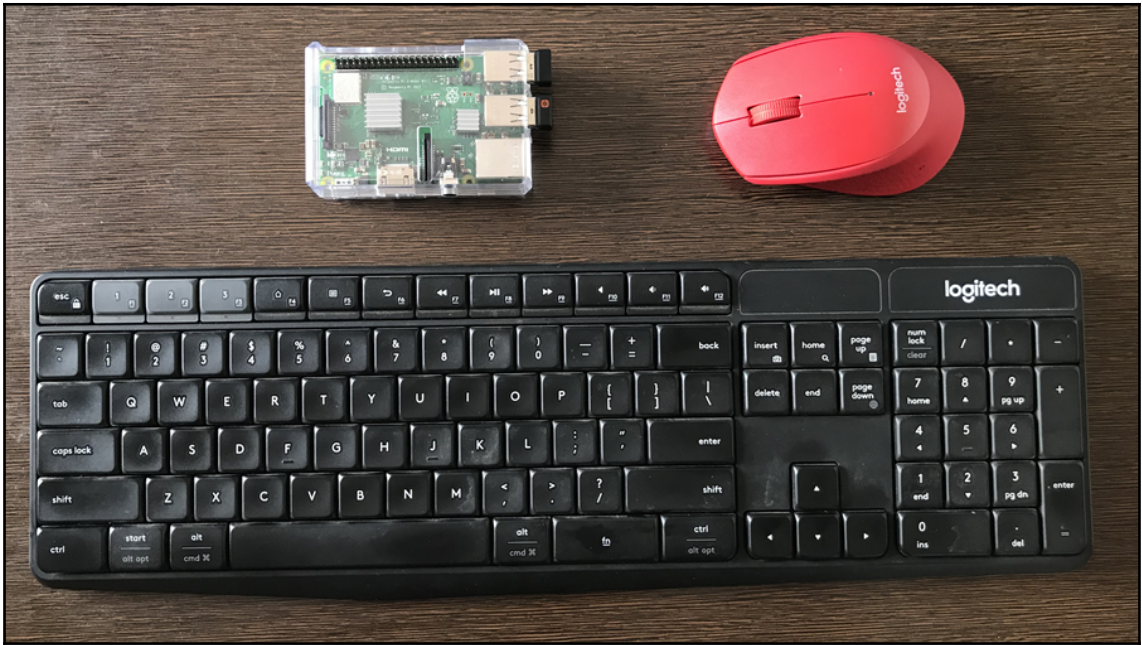
SHA-256: 98444134e98cbb27e112f68422f9b1a42020b64a6fd29e2f6e
6e3aa76e21473ef316c0bfc9efa5c27a27fe46bd698f71de3e06e66 358d171b4
b64a55500

Note: Raspbian and NOOBS contain Java SE Platform Products, licensed to you under the Oracle Binary Code

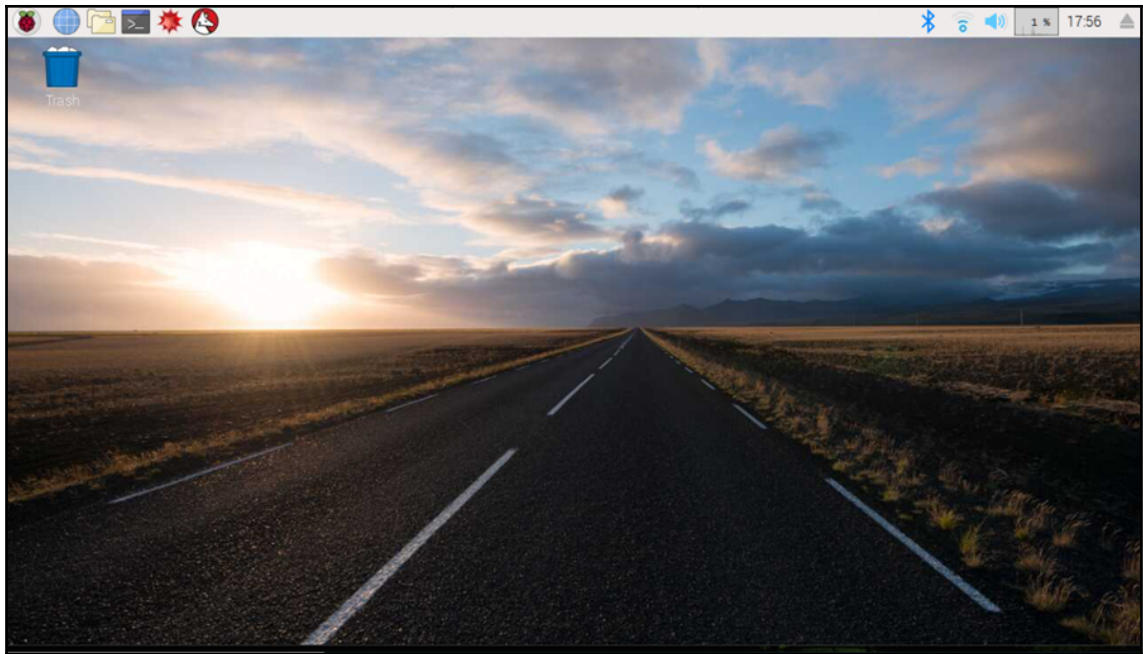


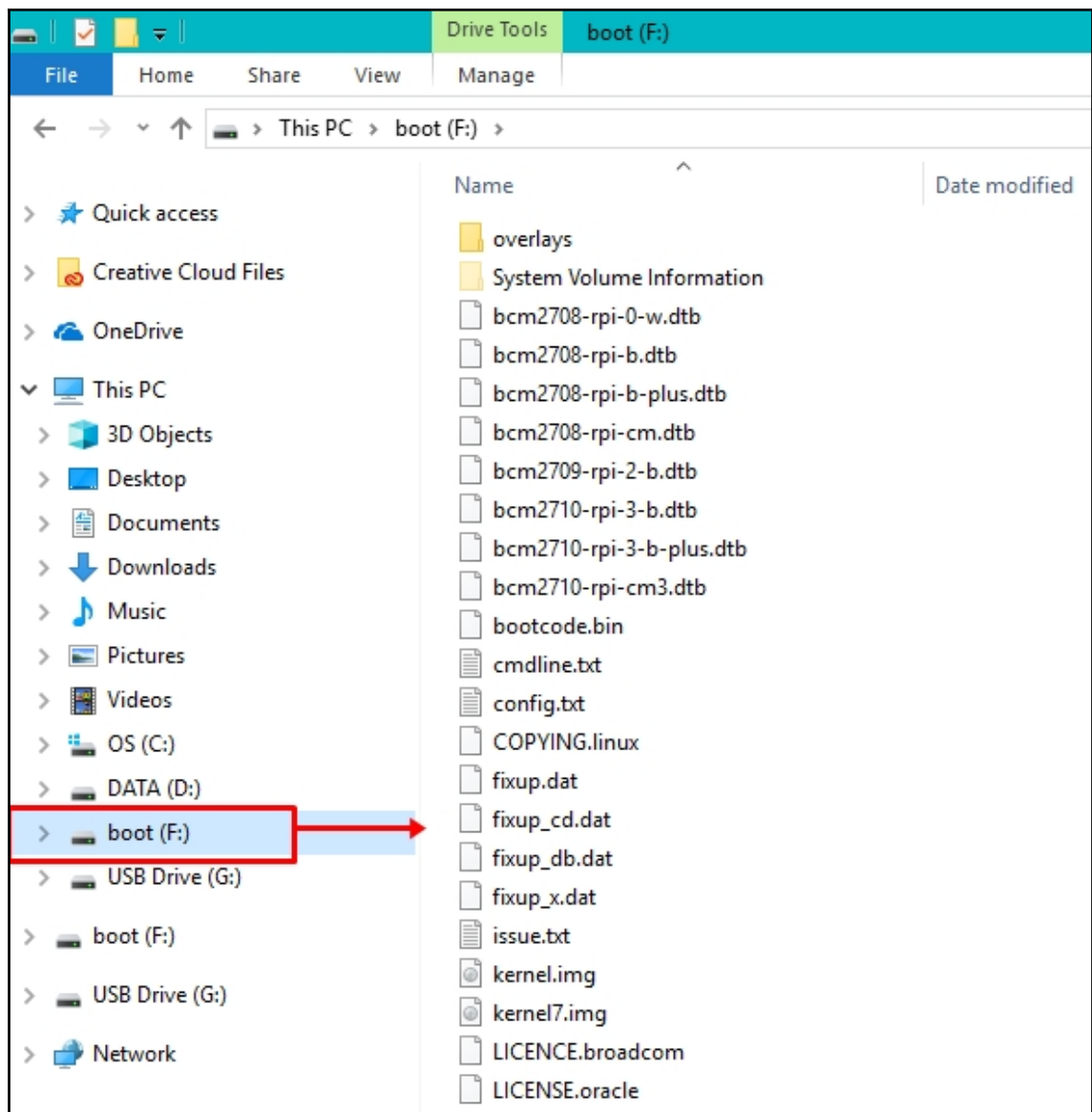


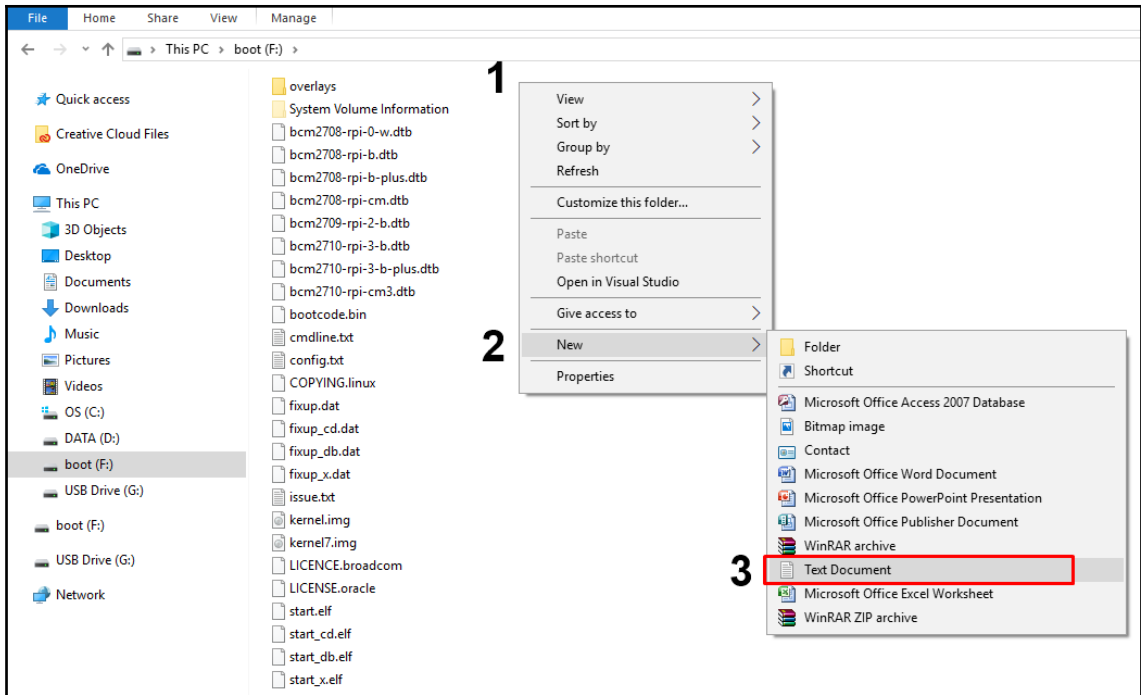


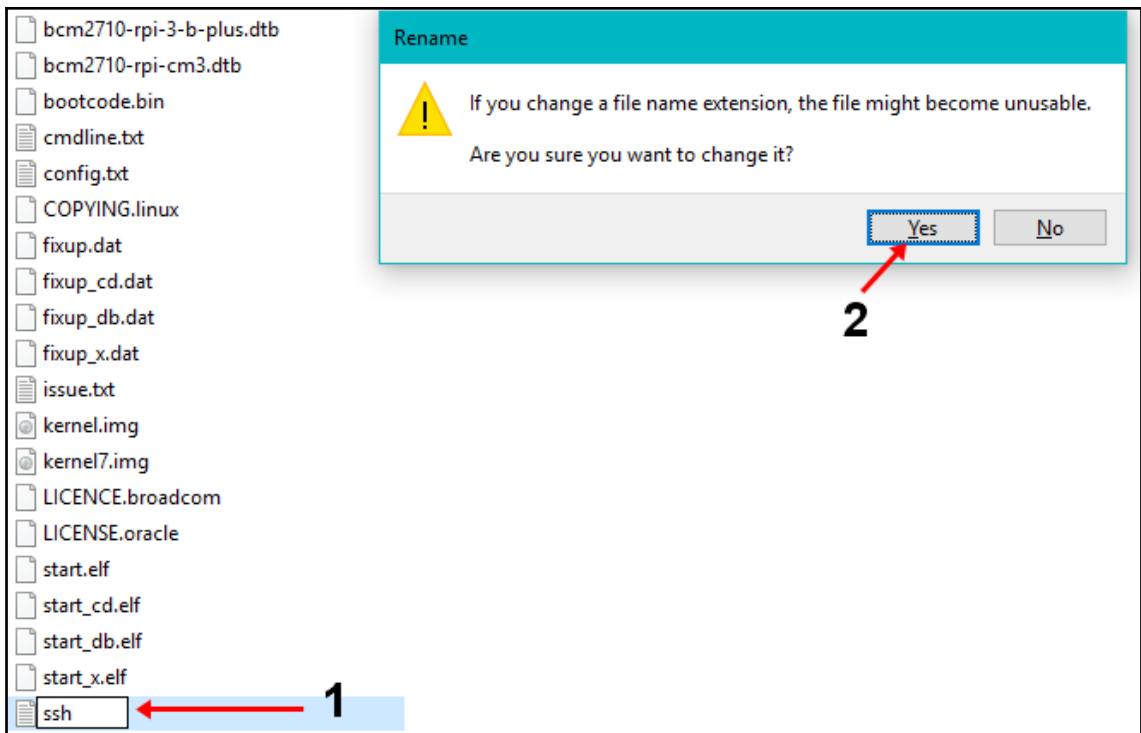


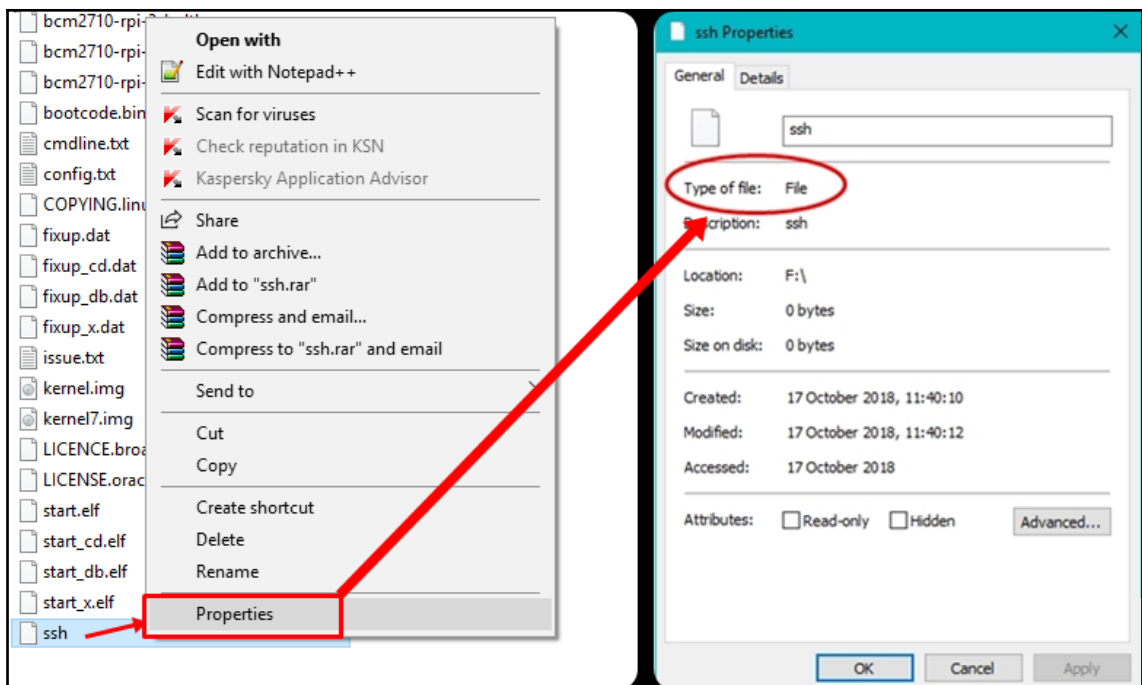


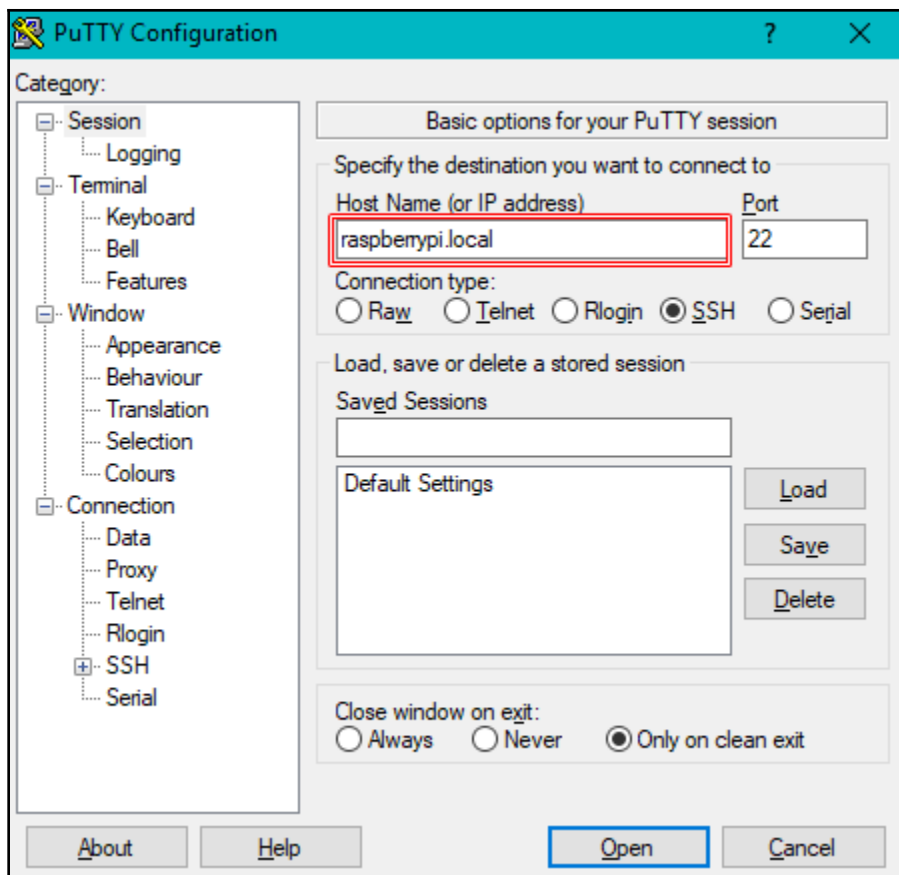


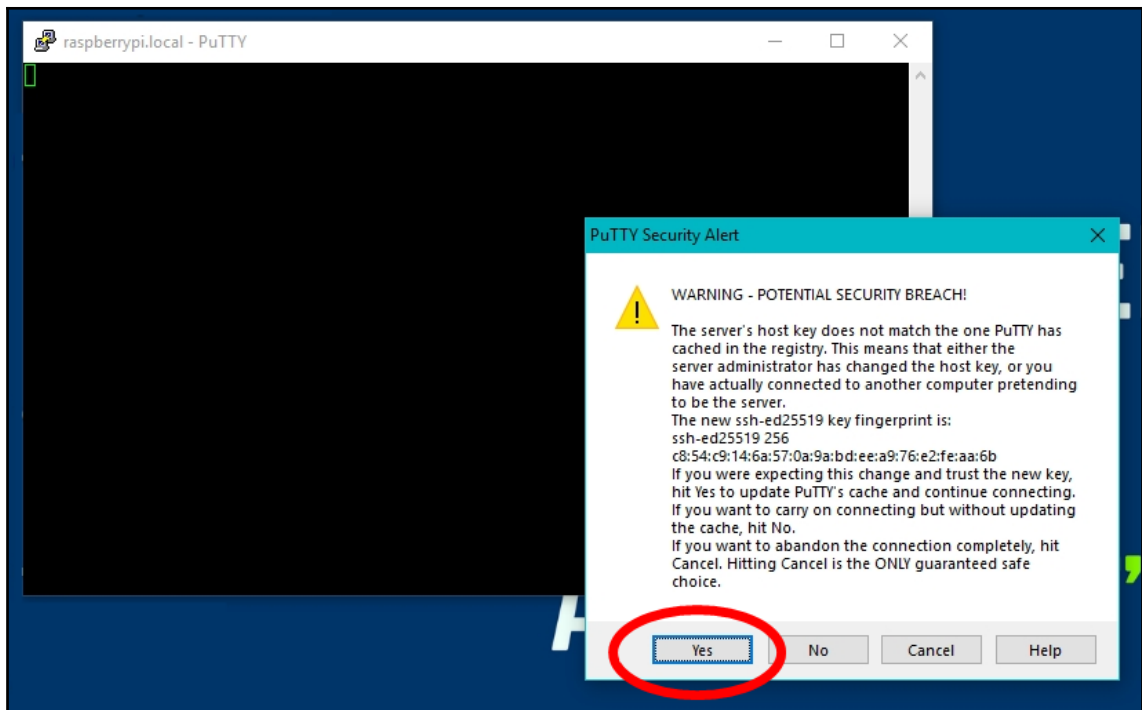












```
pi@raspberrypi: ~  
login as: pi  
pi@raspberrypi.local's password:
```

```
pi@raspberrypi: ~
login as: pi
pi@raspberrypi.local's password:
Linux raspberrypi 4.14.50-v7+ #1122 SMP Tue Jun 19 12:26:26 BST 2018 armv7l

The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.

Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
Last login: Wed Jun 27 01:22:39 2018

SSH is enabled and the default password for the 'pi' user has not been changed.
This is a security risk - please login as the 'pi' user and type 'passwd' to set
a new password.

Wi-Fi is disabled because the country is not set.
Use raspi-config to set the country before use.

pi@raspberrypi:~ $ sudo nano /etc/wpa_supplicant/wpa_supplicant.conf
```

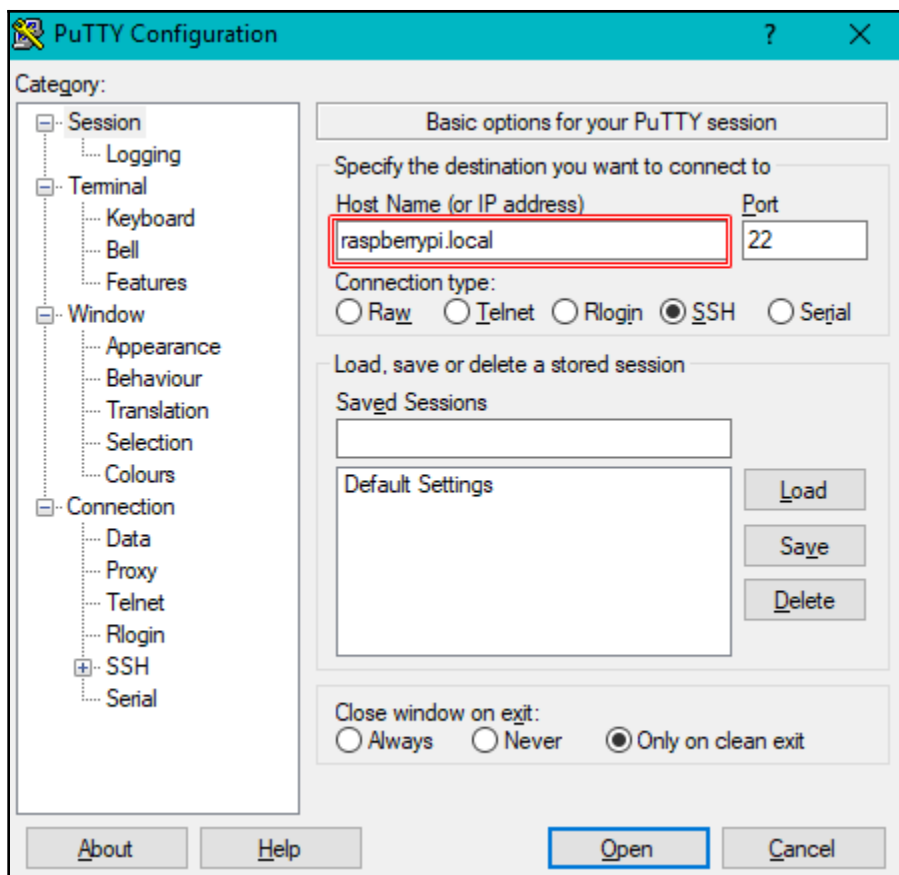
```
pi@raspberrypi: ~
GNU nano 2.7.4 File: /etc/wpa_supplicant/wpa_supplicant.conf

ctrl_interface=DIR=/var/run/wpa_supplicant GROUP=netdev
update_config=1

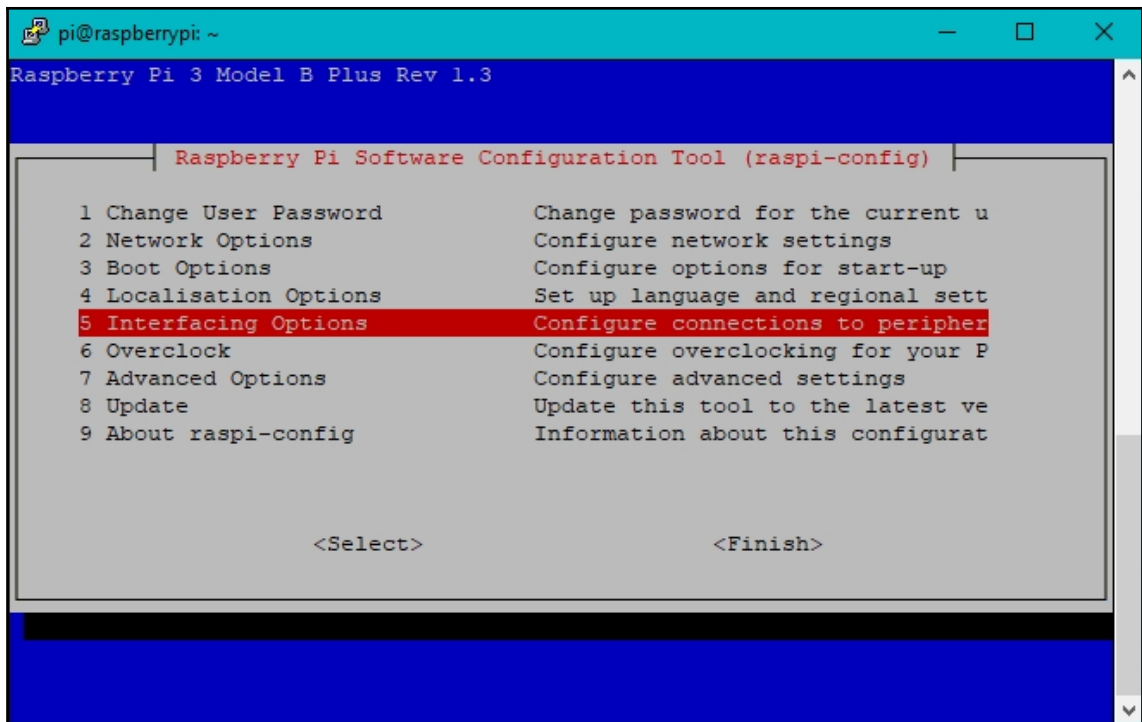
[ Read 2 lines ]
^G Get Help ^O Write Out ^W Where Is ^K Cut Text ^J Justify ^C Cur Pos
^X Exit ^R Read File ^\ Replace ^U Uncut Text ^T To Spell ^_ Go To Line
```

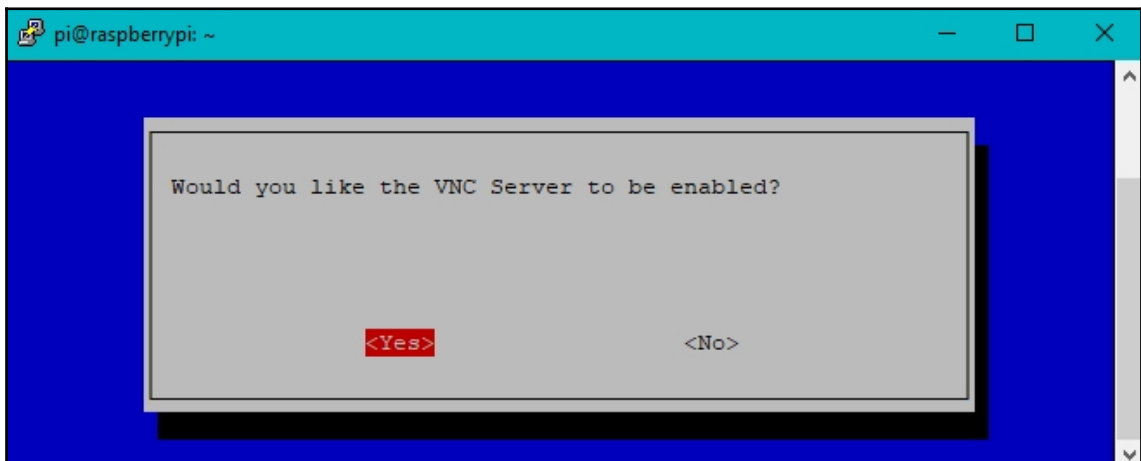
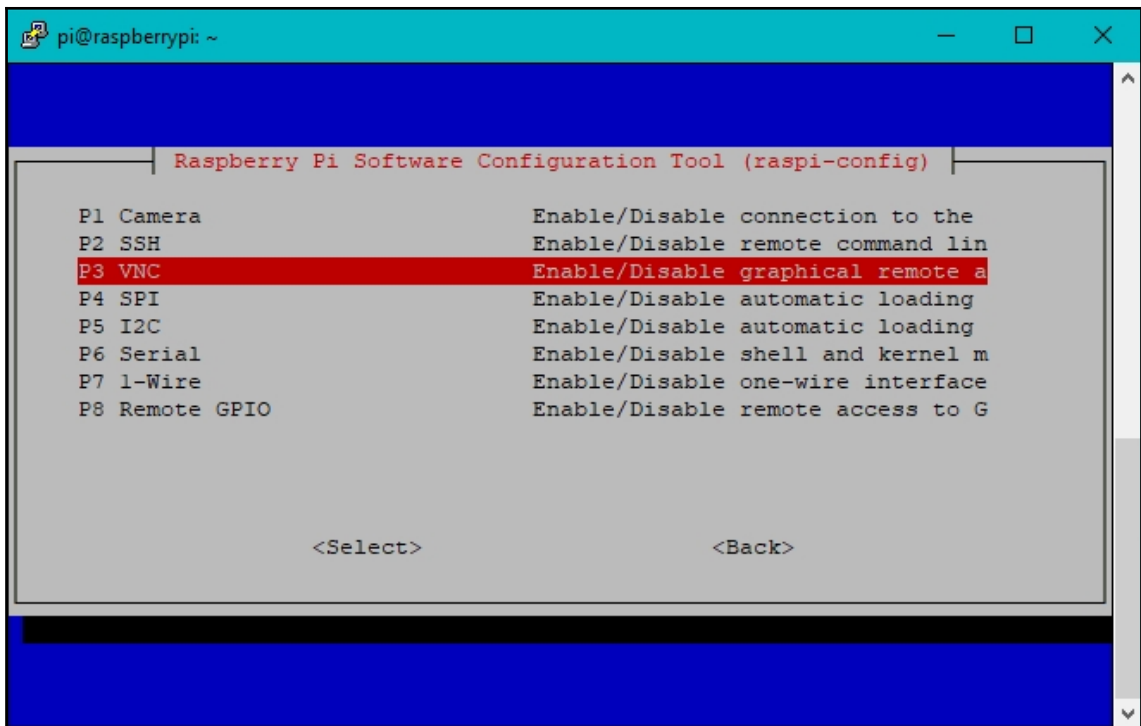
```
pi@raspberrypi: ~  
GNU nano 2.7.4 File: /etc/wpa_supplicant/wpa_supplicant.conf Modified  
ctrl_interface=DIR=/var/run/wpa_supplicant GROUP=netdev  
update_config=1  
network={  
  ssid="Wifi Name"  
  psk="Wifi Password"  
}  
  
^G Get Help ^O Write Out ^W Where Is ^K Cut Text ^J Justify ^C Cur Pos  
^X Exit ^R Read File ^\ Replace ^U Uncut Text ^T To Spell ^_ Go To Line
```

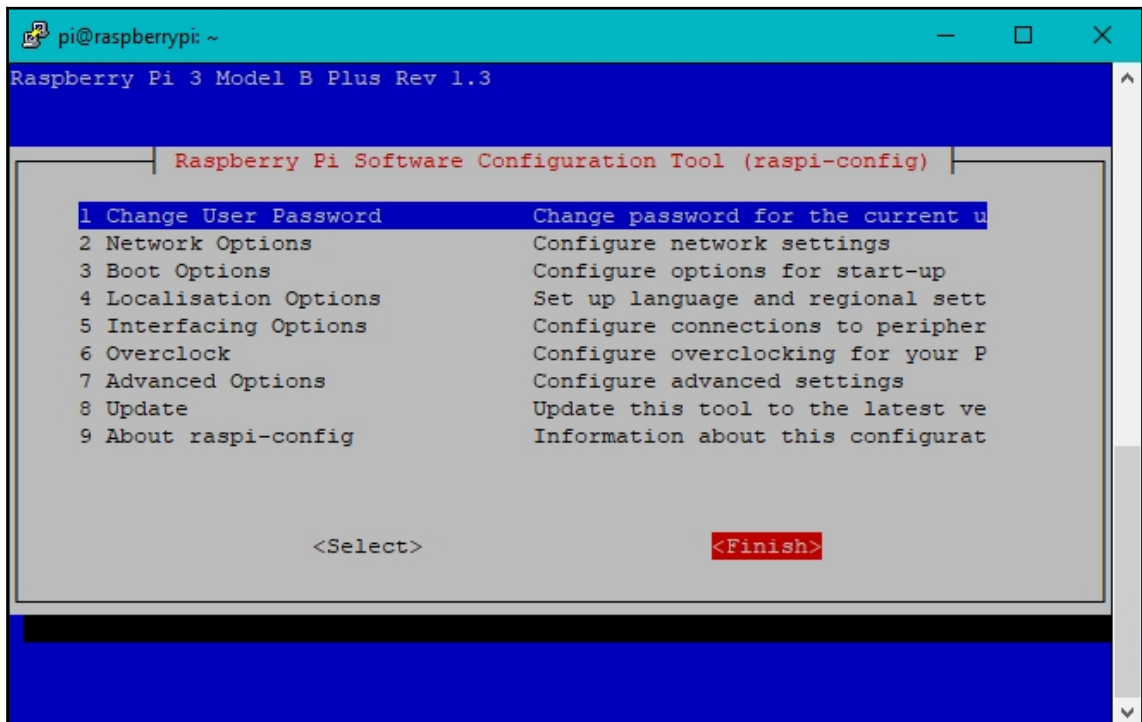
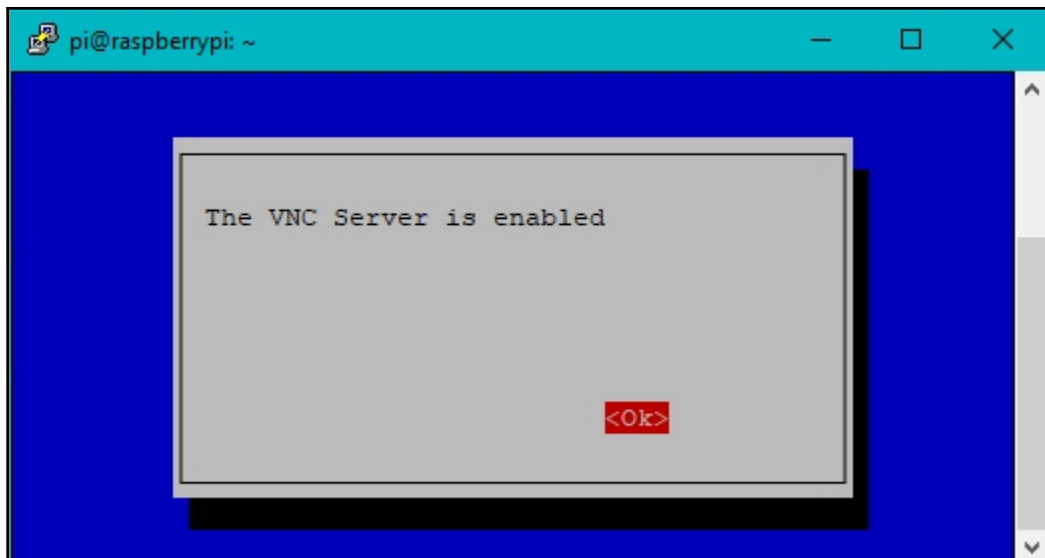
```
pi@raspberrypi: ~  
This is a security risk - please login as the 'pi' user and type 'passwd' to set  
a new password.  
  
Wi-Fi is disabled because the country is not set.  
Use raspi-config to set the country before use.  
  
pi@raspberrypi:~ $ sudo nano /etc/wpa_supplicant/wpa_supplicant.conf  
pi@raspberrypi:~ $ sudo wpa_cli reconfigure  
Selected interface 'p2p-dev-wlan0'  
OK
```

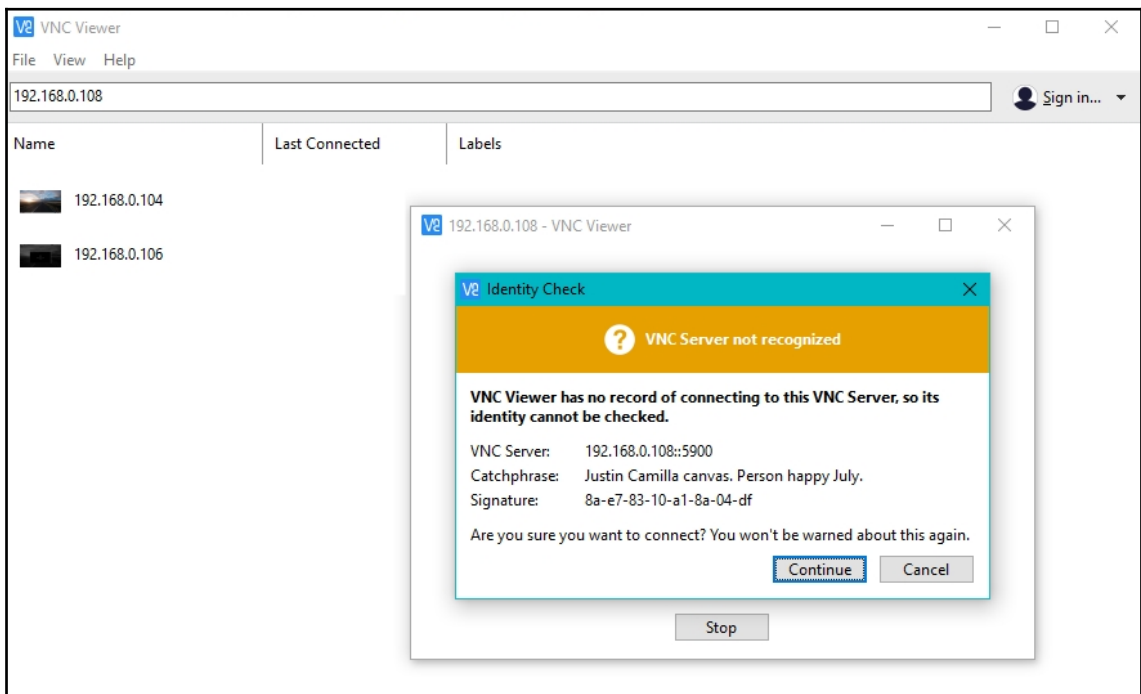
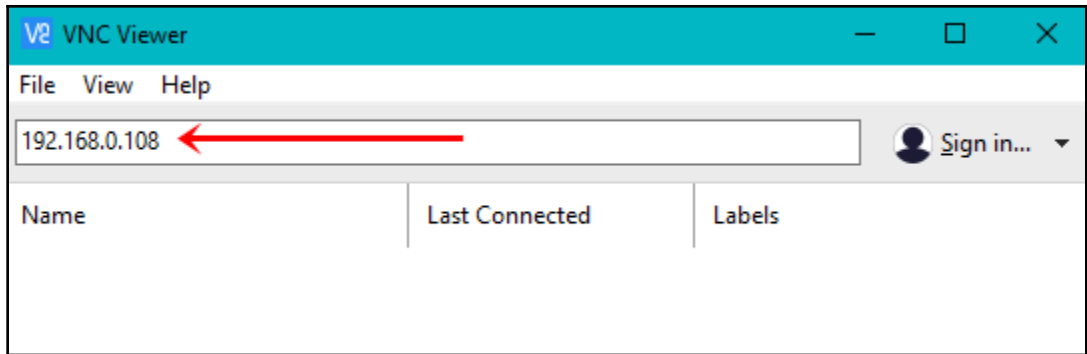


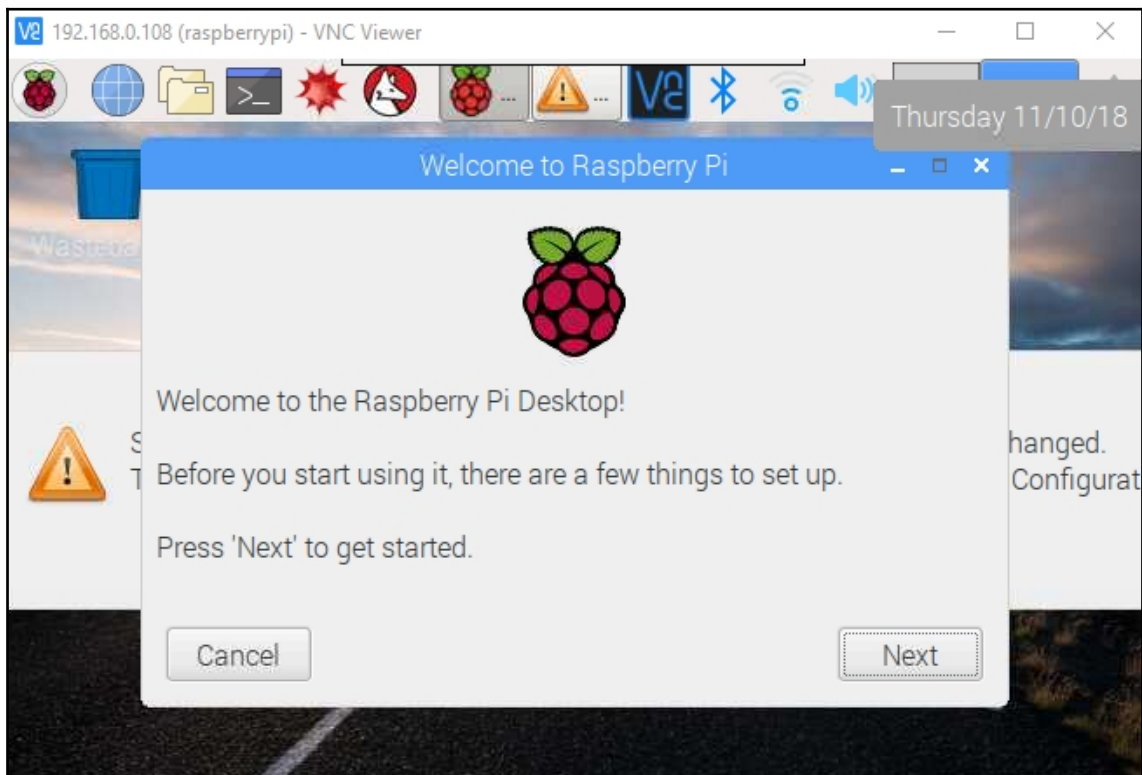
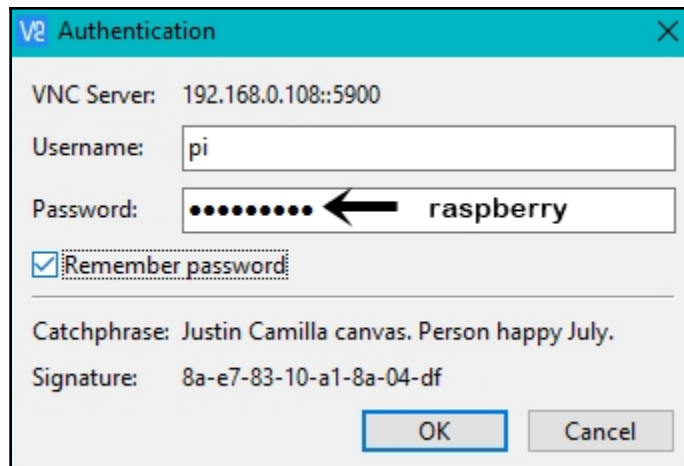
```
pi@raspberrypi: ~  
Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent  
permitted by applicable law.  
Last login: Wed Jun 27 01:22:38 2018  
  
SSH is enabled and the default password for the 'pi' user has not been changed.  
This is a security risk - please login as the 'pi' user and type 'passwd' to set  
a new password.  
  
Wi-Fi is disabled because the country is not set.  
Use raspi-config to set the country before use.  
  
pi@raspberrypi:~ $ sudo nano /etc/wpa_supplicant/wpa_supplicant.conf  
pi@raspberrypi:~ $ ifconfig wlan0 1  
wlan0: flags=4163<UP,BROADCAST,RUNNING,MULTICAST> mtu 1500  
2 inet 192.168.0.108 netmask 255.255.255.0 broadcast 192.168.0.255  
inet6 fe80::ad1b:dad9:b3af:5519 prefixlen 64 scopeid 0x20<link>  
ether b8:27:eb:41:2c:3f txqueuelen 1000 (Ethernet)  
RX packets 156 bytes 28888 (28.2 KiB)  
RX errors 0 dropped 0 overruns 0 frame 0  
TX packets 99 bytes 19006 (18.5 KiB)  
TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0  
  
pi@raspberrypi:~ $
```

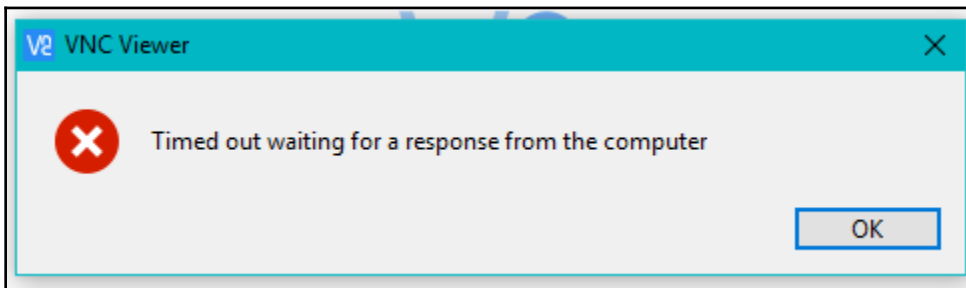
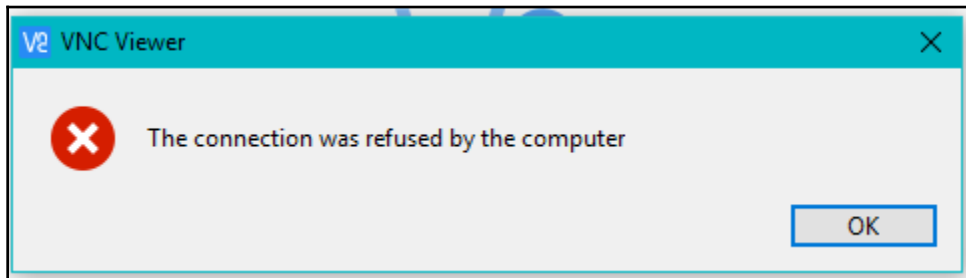


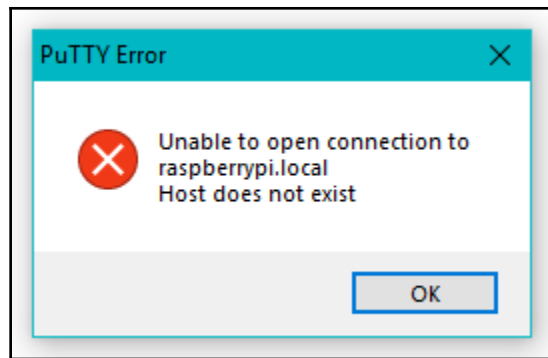




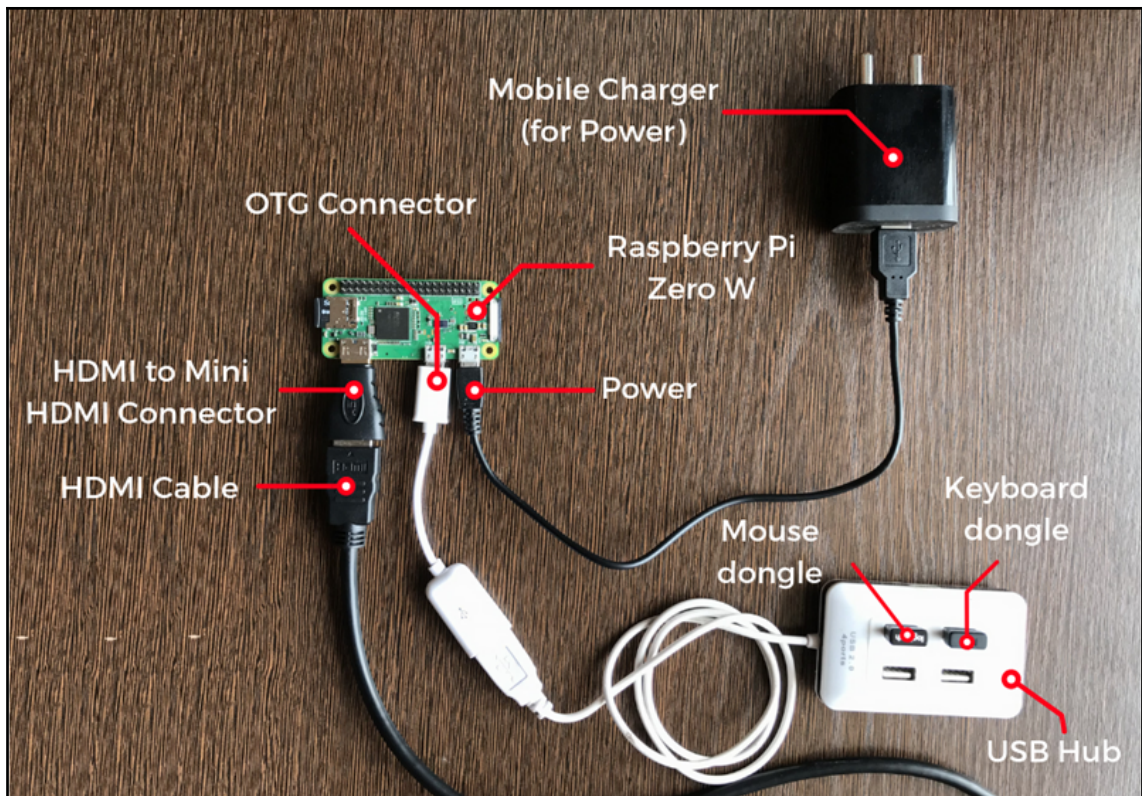


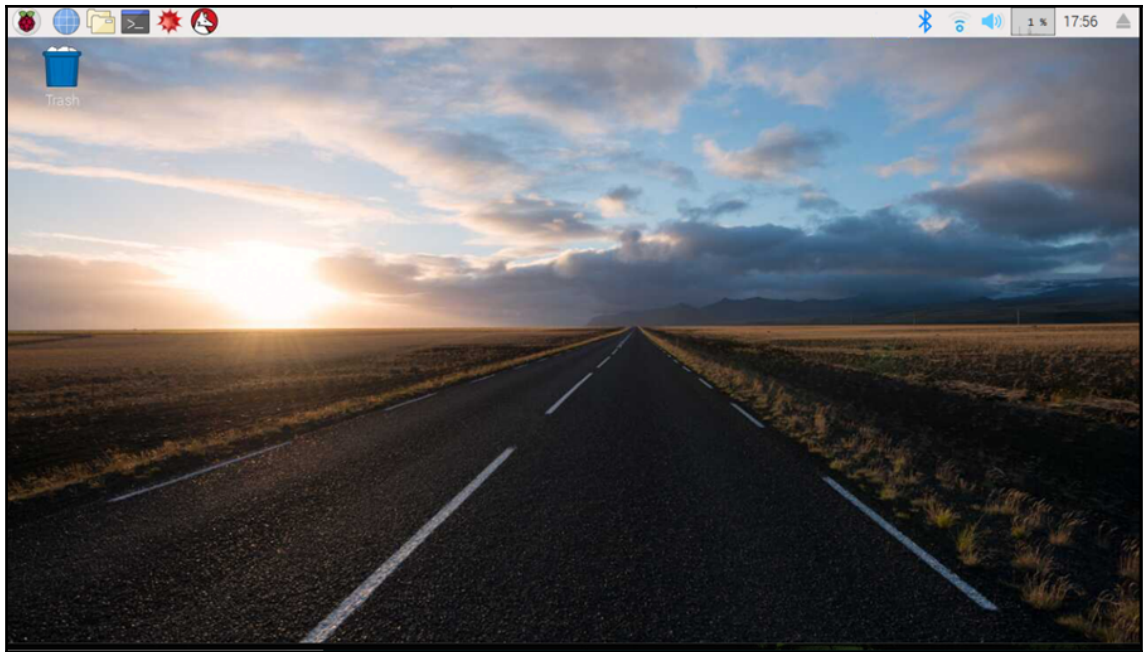
```
pi@raspberrypi: ~  
File Edit Tabs Help  
GNU nano 2.7.4 File: /boot/config.txt  
#framebuffer_width=1280  
#framebuffer_height=720  
# uncomment if hdmi display is not detected and composite is being output  
#hdmi_force_hotplug=1  
# uncomment to force a specific HDMI mode (this will force VGA)  
#hdmi_group=1  
#hdmi_mode=1  
hdmi_ignore_edid=0xa5000080  
hdmi_group=2  
hdmi_mode=85  
# uncomment to force a HDMI mode rather than DVI. This can make audio work in  
# DMT (computer monitor) modes  
#hdmi_drive=2
```

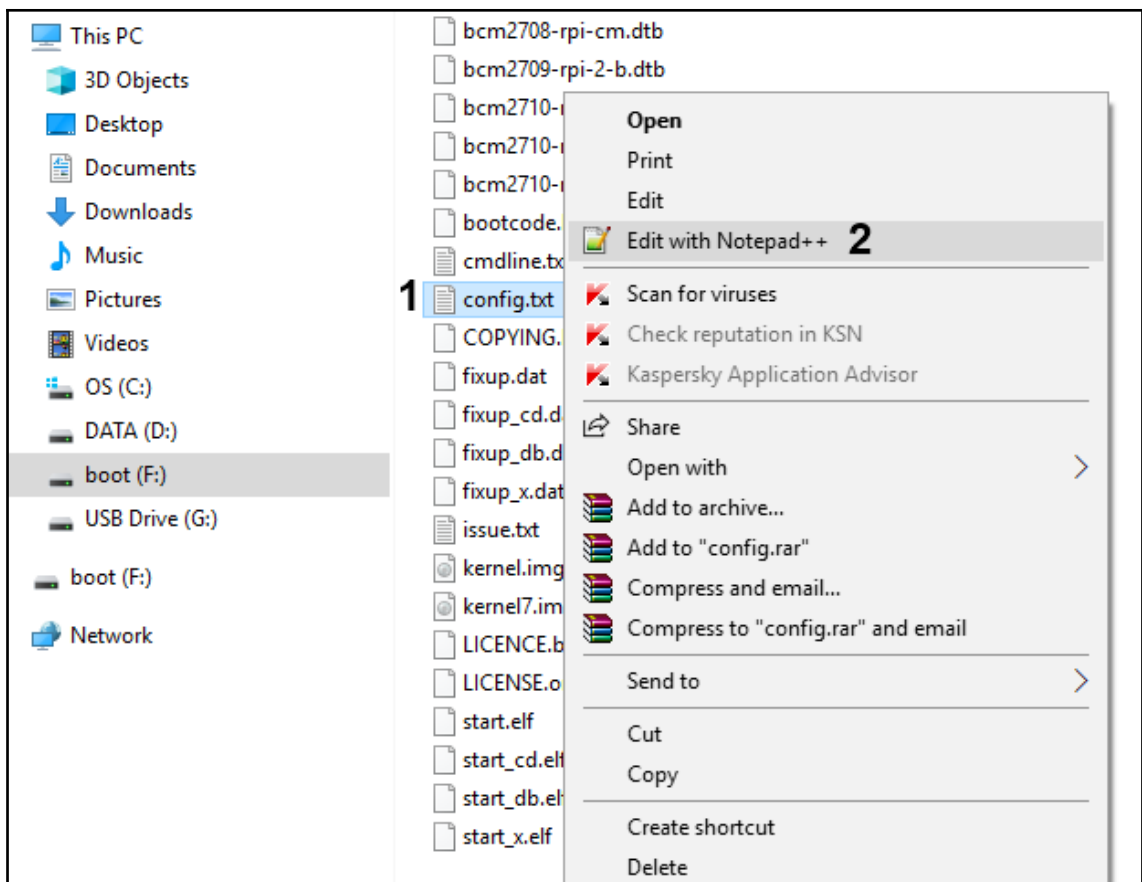


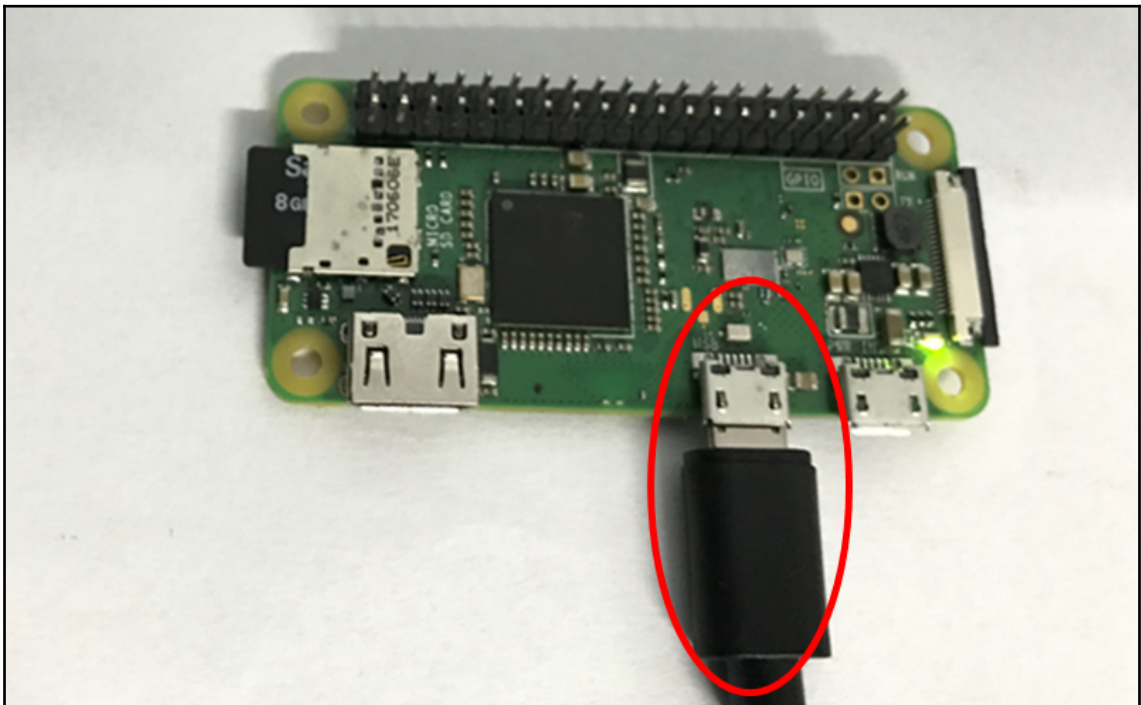
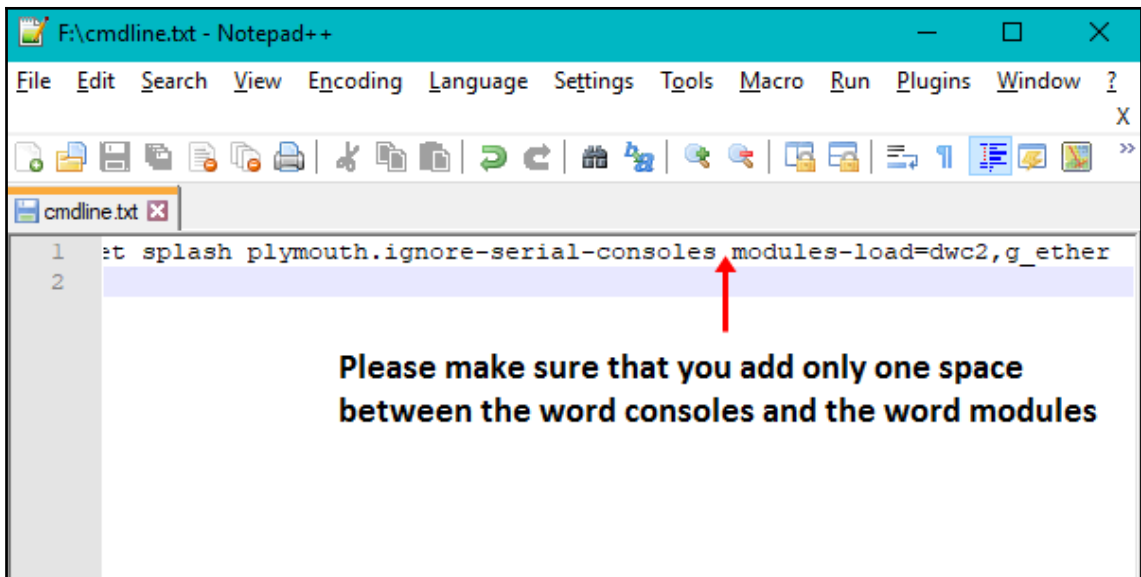


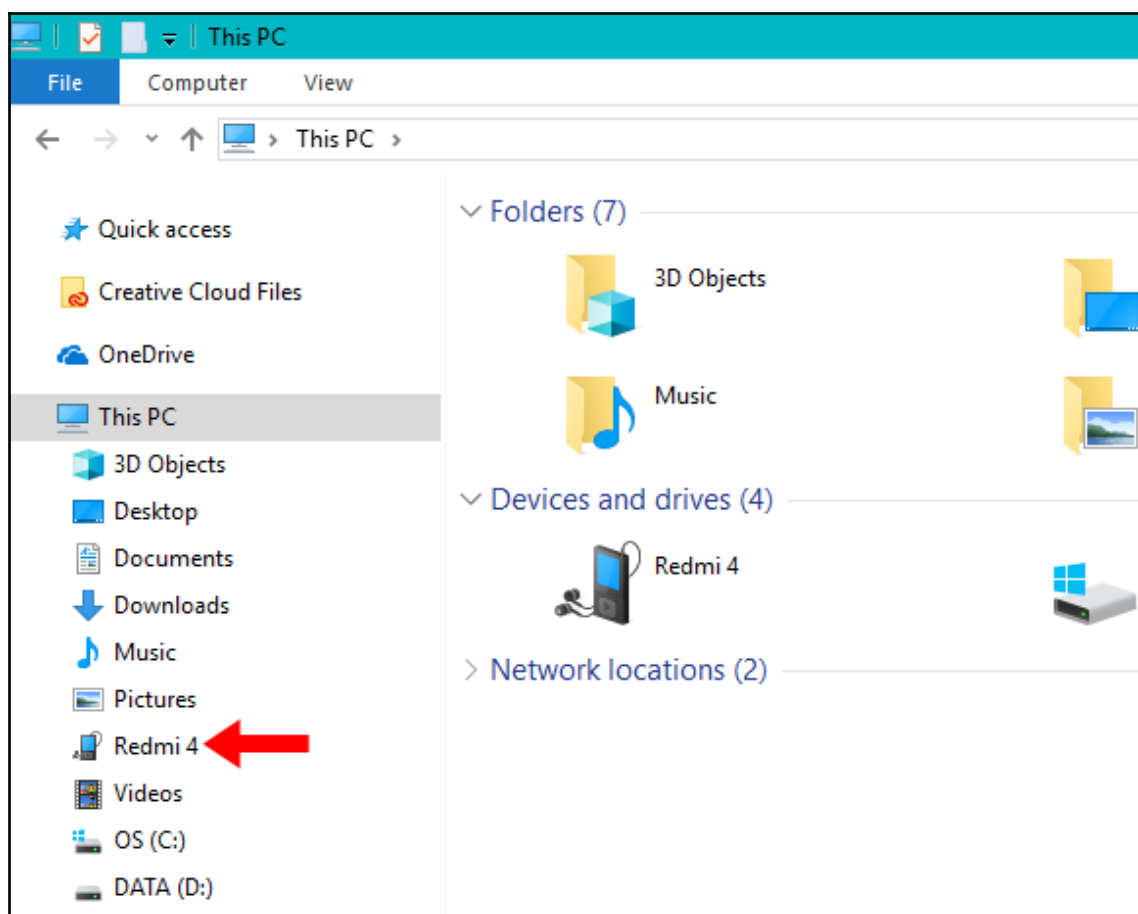
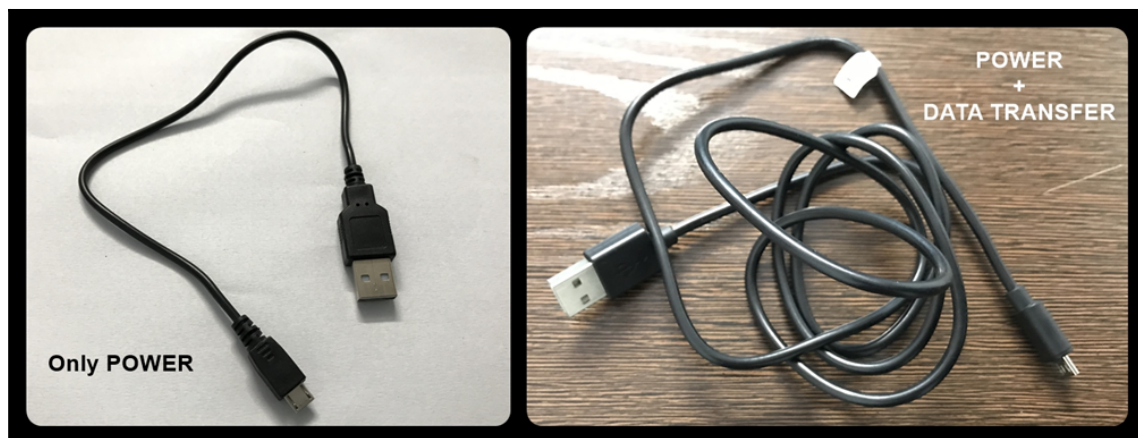




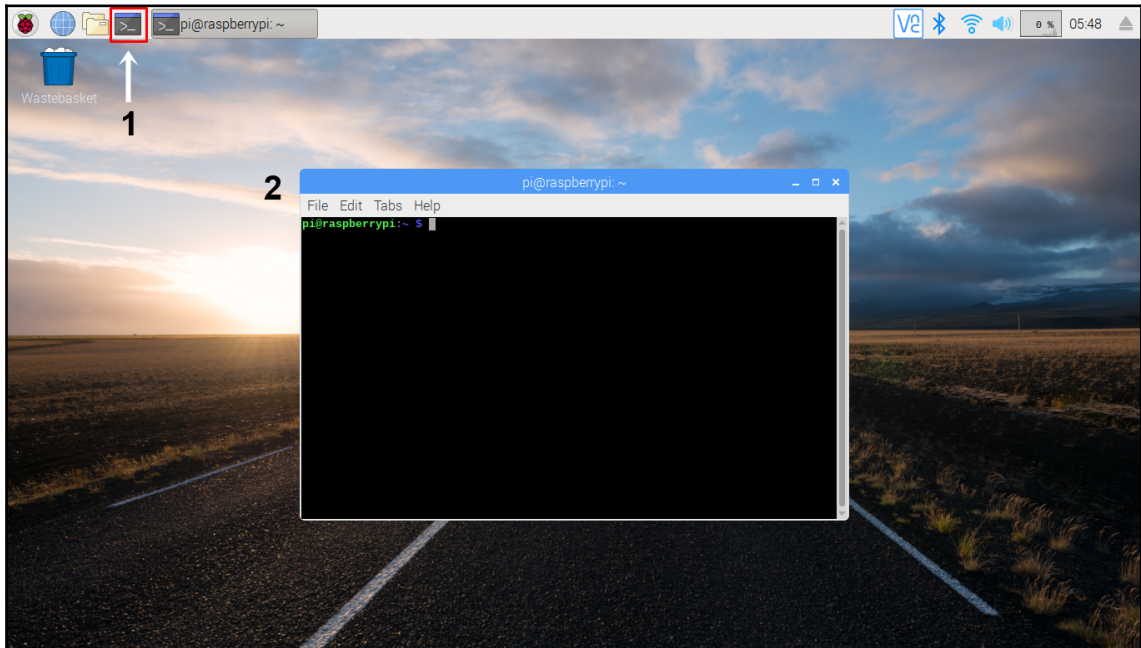








Chapter 2: Implementing Blink with wiringPi

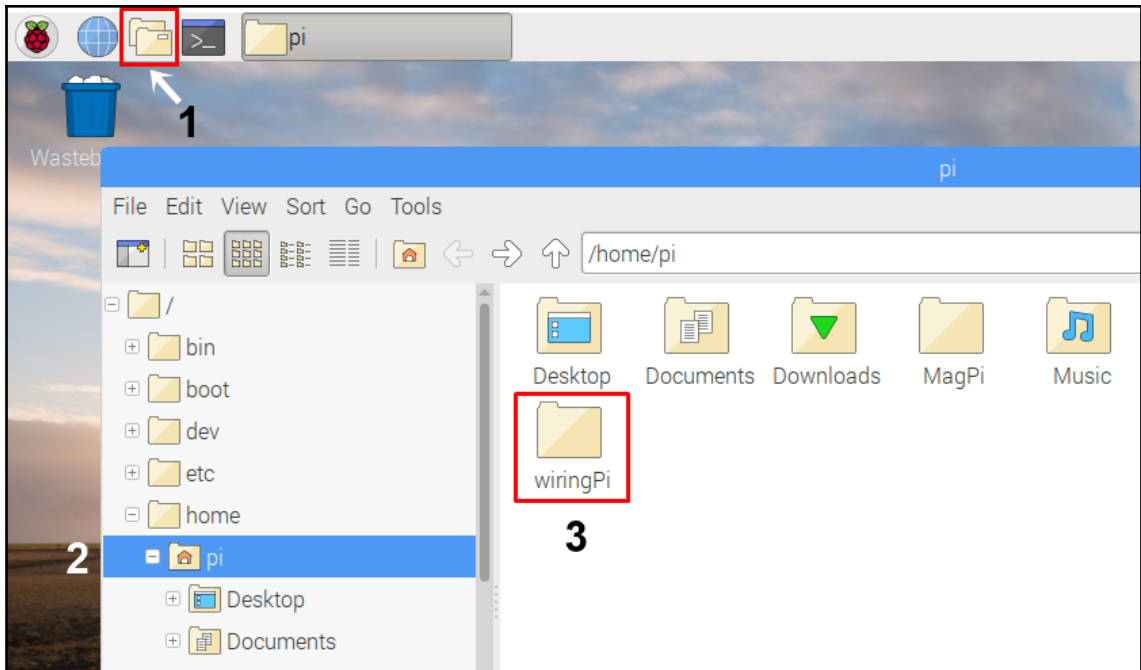


```
pi@raspberrypi: ~  
File Edit Tabs Help  
pi@raspberrypi:~ $ sudo apt-get update  
Get:1 http://raspbian.raspberrypi.org/raspbian stretch InRelease [15.0 kB]  
Get:2 http://archive.raspberrypi.org/debian stretch InRelease [25.3 kB]  
Get:3 http://raspbian.raspberrypi.org/raspbian stretch/main armhf Packages [11.7 MB]  
Get:4 http://archive.raspberrypi.org/debian stretch/main armhf Packages [181 kB]  
Get:5 http://archive.raspberrypi.org/debian stretch/ui armhf Packages [34.3 kB]  
30% [3 Packages 1,562 kB/11.7 MB 13%] 52.0 kB/s 3min 17s
```

```
Updating certificates in /etc/ssl/certs...  
0 added, 0 removed; done.  
Running hooks in /etc/ca-certificates/update.d...  
done.  
pi@raspberrypi:~ $
```

```
Processing triggers for libc-bin (2.24-11+deb9u3) ...
Processing triggers for ca-certificates (20161130+nmu1+deb9u1) ...
Updating certificates in /etc/ssl/certs...
0 added, 0 removed; done.
Running hooks in /etc/ca-certificates/update.d...
done.
pi@raspberrypi:~ $ sudo apt-get install git-core ←
Reading package lists... Done
Building dependency tree
Reading state information... Done
The following NEW packages will be installed:
  git-core
0 upgraded, 1 newly installed, 0 to remove and 2 not upgraded.
Need to get 1,414 B of archives.
After this operation, 8,192 B of additional disk space will be used.
Get:1 http://raspbian.raspberrypi.org/raspbian stretch/main armhf git-core all 1
:2.11.0-3+deb9u4 [1,414 B]
Fetched 1,414 B in 0s (2,276 B/s)
Selecting previously unselected package git-core.
(Reading database ... 115961 files and directories currently installed.)
Preparing to unpack ../git-core_1%3a2.11.0-3+deb9u4_all.deb ...
Unpacking git-core (1:2.11.0-3+deb9u4) ...
Setting up git-core (1:2.11.0-3+deb9u4) ...
pi@raspberrypi:~ $
```

```
pi@raspberrypi:~ $ git clone git://git.drogon.net/wiringPi
Cloning into 'wiringPi' ...
remote: Counting objects: 1177, done.
remote: Compressing objects: 100% (980/980), done.
remote: Total 1177 (delta 822), reused 212 (delta 142)
Receiving objects: 100% (1177/1177), 369.48 KiB | 247.00 KiB/s, done.
Resolving deltas: 100% (822/822), done.
pi@raspberrypi:~ $
```



```
0 upgraded, 0 newly installed, 0 to remove and
pi@raspberrypi:~ $ cd wiringPi
pi@raspberrypi:~/wiringPi $
```

```
pi@raspberrypi:~ $ cd wiringPi
pi@raspberrypi:~/wiringPi $ git pull origin
Already up-to-date.
pi@raspberrypi:~/wiringPi $
```

```
pi@raspberrypi:~/wiringPi $ git pull origin
Already up-to-date.
pi@raspberrypi:~/wiringPi $ ./build ←
```



```
GPIO Utility
[Compile] gpio.c
[Compile] readall.c
[Link]
[Install]

All Done.

NOTE: To compile programs with wiringPi, you need to add:
      -lwiringPi
to your compile line(s) To use the Gertboard, MaxDetect, etc.
code (the devLib), you need to also add:
      -lwiringPiDev
to your compile line(s).

pi@raspberrypi:~/wiringPi $
```

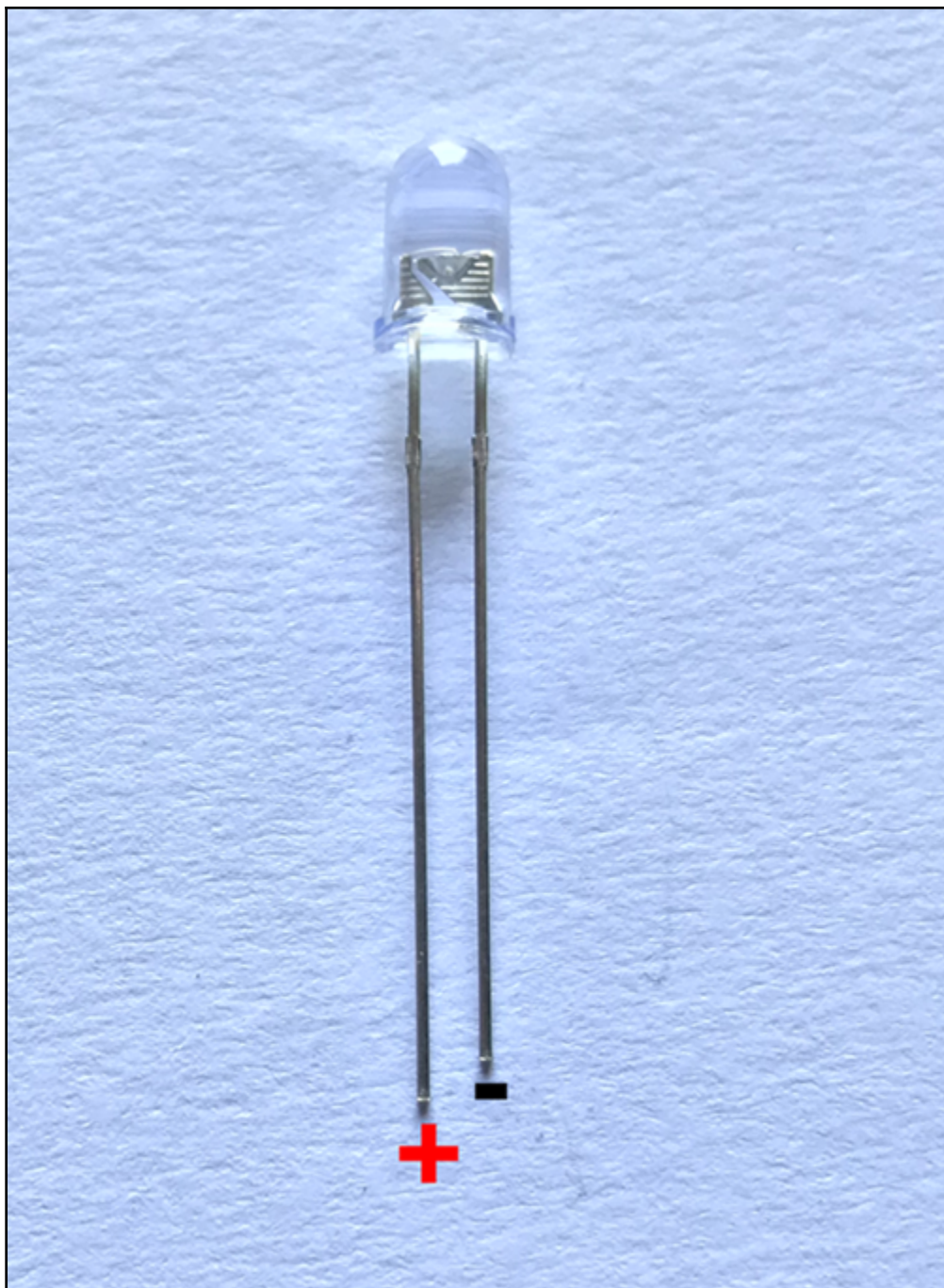
```
pi@raspberrypi: ~
File Edit Tabs Help
pi@raspberrypi:~ $ gpio readall
```

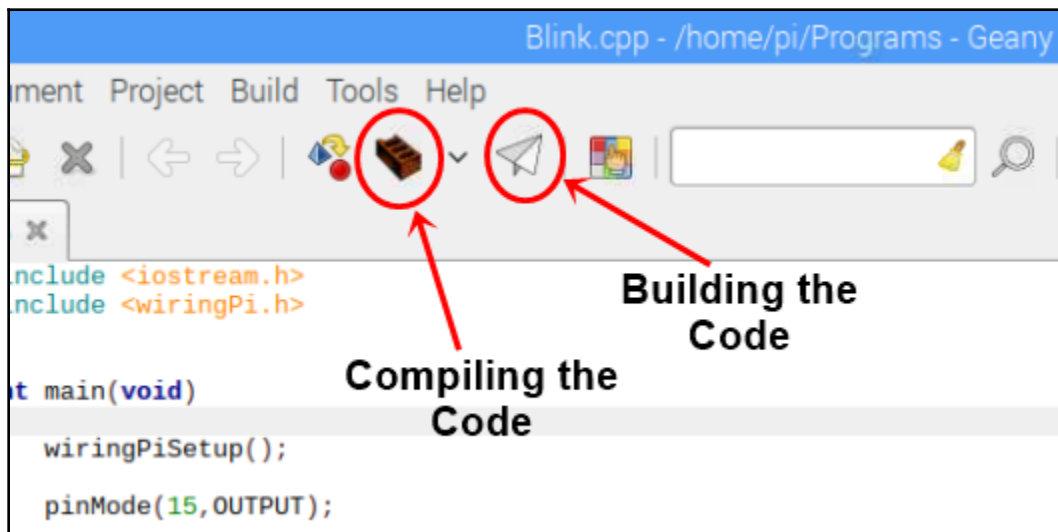
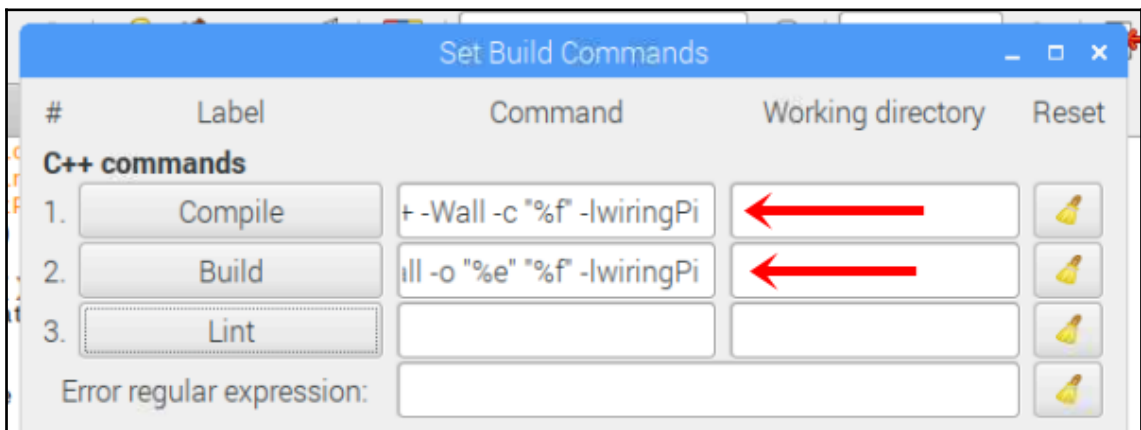
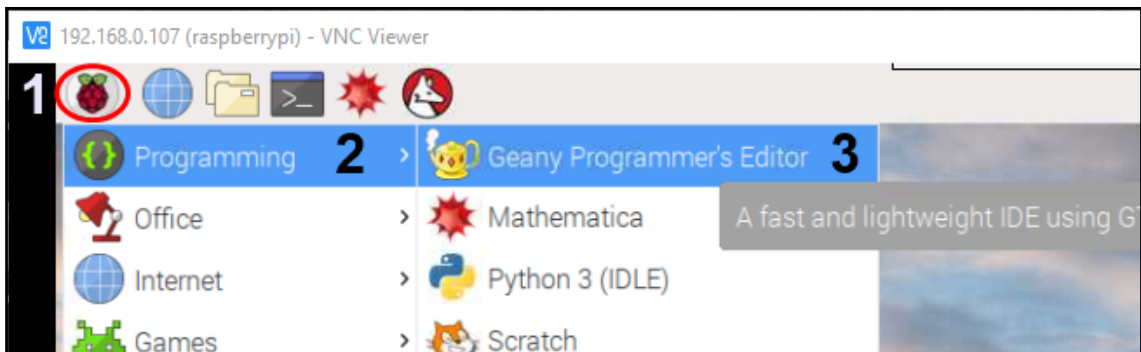
BCM	wPi	Name	Mode	V	Physical	V	Mode	Name	wPi	BCM
		3.3v			1 2			5v		
2	8	SBA.1	IN	1	3 4			5v		
3	9	SCL.1	IN	1	5 6			0v		
4	7	GPIO.7	IN	1	7 8	0	IN	TxD	15	14
		0v			9 10	1	IN	RxD	16	15
17	0	GPIO.0	IN	0	11 12	0	IN	GPIO.4	1	18
27	2	GPIO.2	IN	0	13 14			0v		
22	3	GPIO.3	IN	0	15 16	0	IN	GPIO.1	4	23
		3.3v			17 18	0	IN	GPIO.5	5	24
10	12	MOSI	IN	0	19 20			0v		
9	13	MISO	IN	0	21 22	0	IN	GPIO.6	6	25
11	14	SCLK	IN	0	23 24	1	IN	CE0	10	8
		0v			25 26	1	IN	CE1	11	7
0	30	SBA.0	IN	1	27 28	1	IN	SCL.0	31	1
5	21	GPIO.21	IN	1	29 30			0v		
6	22	GPIO.22	IN	1	31 32	0	IN	GPIO.26	26	12
13	23	GPIO.23	IN	0	33 34			0v		
19	24	GPIO.24	IN	0	35 36	0	IN	GPIO.27	27	16
26	25	GPIO.25	IN	0	37 38	0	IN	GPIO.20	28	20
		0v			39 40	0	IN	GPIO.29	29	21

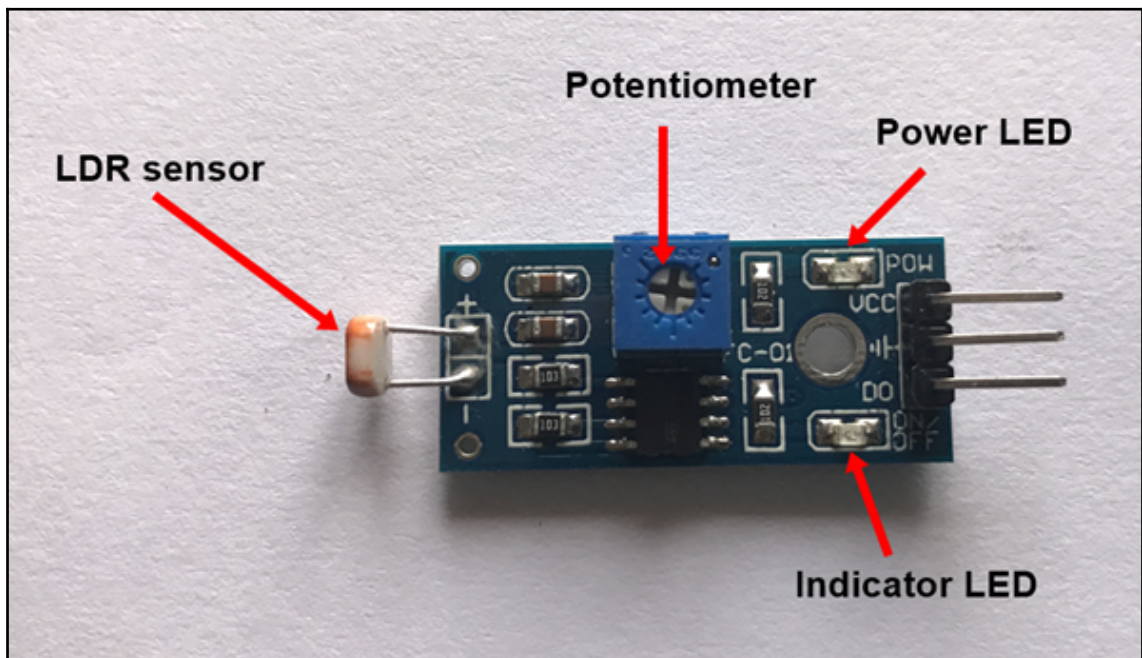
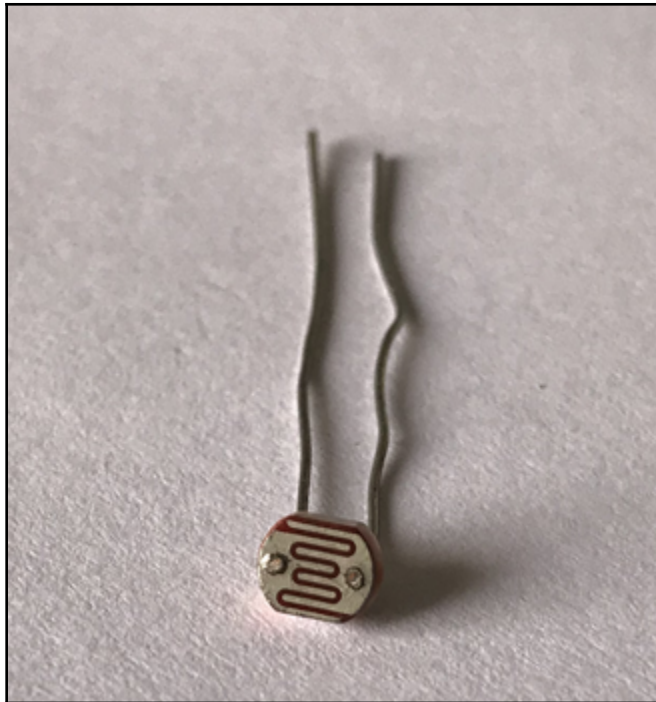
```
pi@raspberrypi:~ $
```

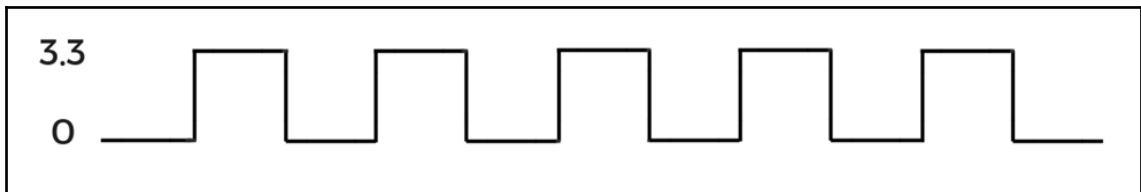
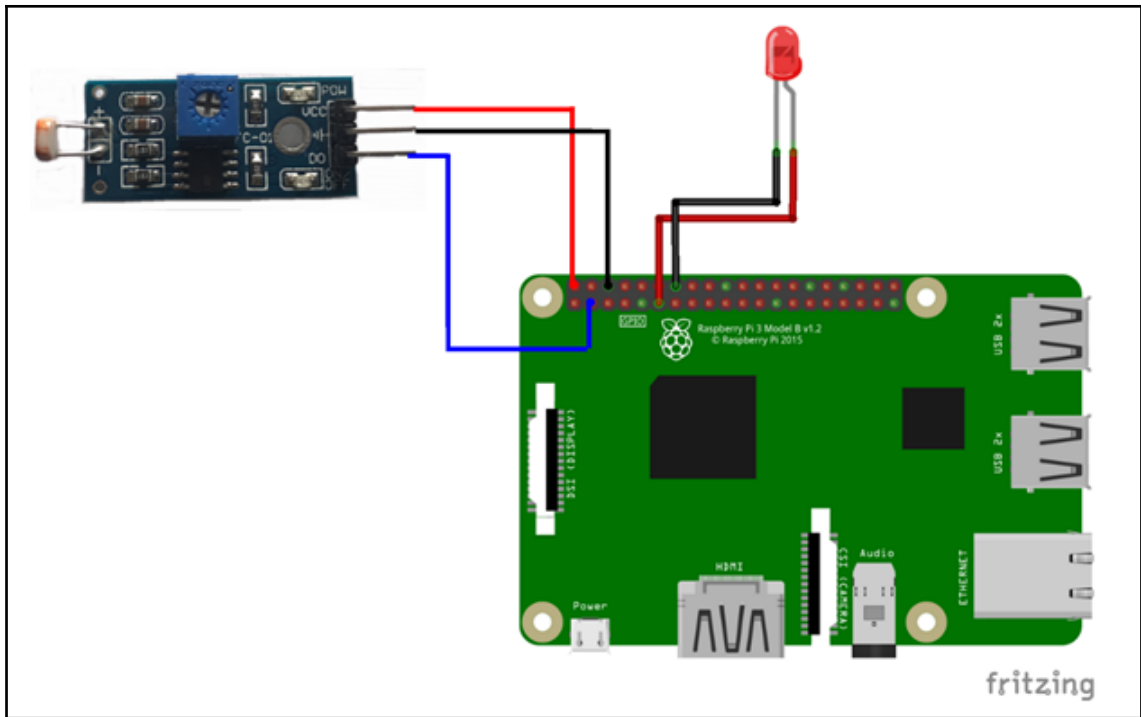
Raspberry Pi Pinout

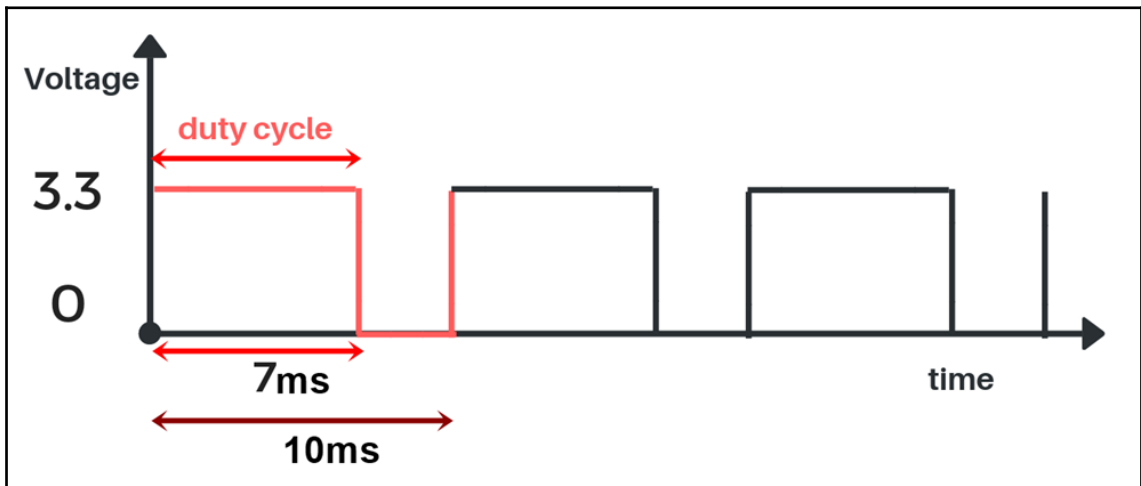
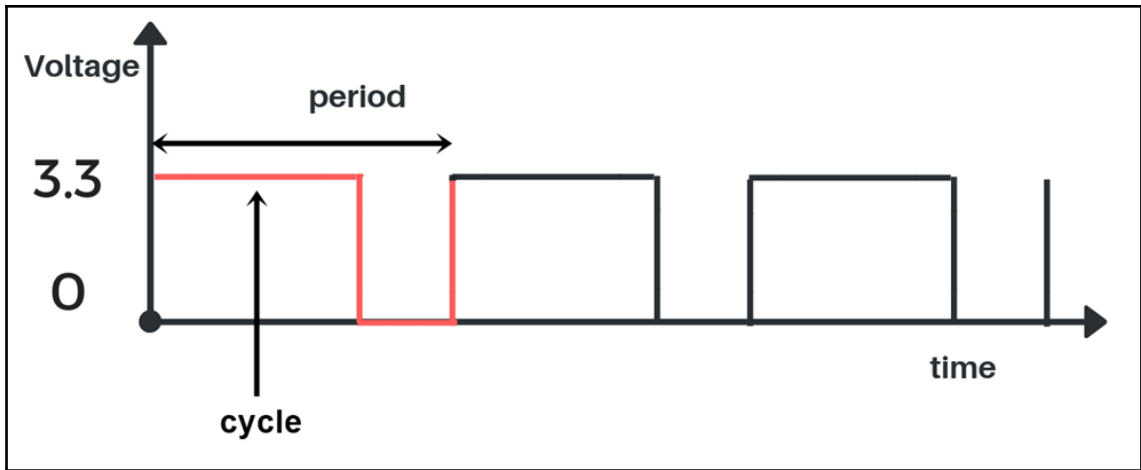
3v3 Power	1			2	5v Power
BCM 2 (WiringPi 8)	3			4	5v Power
BCM 3 (WiringPi 9)	5			6	Ground
BCM 4 (WiringPi 7)	7			8	BCM 14 (WiringPi 15)
Ground	9			10	BCM 15 (WiringPi 16)
BCM 17 (WiringPi 0)	11			12	BCM 18 (WiringPi 1)
BCM 27 (WiringPi 2)	13			14	Ground
BCM 22 (WiringPi 3)	15			16	BCM 23 (WiringPi 4)
3v3 Power	17			18	BCM 24 (WiringPi 5)
BCM 10 (WiringPi 12)	19			20	Ground
BCM 09 (WiringPi 13)	21			22	BCM 25 (WiringPi 06)
BCM 11 (WiringPi 14)	23			24	BCM 8 (WiringPi 10)
Ground	25			26	BCM 7 (WiringPi 11)
BCM 0 (WiringPi 30)	27			28	BCM 1 (WiringPi 31)
BCM 5 (WiringPi 21)	29			30	Ground
BCM 6 (WiringPi 22)	31			32	BCM 12 (WiringPi 26)
BCM 13 (WiringPi 23)	33			34	Ground
BCM 19 (WiringPi 24)	35			36	BCM 16 (WiringPi 27)
BCM 19 (WiringPi 25)	37			38	BCM 20 (WiringPi 28)
Ground	39			40	BCM 21 (WiringPi 29)

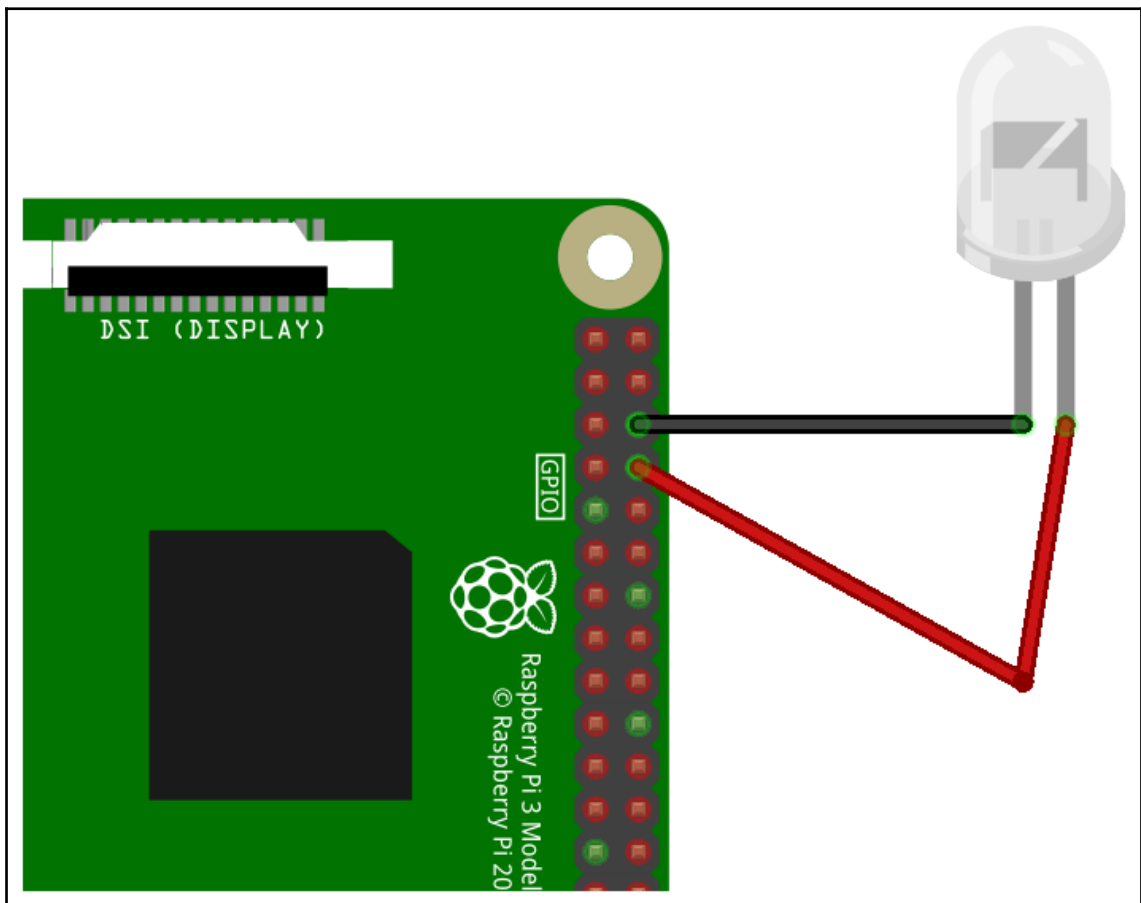
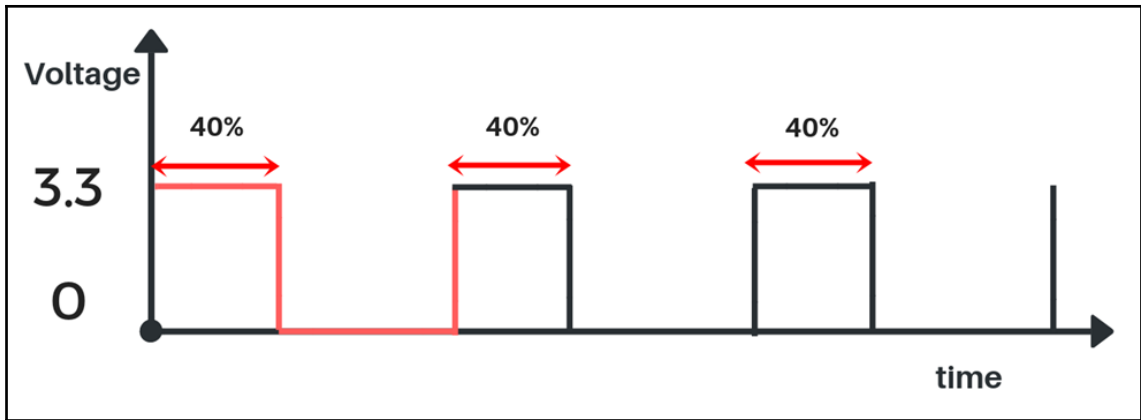




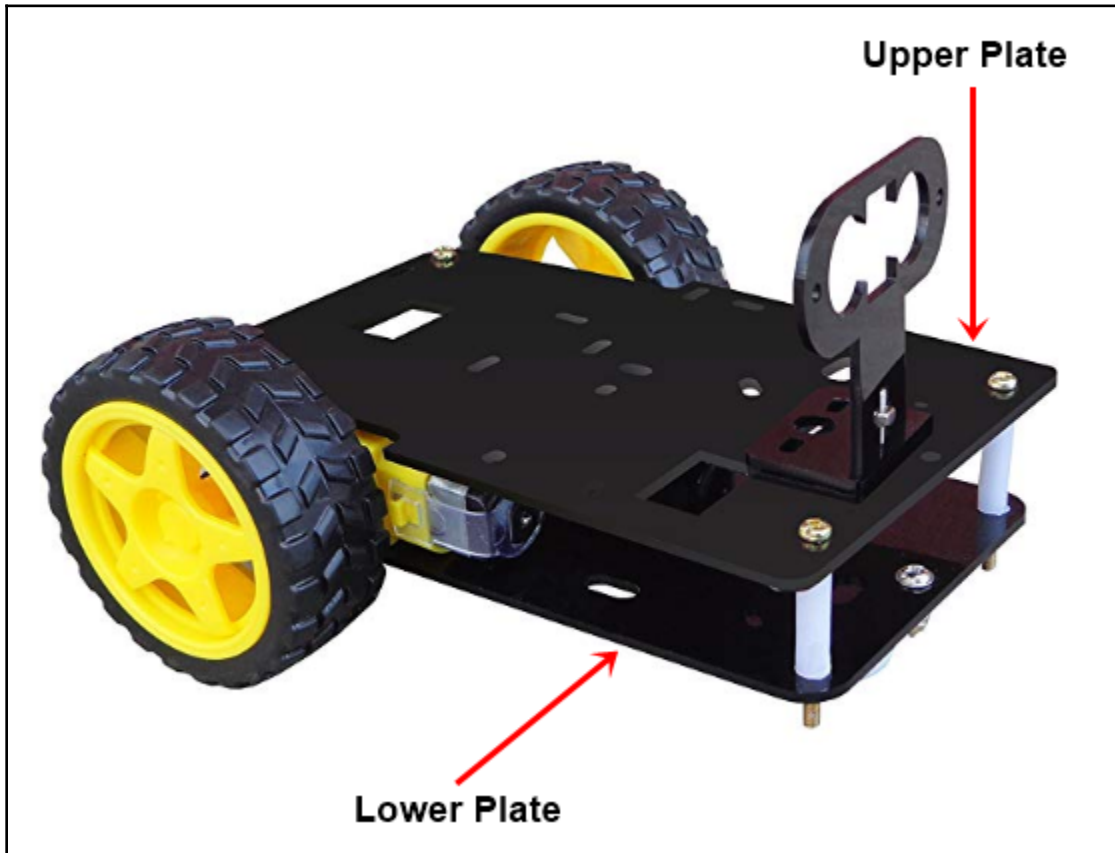


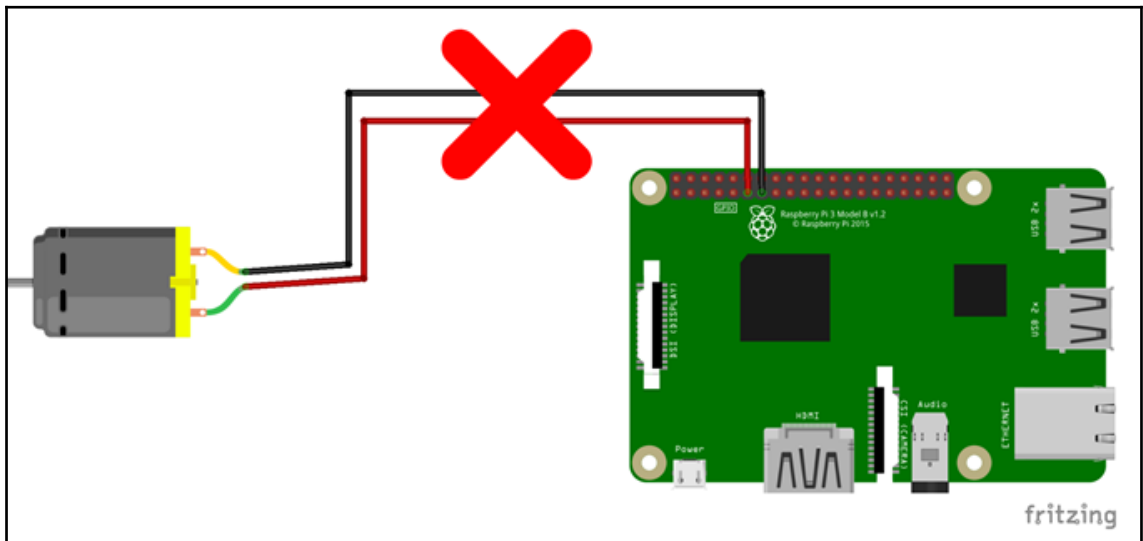
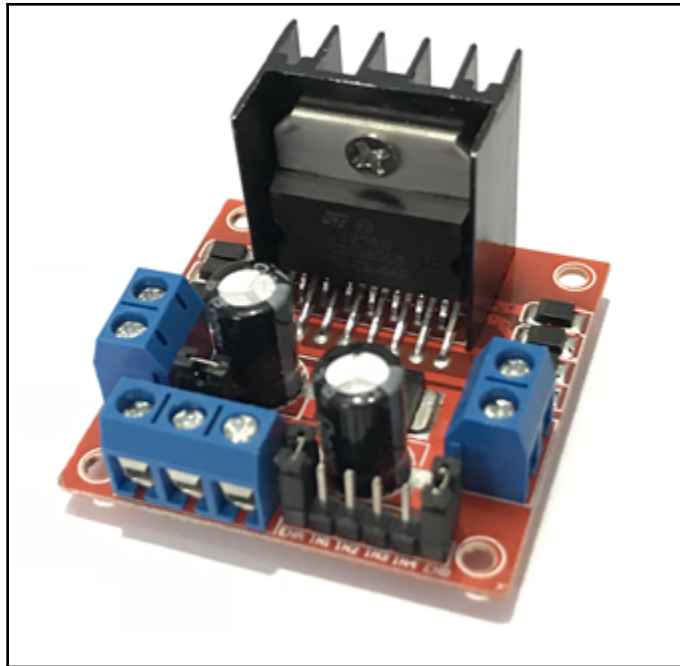


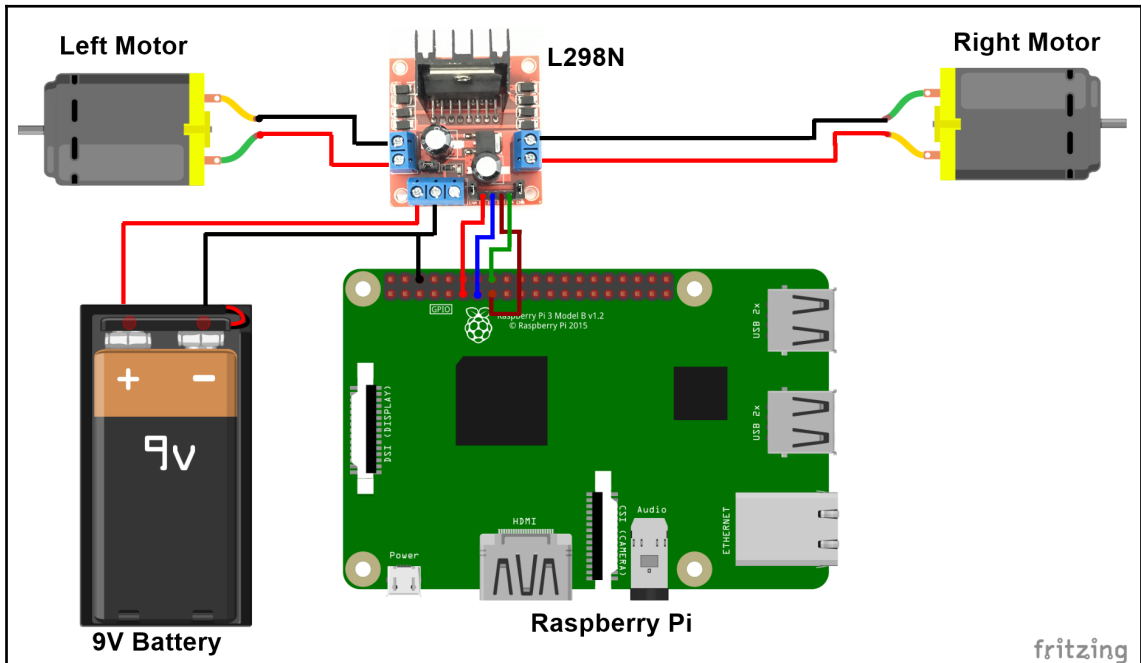
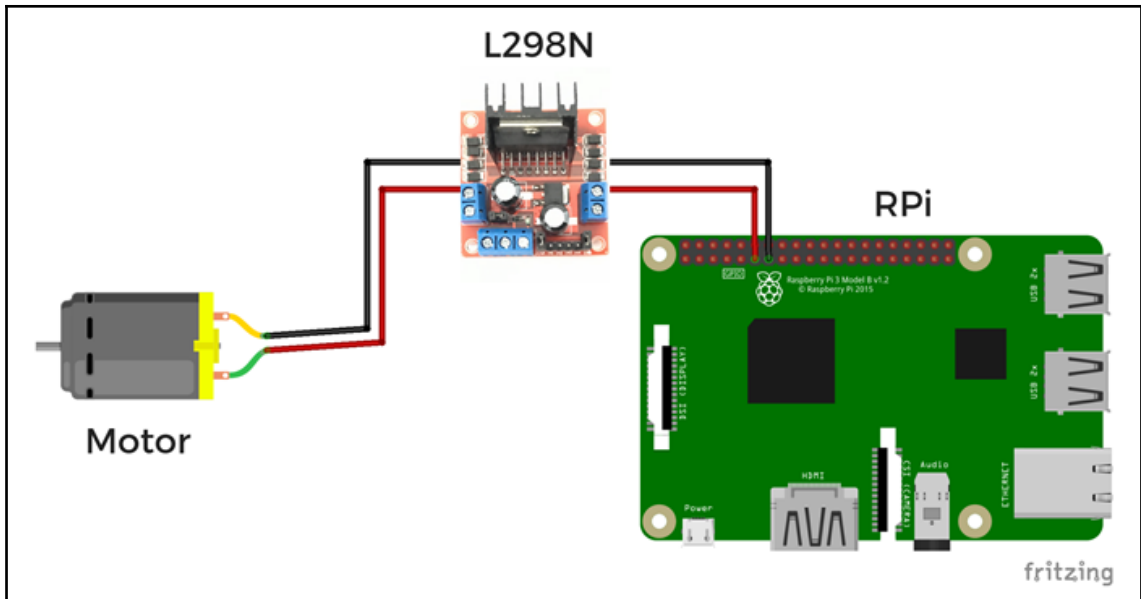


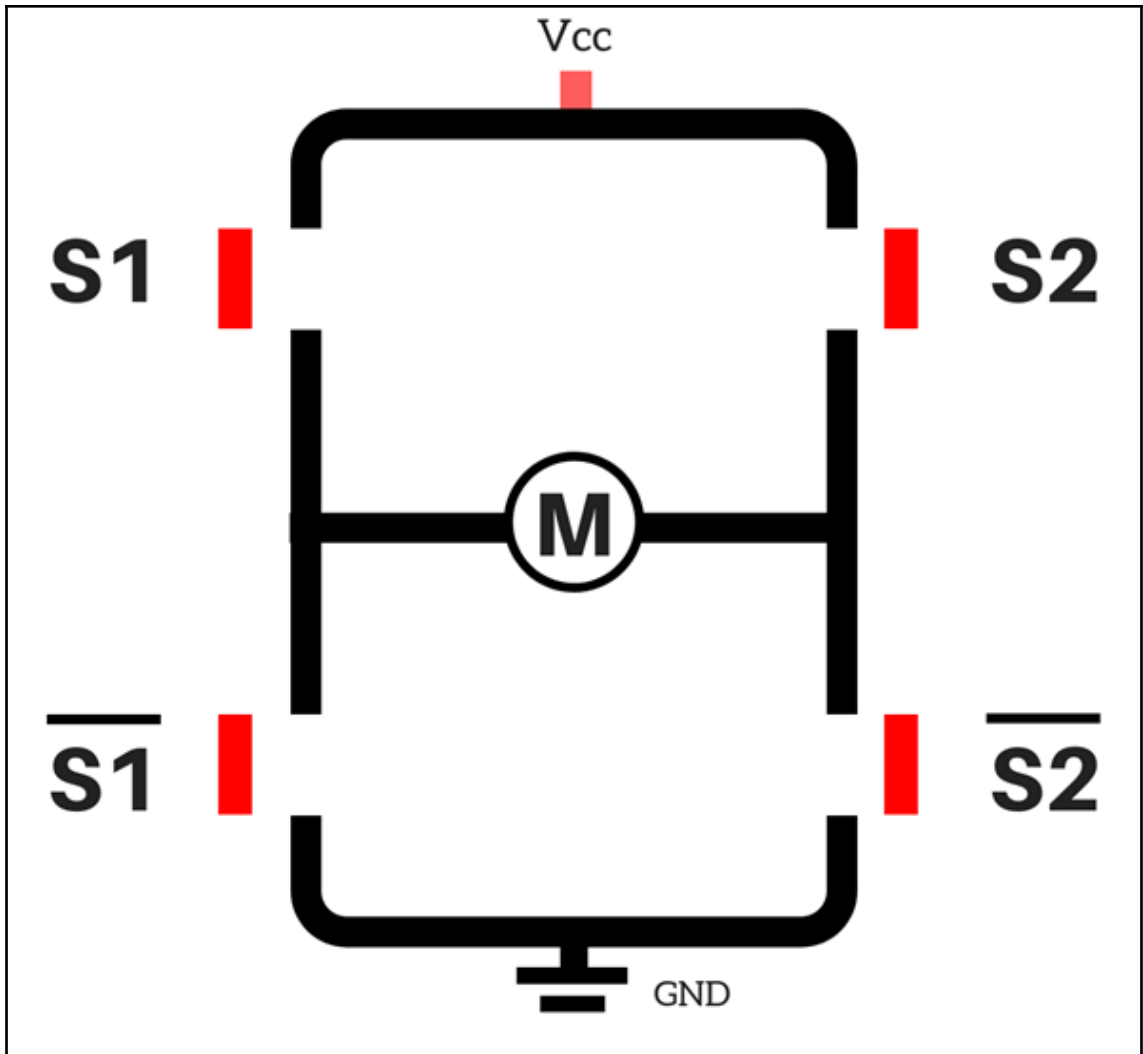


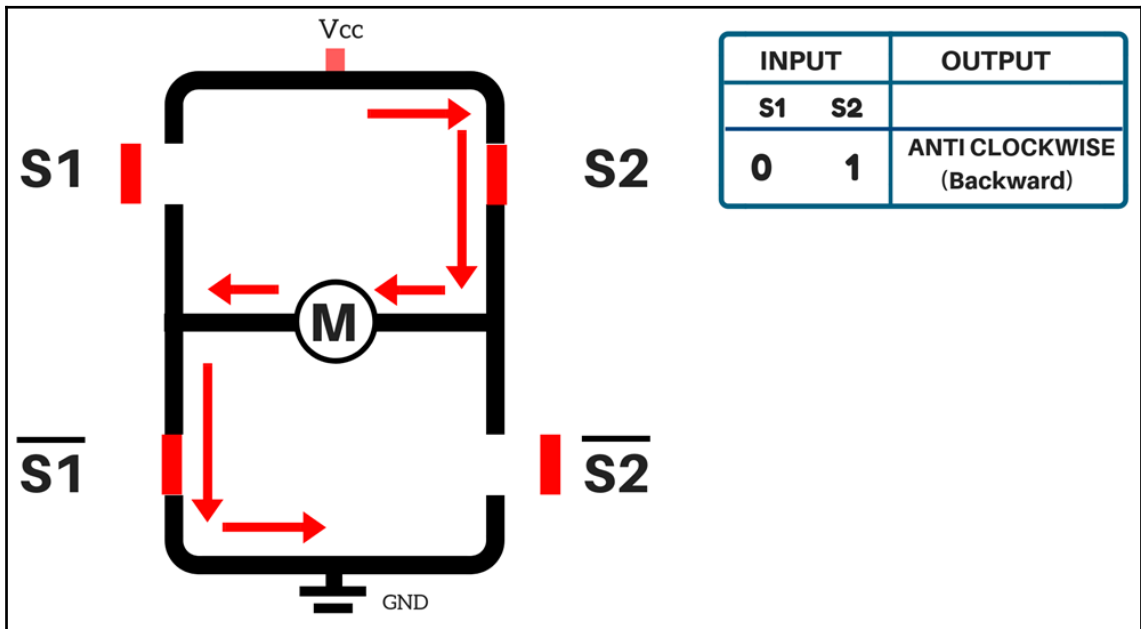
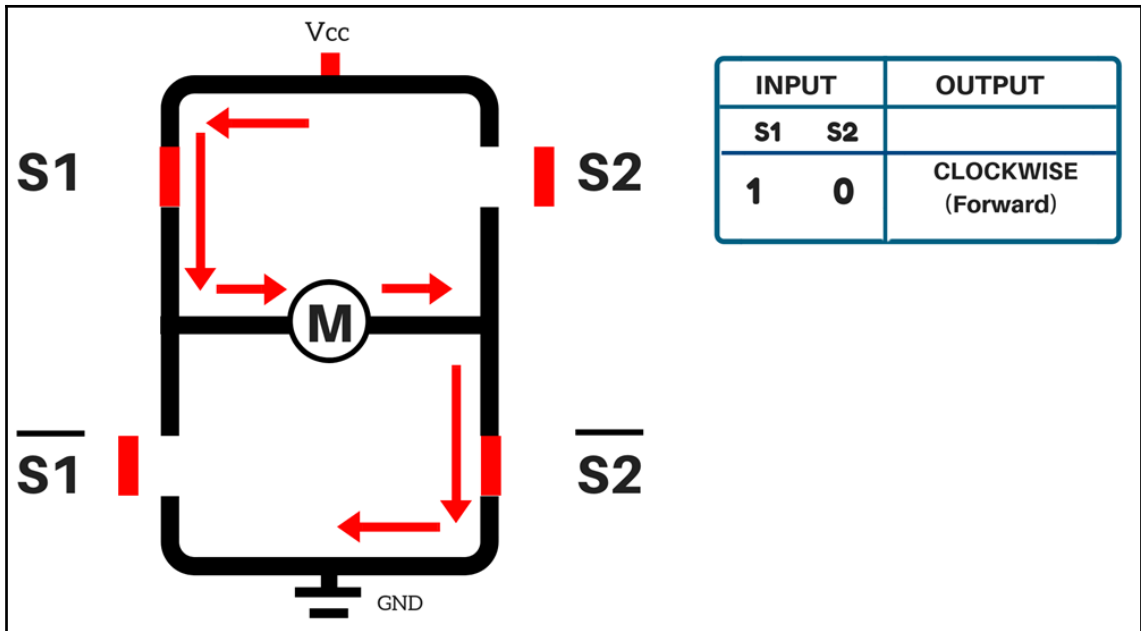
Chapter 3: Programming the Robot

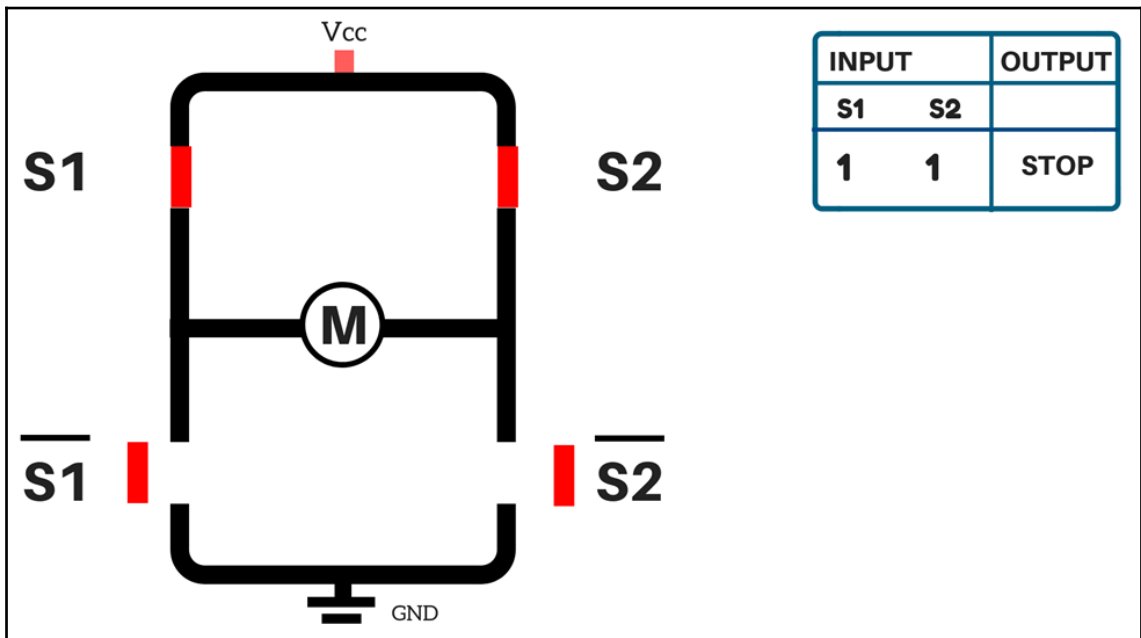
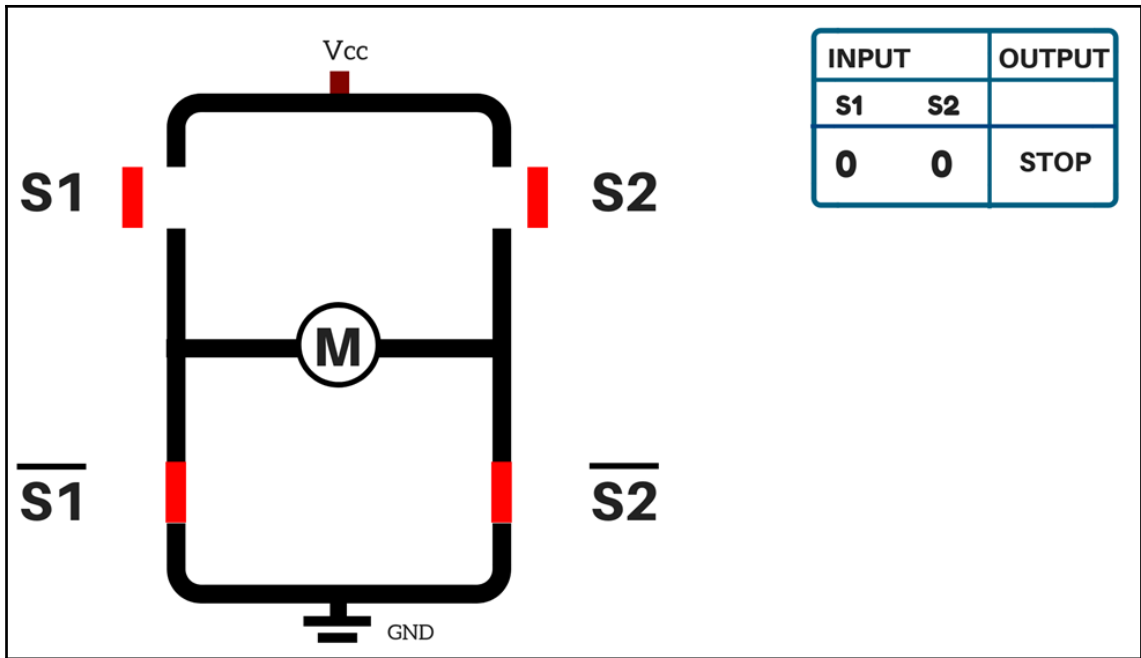


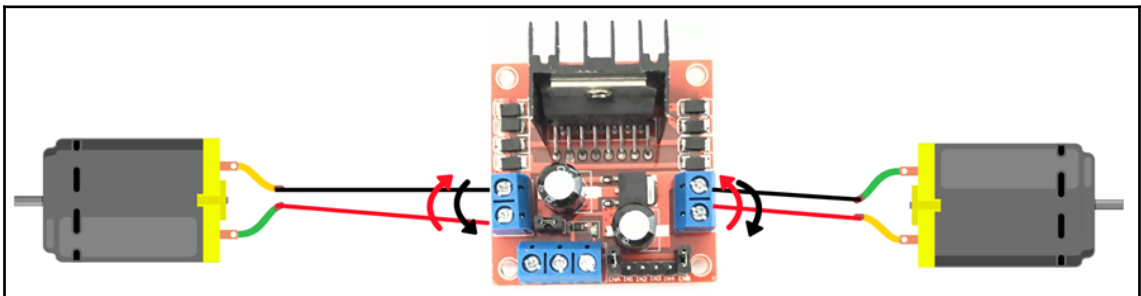
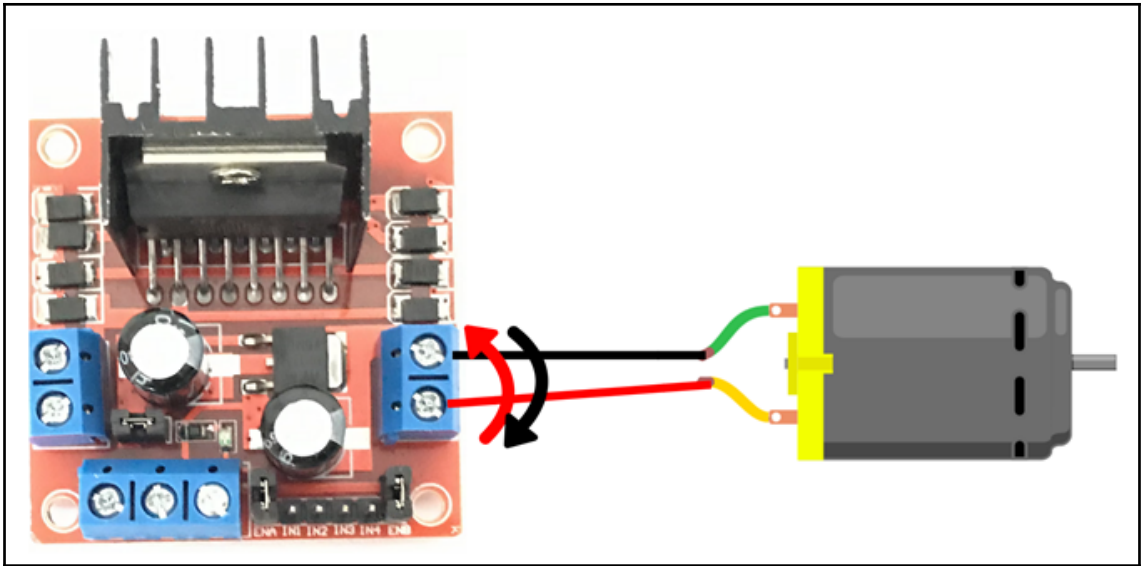


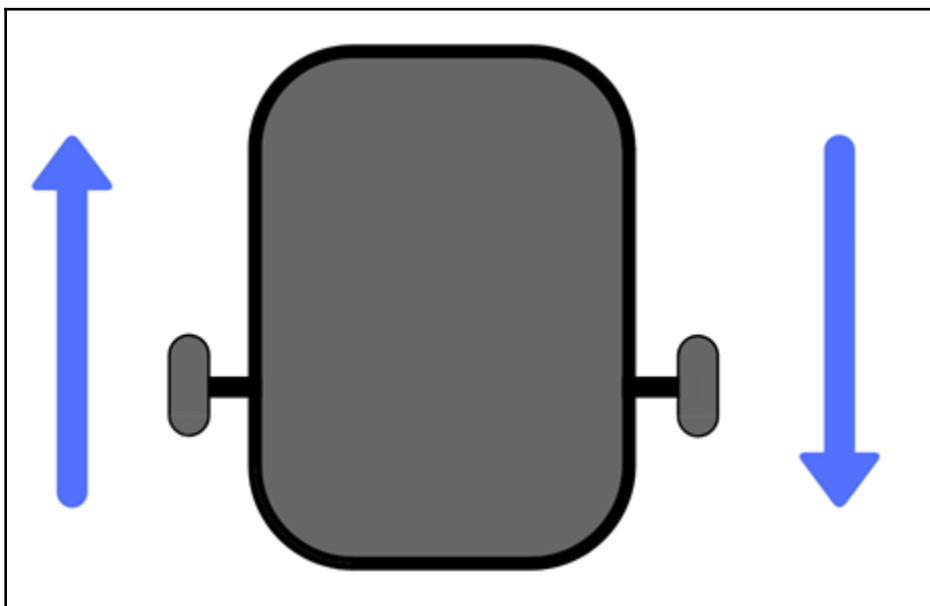
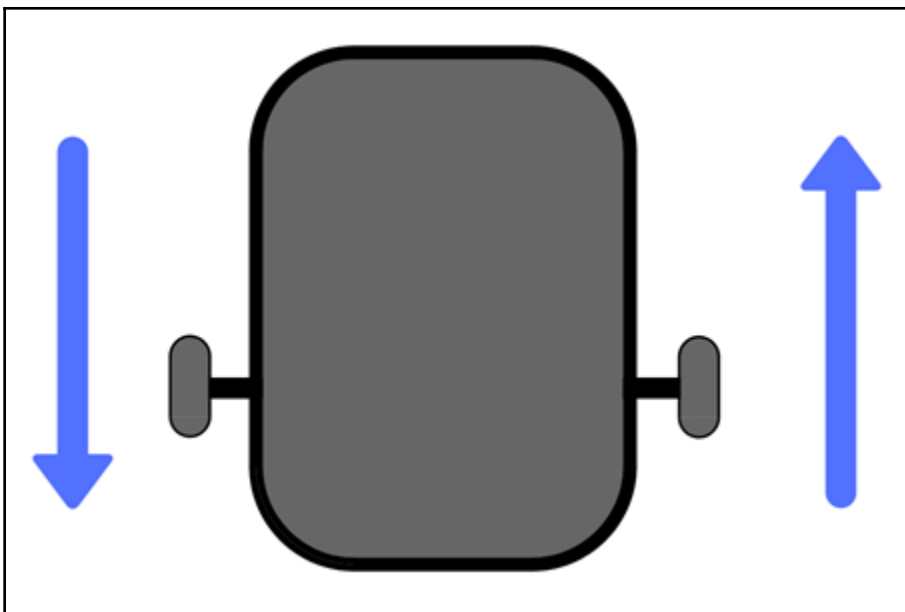


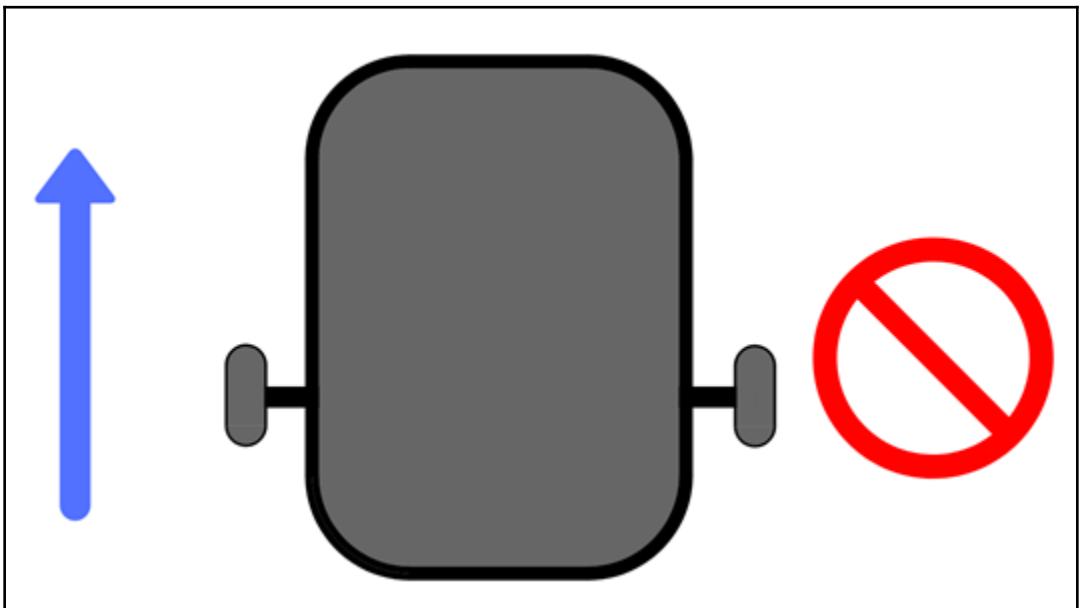
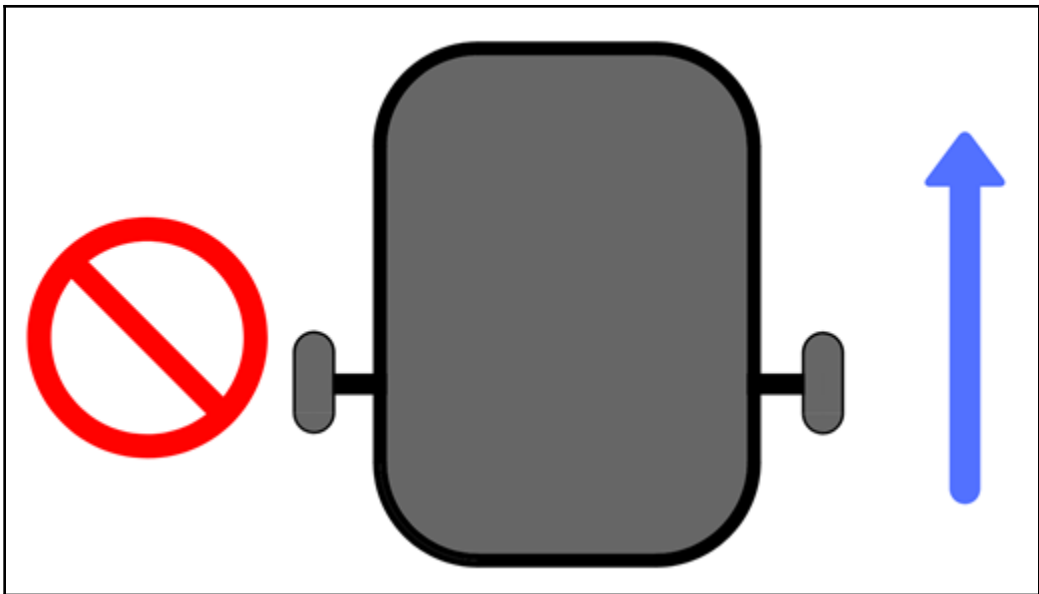




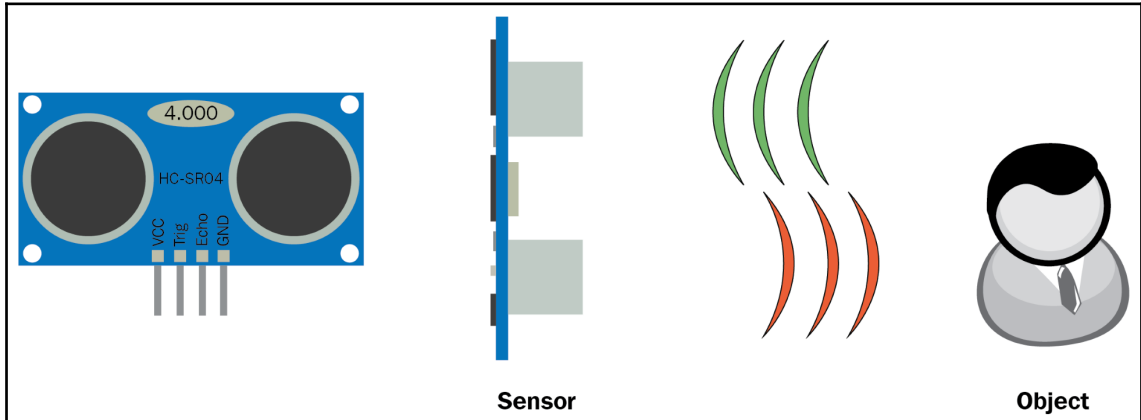


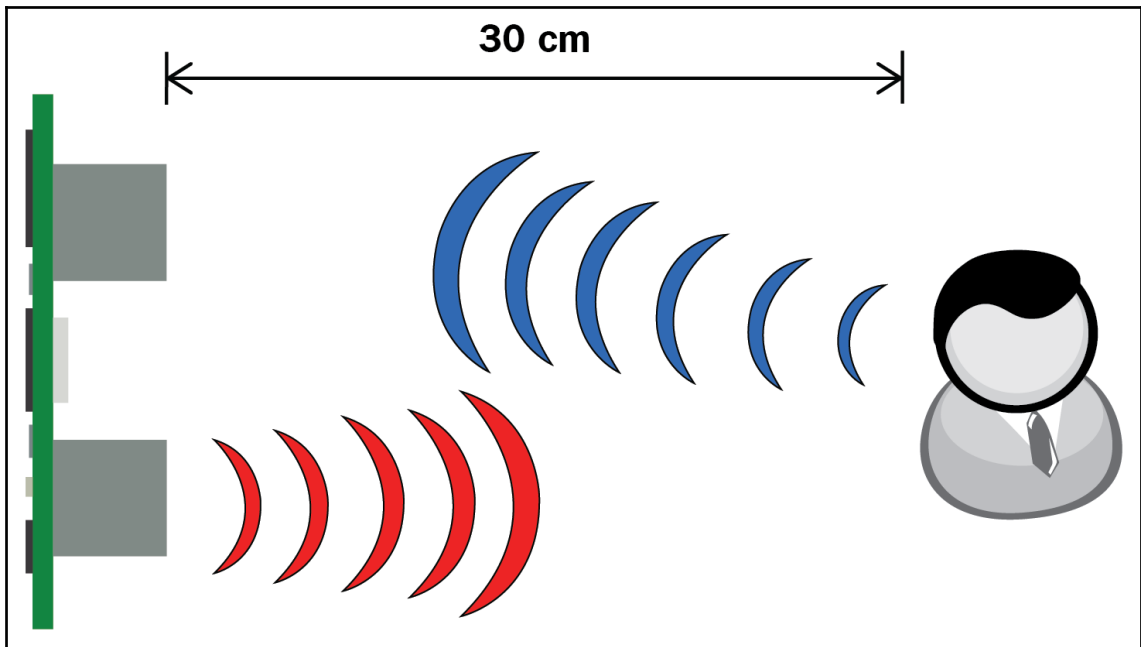
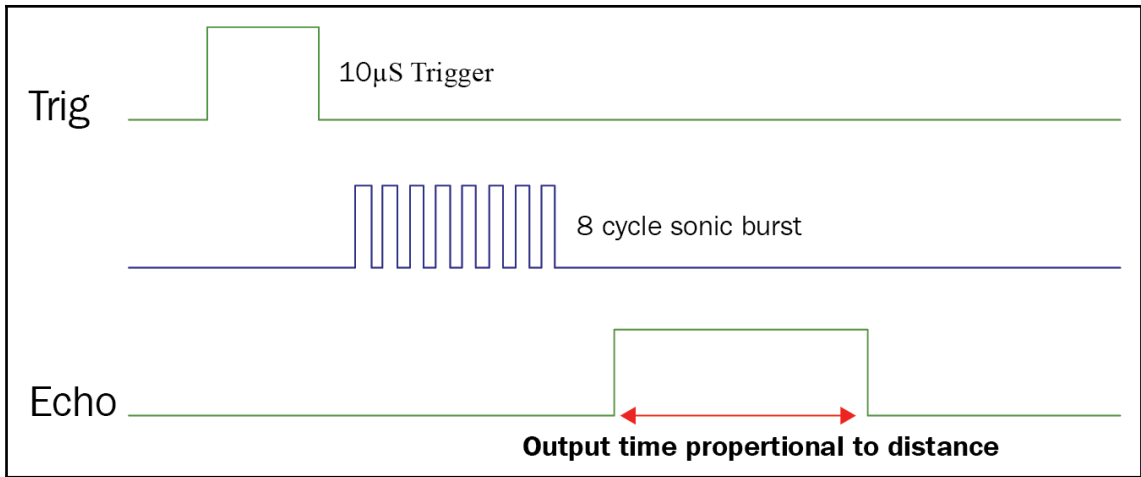


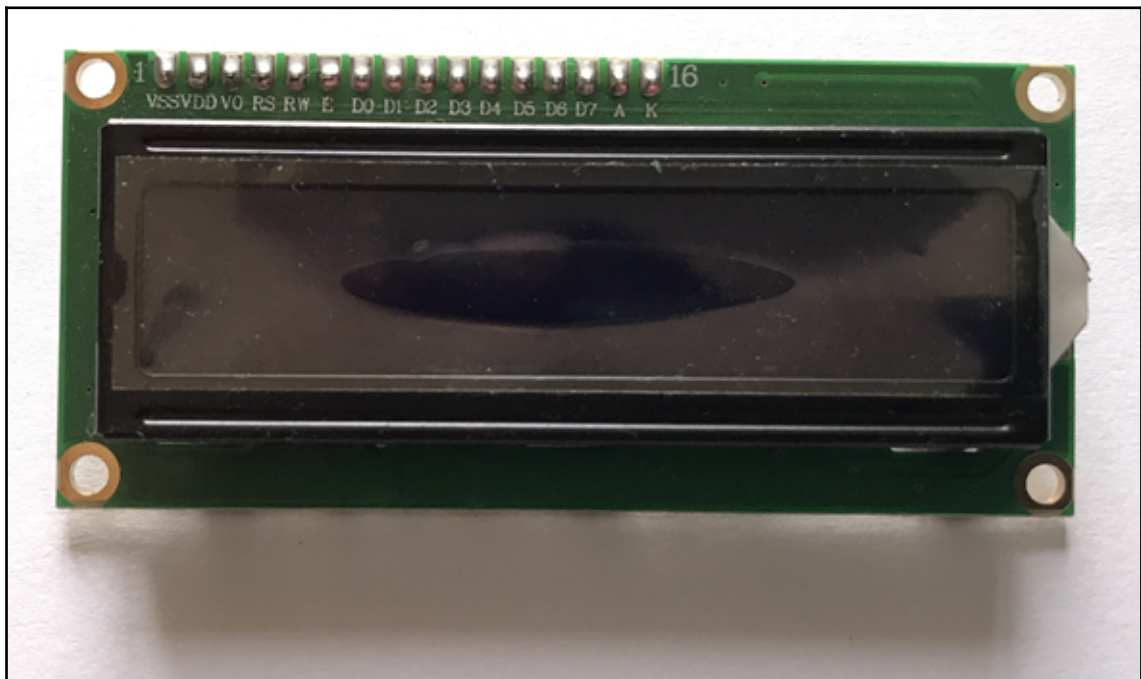
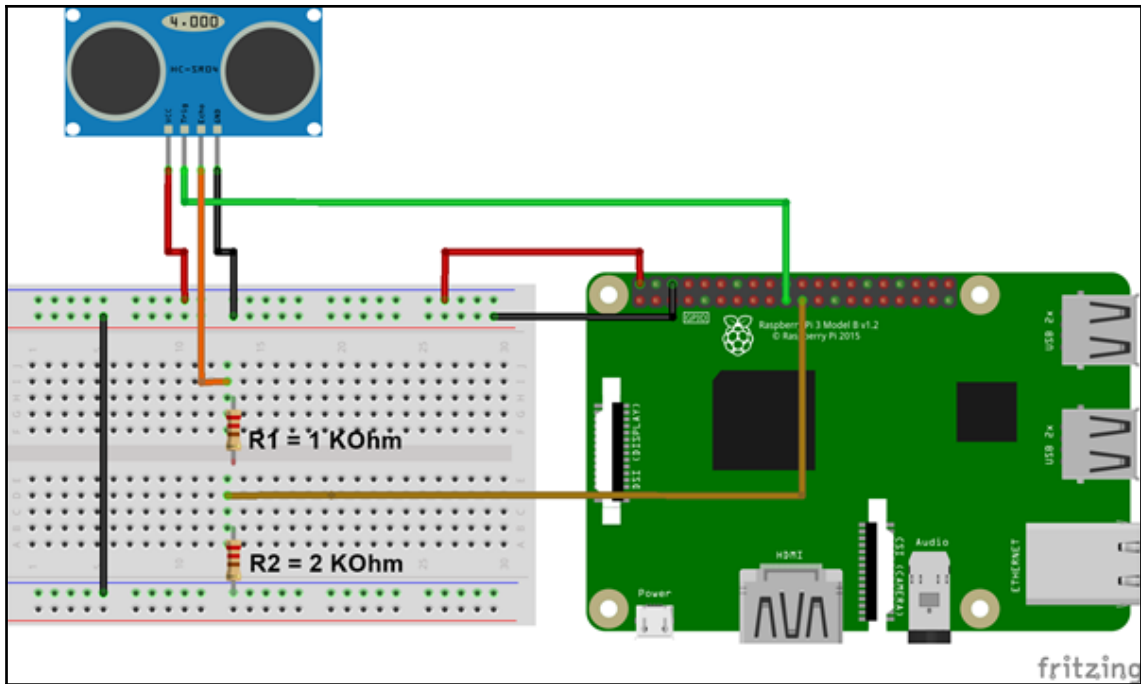




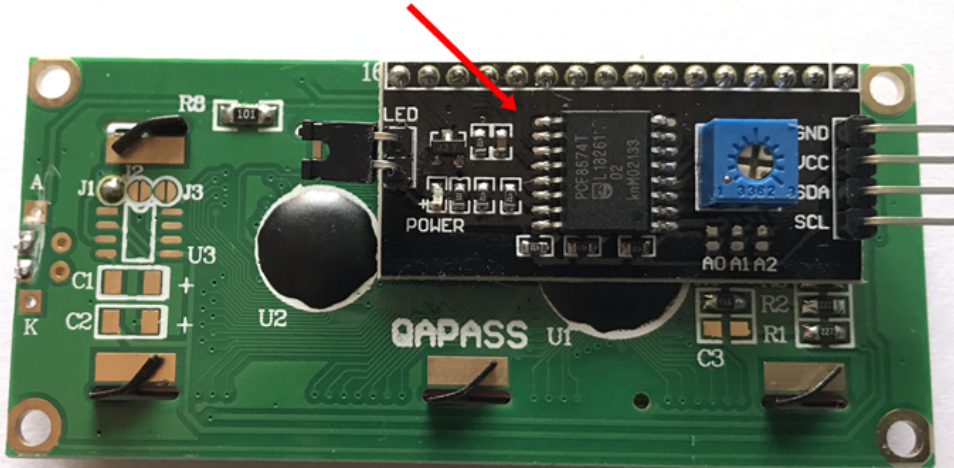
Chapter 4: Building an Obstacle-Avoiding Robot

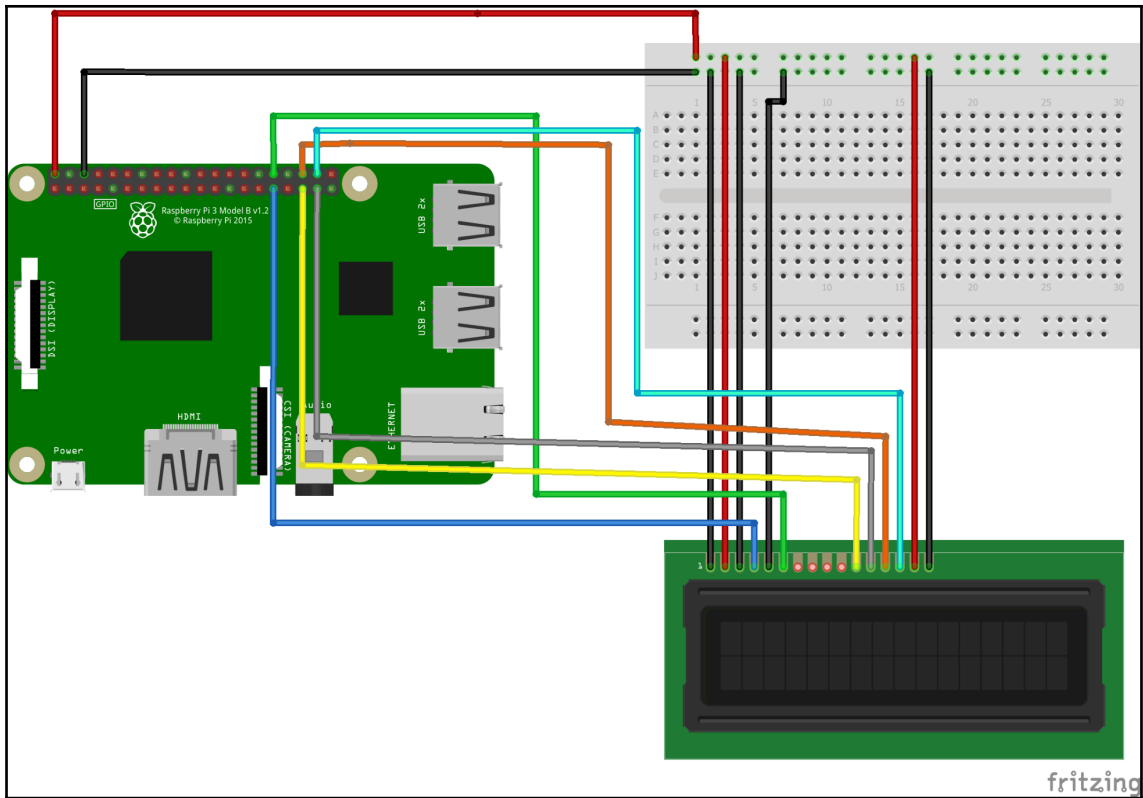




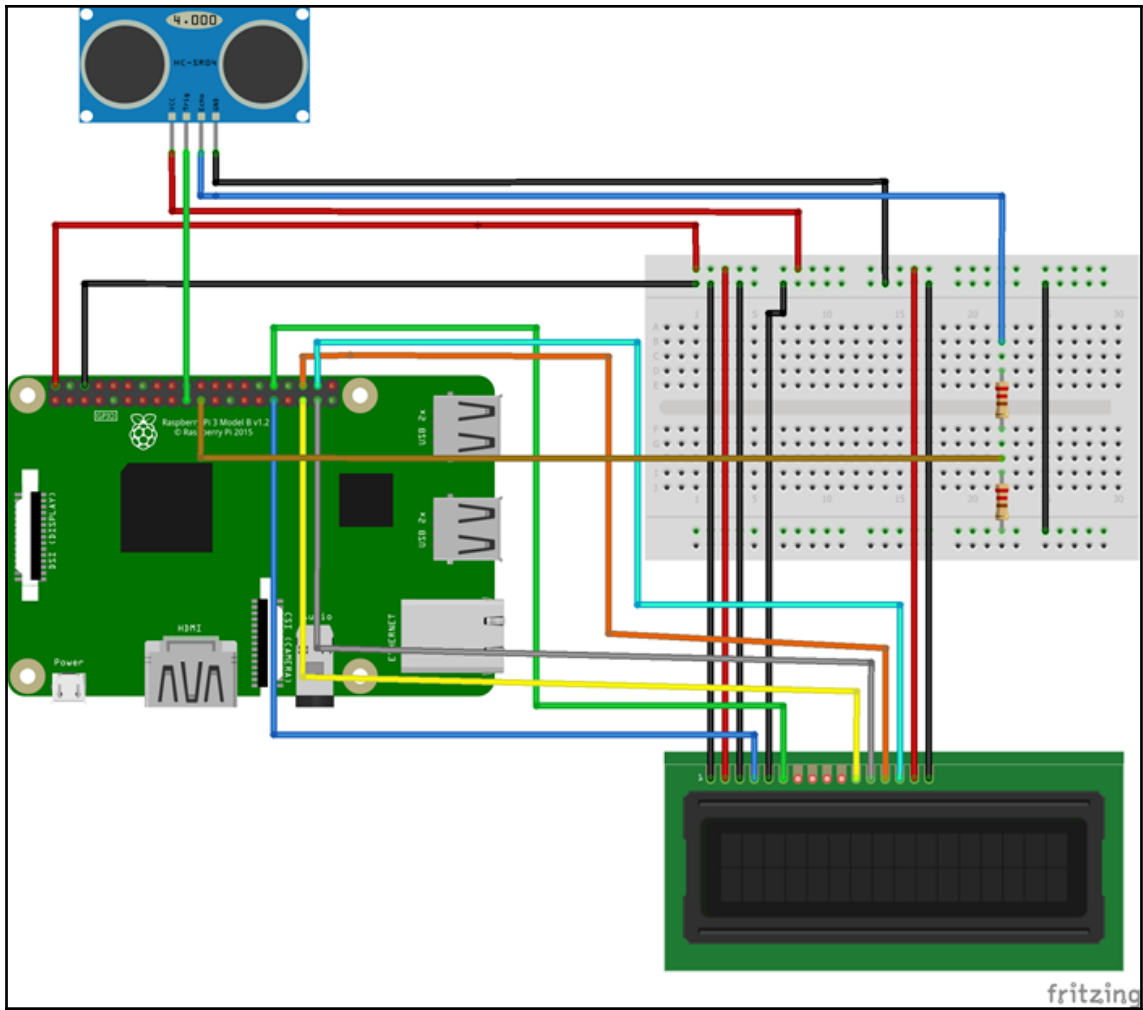


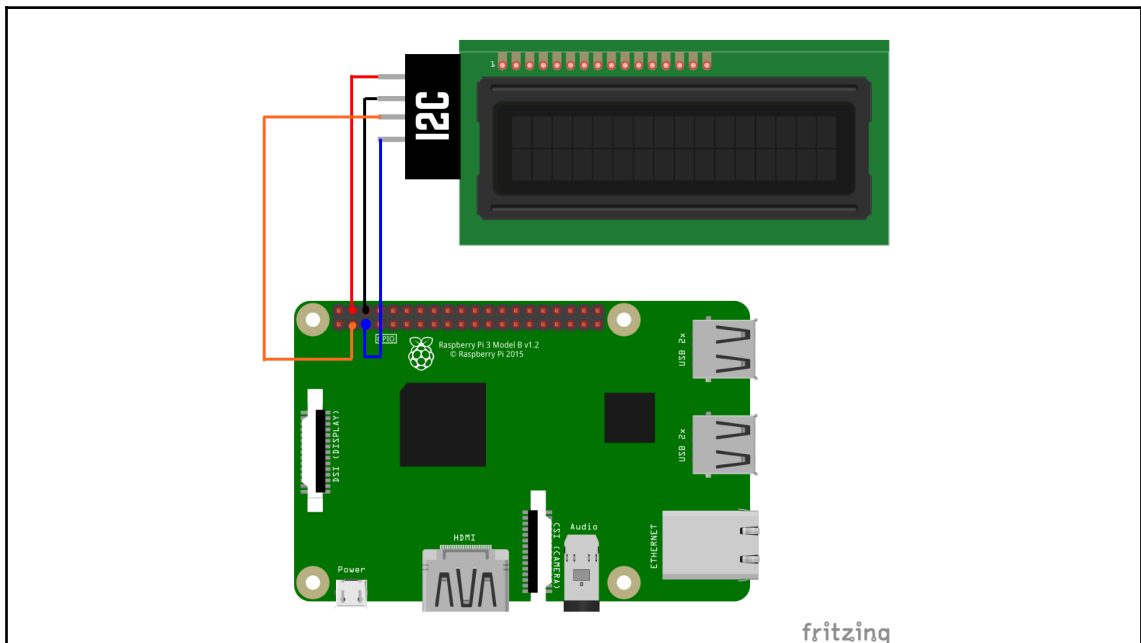
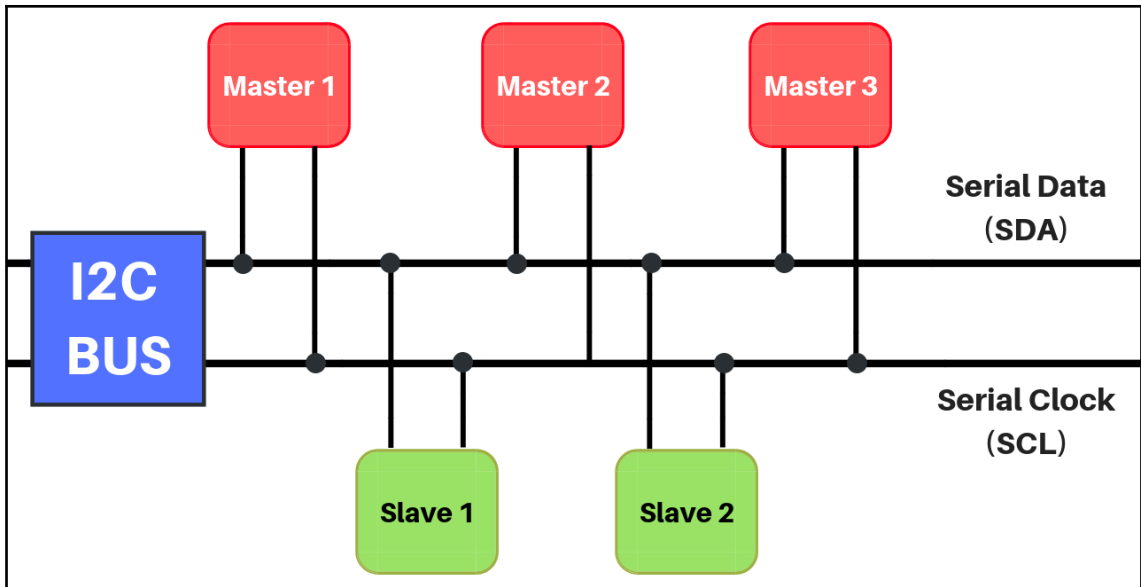
I2C LCD Adapter module

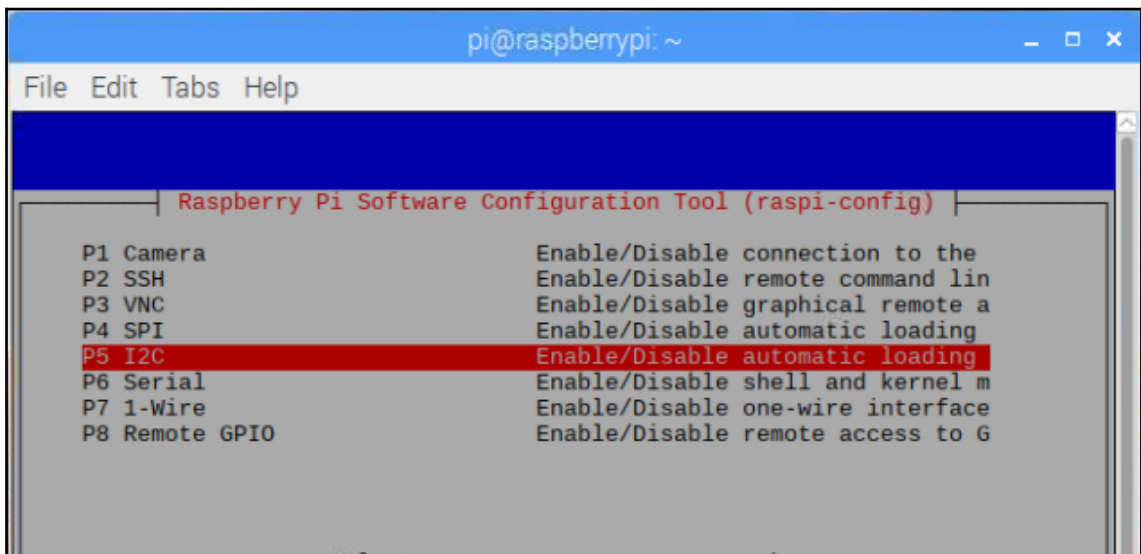
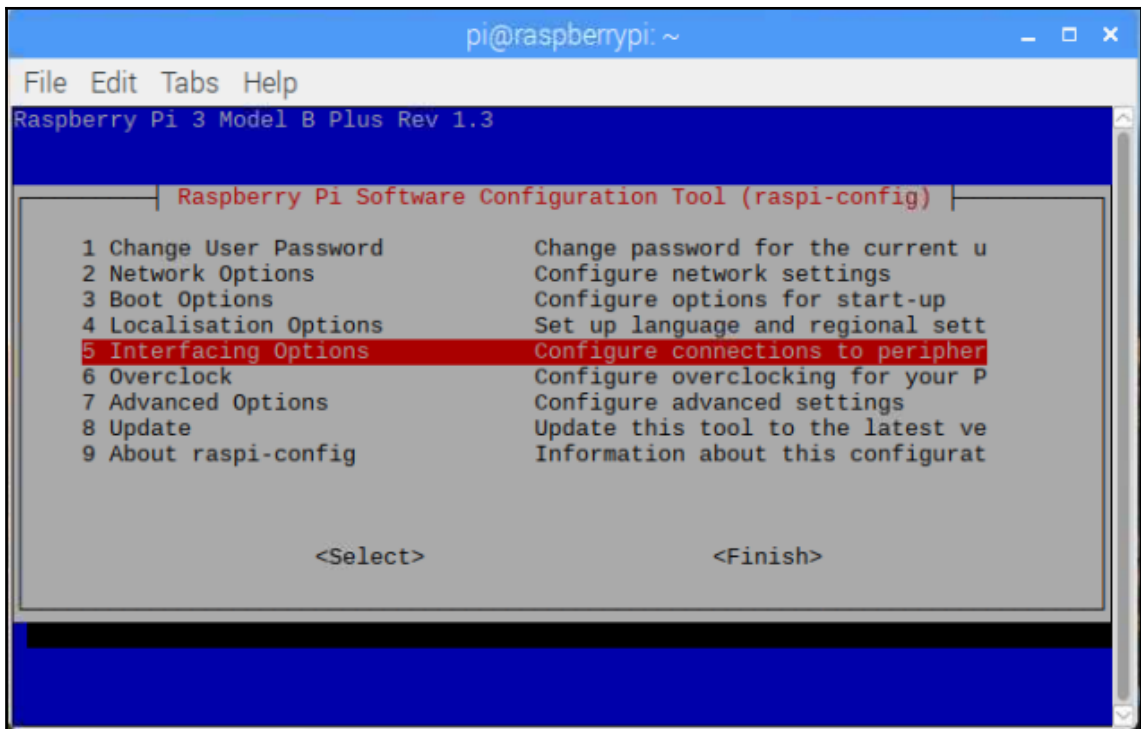


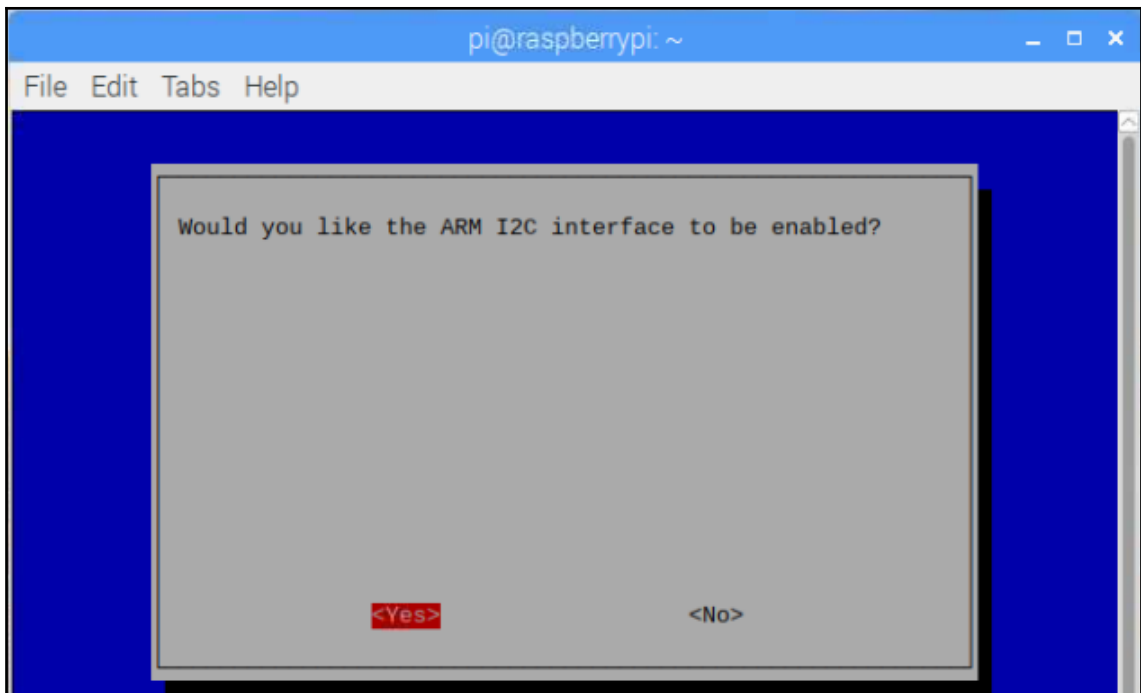


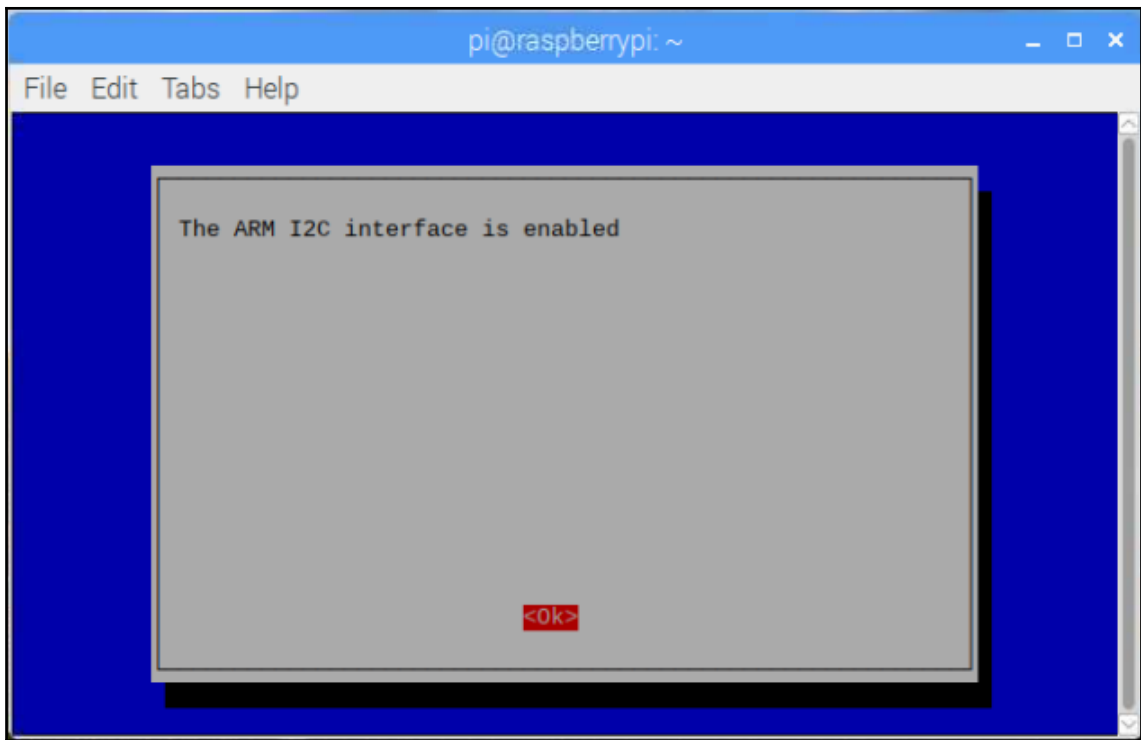
Set Build Commands				
#	Label	Command	Working directory	Reset
C commands				
1.	Compile	<code>gcc -Wall -c "%f" -lwiringPi -lwiringPiDev</code>		
2.	Build	<code>gcc -Wall -o "%e" "%f" -lwiringPi -lwiringPiDev</code>		

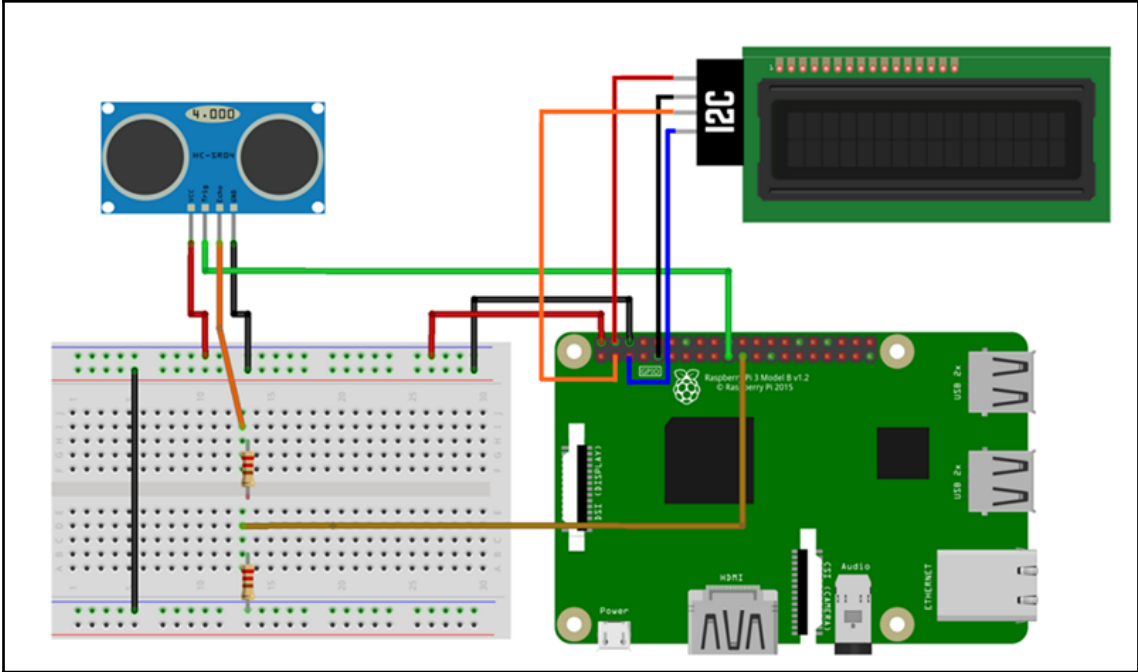


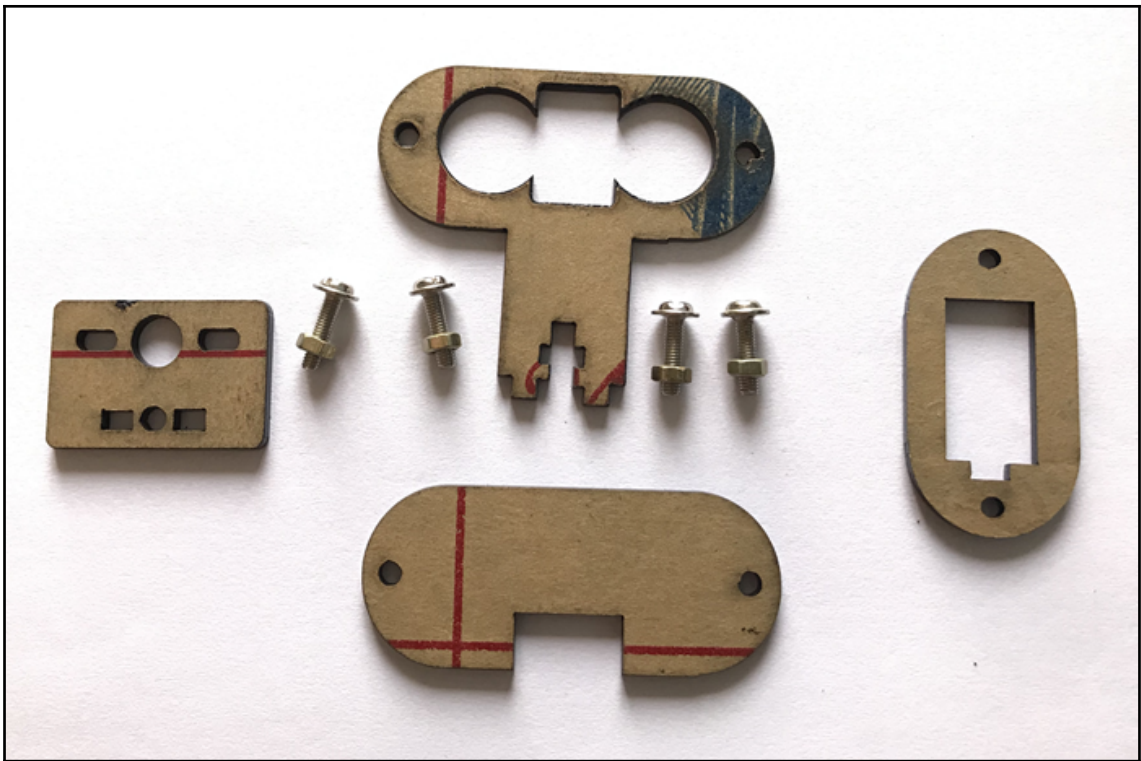


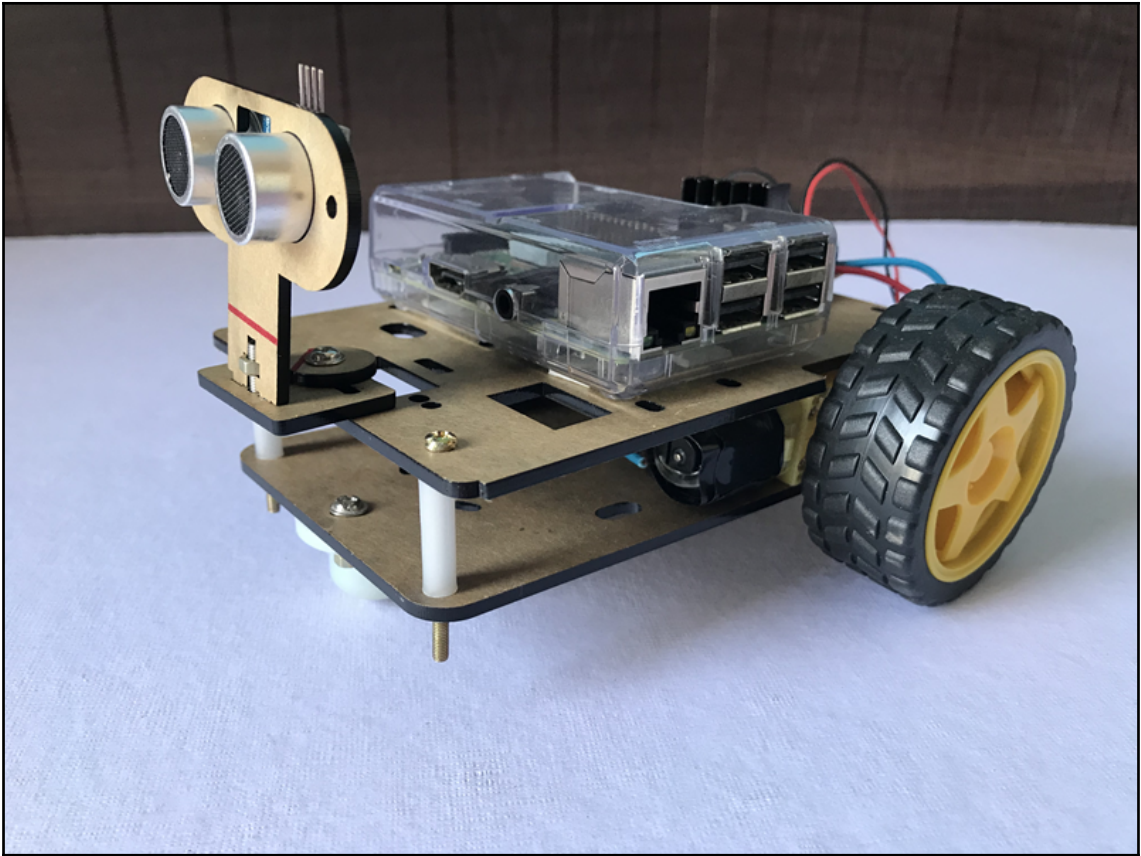




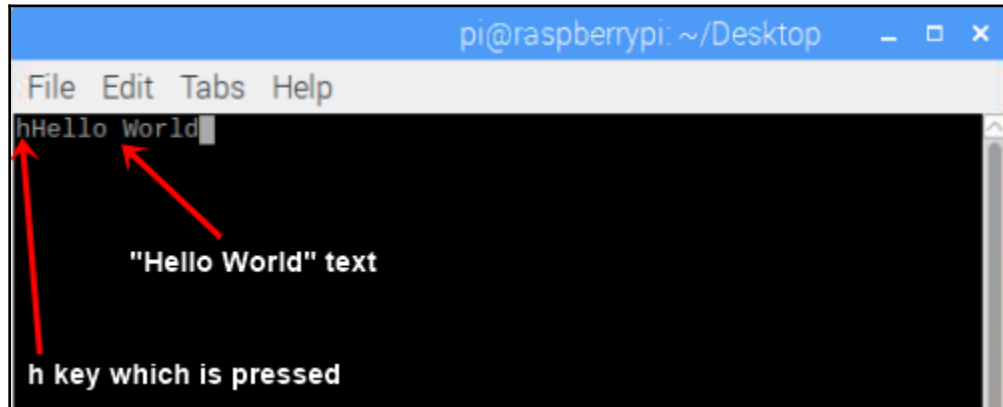








Chapter 5: Controlling a Robot Using a Laptop

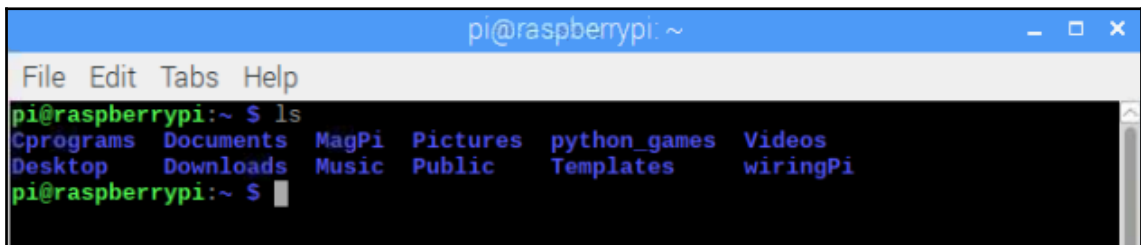


A screenshot of a Raspberry Pi terminal window titled "pi@raspberrypi: ~/Desktop". The window has a menu bar with "File", "Edit", "Tabs", and "Help". The terminal shows the command "hHello World" with a cursor at the end. Two red arrows point to the "h" and the "Hello World" text. Below the terminal, the text "h key which is pressed" and "\"Hello World\" text" are written.

```
pi@raspberrypi: ~/Desktop
File Edit Tabs Help
hHello World
```

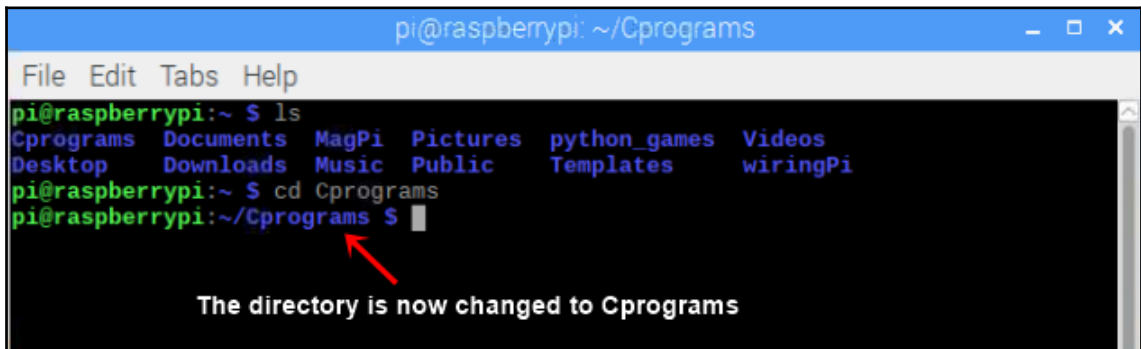
h key which is pressed

"Hello World" text



A screenshot of a Raspberry Pi terminal window titled "pi@raspberrypi: ~". The window has a menu bar with "File", "Edit", "Tabs", and "Help". The terminal shows the command "ls" and its output, which lists the contents of the home directory.

```
pi@raspberrypi: ~
File Edit Tabs Help
pi@raspberrypi:~ $ ls
Cprograms  Documents  MagPi  Pictures  python_games  Videos
Desktop    Downloads  Music  Public   Templates      wiringPi
pi@raspberrypi:~ $
```



A screenshot of a Raspberry Pi terminal window titled "pi@raspberrypi: ~/Cprograms". The window has a menu bar with "File", "Edit", "Tabs", and "Help". The terminal shows the command "cd Cprograms" and its output, which shows the current directory has changed to "Cprograms". A red arrow points to the "Cprograms" in the output.

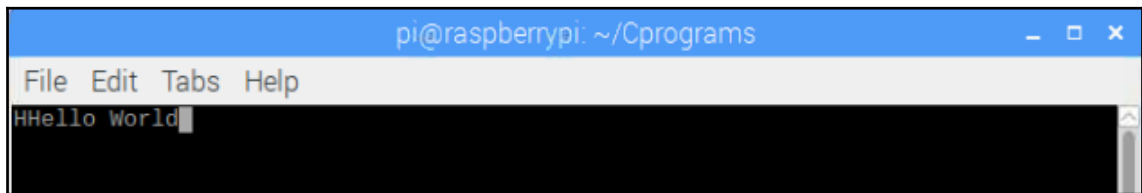
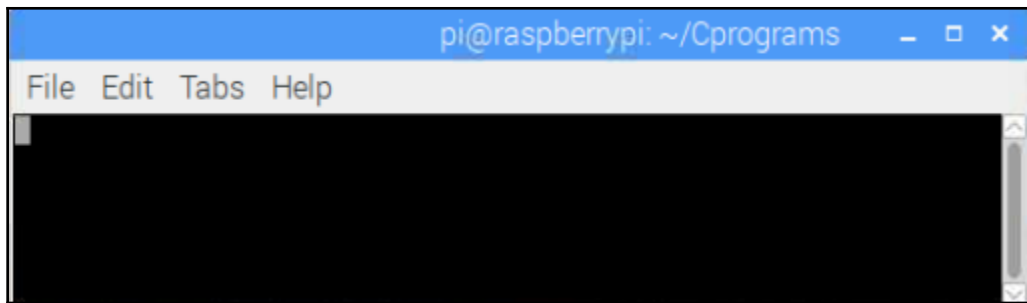
```
pi@raspberrypi: ~/Cprograms
File Edit Tabs Help
pi@raspberrypi:~ $ ls
Cprograms  Documents  MagPi  Pictures  python_games  Videos
Desktop    Downloads  Music  Public   Templates      wiringPi
pi@raspberrypi:~ $ cd Cprograms
pi@raspberrypi:~/Cprograms $
```

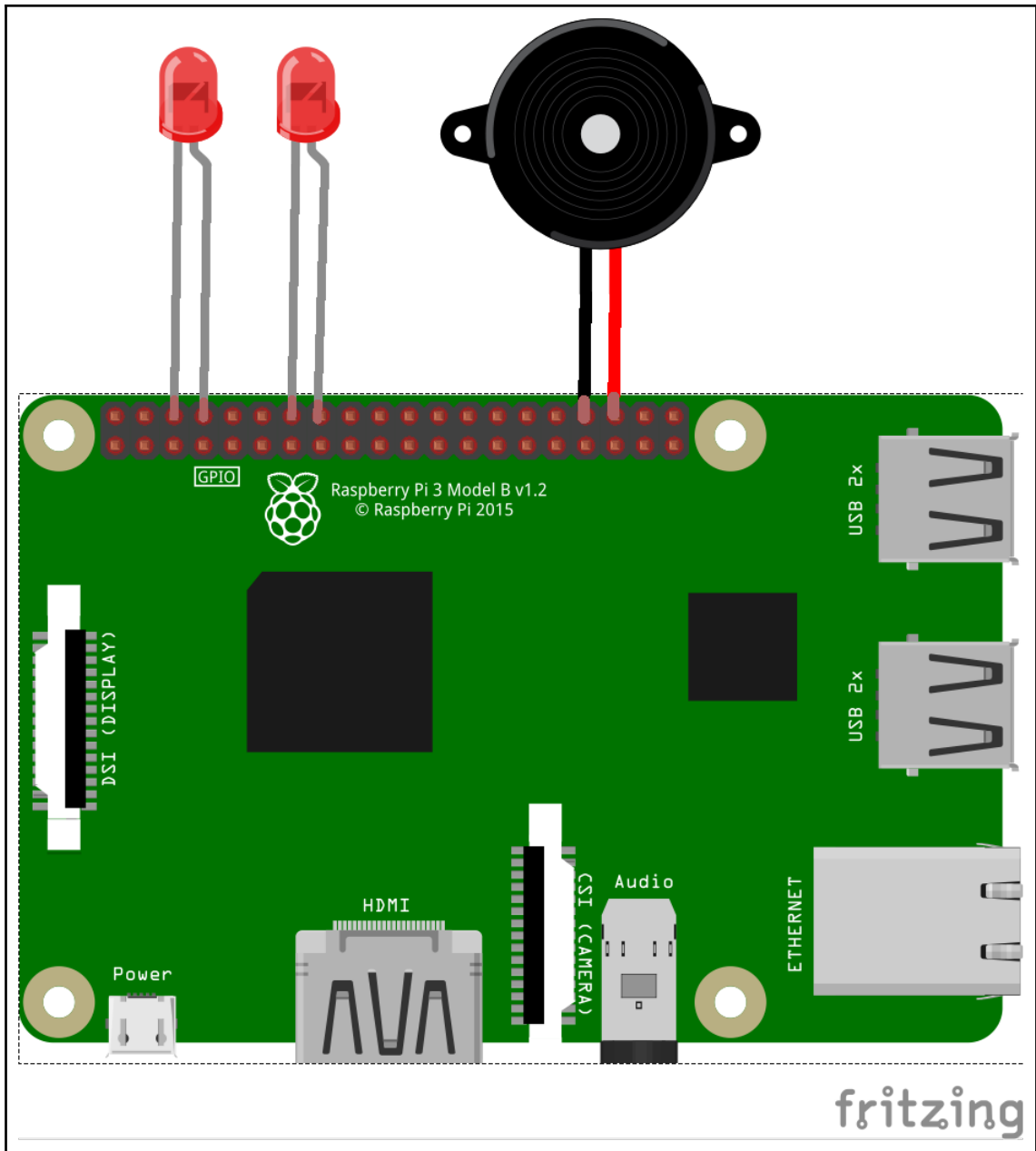
The directory is now changed to Cprograms

```
pi@raspberrypi: ~/Cprograms
File Edit Tabs Help
pi@raspberrypi:~ $ ls
Cprograms Documents MagPi Pictures python_games Videos
Desktop Downloads Music Public Templates wiringPi
pi@raspberrypi:~ $ cd Cprograms
pi@raspberrypi:~/Cprograms $ ls
Blink.cpp Data HelloWorld.cpp TimeControlRobot.cpp UltrasonicSensor.cpp
pi@raspberrypi:~/Cprograms $
```

```
pi@raspberrypi: ~/Cprograms
File Edit Tabs Help
pi@raspberrypi:~ $ ls
Cprograms Documents MagPi Pictures python_games Videos
Desktop Downloads Music Public Templates wiringPi
pi@raspberrypi:~ $ cd Cprograms
pi@raspberrypi:~/Cprograms $ ls
Blink.cpp Data HelloWorld.cpp TimeControlRobot.cpp UltrasonicSensor.cpp
pi@raspberrypi:~/Cprograms $ gcc -o HelloWorld -Iincurses HelloWorld.cpp
pi@raspberrypi:~/Cprograms $
```

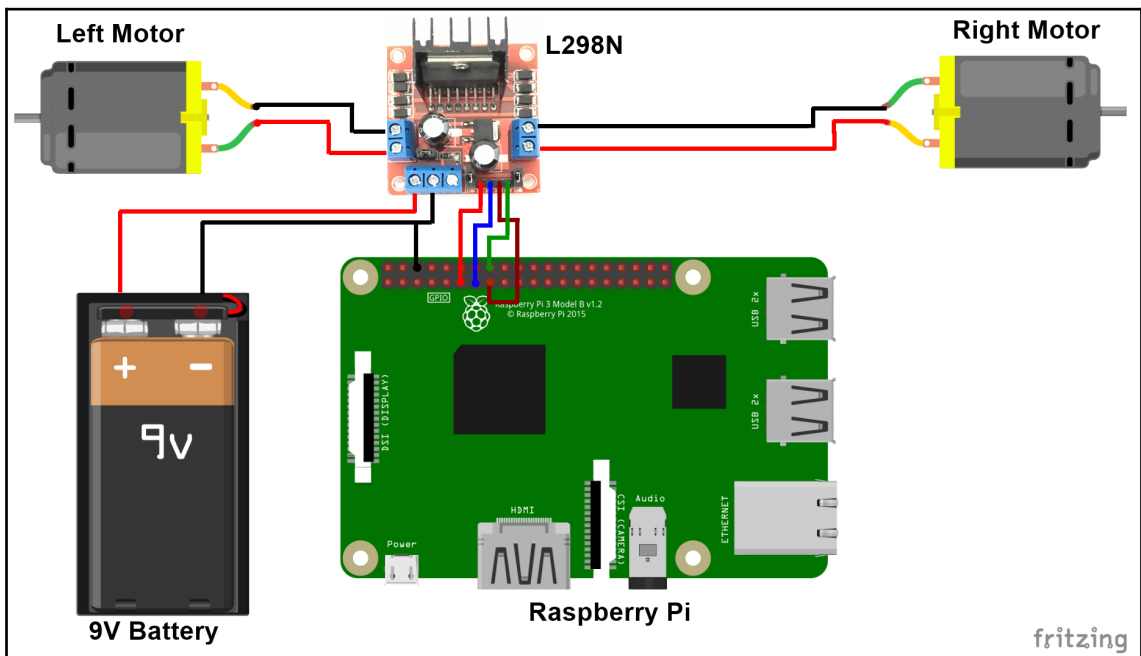
```
pi@raspberrypi: ~/Cprograms
File Edit Tabs Help
pi@raspberrypi:~ $ ls
Cprograms Documents MagPi Pictures python_games Videos
Desktop Downloads Music Public Templates wiringPi
pi@raspberrypi:~ $ cd Cprograms
pi@raspberrypi:~/Cprograms $ ls
Blink.cpp Data HelloWorld.cpp TimeControlRobot.cpp UltrasonicSensor.cpp
pi@raspberrypi:~/Cprograms $ ./HelloWorld
```

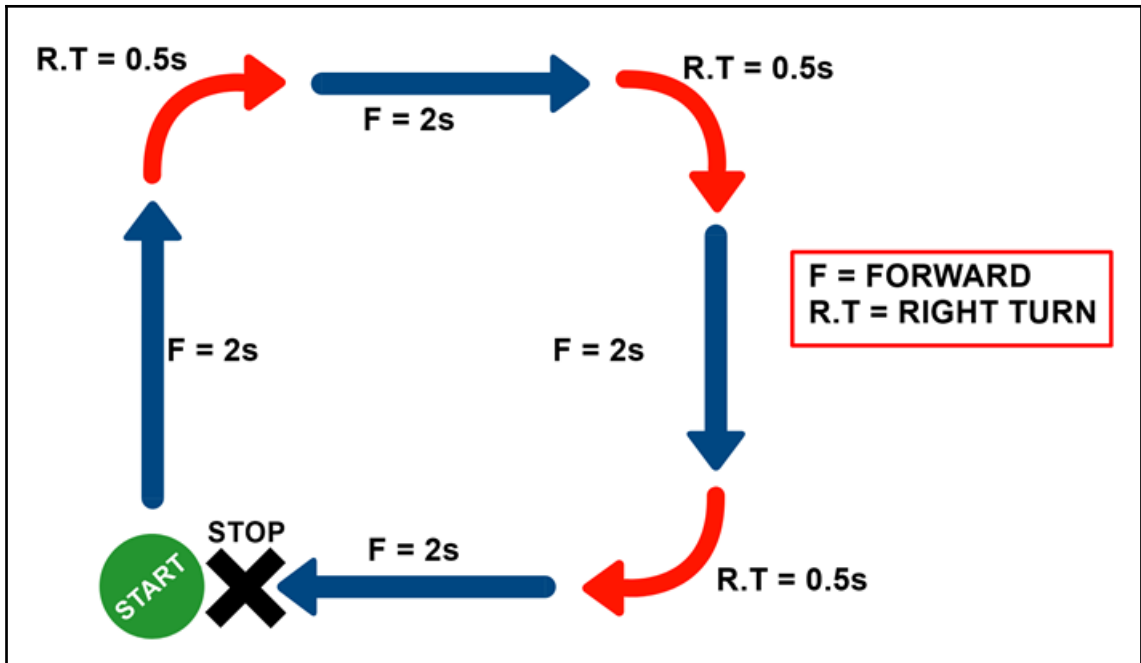





```
pi@raspberrypi: ~/Cprograms
File Edit Tabs Help
pi@raspberrypi:~ $ cd Cprograms
pi@raspberrypi:~/Cprograms $ ls
Blink.cpp HelloWorld LEDBuzzer TimeControlRobot.cpp
Data HelloWorld.cpp LEDBuzzer.cpp UltrasonicSensor.cpp
pi@raspberrypi:~/Cprograms $ gcc -o LEDBuzzer -lcurses -lwiringPi LEDBuzzer.cpp
```

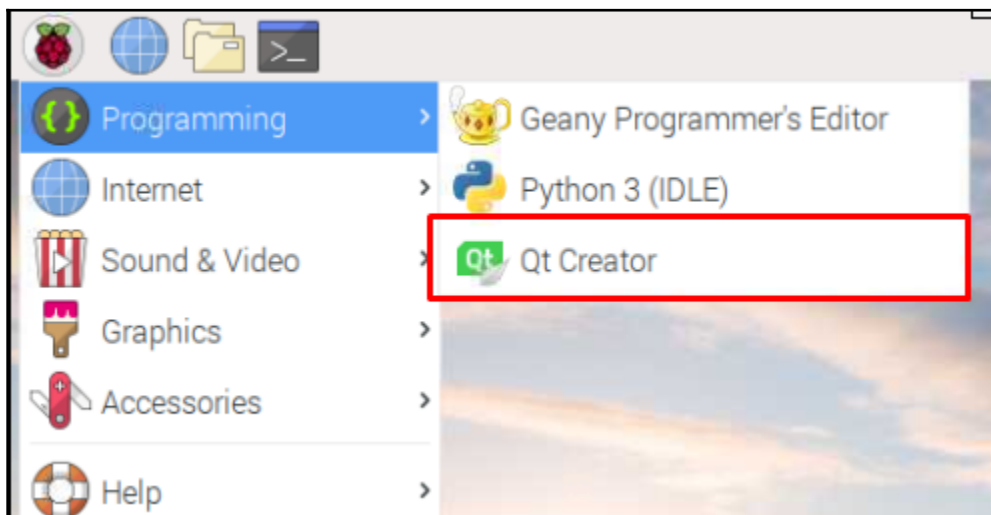
```
pi@raspberrypi: ~/Cprograms
File Edit Tabs Help
pi@raspberrypi:~ $ cd Cprograms
pi@raspberrypi:~/Cprograms $ ls
Blink.cpp  HelloWorld  LEDBuzzer  TimeControlRobot.cpp
Data       HelloWorld.cpp LEDBuzzer.cpp UltrasonicSensor.cpp
pi@raspberrypi:~/Cprograms $ gcc -o LEDBuzzer -lcurses -lwiringPi LEDBuzzer.cpp
pi@raspberrypi:~/Cprograms $ ./LEDBuzzer
```

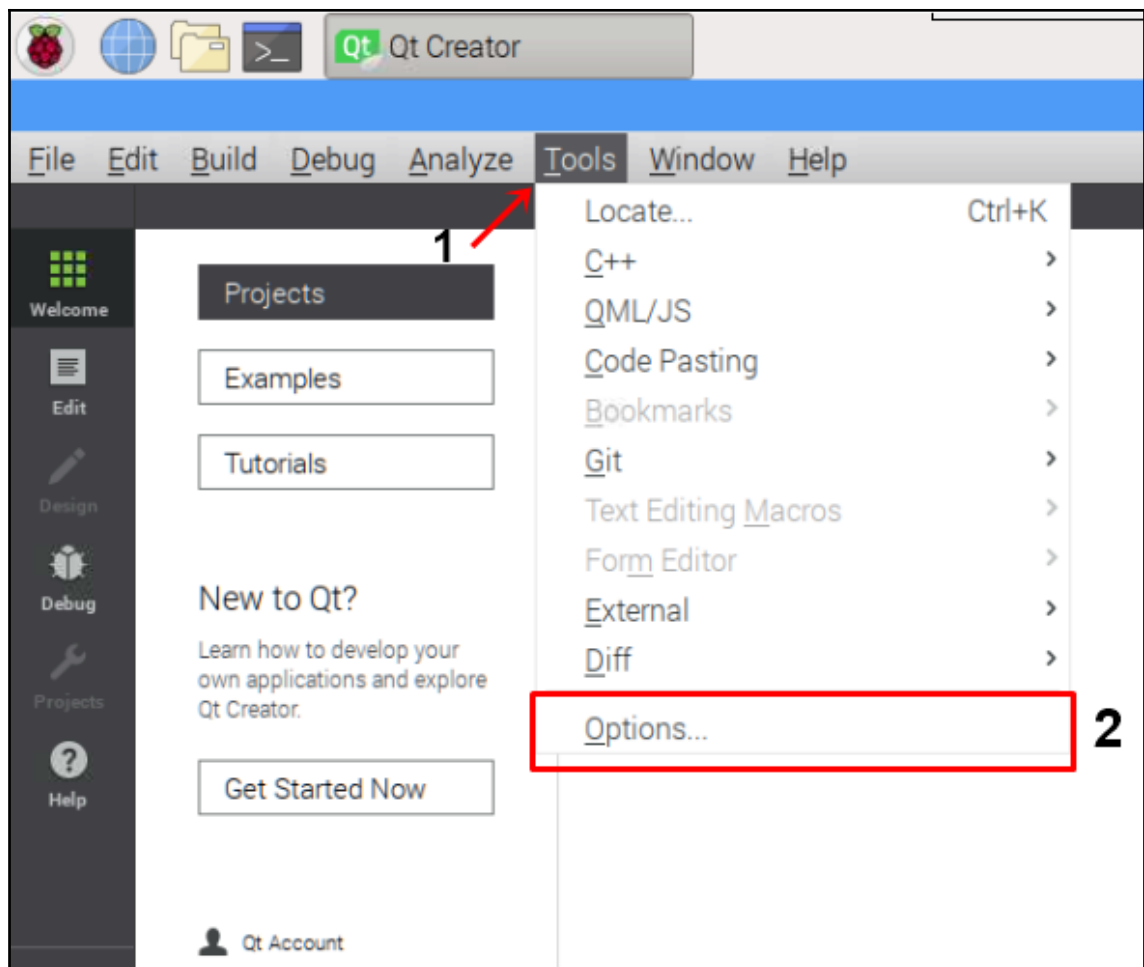


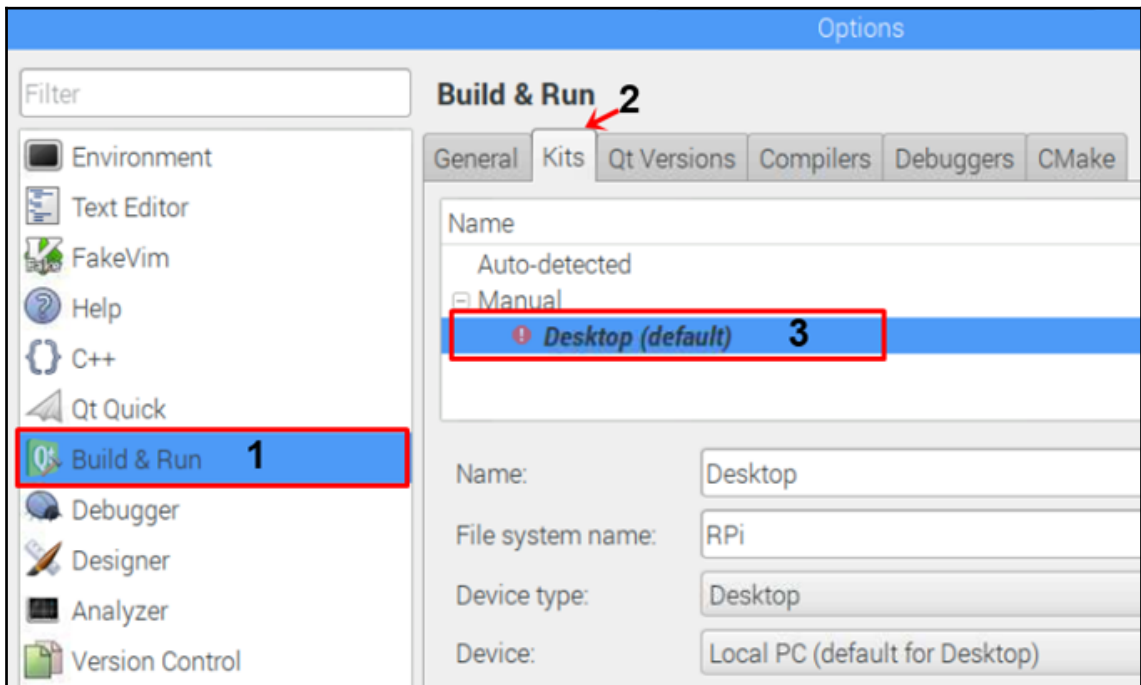
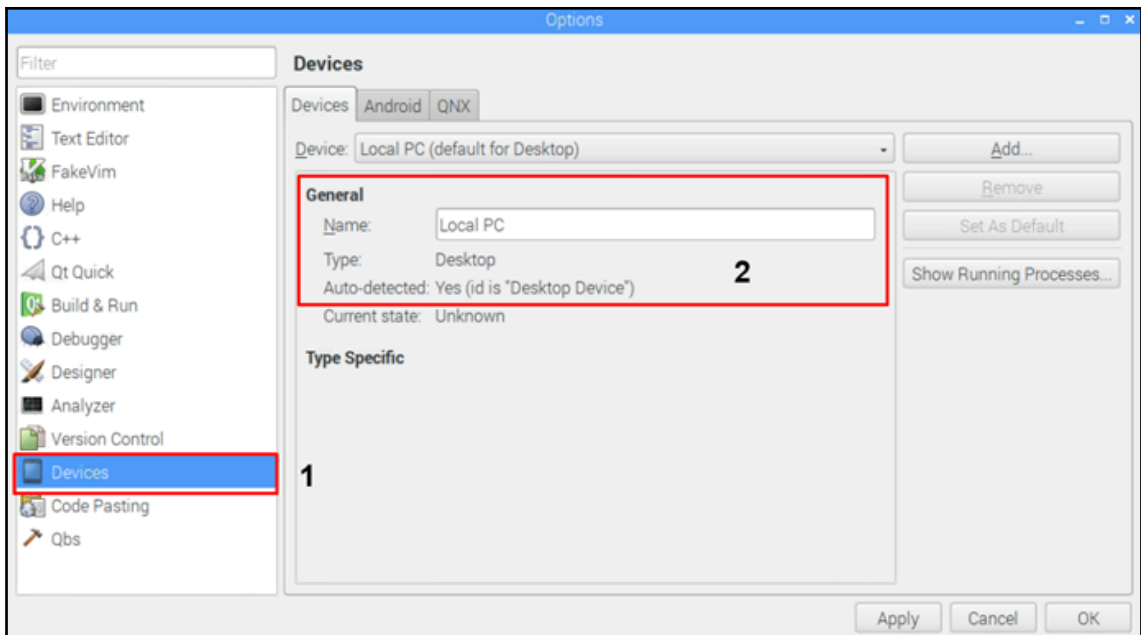


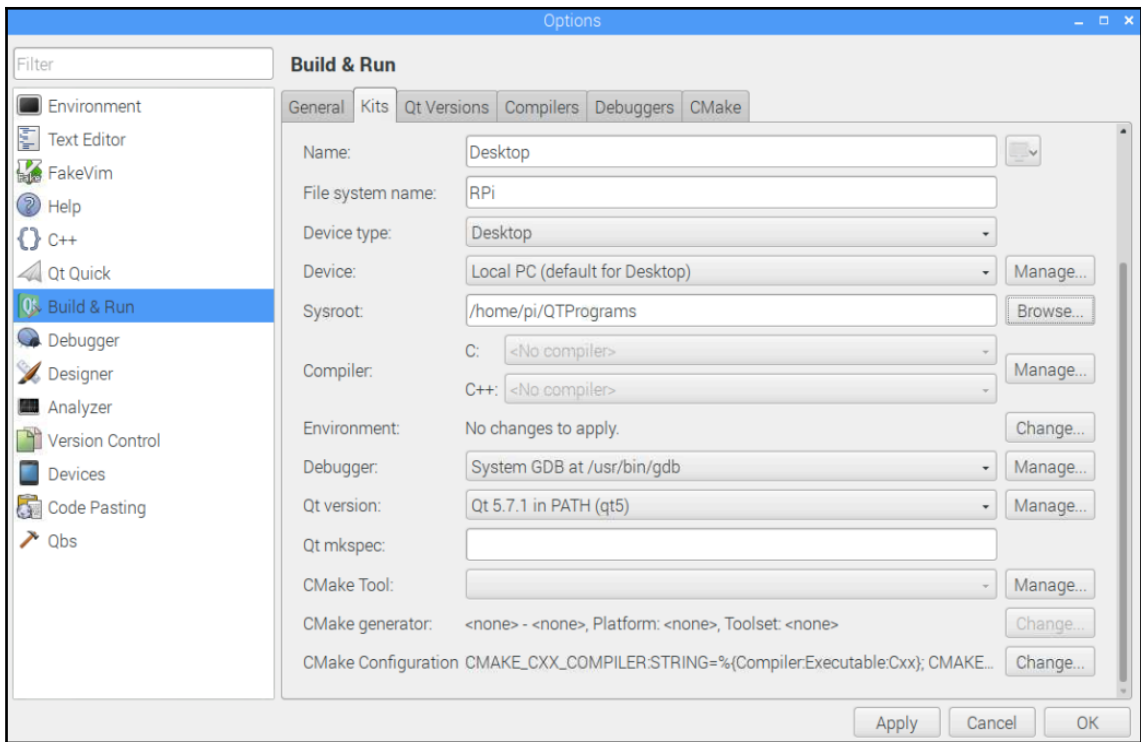
```
pi@raspberrypi: ~  
File Edit Tabs Help  
pi@raspberrypi:~ $ sudo apt-get install qt5-default  
Reading package lists... Done  
Building dependency tree  
Reading state information... Done  
The following additional packages will be installed:  
  libdrm-dev libdrm-exynos1 libdrm-omap1 libdrm-tegra0 libegl1-mesa-dev  
  libgles2-mesa-dev libpthread-stubs0-dev libqt5opengl5 libqt5opengl5-dev  
  libqt5test5 libwayland-bin libwayland-dev libx11-dev libx11-doc  
  libx11-xcb-dev libxau-dev libxcb-dri2-0-dev libxcb-dri3-dev libxcb-glx0-dev  
  libxcb-present-dev libxcb-randr0-dev libxcb-render0-dev libxcb-shape0-dev  
  libxcb-sync-dev libxcb-xf86vm-dev libxcb1-dev libxdamage-dev libxdmcp-dev  
  libxext-dev libxfixes-dev libxshmfence-dev libxxf86vm-dev qt5-qmake  
  qtbase5-dev qtbase5-dev-tools qtchooser x11proto-core-dev  
  x11proto-damage-dev x11proto-dri2-dev x11proto-fixes-dev x11proto-glx-dev
```

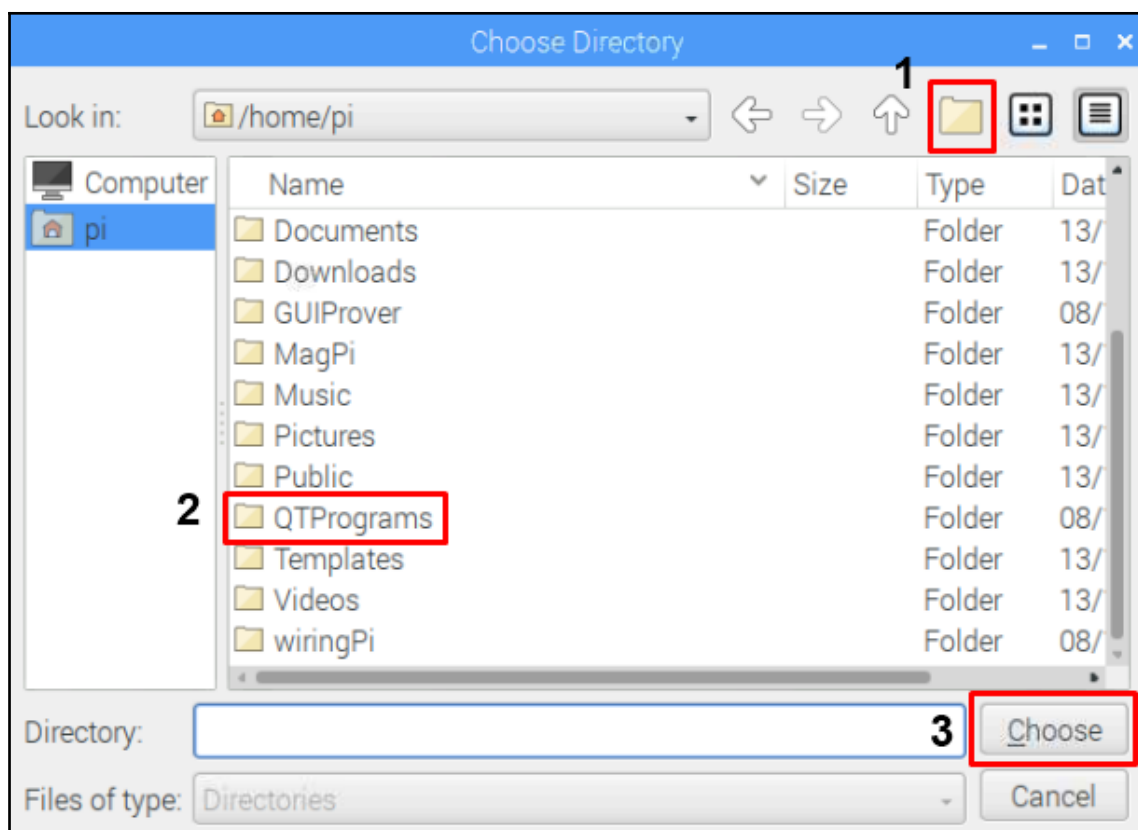
```
pi@raspberrypi: ~  
File Edit Tabs Help  
Setting up x11proto-input-dev (2.3.2-1) ...  
Setting up libxcb-sync-dev:armhf (1.12-1) ...  
Setting up libxcb-dri2-0-dev:armhf (1.12-1) ...  
Setting up libxcb-render0-dev:armhf (1.12-1) ...  
Setting up libxcb-dri3-dev:armhf (1.12-1) ...  
Setting up x11proto-xext-dev (7.3.0-1) ...  
Setting up libxcb-shape0-dev:armhf (1.12-1) ...  
Setting up libx11-dev:armhf (2:1.6.4-3+deb9u1) ...  
Setting up libxxf86vm-dev:armhf (1:1.1.4-1) ...  
Setting up libx11-xcb-dev:armhf (2:1.6.4-3+deb9u1) ...  
Setting up libxcb-randr0-dev:armhf (1.12-1) ...  
Setting up libxcb-xfixes0-dev:armhf (1.12-1) ...  
Setting up x11proto-fixes-dev (1:5.0-2) ...  
Setting up x11proto-damage-dev (1:1.2.1-2) ...  
Setting up libxext-dev:armhf (2:1.3.3-1) ...  
Setting up libxcb-present-dev:armhf (1.12-1) ...  
Setting up libxfixes-dev:armhf (1:5.0.3-1) ...  
Setting up libxdamage-dev:armhf (1:1.1.4-2+b1) ...  
Setting up libegl1-mesa-dev:armhf (13.0.6-1+rpi2) ...  
Setting up libgles2-mesa-dev:armhf (13.0.6-1+rpi2) ...  
Setting up qtbase5-dev:armhf (5.7.1+dfsg-3+rpi1) ...  
Setting up libqt5opengl5-dev:armhf (5.7.1+dfsg-3+rpi1) ...  
Setting up qt5-default (5.7.1+dfsg-3+rpi1) ...  
pi@raspberrypi:~ $ sudo apt-get install qtcreator
```

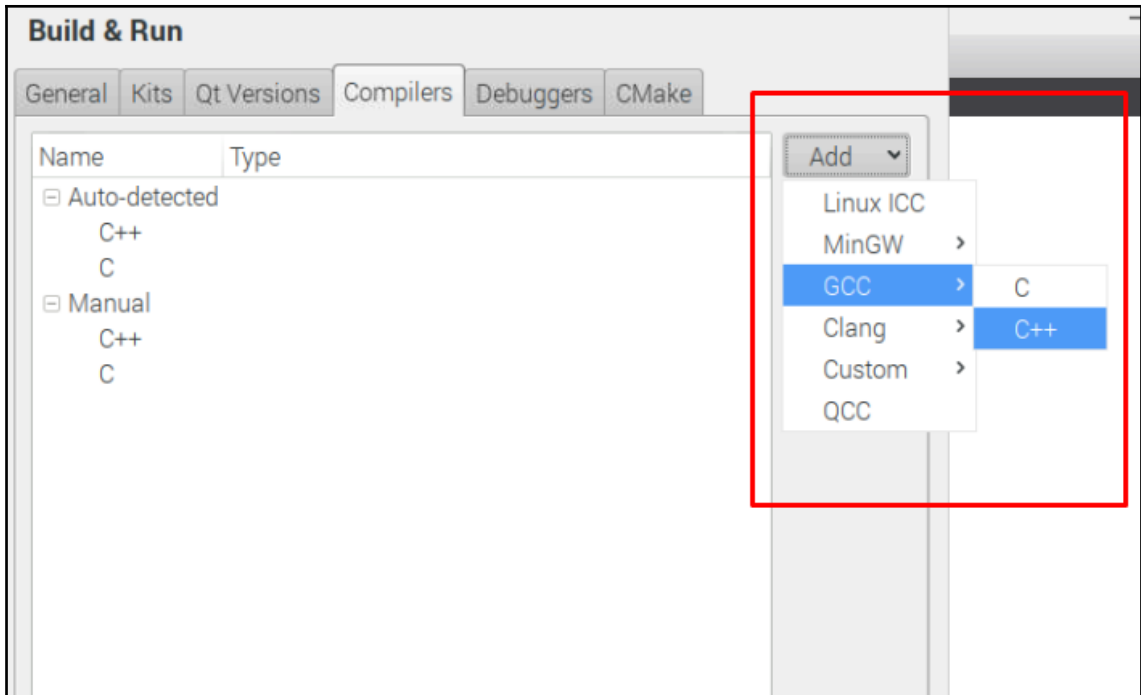


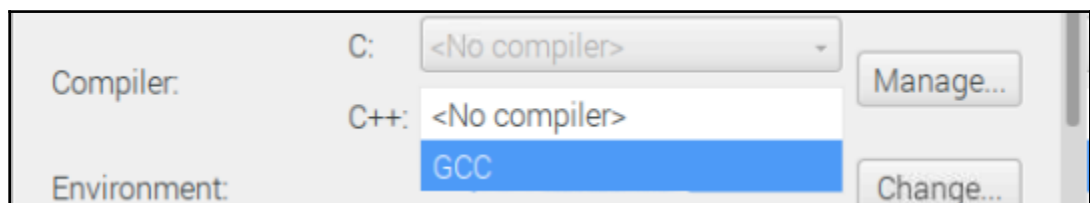
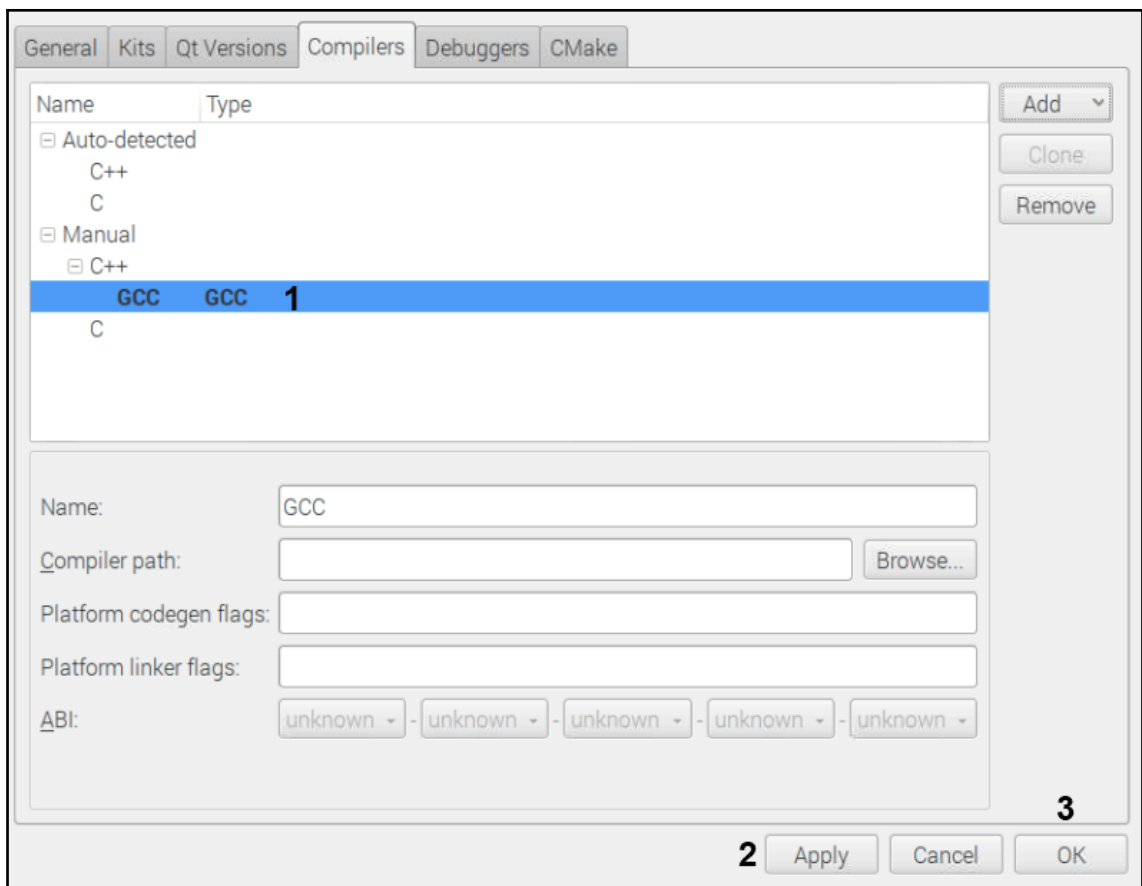


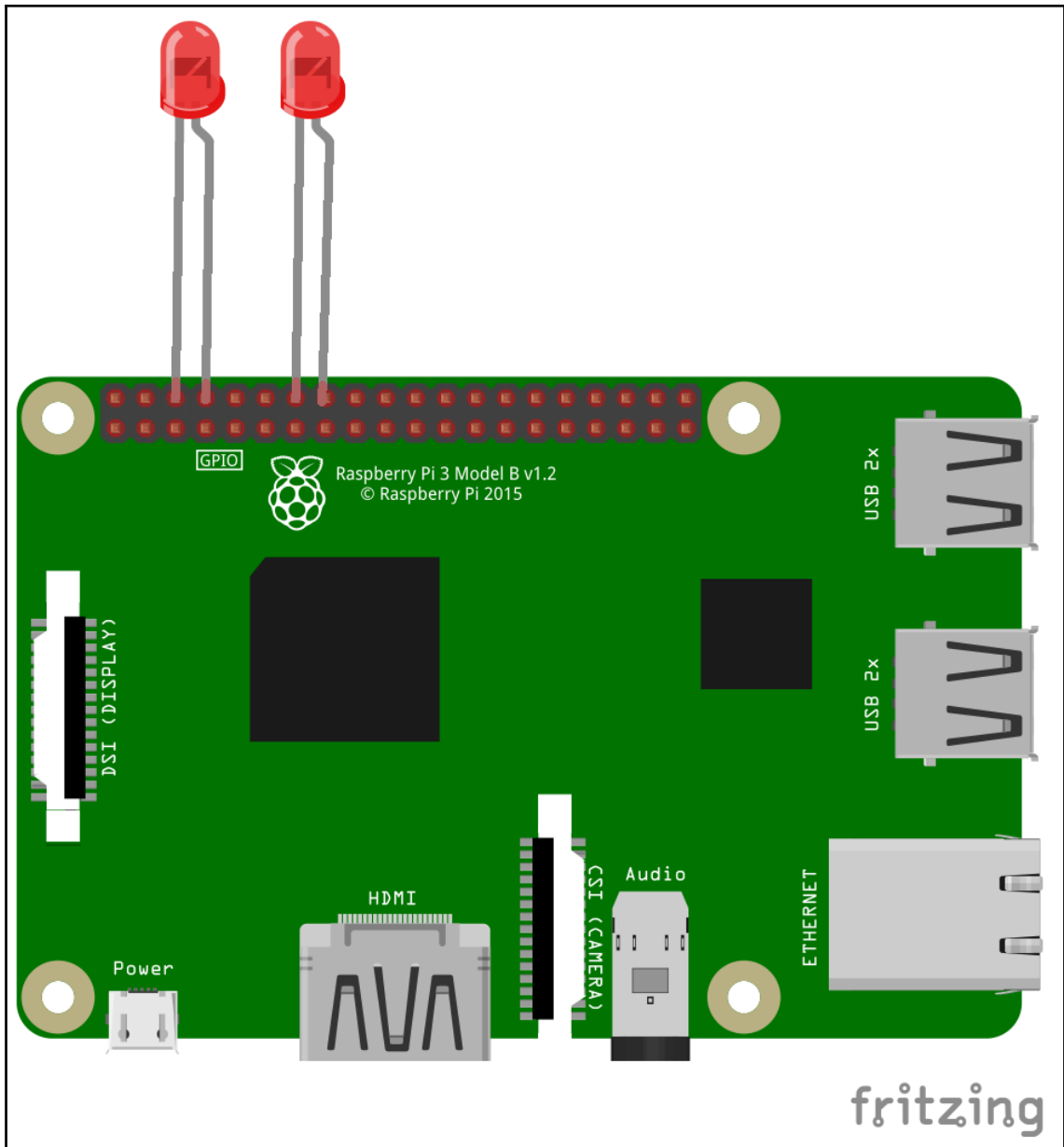


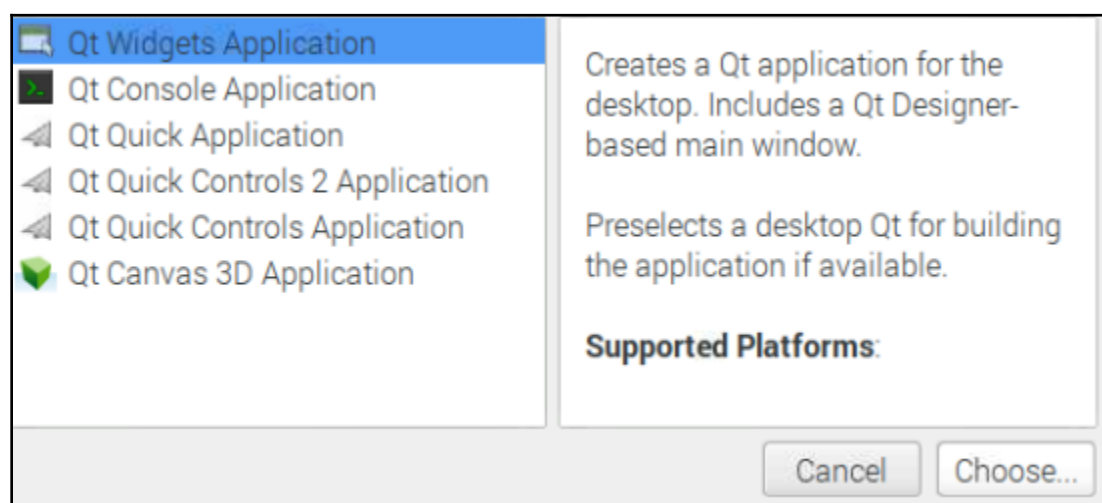
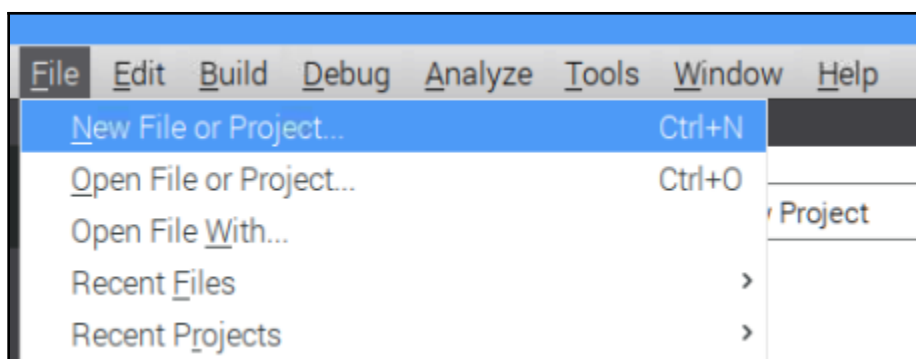


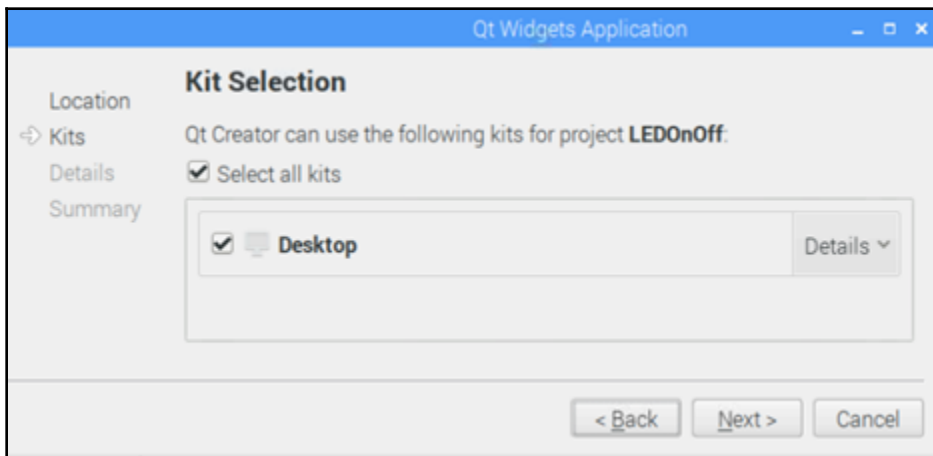
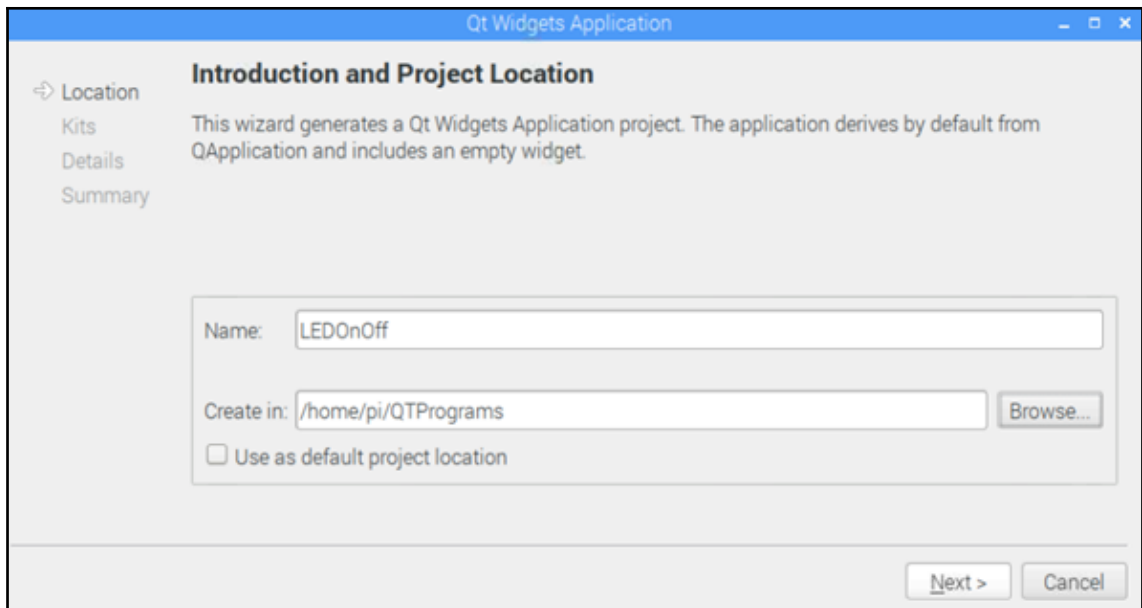












Qt Widgets Application

Location
Kits
Details
Summary

Class Information

Specify basic information about the classes for which you want to generate skeleton source code files.

Class name:

Base class:

Header file:

Source file:

Generate form: ☒

Form file:

< Back Next > Cancel

Qt Widgets Application

Location
Kits
Details
Summary

Project Management

Add as a subproject to project:

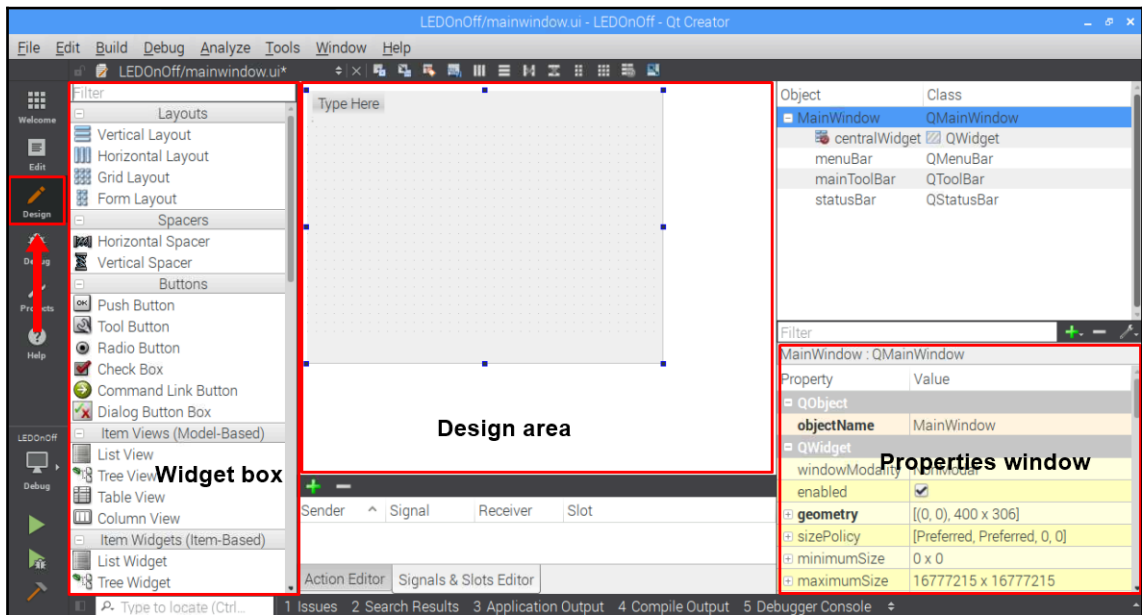
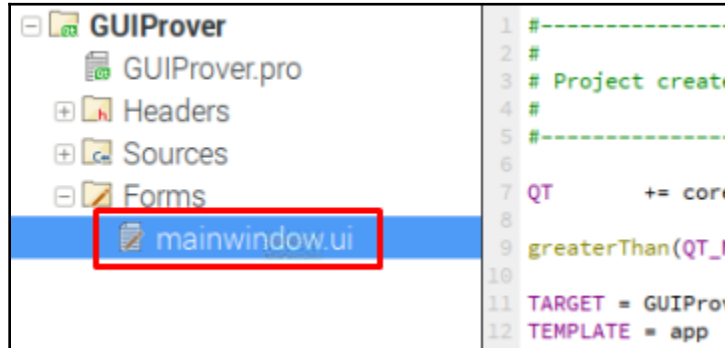
Add to version control:

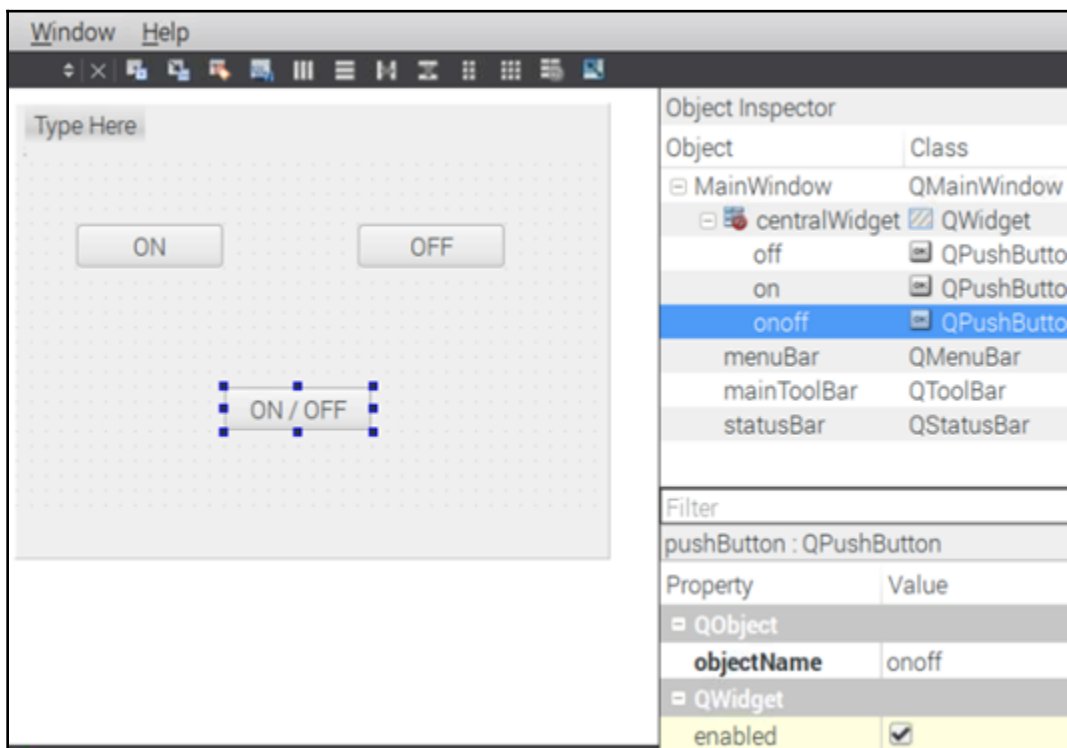
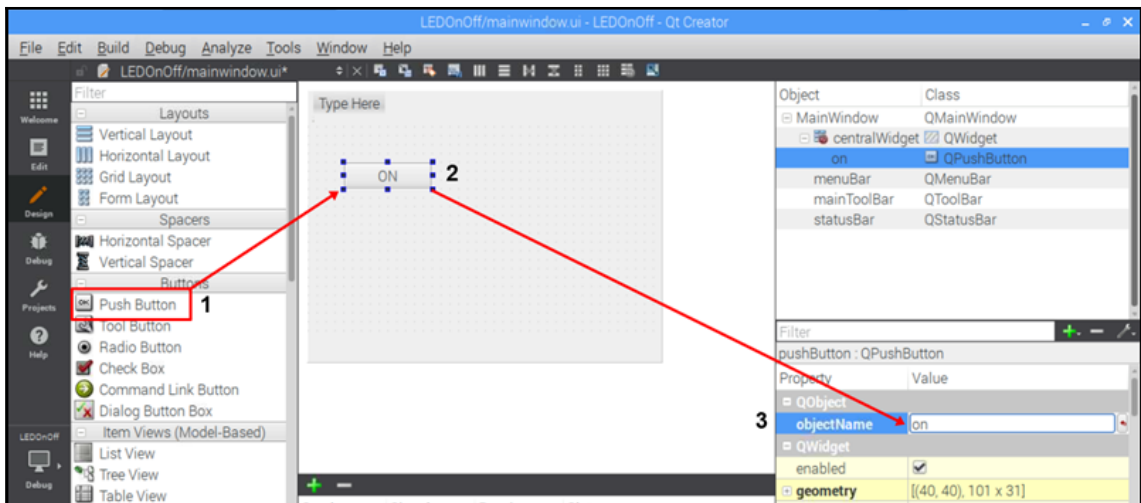
Files to be added in
/home/pi/QTPrograms/LEDOOnOff:

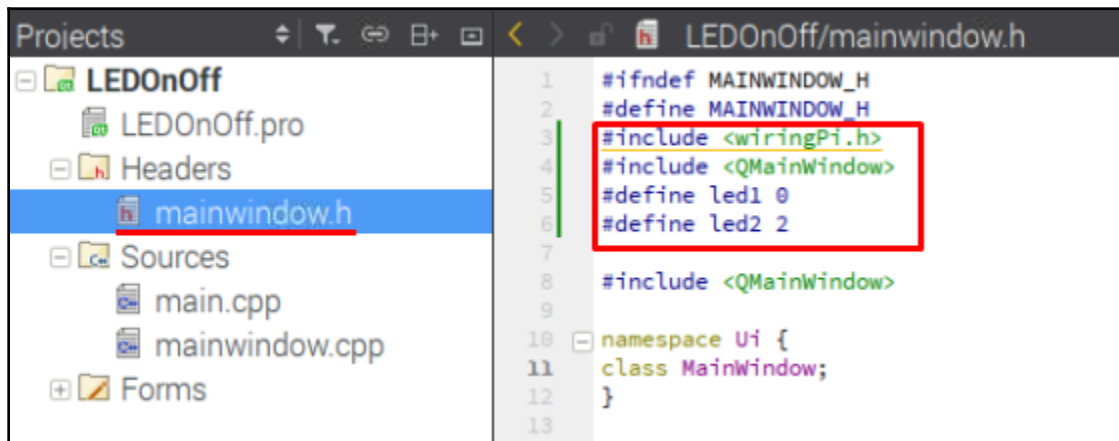
LEDOOnOff.pro
main.cpp
mainwindow.cpp
mainwindow.h
mainwindow.ui

< Back Finish Cancel

```
HEADERS += mainwindow.h
FORMS += mainwindow.ui
LIBS += -L/usr/local/lib -lwiringPi
```



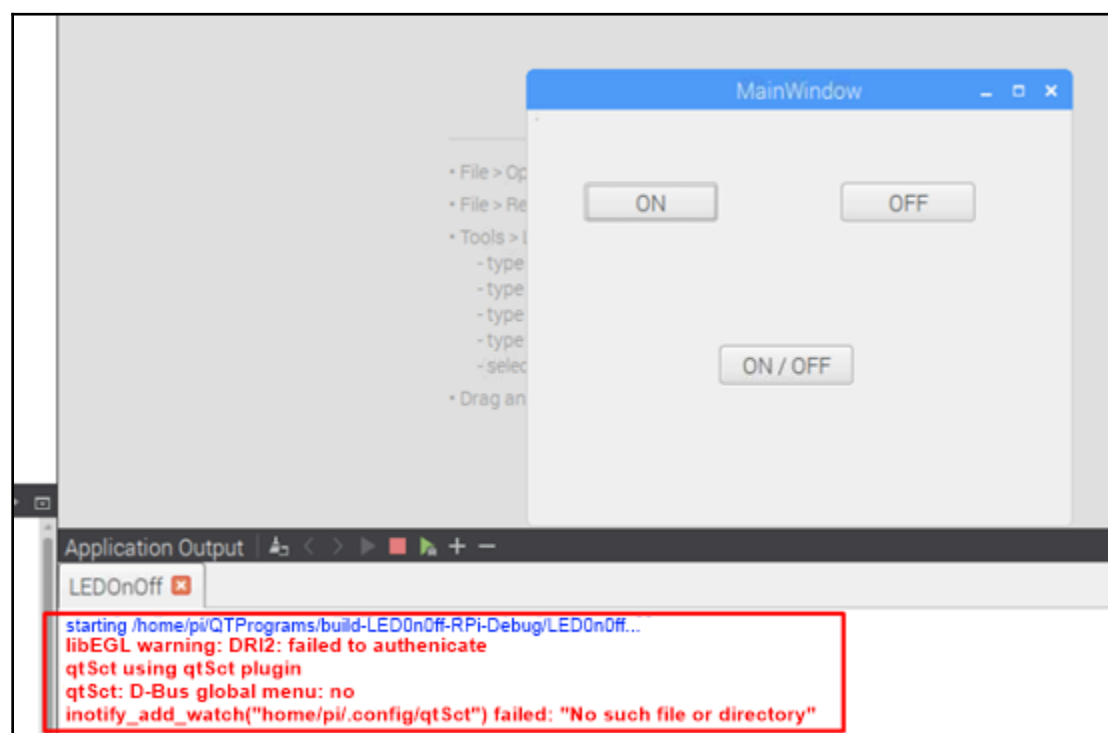
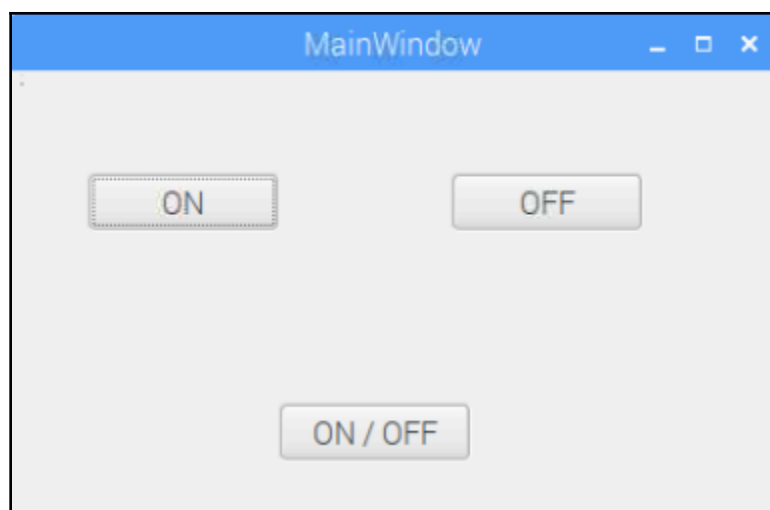




```
1 #include "mainwindow.h"
2 #include "ui_mainwindow.h"
3
4 MainWindow::MainWindow(QWidget *parent) :
5     QMainWindow(parent),
6     ui(new Ui::MainWindow)
7 {
8     ui->setupUi(this);
9     wiringPiSetup();
10    pinMode(led1,OUTPUT);
11    pinMode(led2,OUTPUT);
12 }
13
14 MainWindow::~MainWindow()
15 {
16     delete ui;
17 }
18
19 void MainWindow::on_on_clicked()
20 {
21     digitalWrite(led1,HIGH);
22     digitalWrite(led2,HIGH);
23 }
```

```
void MainWindow::on_onoff_pressed()
{
    digitalWrite(led1,HIGH);
    digitalWrite(led2,HIGH);
}

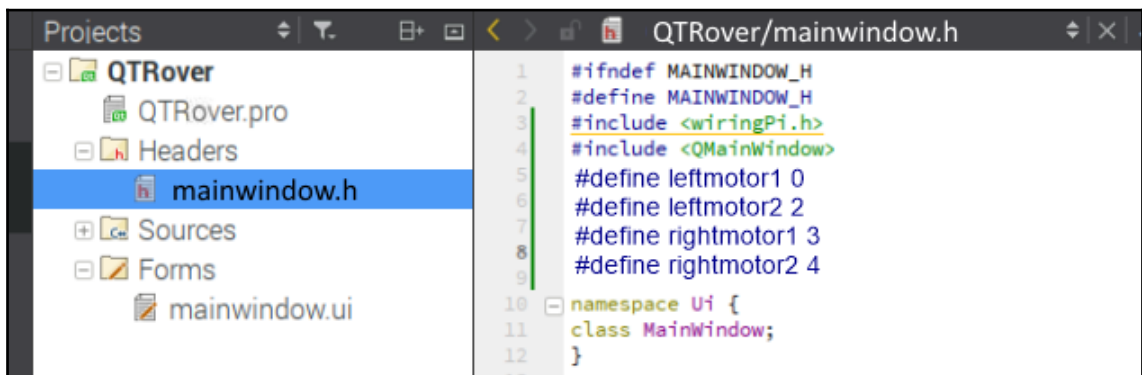
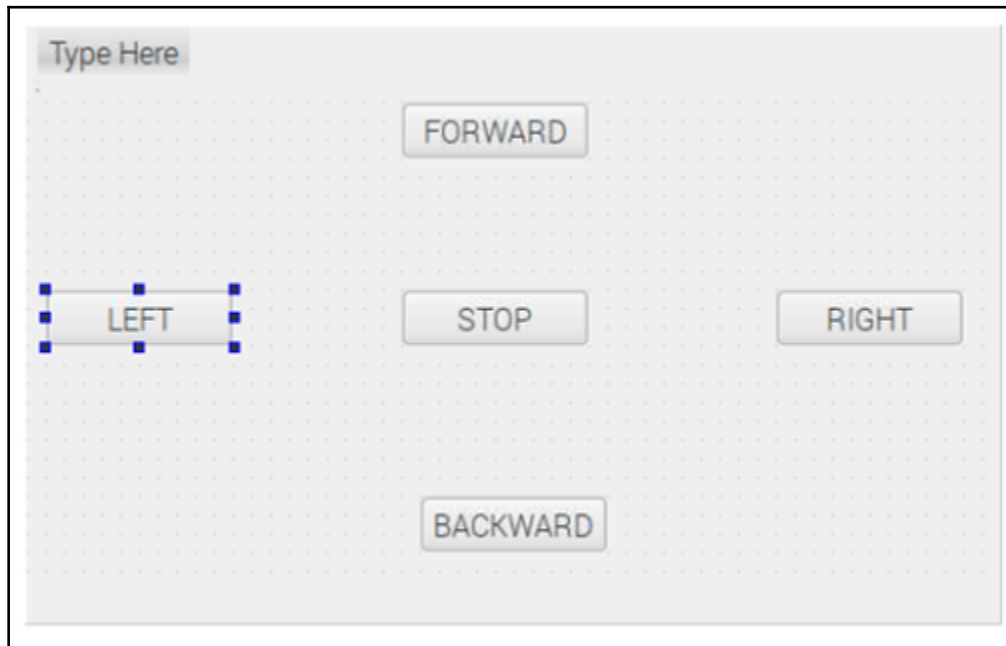
void MainWindow::on_onoff_released()
{
    digitalWrite(led1,LOW);
    digitalWrite(led2,LOW);
}
```



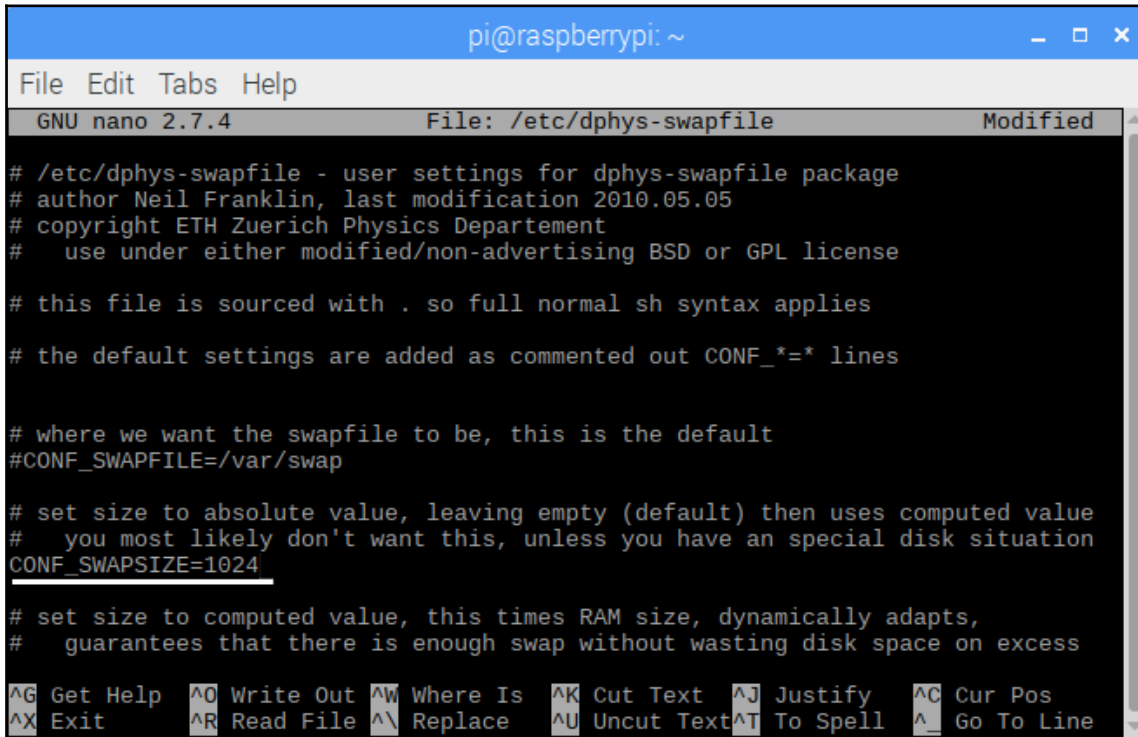
```
28     digitalWrite(led2,LOW);
29 }
```

Compile Output

Error while building/deploying project LEDOnOff (kit: Desktop)
When executing step "qmake"



Chapter 6: Accessing the RPi Camera with OpenCV



```
pi@raspberrypi: ~
File Edit Tabs Help
GNU nano 2.7.4 File: /etc/dphys-swapfile Modified

# /etc/dphys-swapfile - user settings for dphys-swapfile package
# author Neil Franklin, last modification 2010.05.05
# copyright ETH Zuerich Physics Departement
# use under either modified/non-advertising BSD or GPL license

# this file is sourced with . so full normal sh syntax applies

# the default settings are added as commented out CONF_*=* lines

# where we want the swapfile to be, this is the default
#CONF_SWAPFILE=/var/swap

# set size to absolute value, leaving empty (default) then uses computed value
# you most likely don't want this, unless you have an special disk situation
CONF_SWAPSIZE=1024

# set size to computed value, this times RAM size, dynamically adapts,
# guarantees that there is enough swap without wasting disk space on excess

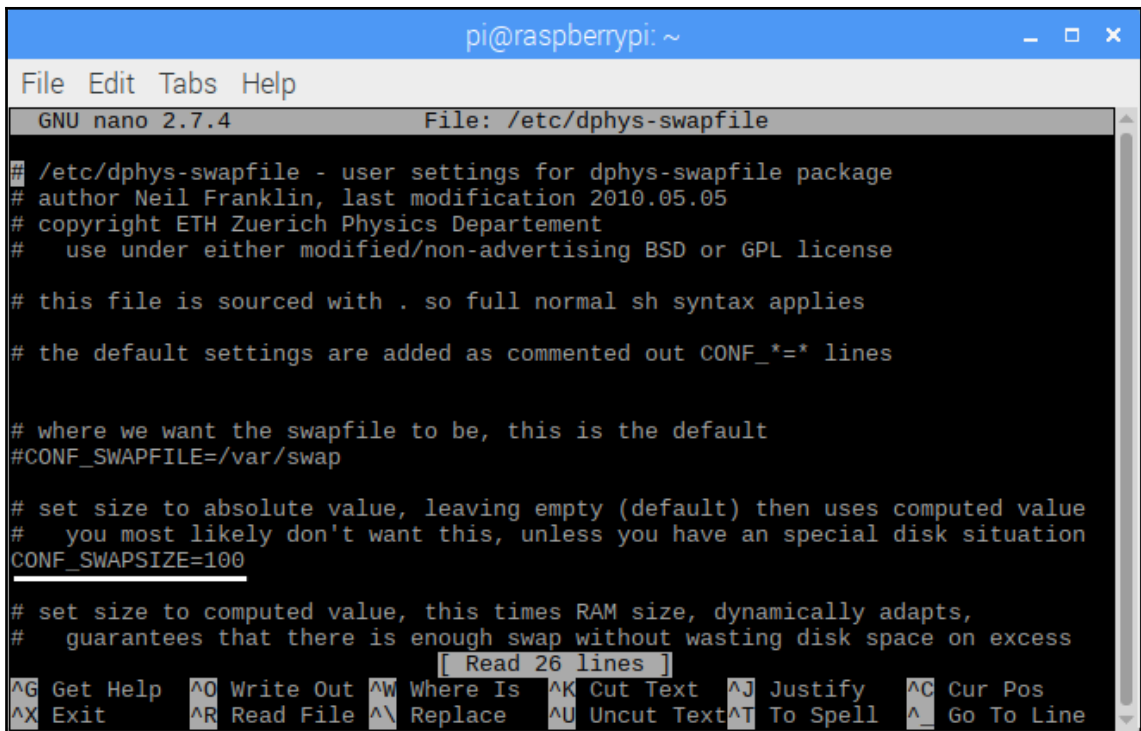
^G Get Help ^O Write Out ^W Where Is ^K Cut Text ^J Justify ^C Cur Pos
^X Exit ^R Read File ^\ Replace ^U Uncut Text ^T To Spell ^_ Go To Line
```



```
pi@raspberrypi: ~  
File Edit Tabs Help  
pi@raspberrypi:~ $ python3  
Python 3.5.3 (default, Sep 27 2018, 17:25:39)  
[GCC 6.3.0 20170516] on linux  
Type "help", "copyright", "credits" or "license" for more information.  
>>> █
```

```
pi@raspberrypi: ~  
File Edit Tabs Help  
pi@raspberrypi:~ $ python3  
Python 3.5.3 (default, Sep 27 2018, 17:25:39)  
[GCC 6.3.0 20170516] on linux  
Type "help", "copyright", "credits" or "license" for more information.  
>>> import cv2  
>>> cv2.__version__  
'4.0.0'  
>>> █
```

```
pi@raspberrypi: ~  
File Edit Tabs Help  
pi@raspberrypi:~ $ python3  
Python 3.5.3 (default, Sep 27 2018, 17:25:39)  
[GCC 6.3.0 20170516] on linux  
Type "help", "copyright", "credits" or "license" for more information.  
>>> import cv2  
>>> cv2.__version__  
'4.0.0'  
>>> exit()  
pi@raspberrypi:~ $ █
```



The image shows a terminal window titled 'pi@raspberrypi: ~' with the nano text editor open. The editor's title bar indicates it is editing the file '/etc/dphys-swapfile'. The menu bar includes 'File', 'Edit', 'Tabs', and 'Help'. The status bar at the bottom shows 'GNU nano 2.7.4' and 'File: /etc/dphys-swapfile'. The main text area contains the following configuration file content:

```
# /etc/dphys-swapfile - user settings for dphys-swapfile package
# author Neil Franklin, last modification 2010.05.05
# copyright ETH Zuerich Physics Departement
#   use under either modified/non-advertising BSD or GPL license

# this file is sourced with . so full normal sh syntax applies
# the default settings are added as commented out CONF_*=* lines

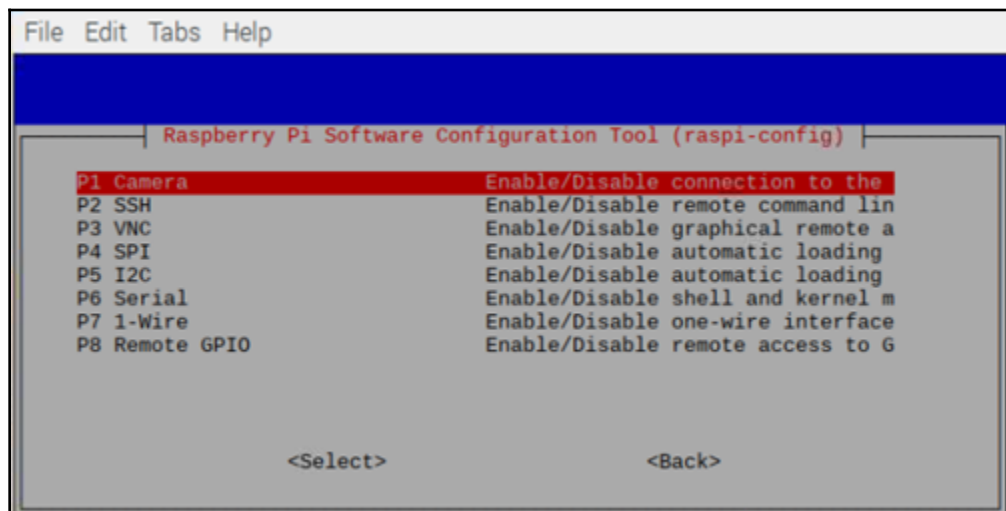
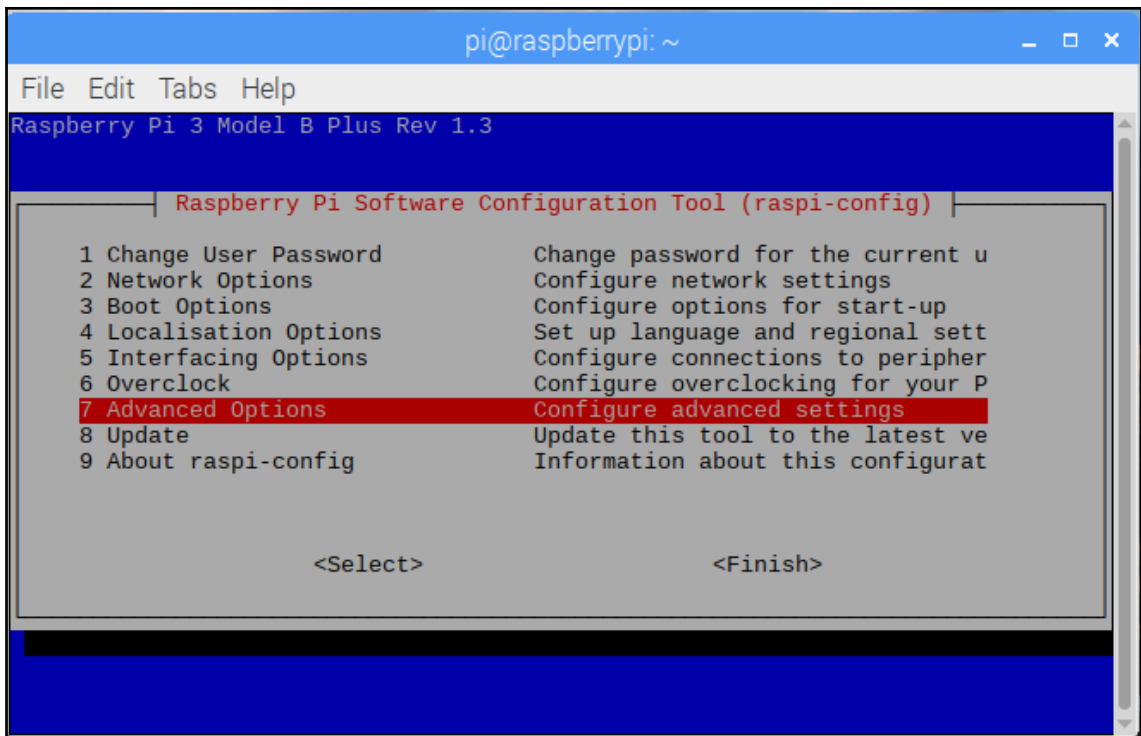
# where we want the swapfile to be, this is the default
#CONF_SWAPFILE=/var/swap

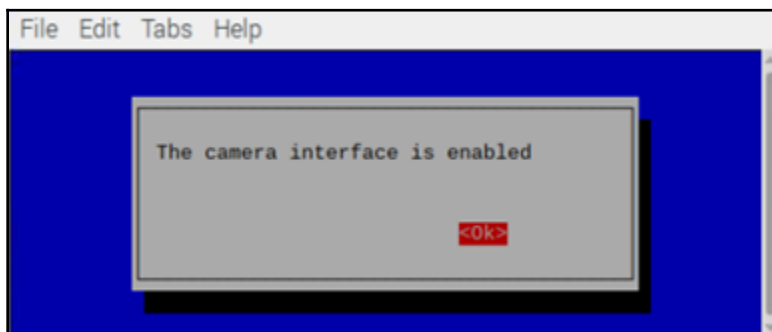
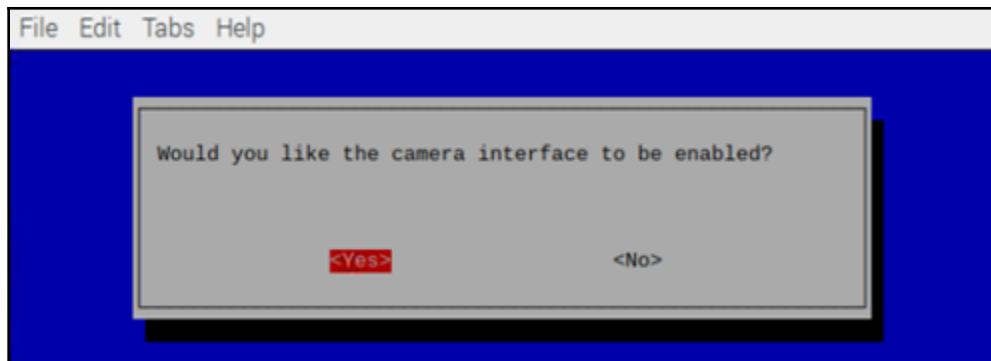
# set size to absolute value, leaving empty (default) then uses computed value
#   you most likely don't want this, unless you have an special disk situation
CONF_SWAPSIZE=100

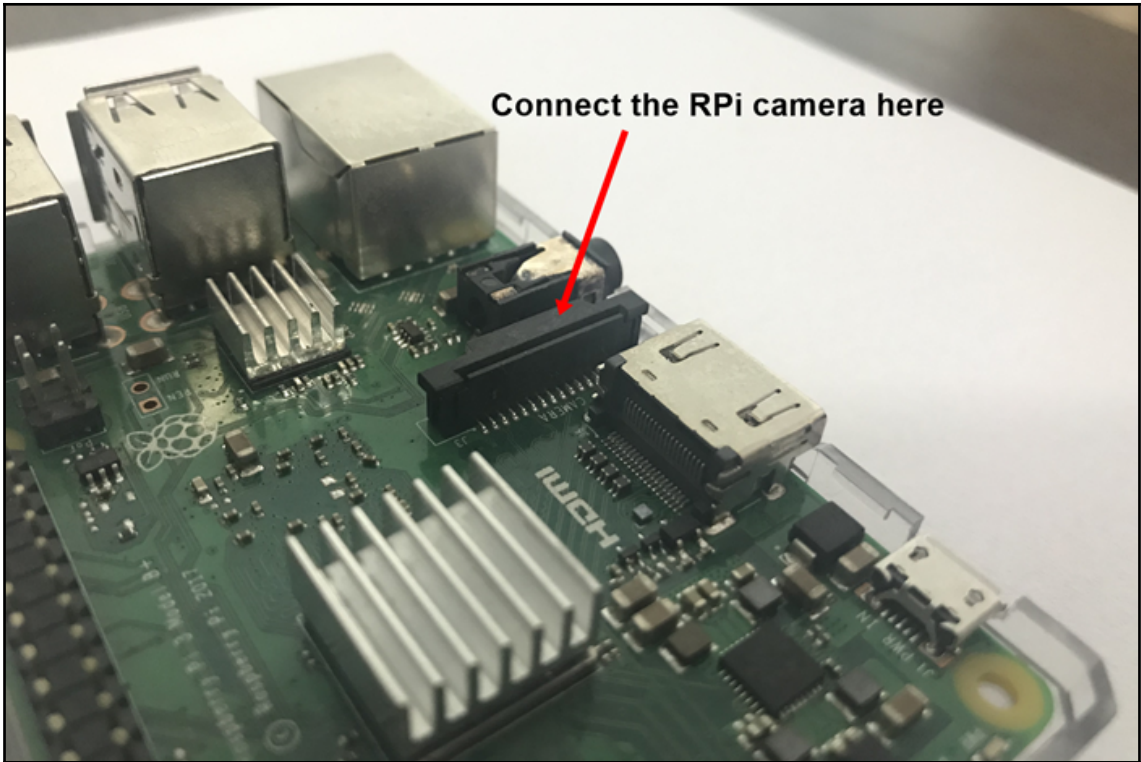
# set size to computed value, this times RAM size, dynamically adapts,
#   guarantees that there is enough swap without wasting disk space on excess
[ Read 26 lines ]
```

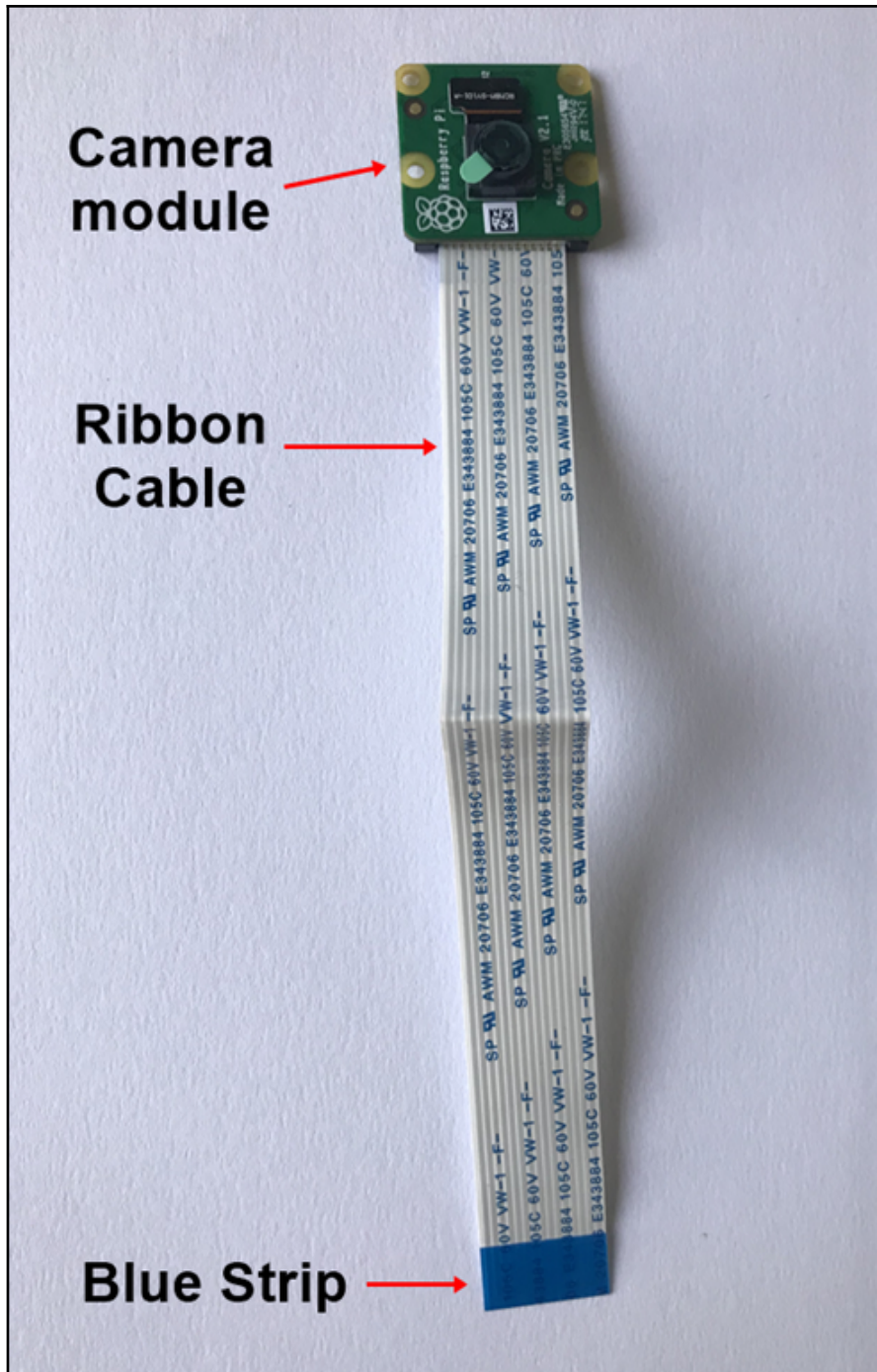
The status bar at the bottom of the editor displays various keyboard shortcuts:

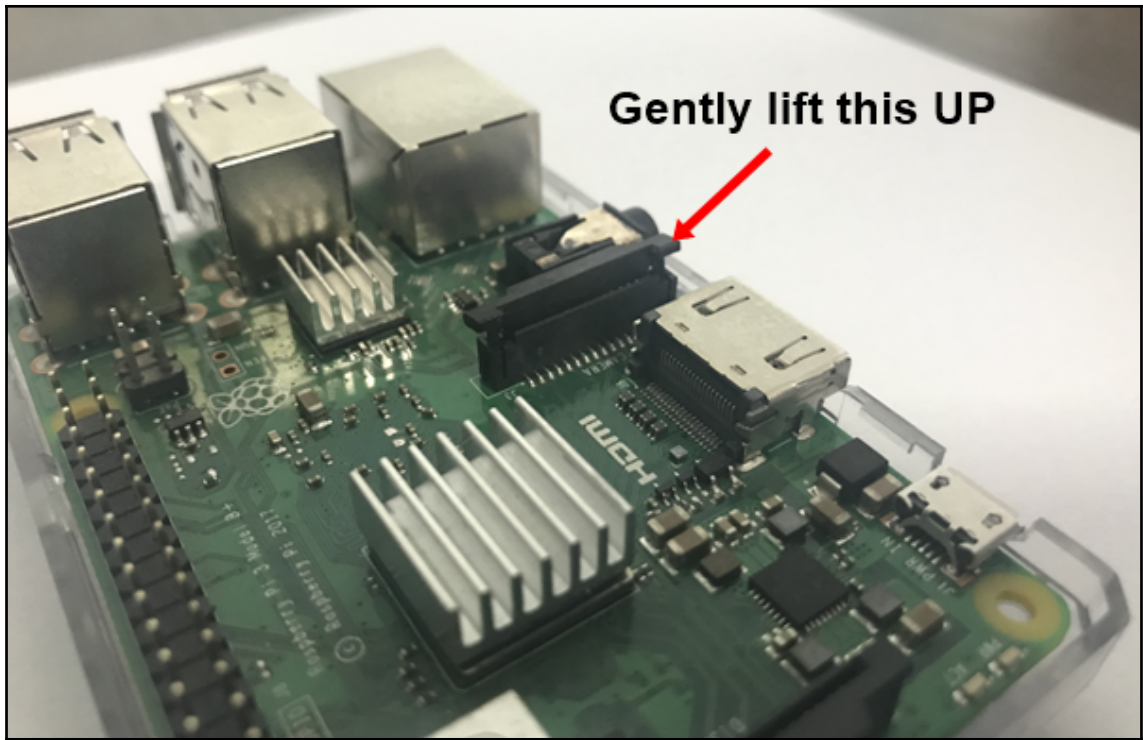
^G Get Help	^O Write Out	^W Where Is	^K Cut Text	^J Justify	^C Cur Pos
^X Exit	^R Read File	^_\ Replace	^U Uncut Text	^T To Spell	^_ Go To Line

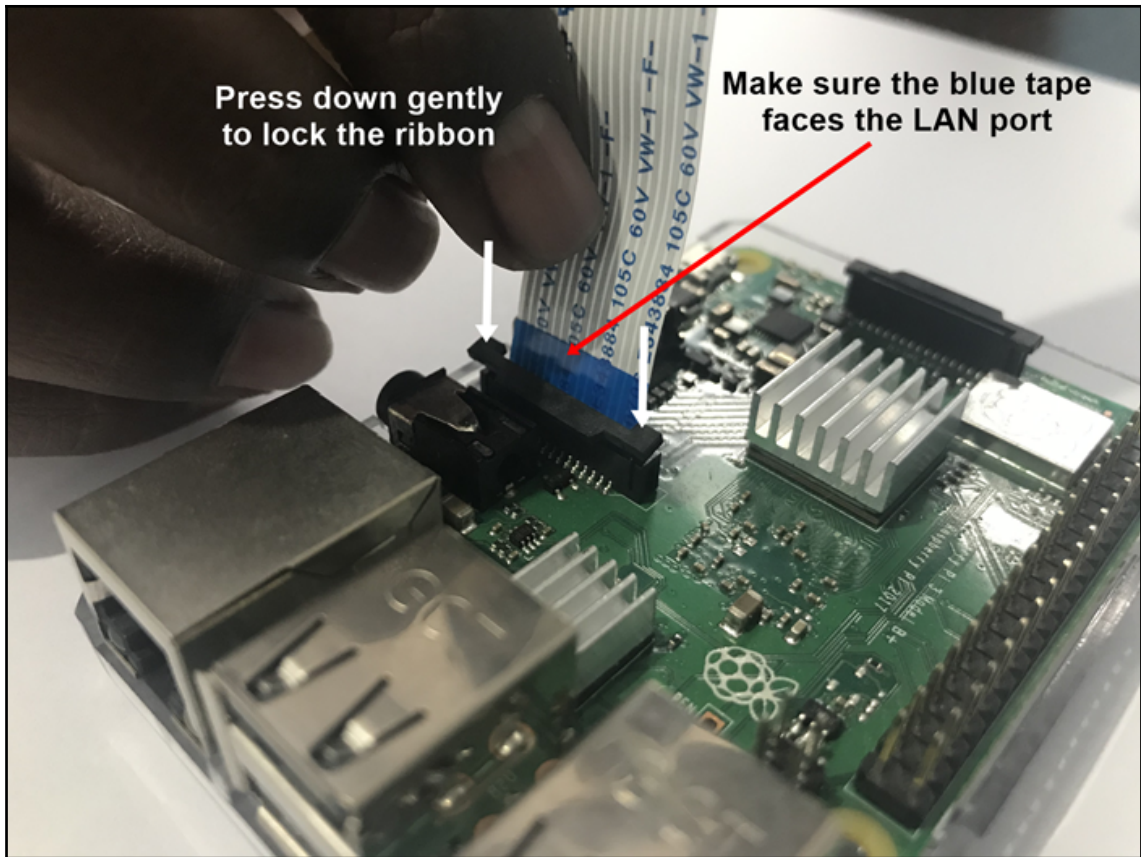


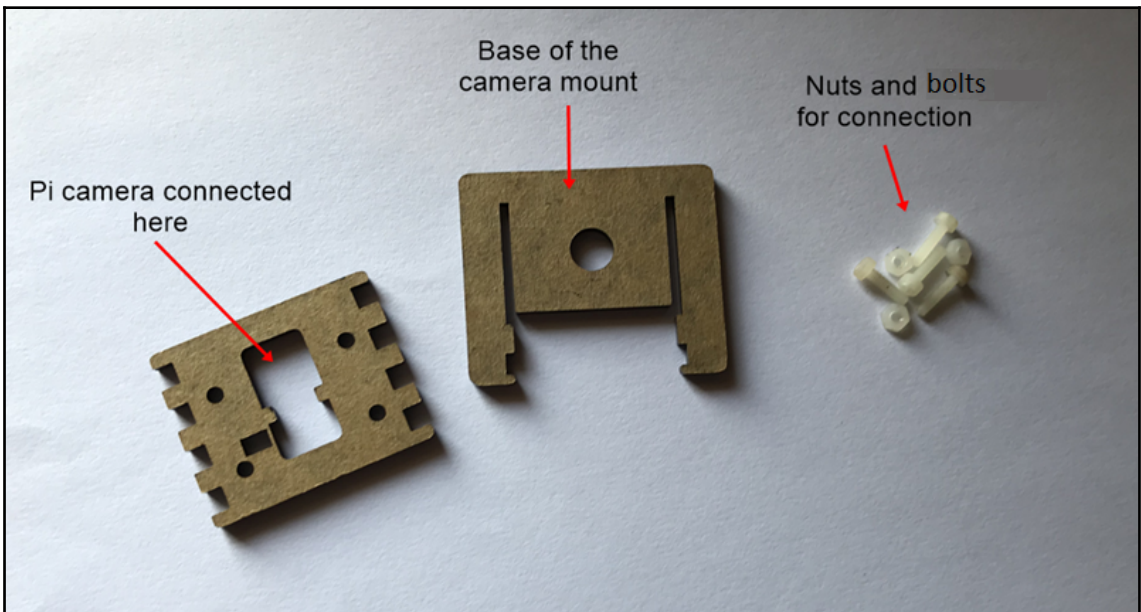
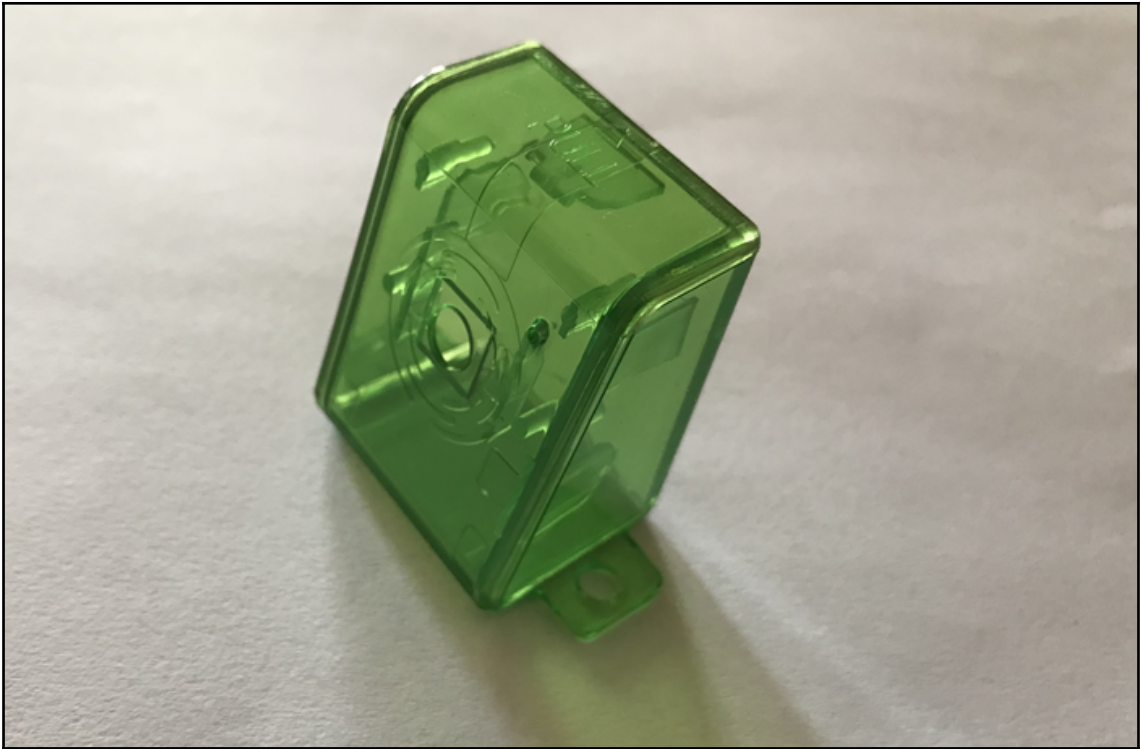


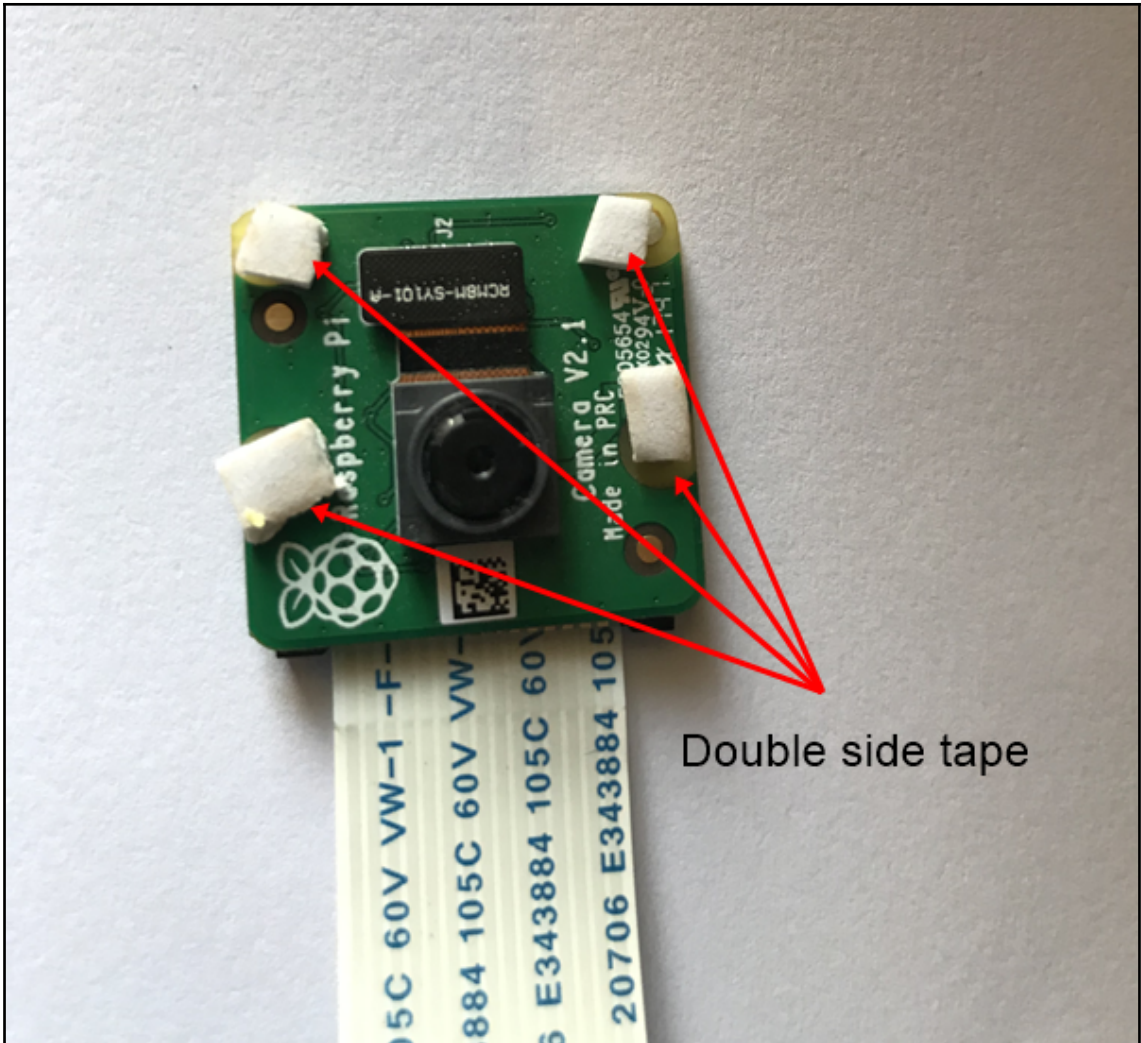


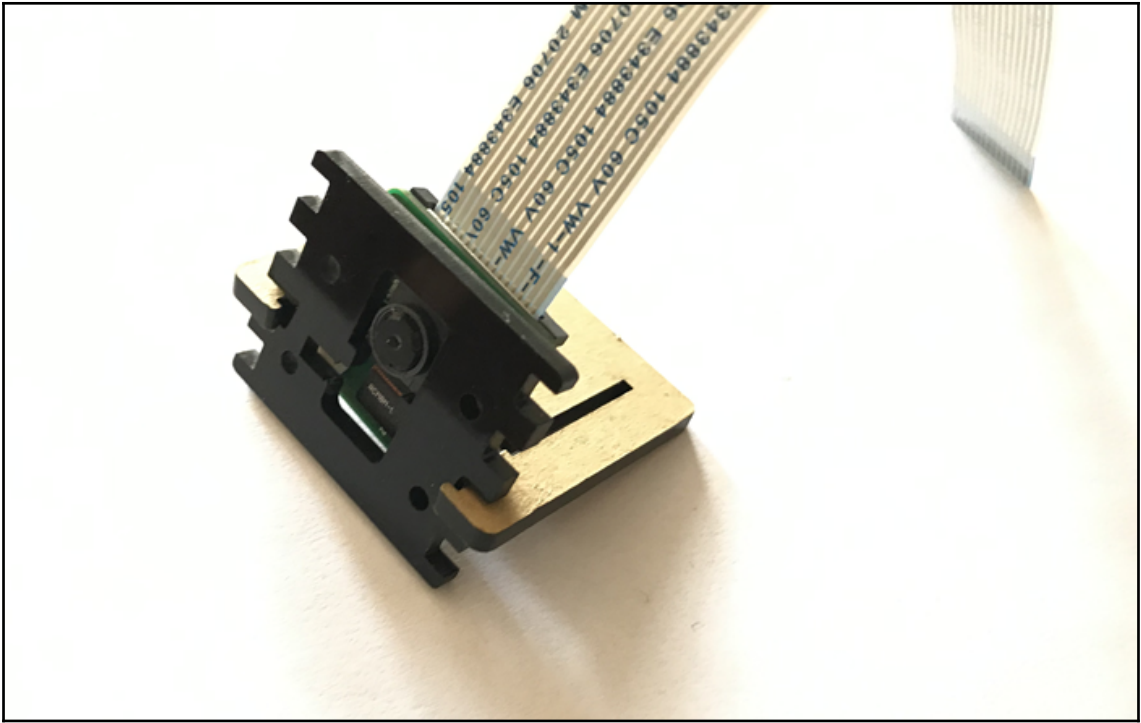


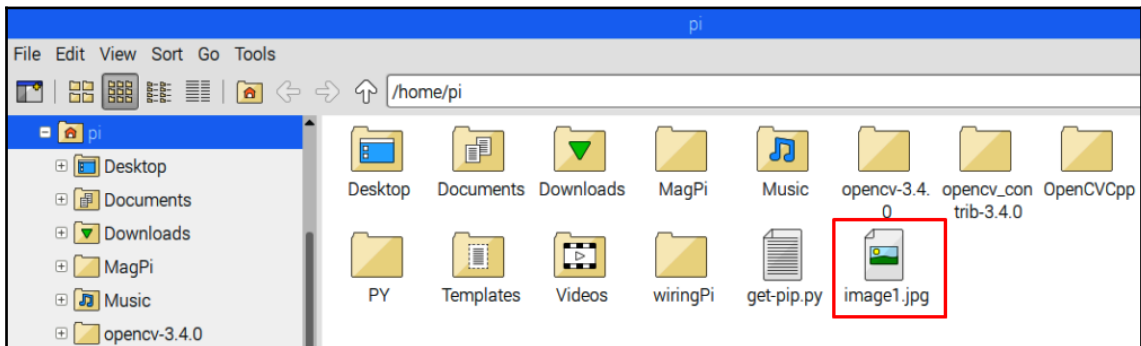
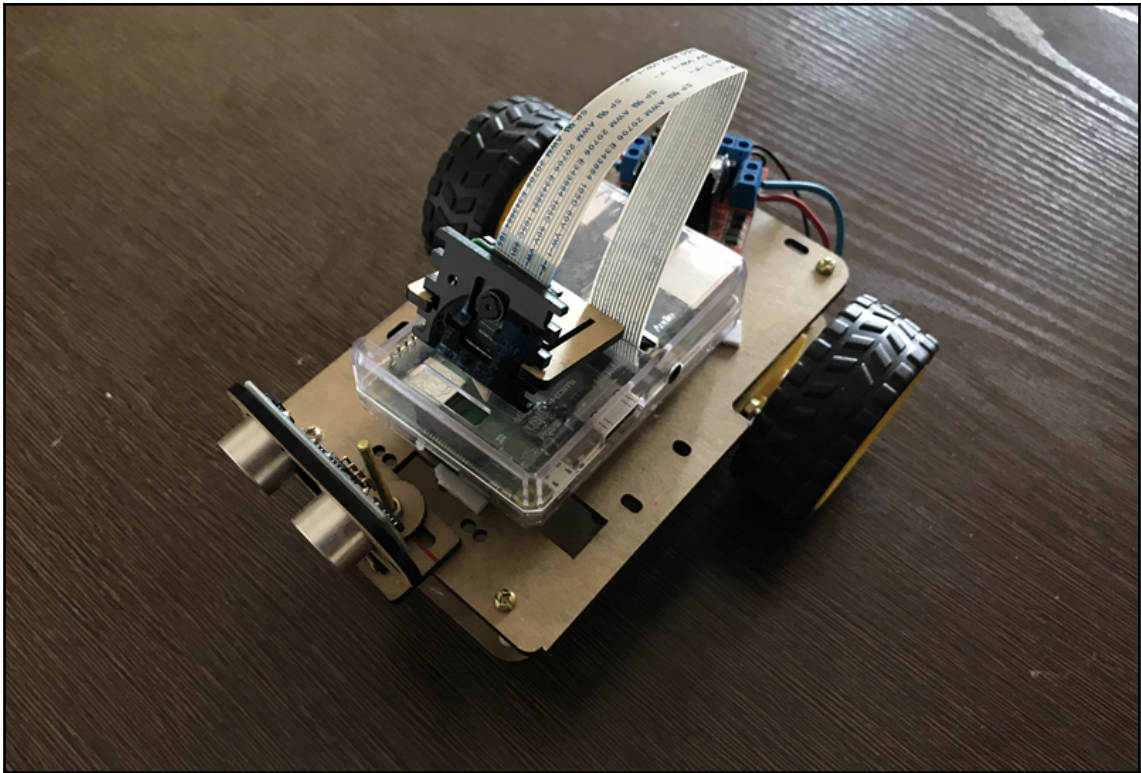




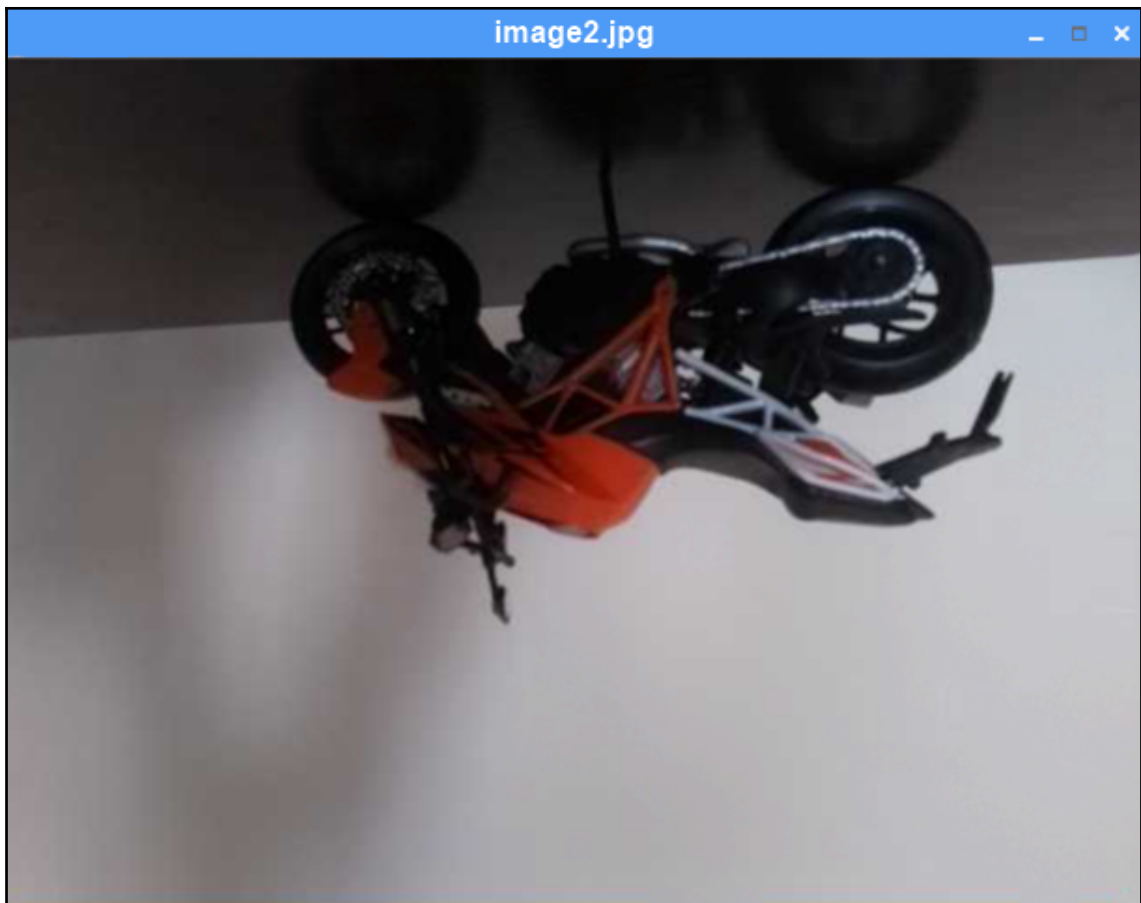




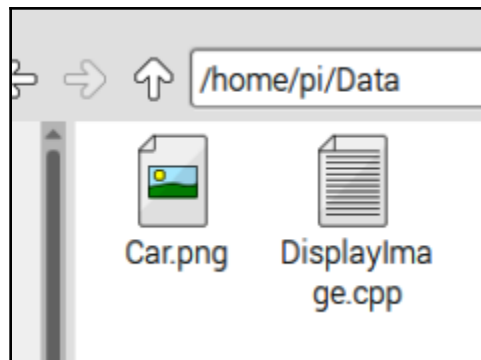
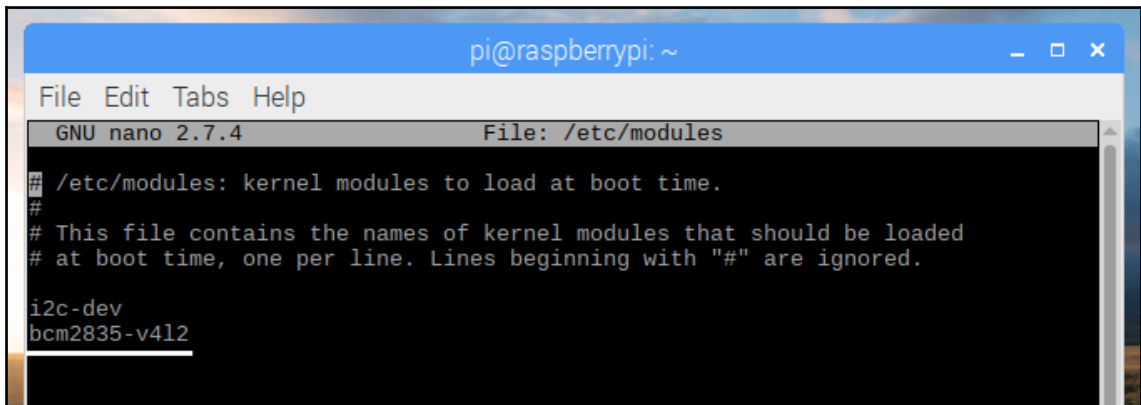
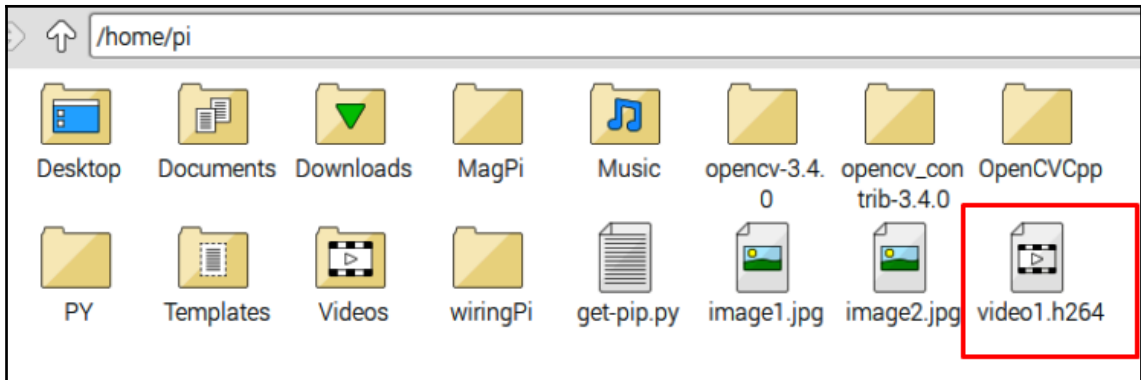


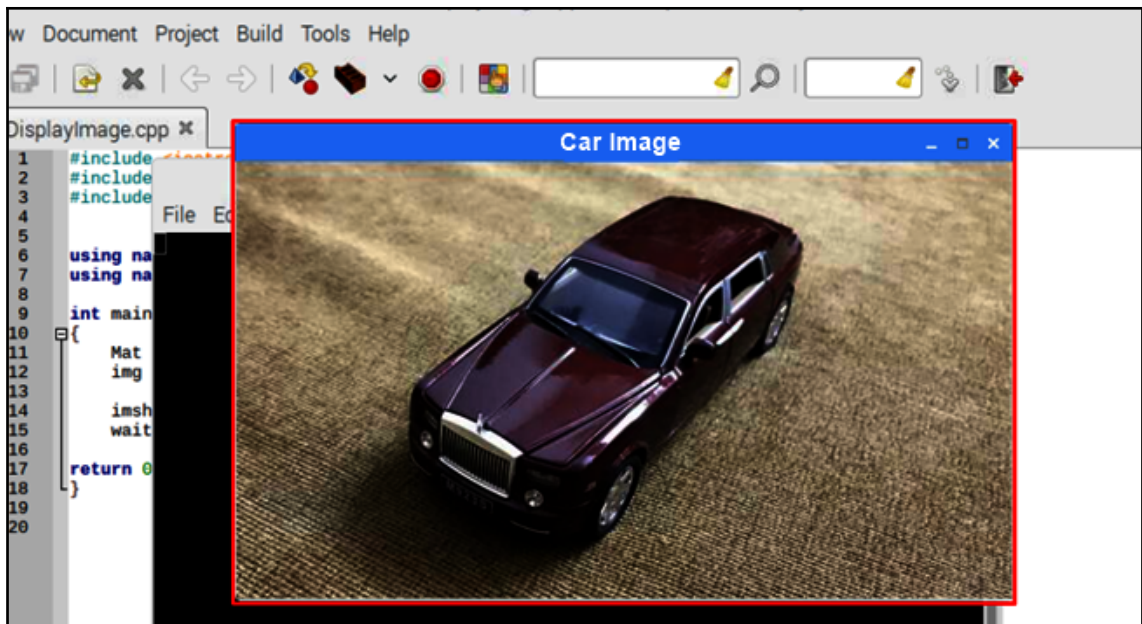




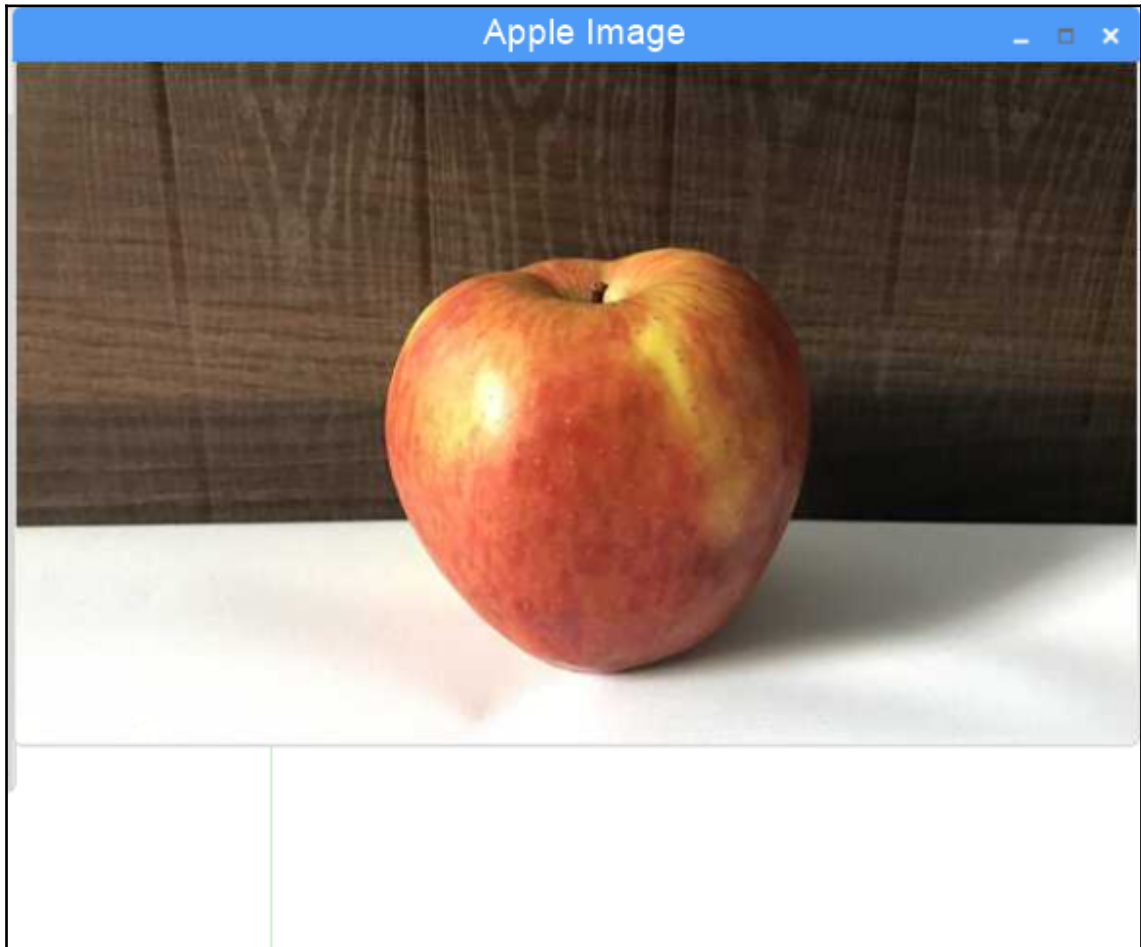
A terminal window titled "pi@raspberrypi: ~" with standard window controls in the top right corner. The terminal has a menu bar with "File", "Edit", "Tabs", and "Help". It shows a sequence of four commands being entered at the prompt "pi@raspberrypi:~ \$":

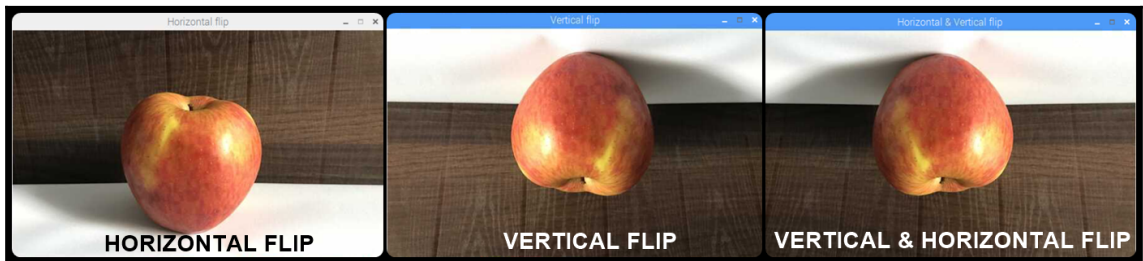
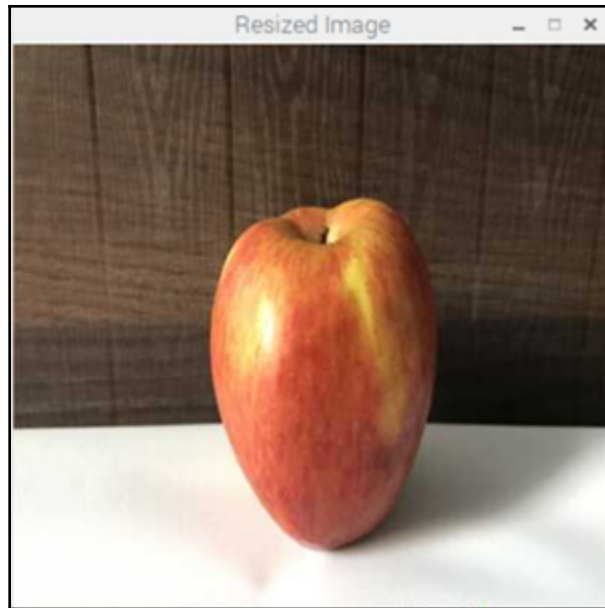
```
pi@raspberrypi:~ $ raspistill -o image1.jpg
pi@raspberrypi:~ $ raspistill -vf -hf -o image2.jpg
pi@raspberrypi:~ $ raspivid -o video1.h264 -t 5000
pi@raspberrypi:~ $
```

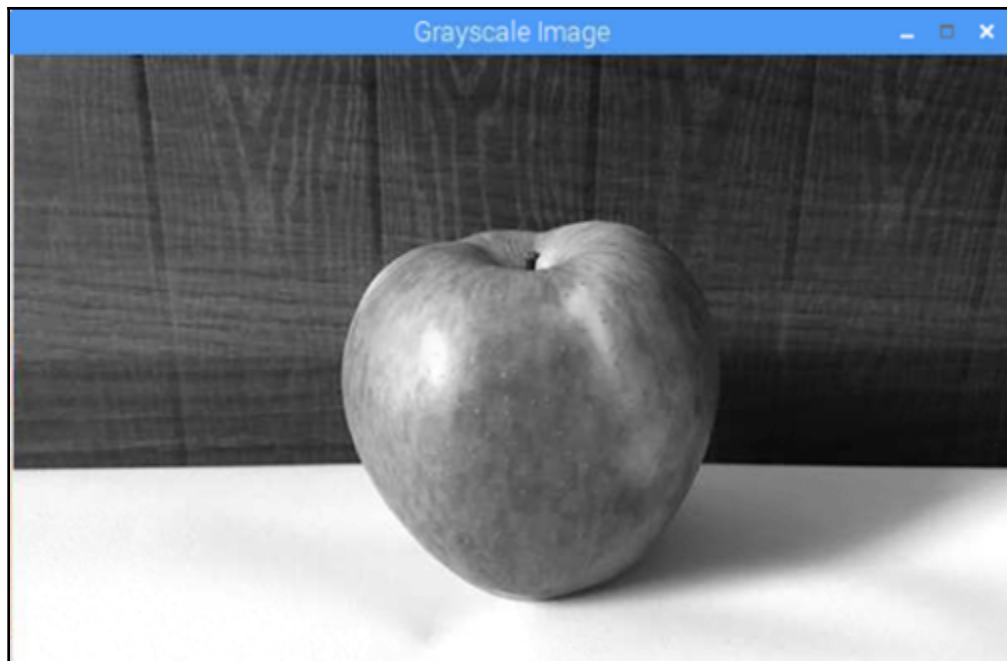


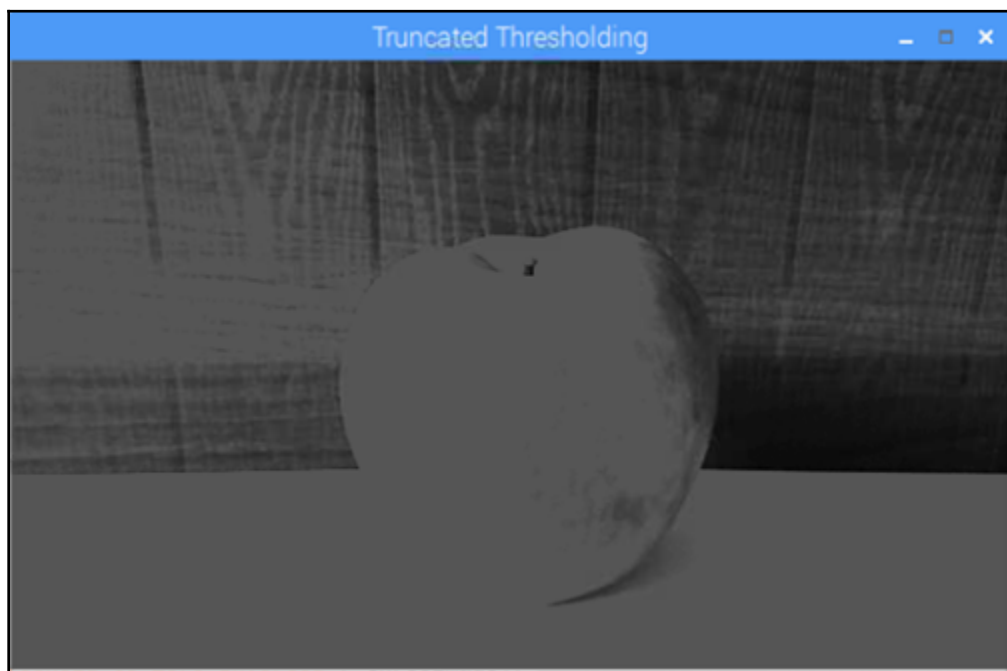
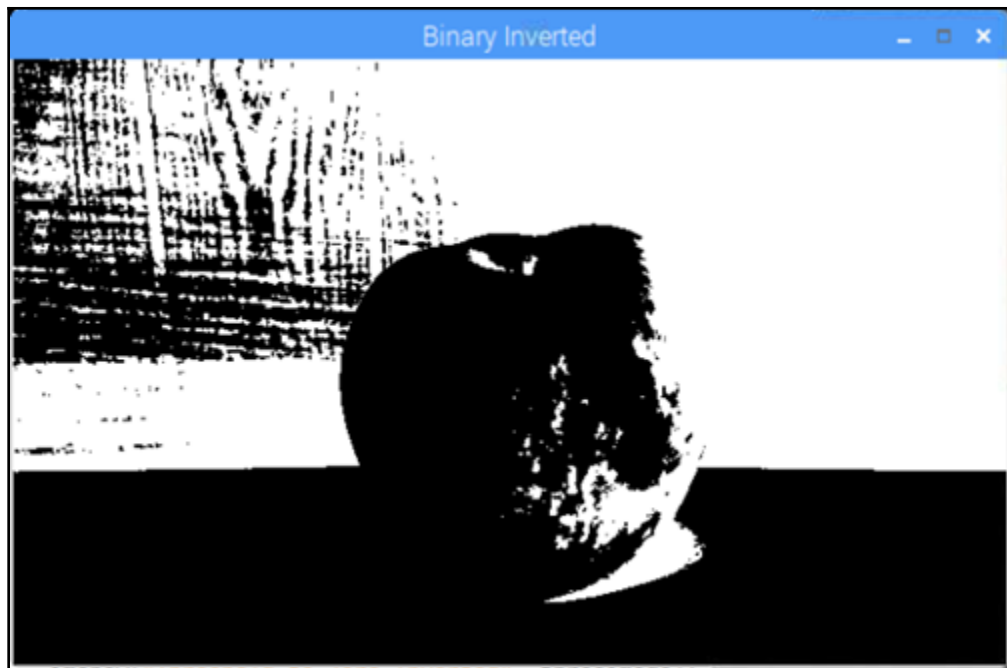


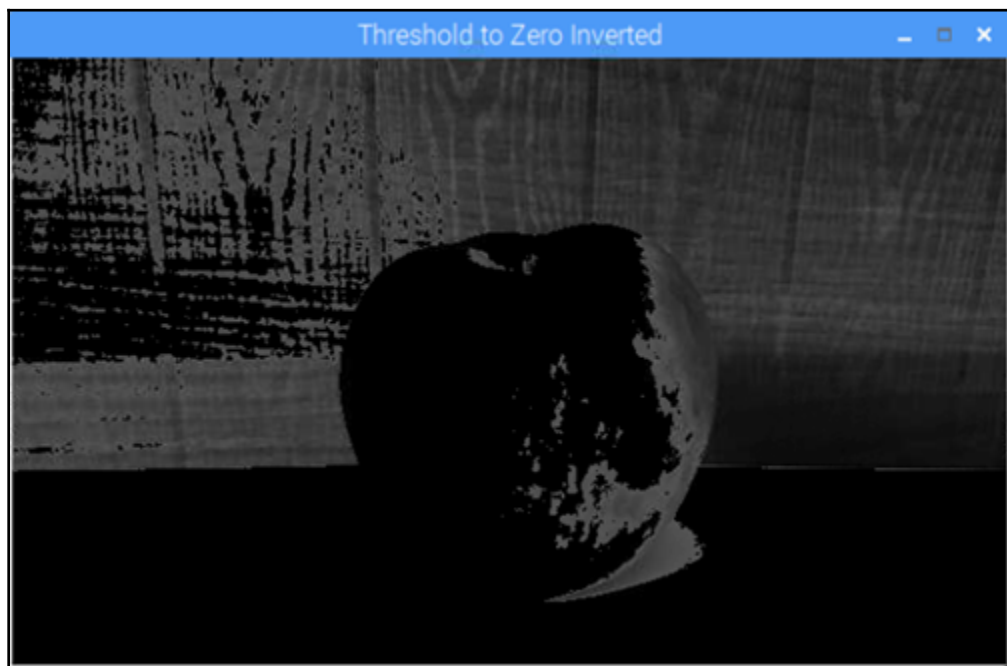
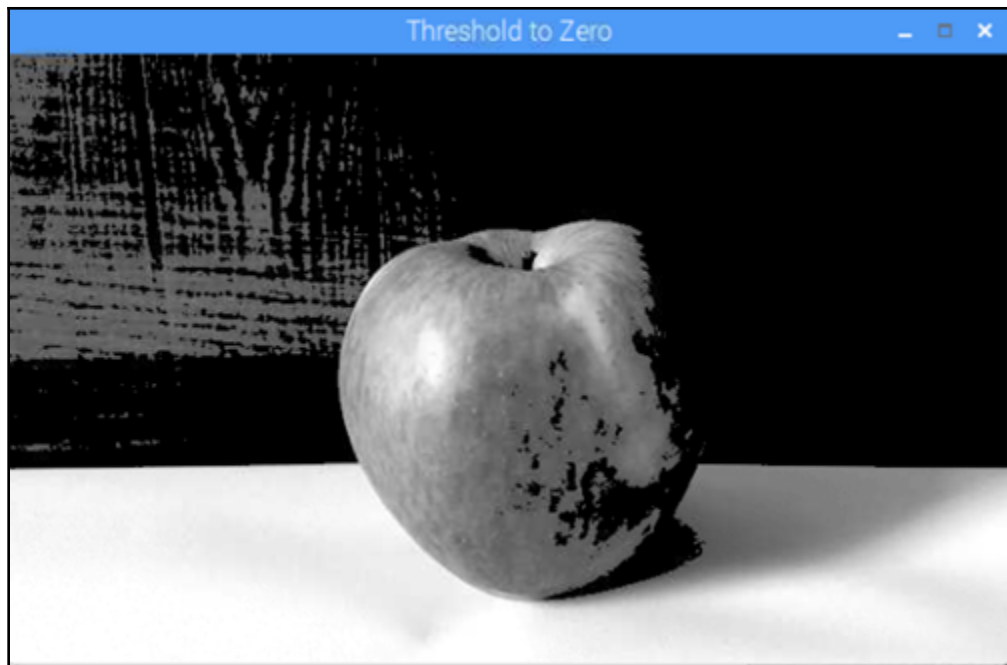
Chapter 7: Building an Object-Following Robot with OpenCV





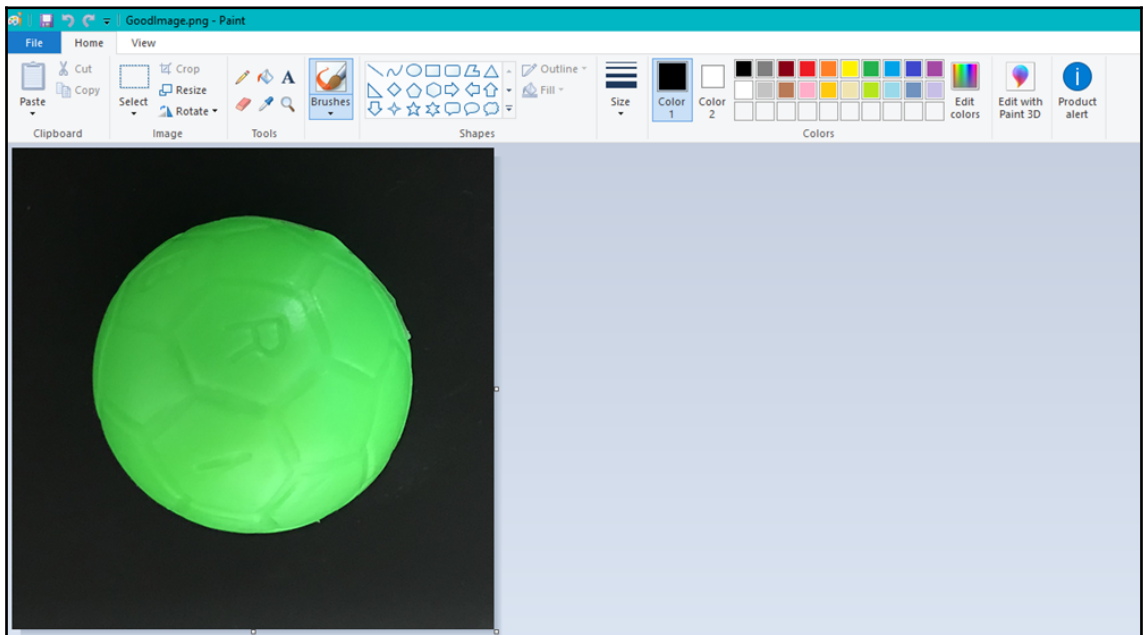
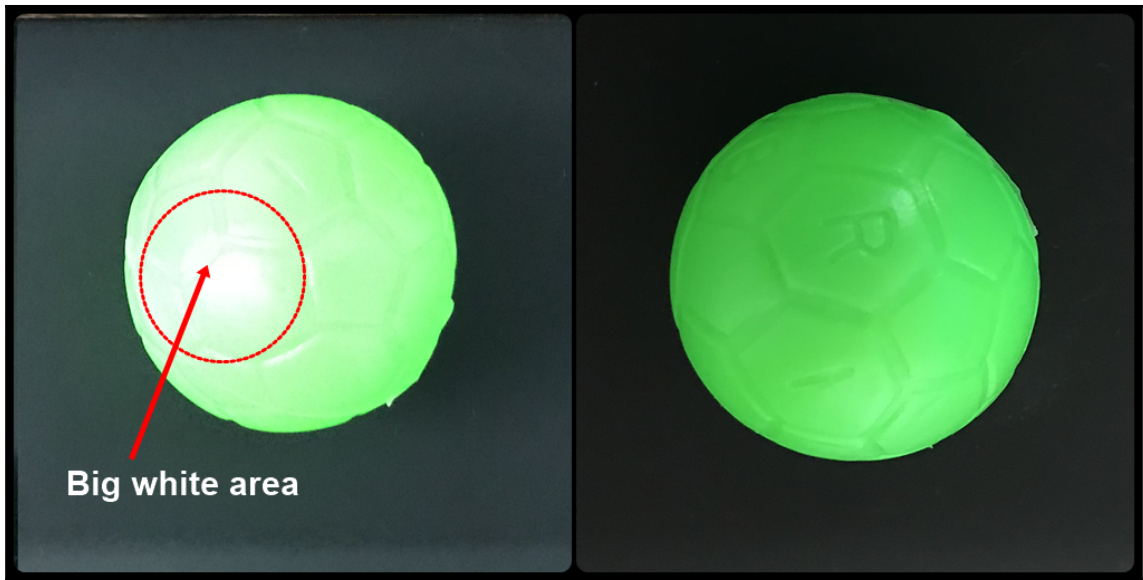


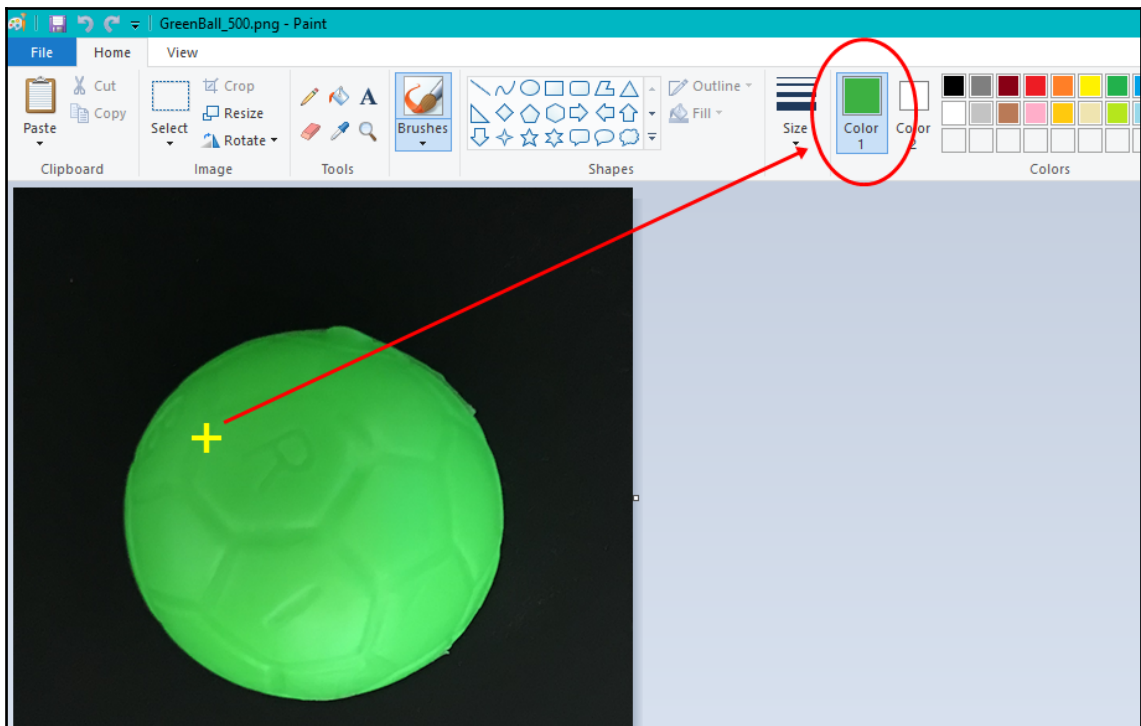
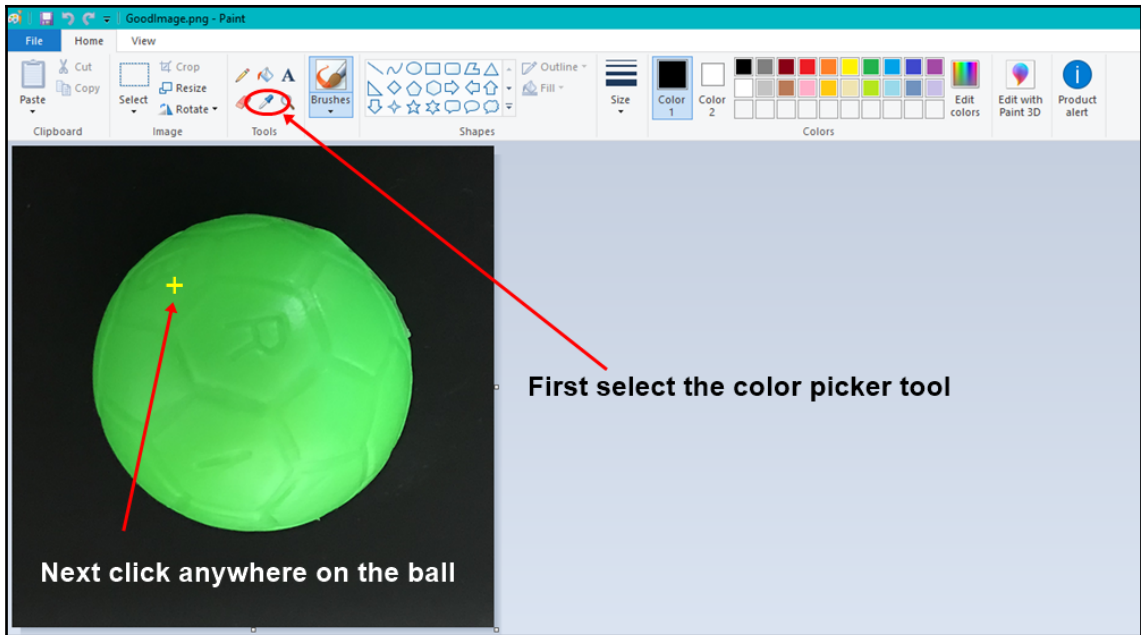


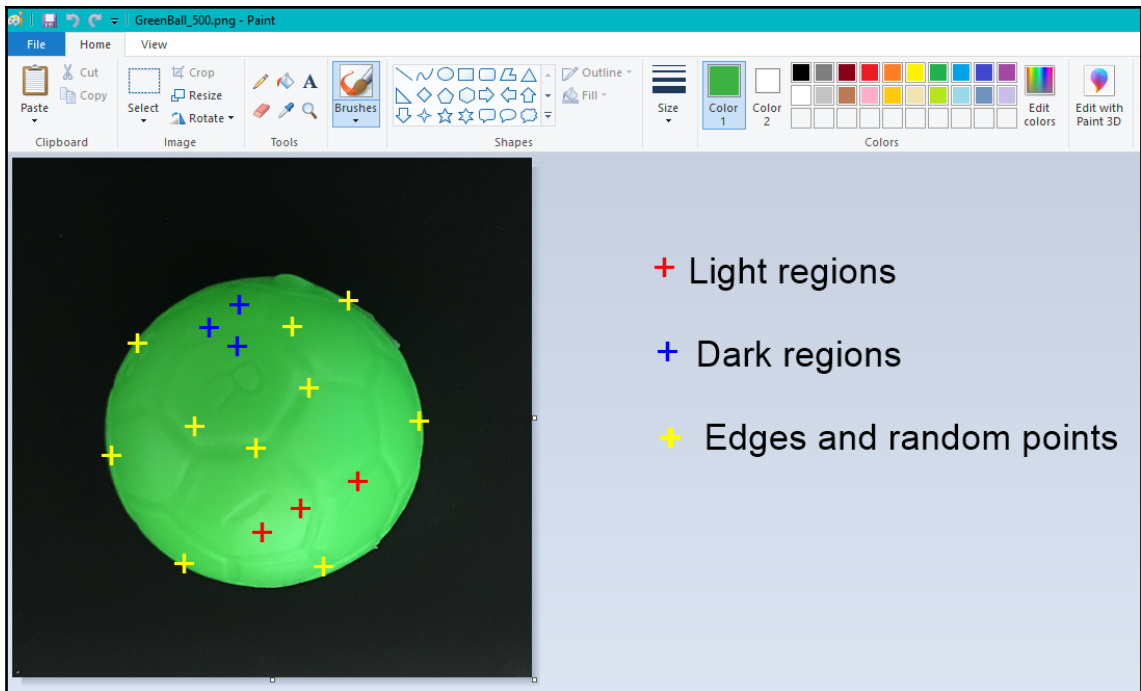
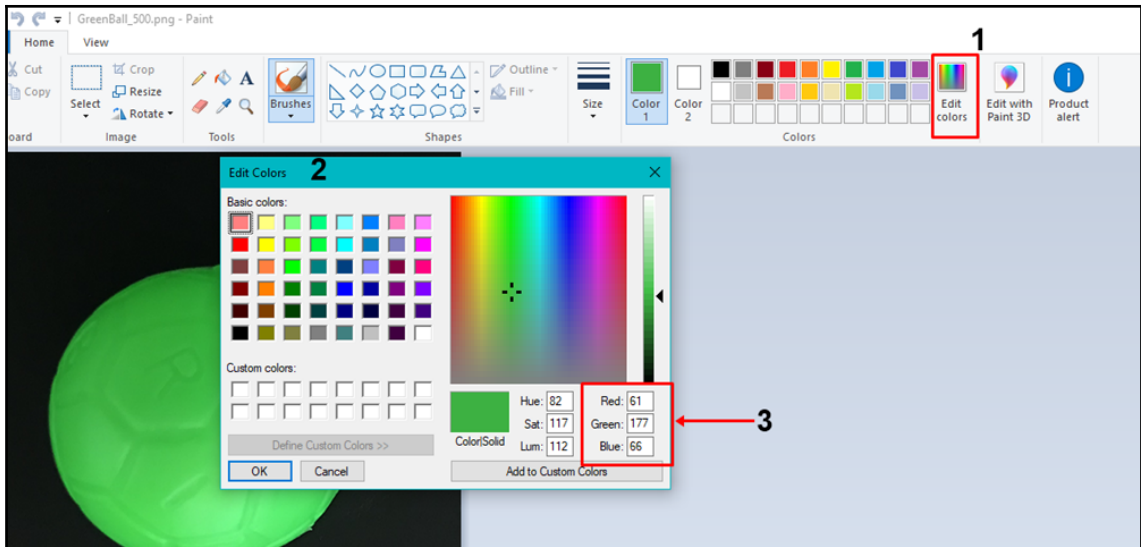


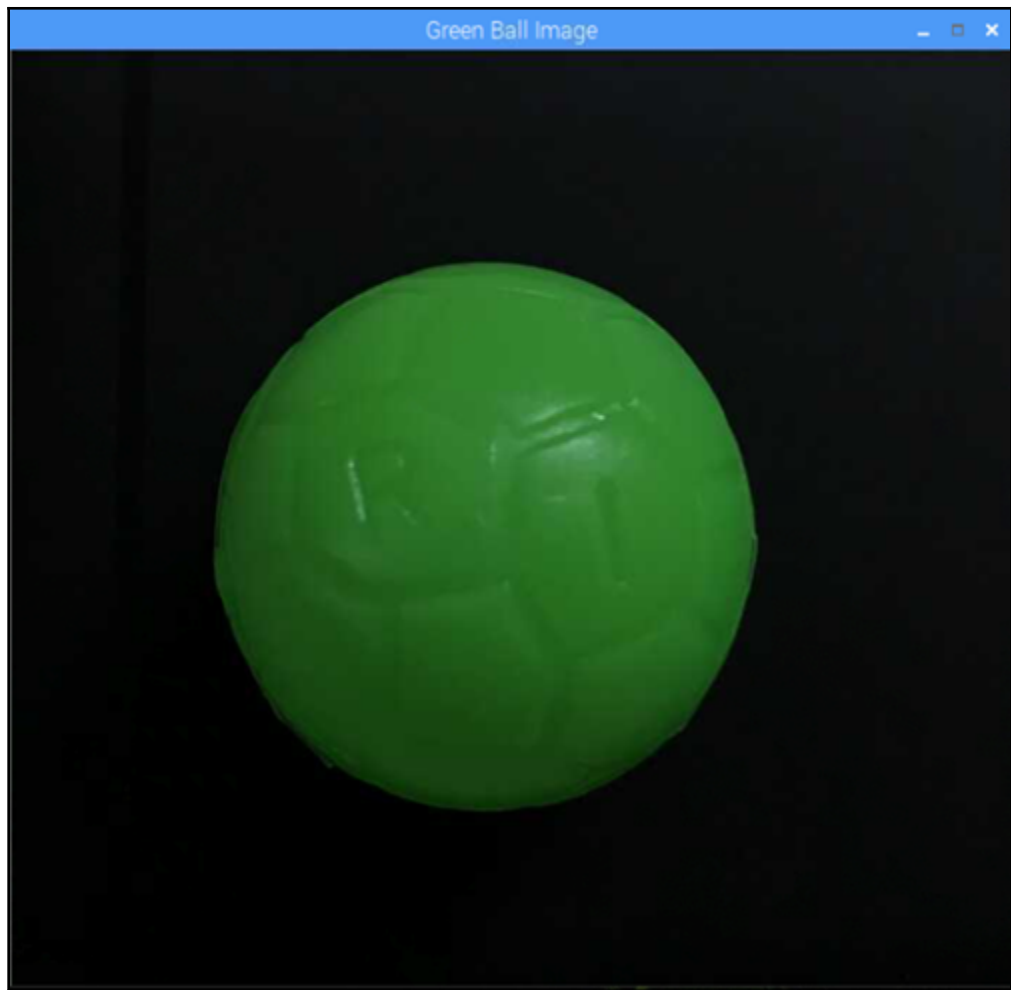


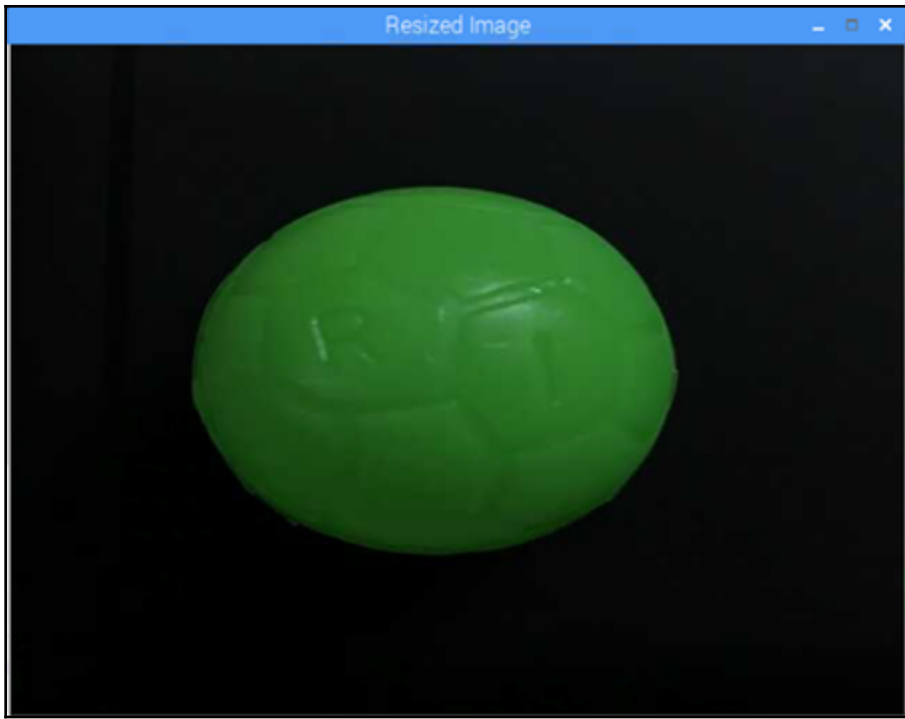


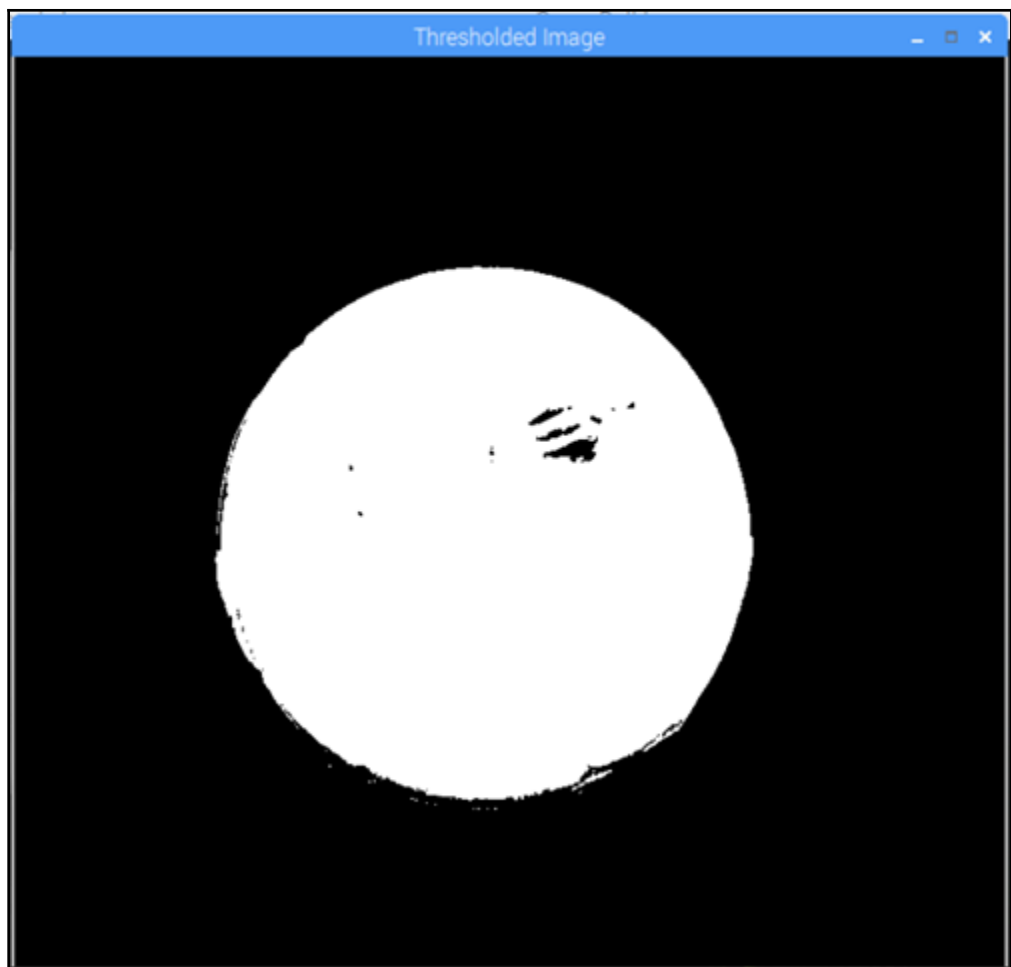


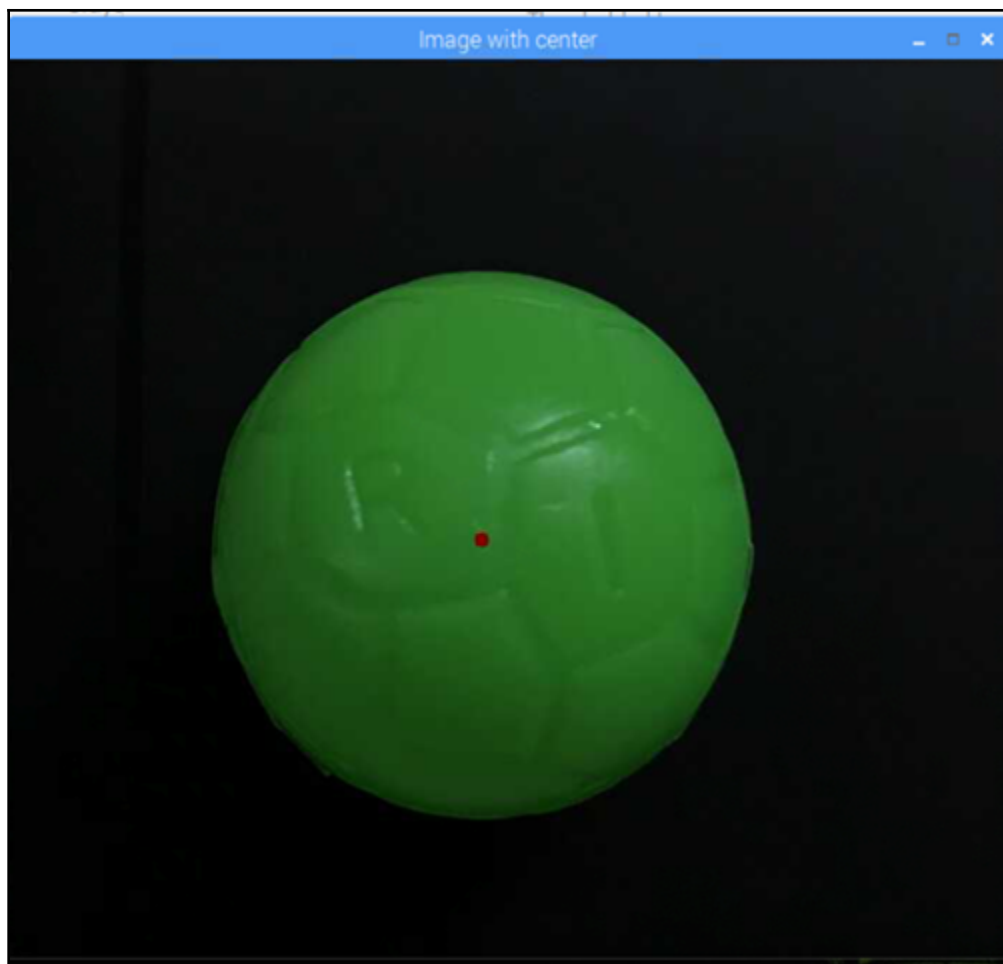


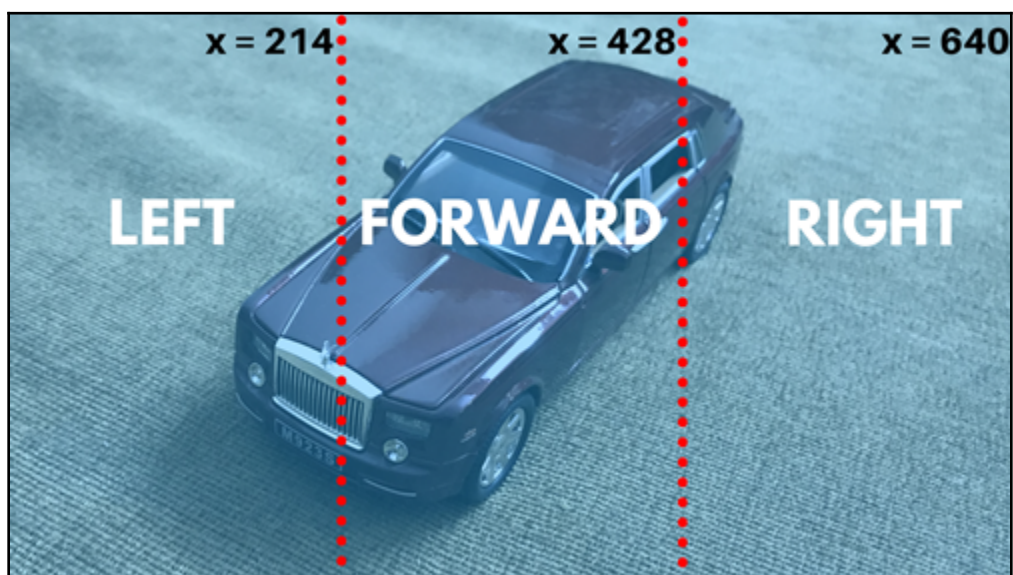
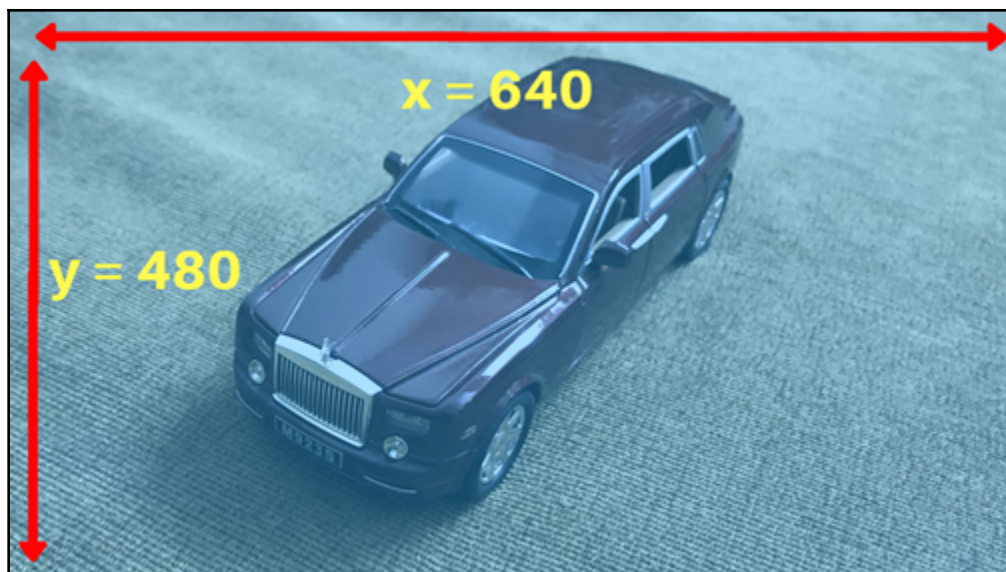


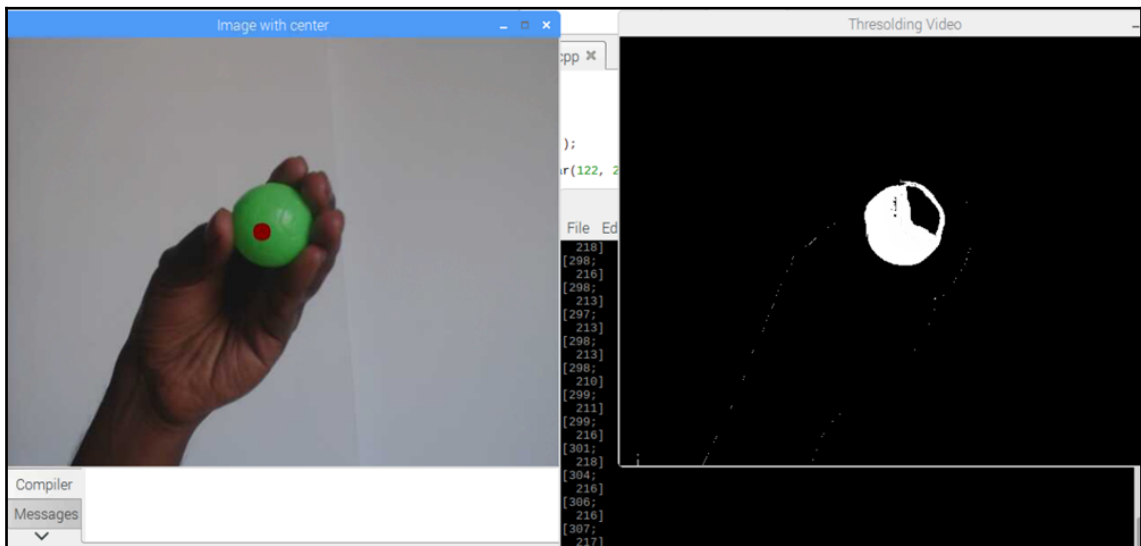
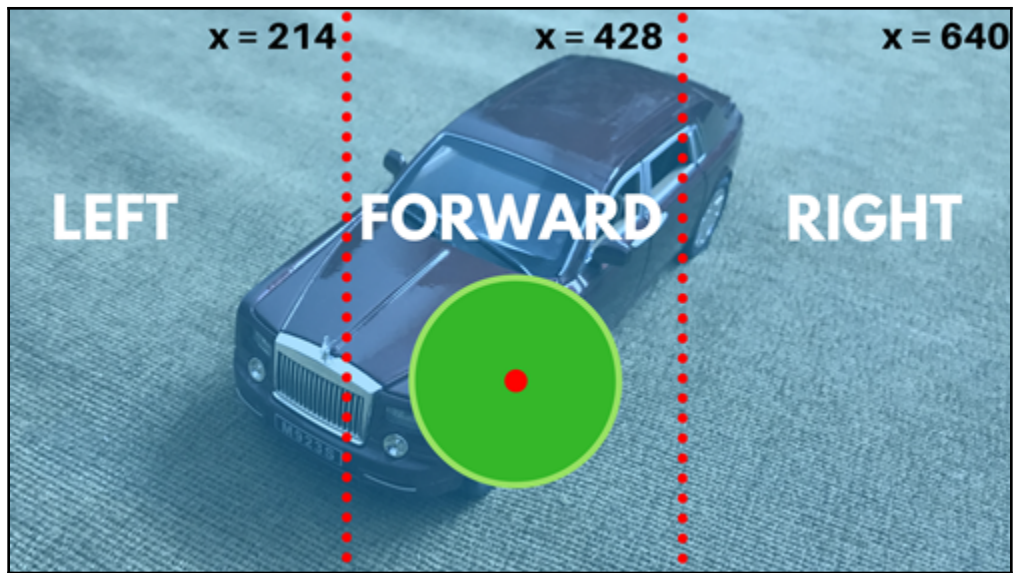


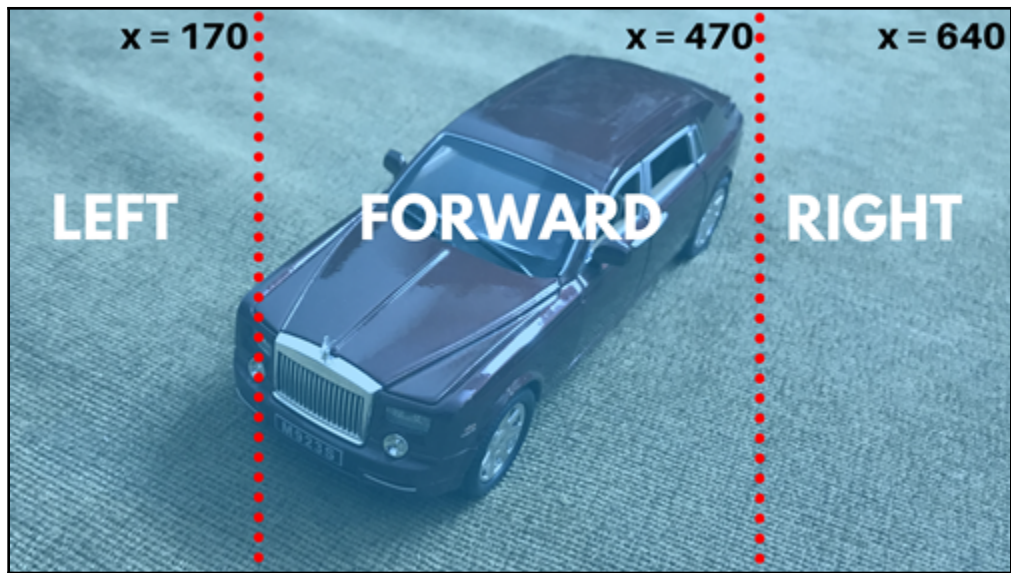




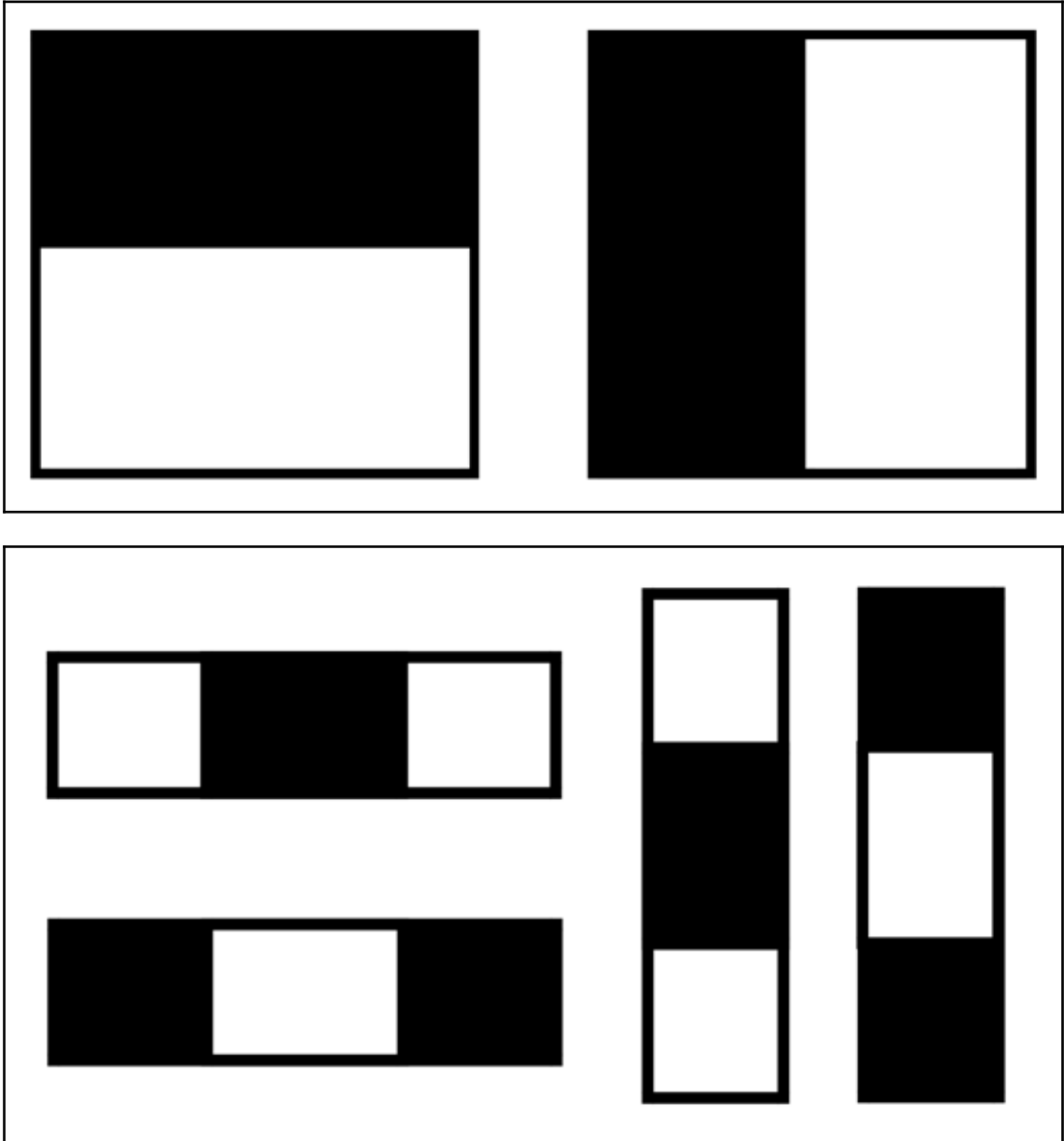


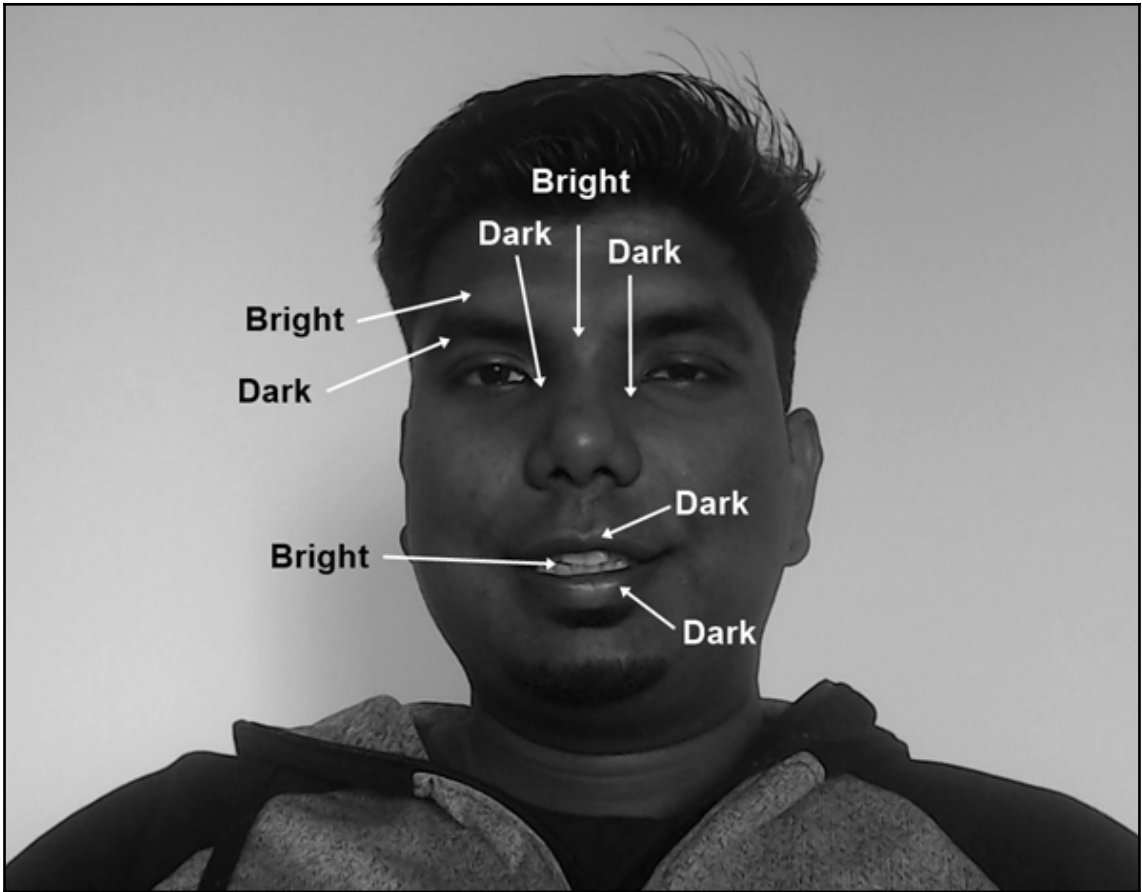


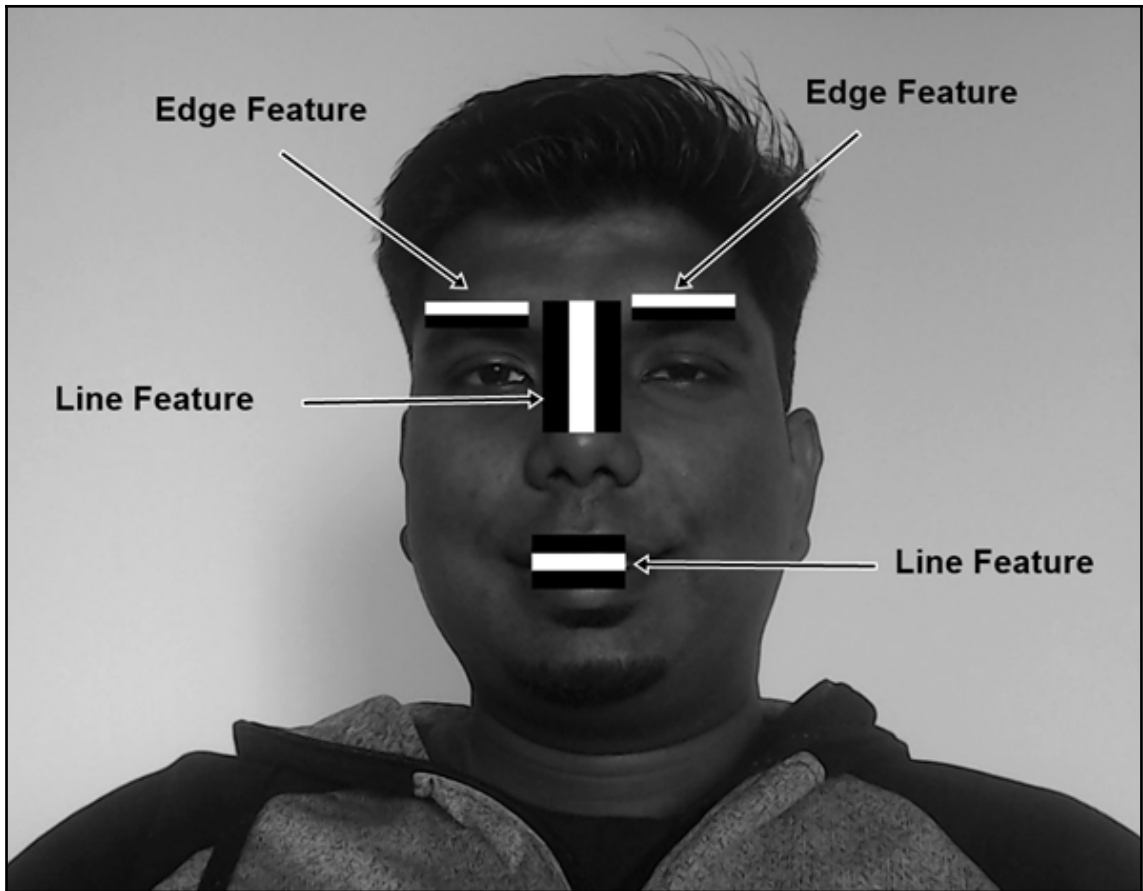


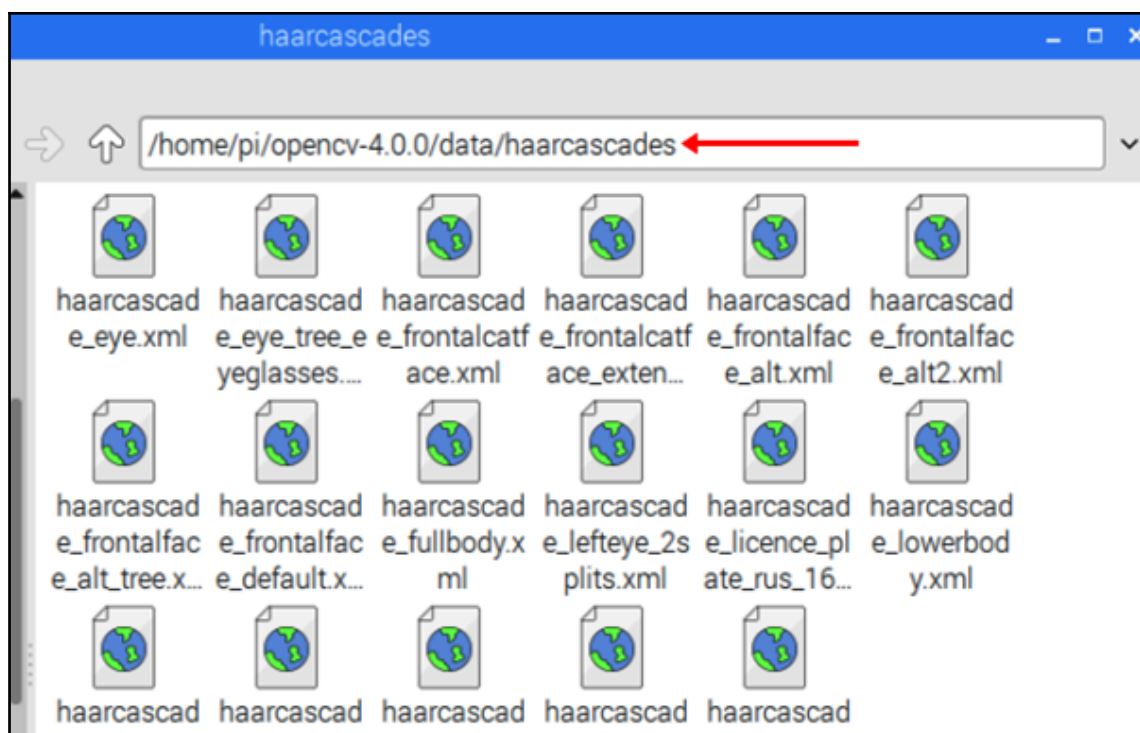


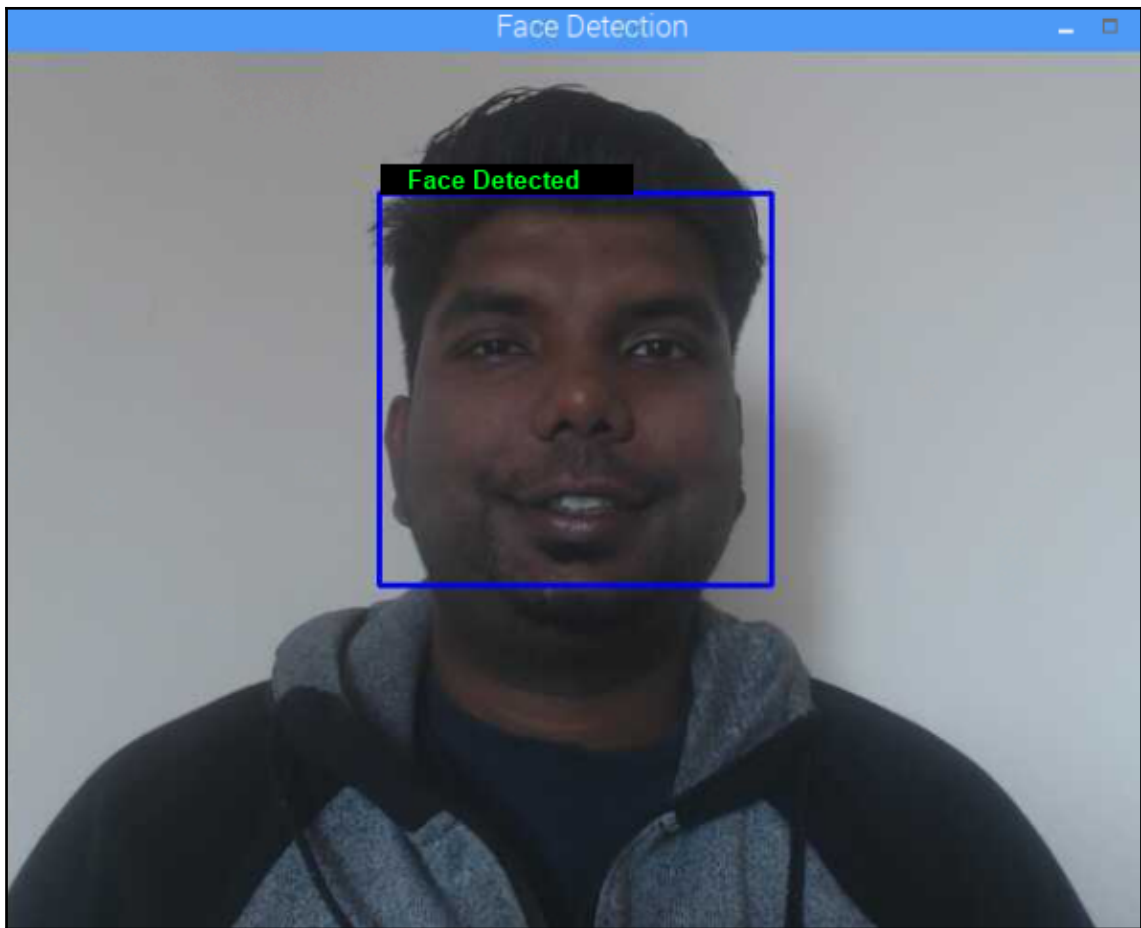
Chapter 8: Face Detection and Tracking Using the Haar Classifier

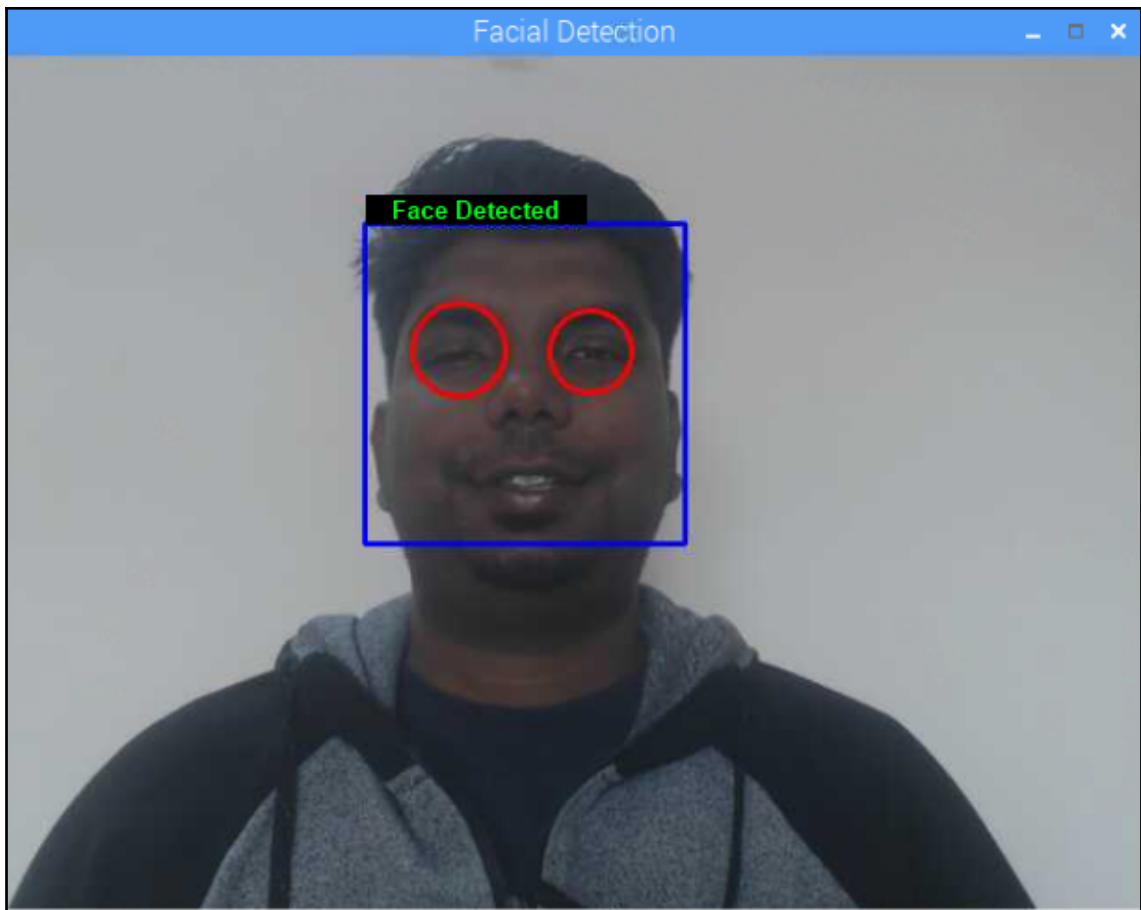


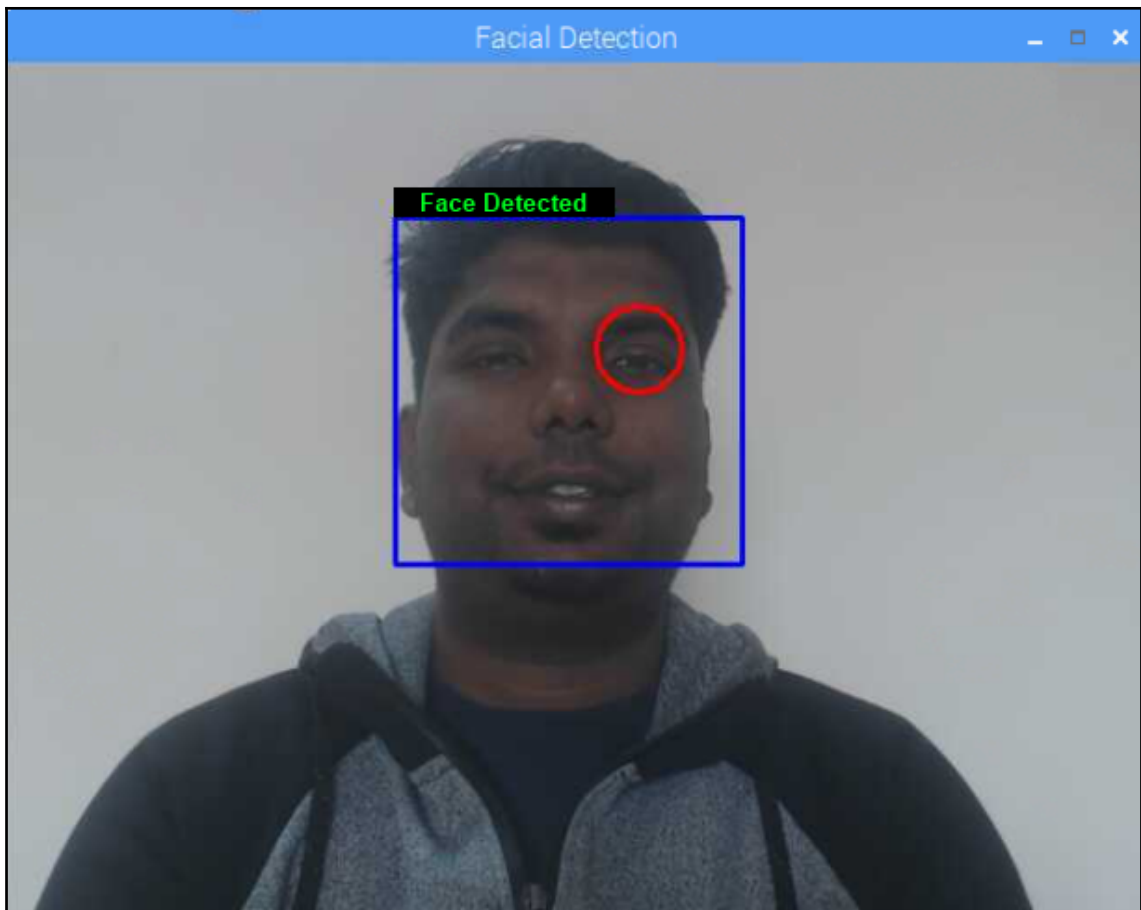


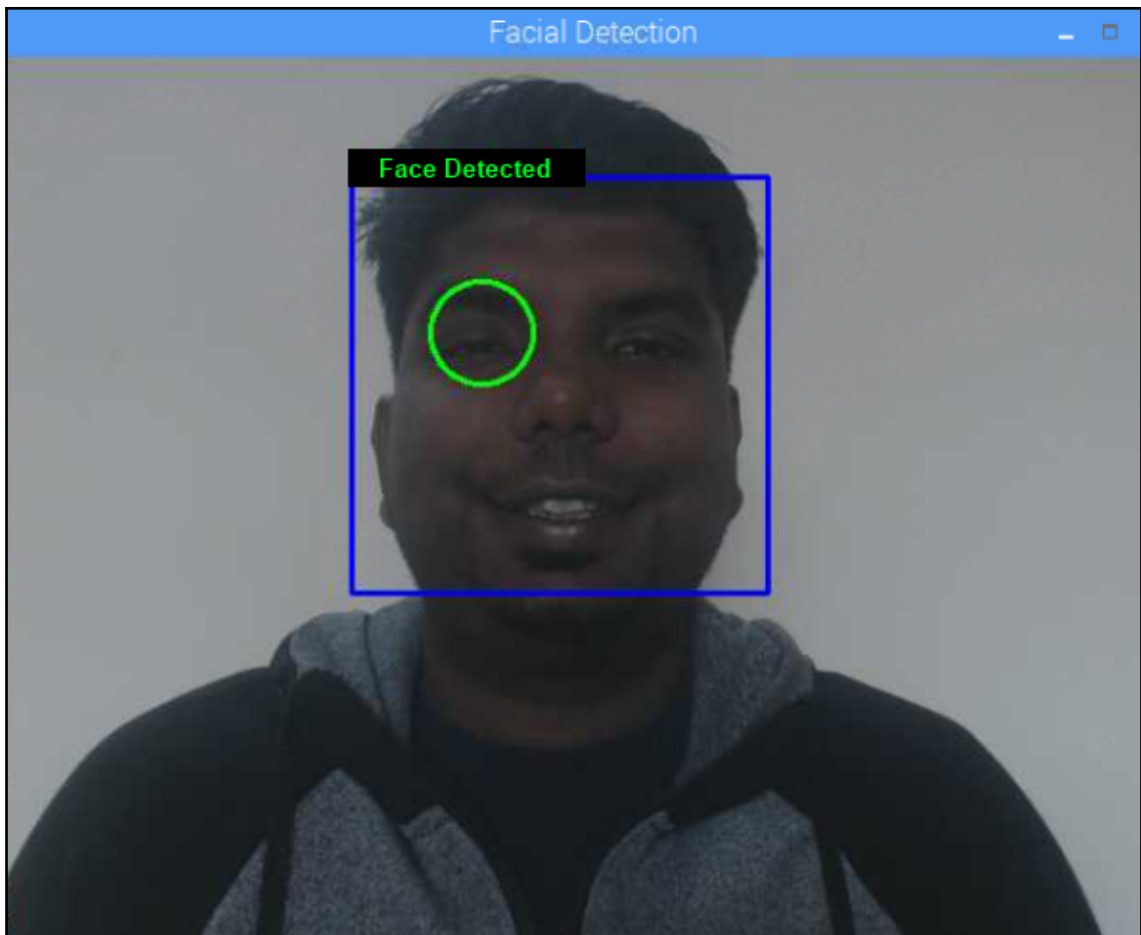


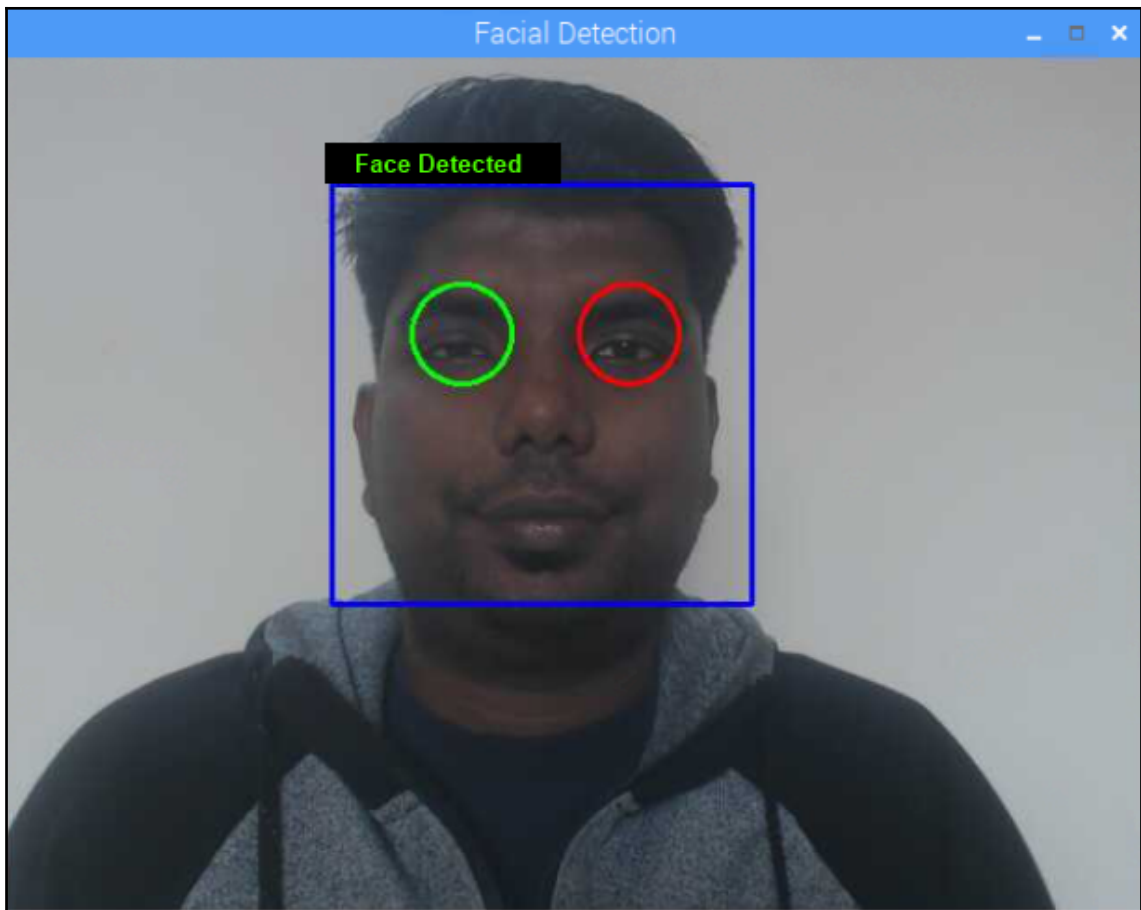


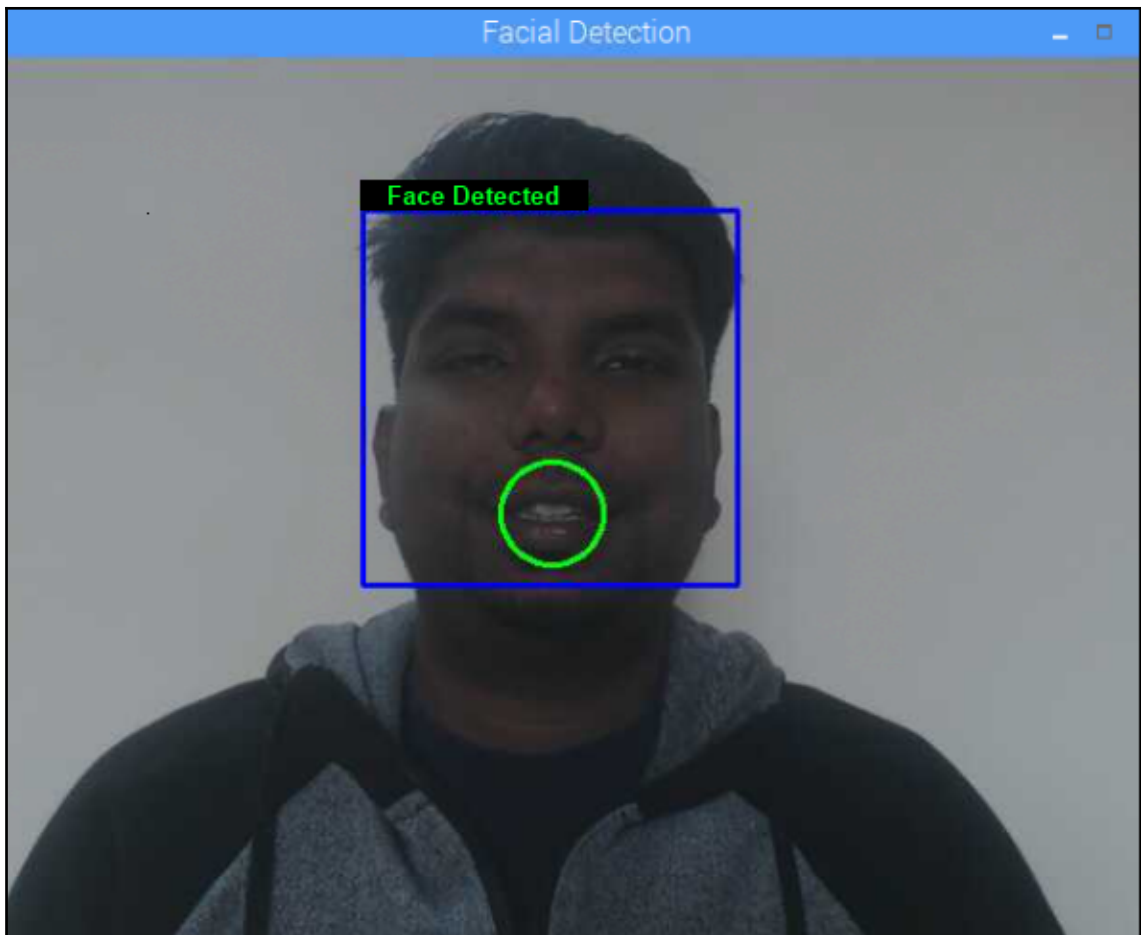


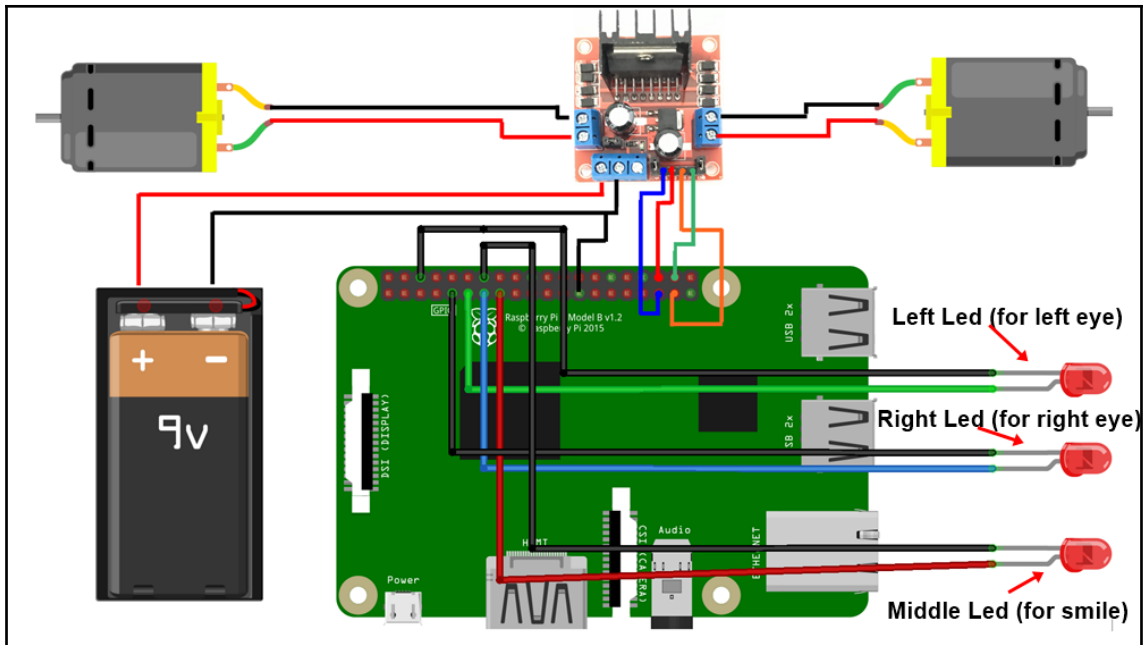


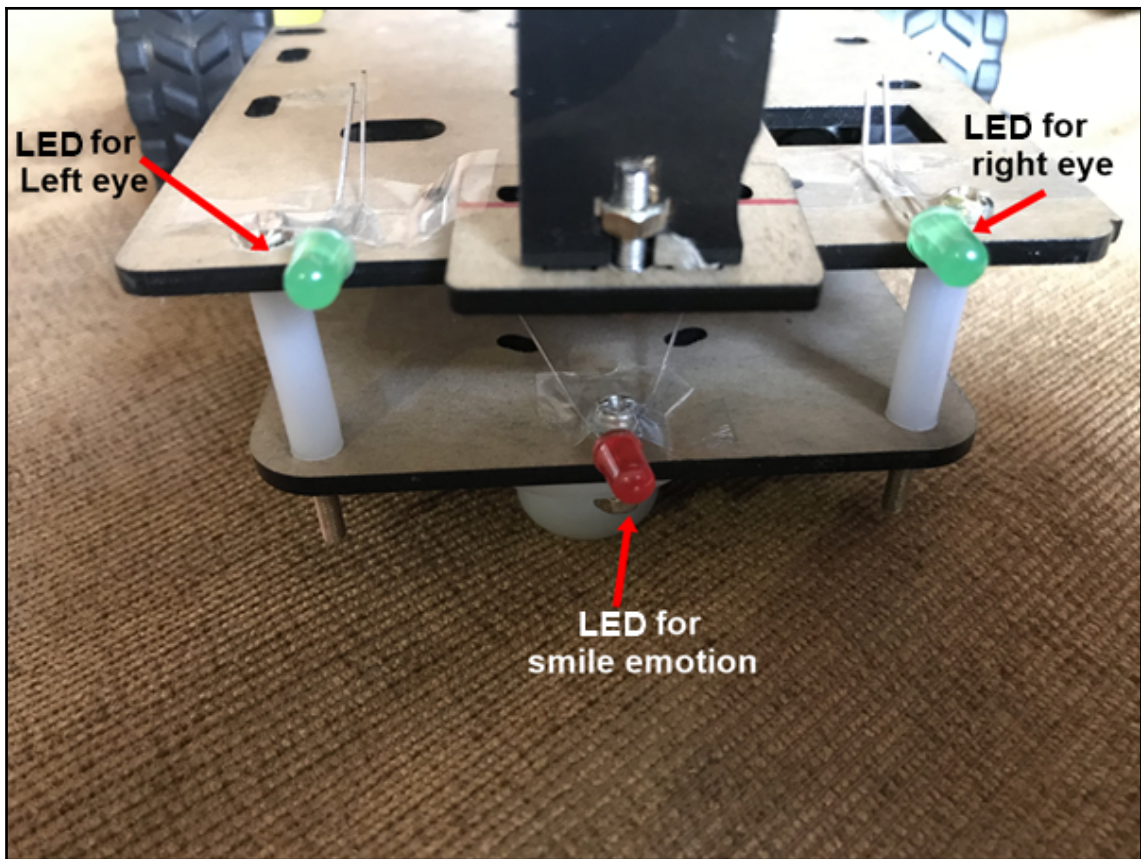


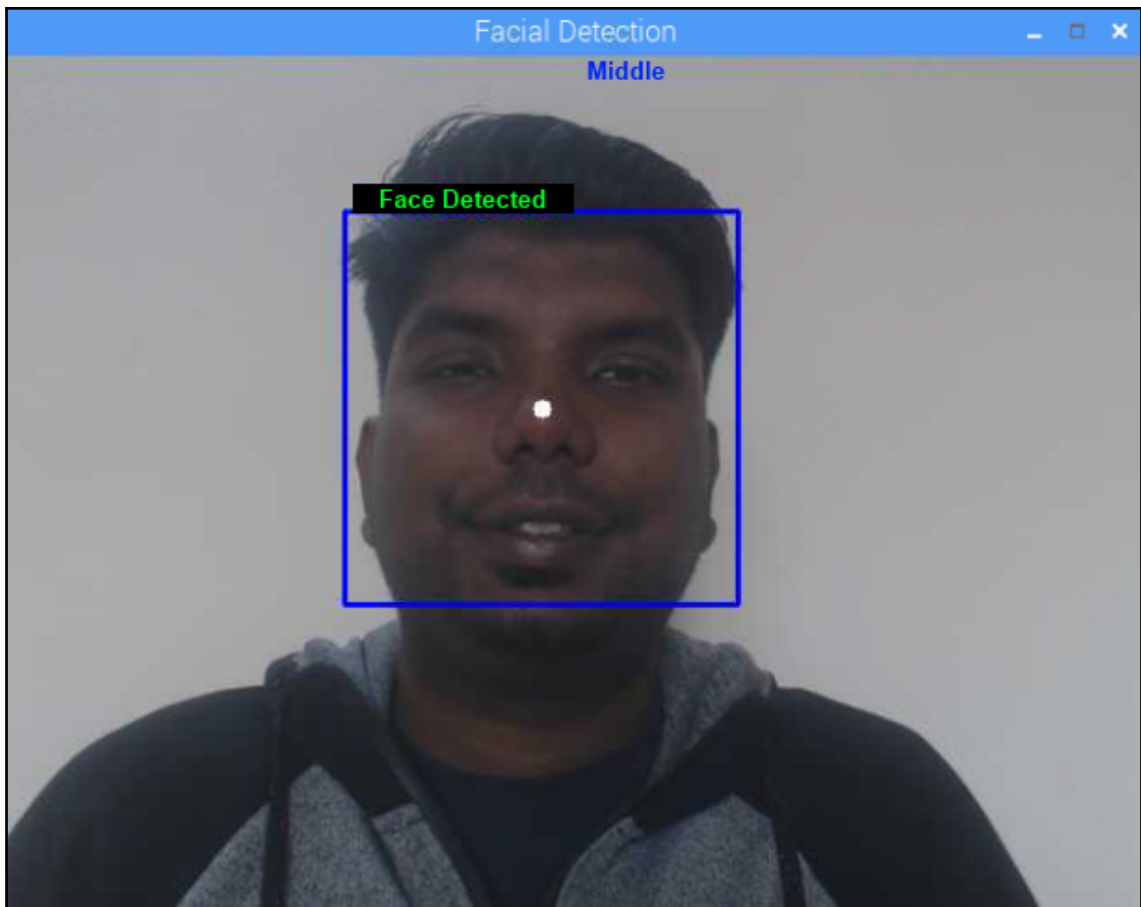


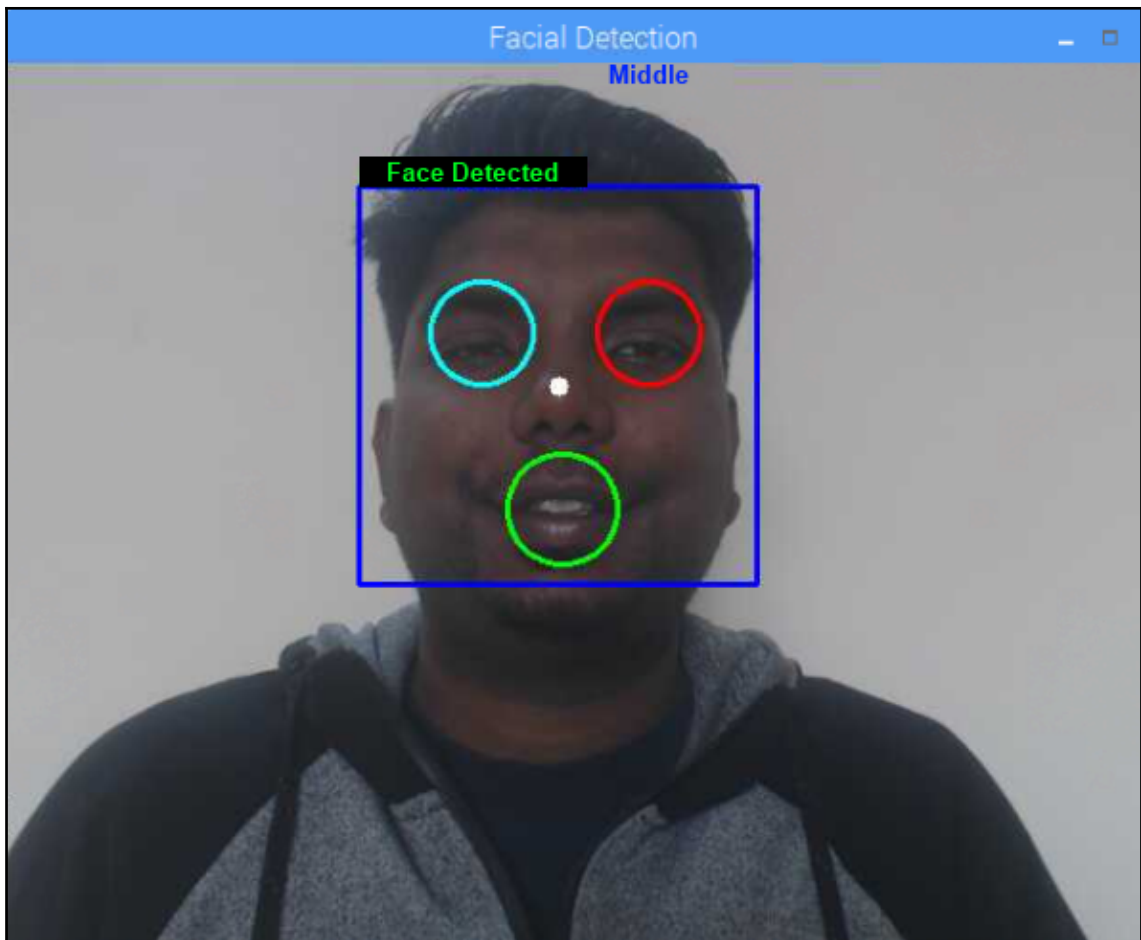


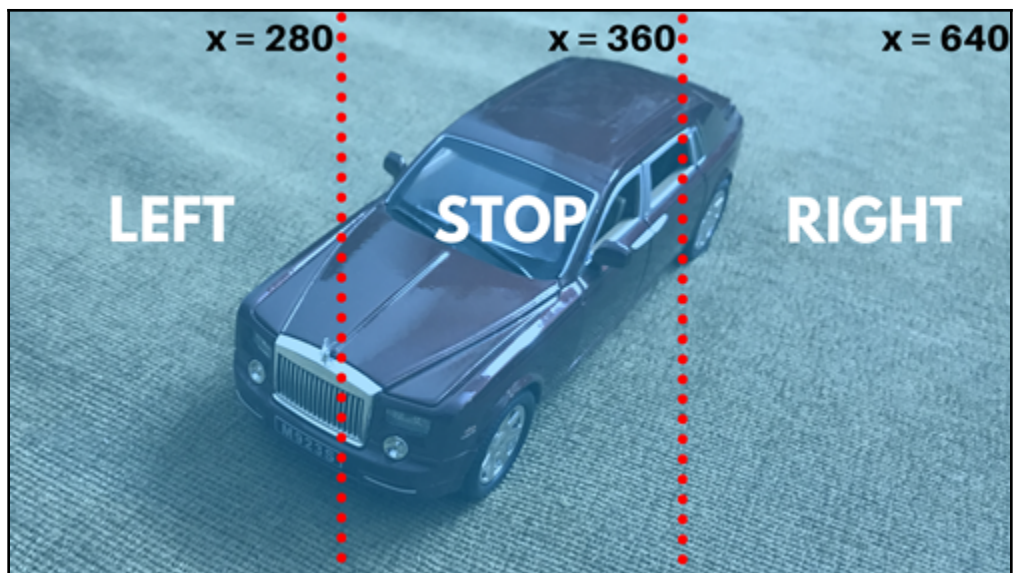




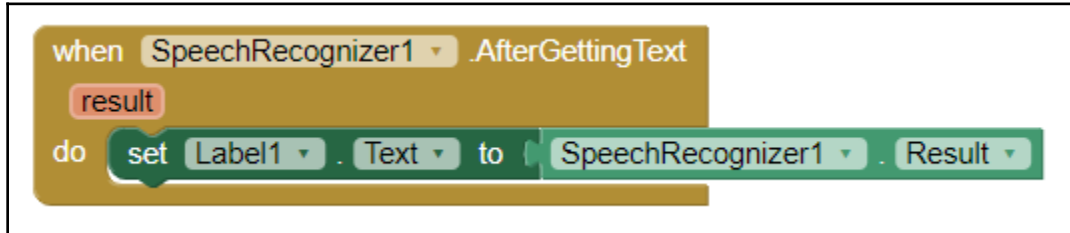


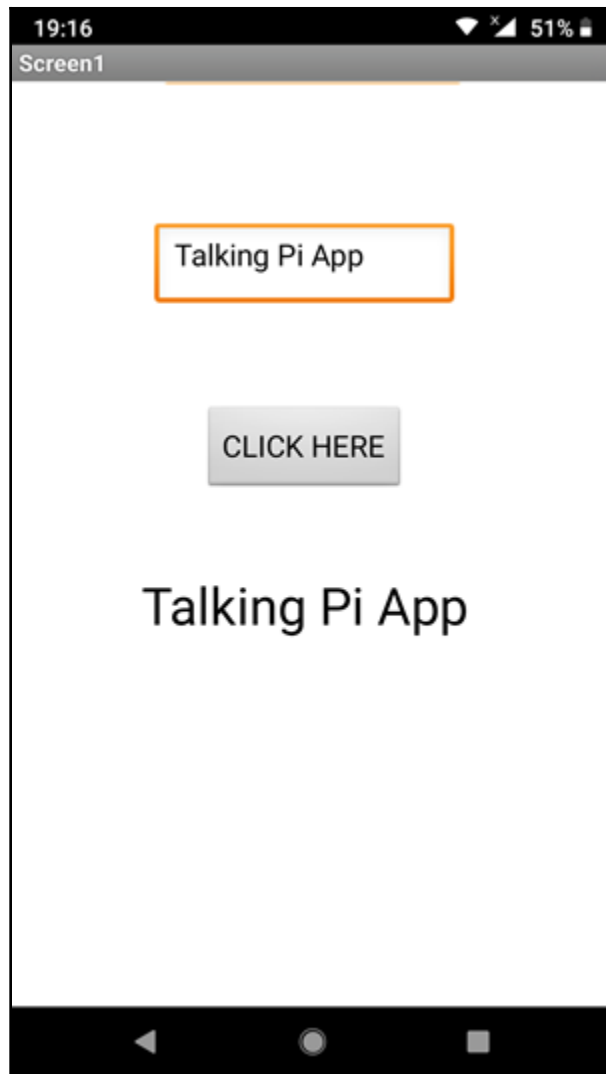


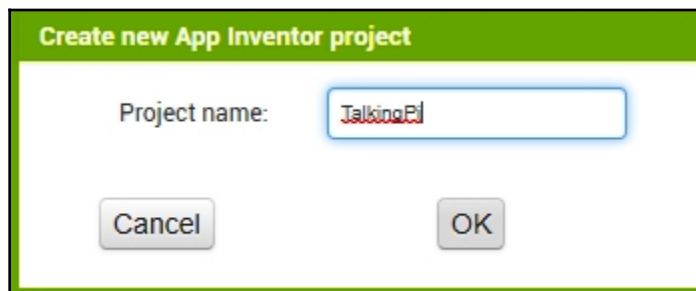
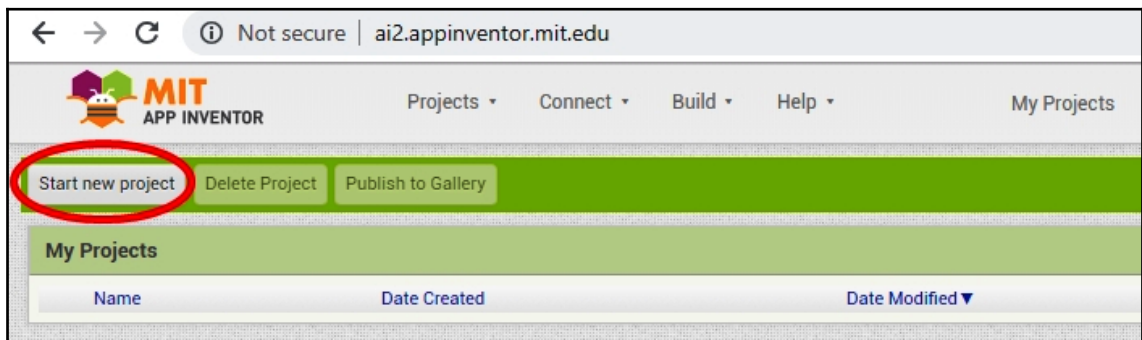
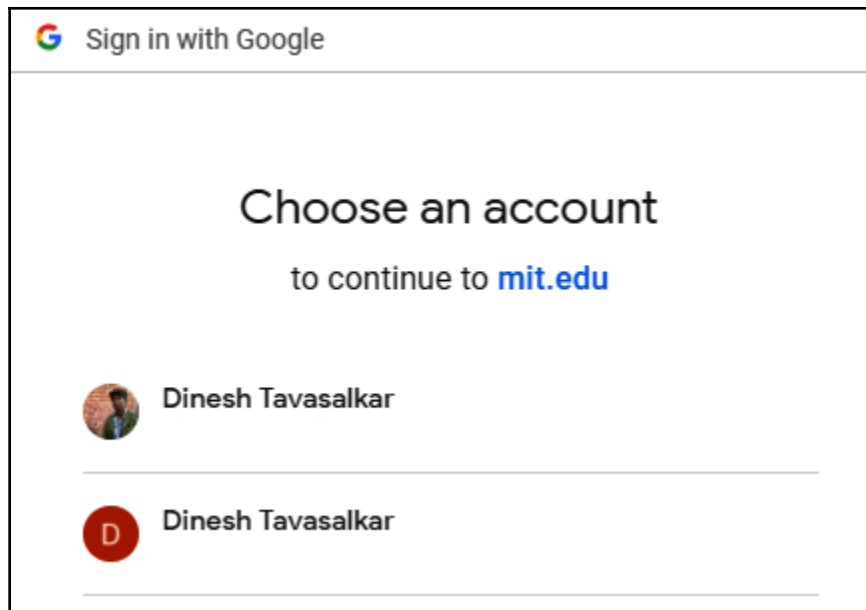


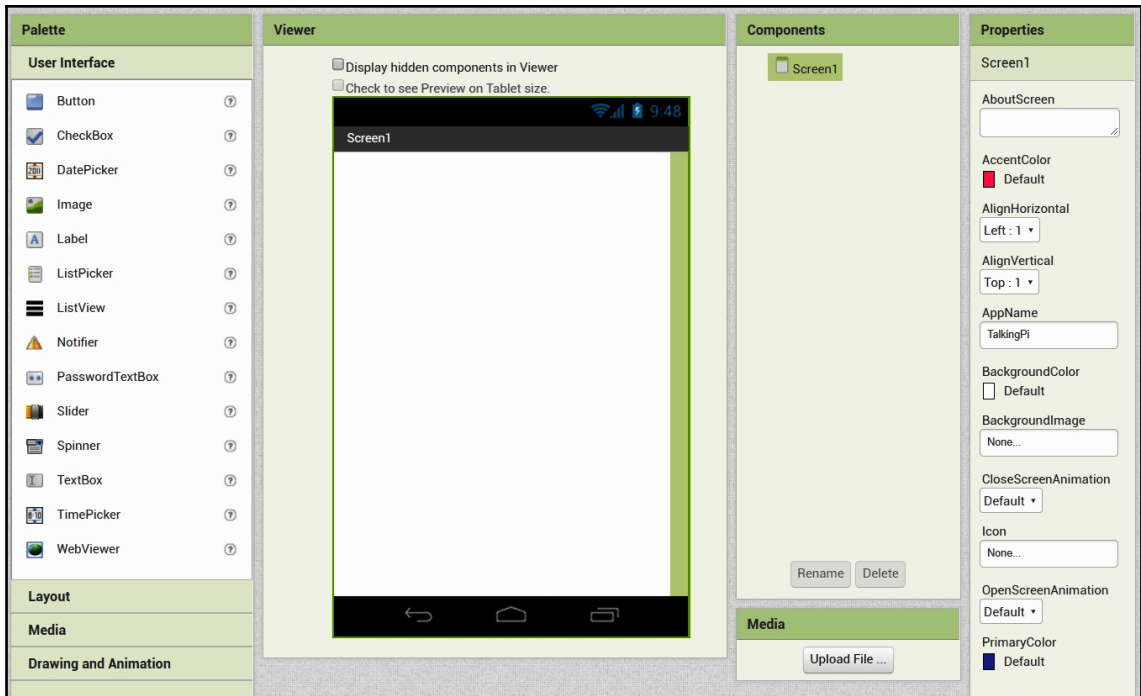


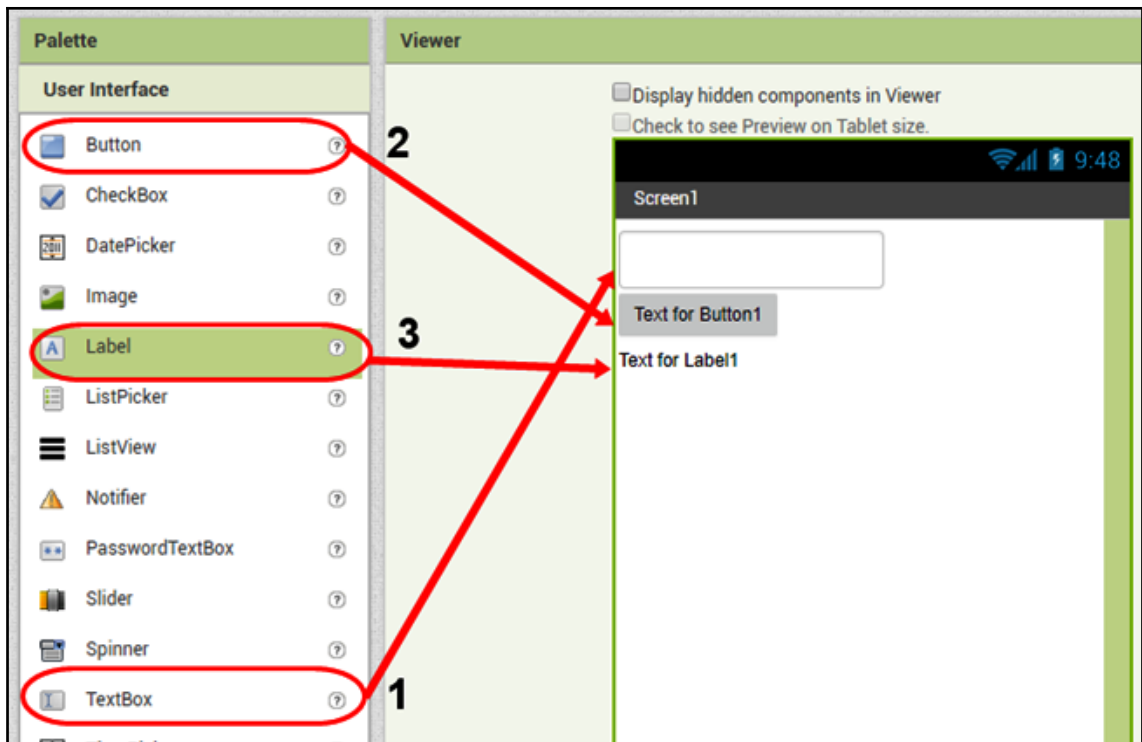
Chapter 9: Building a Voice-Controlled Robot

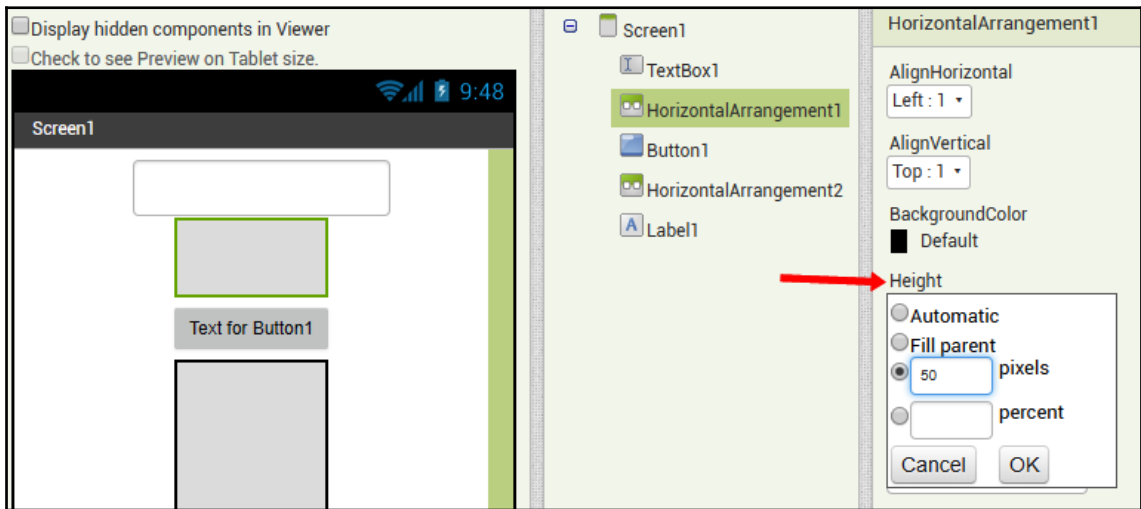
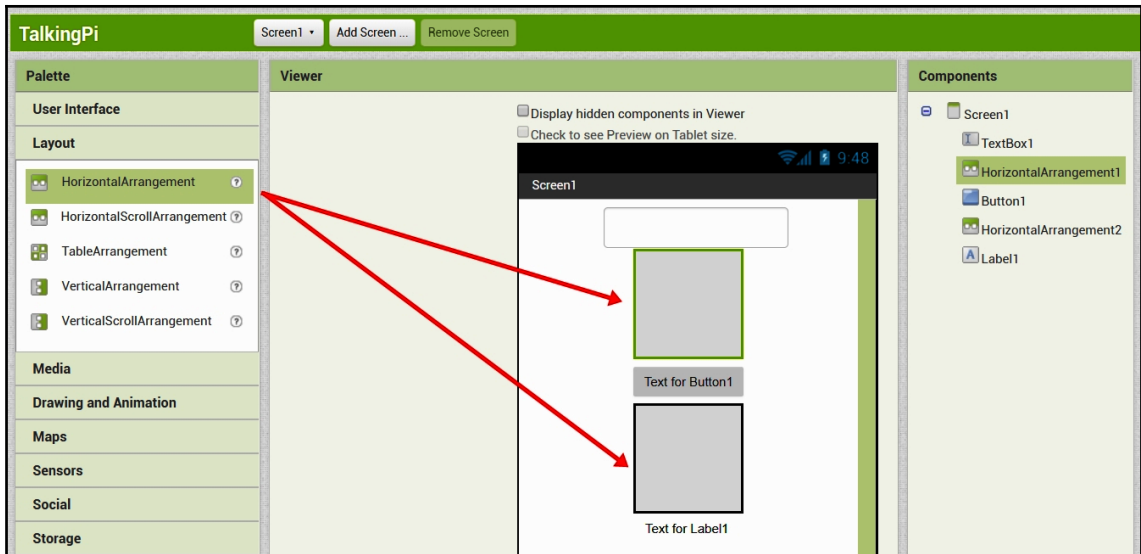


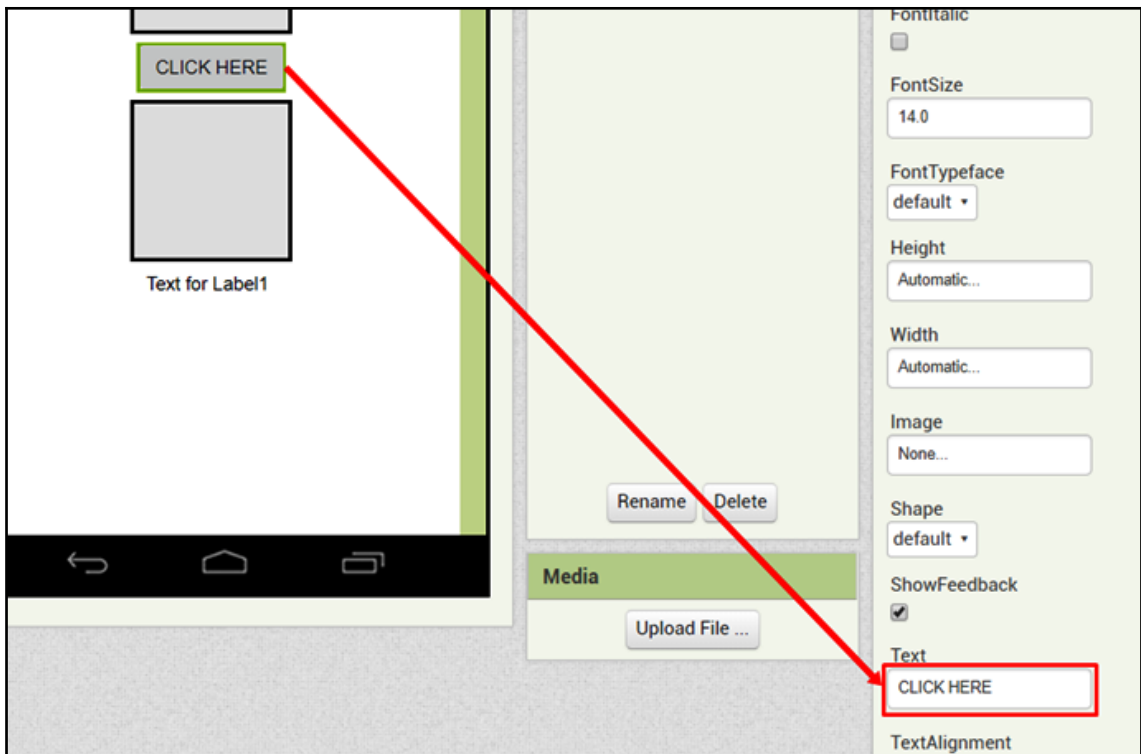


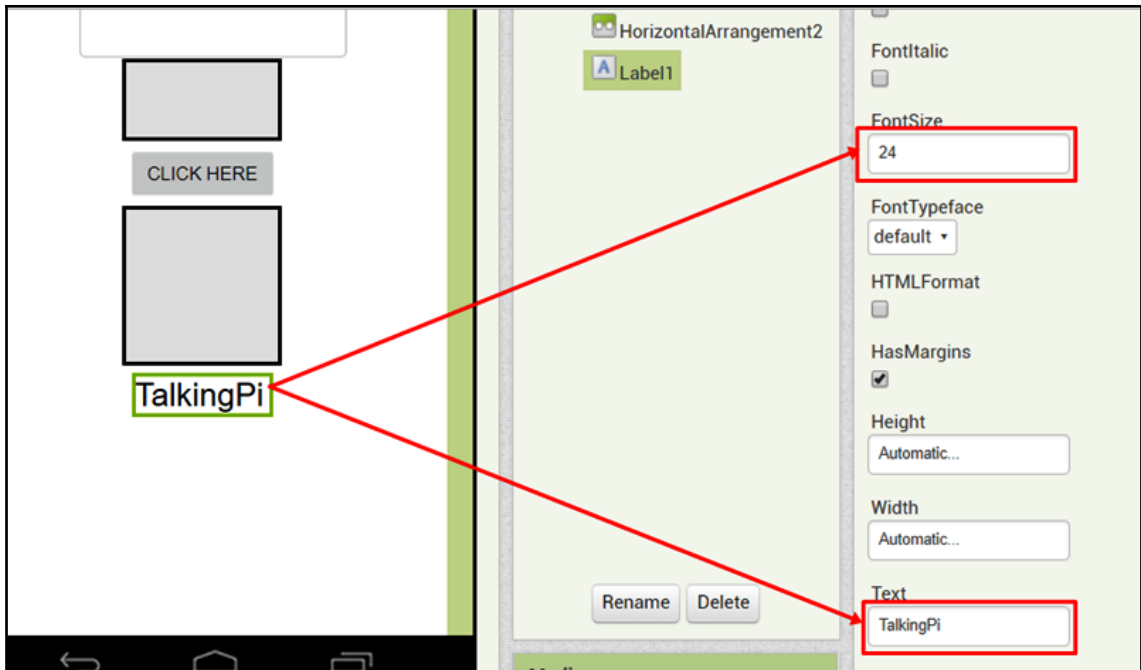


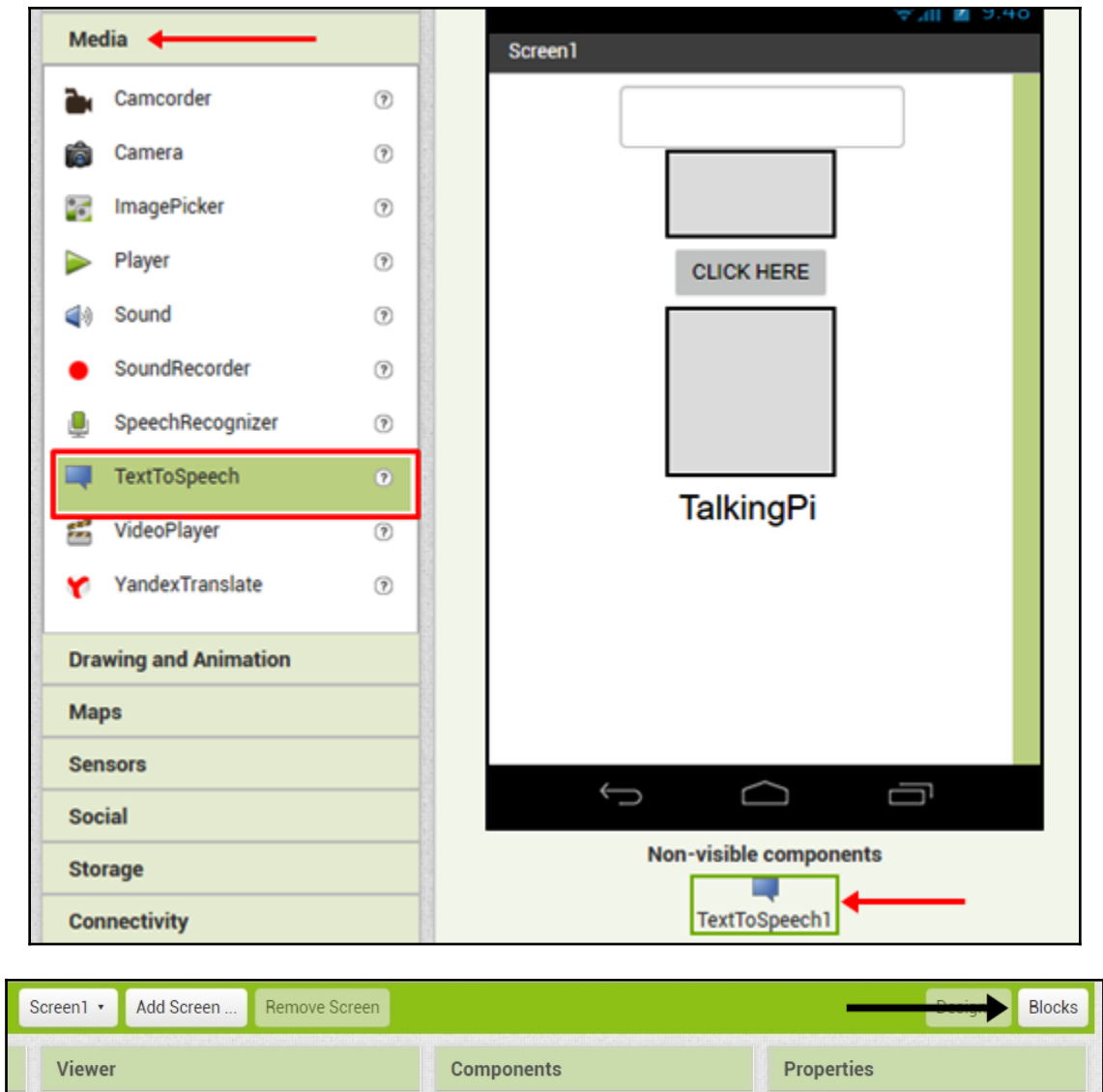


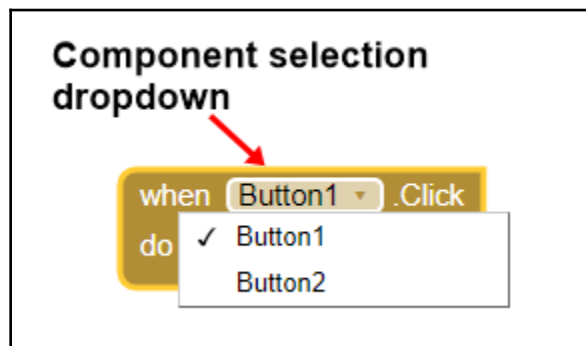
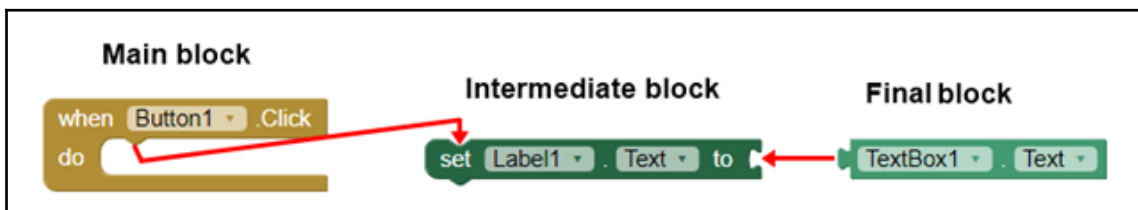
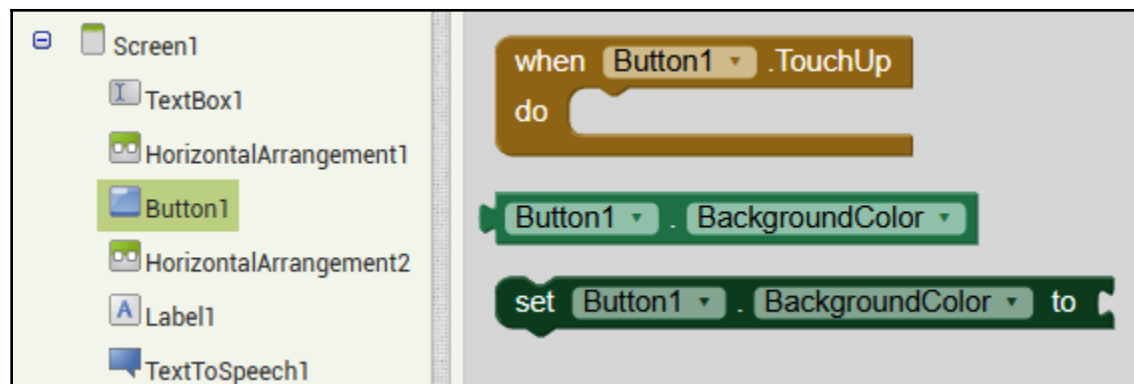


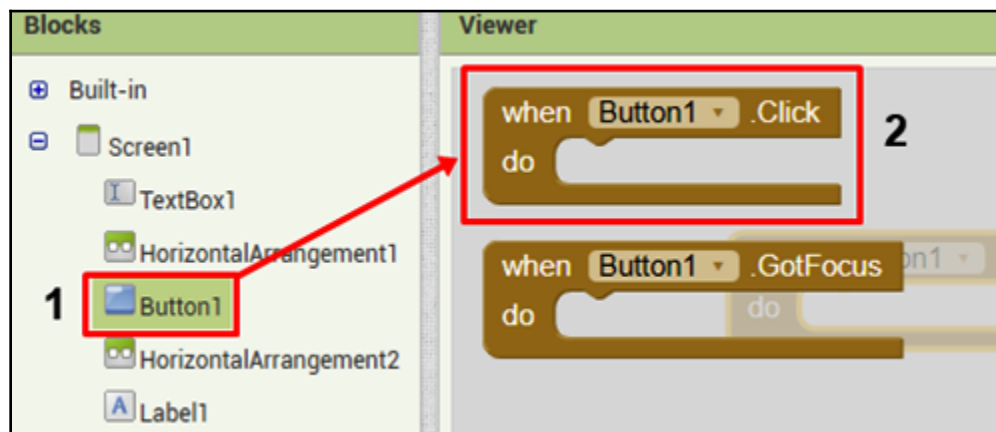
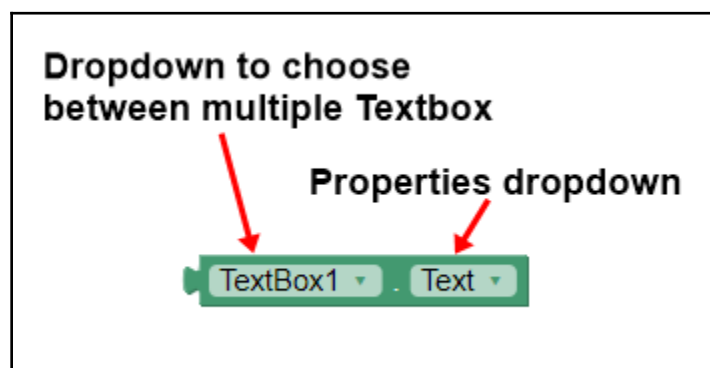
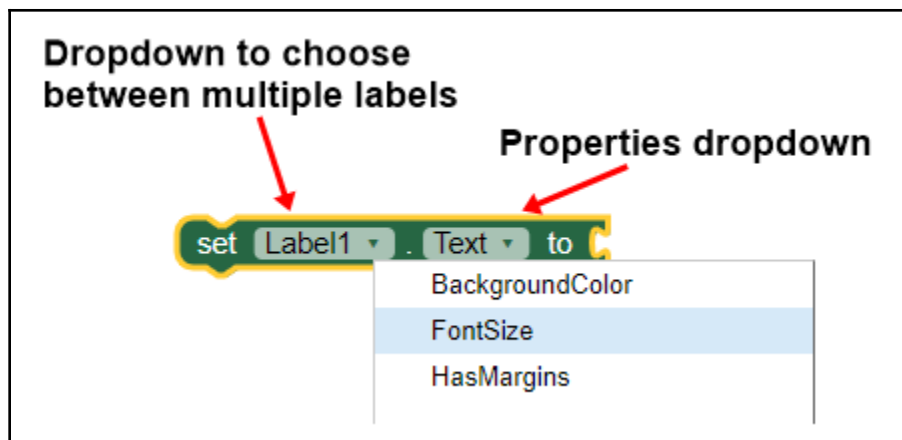


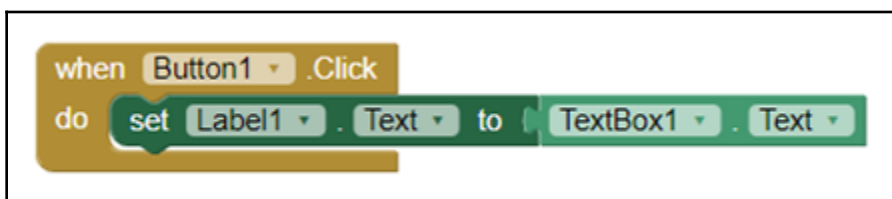
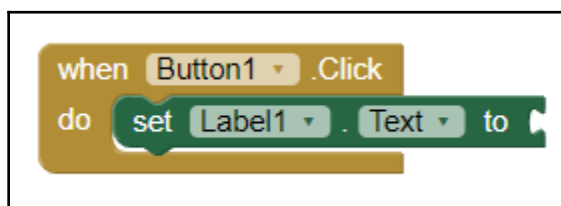


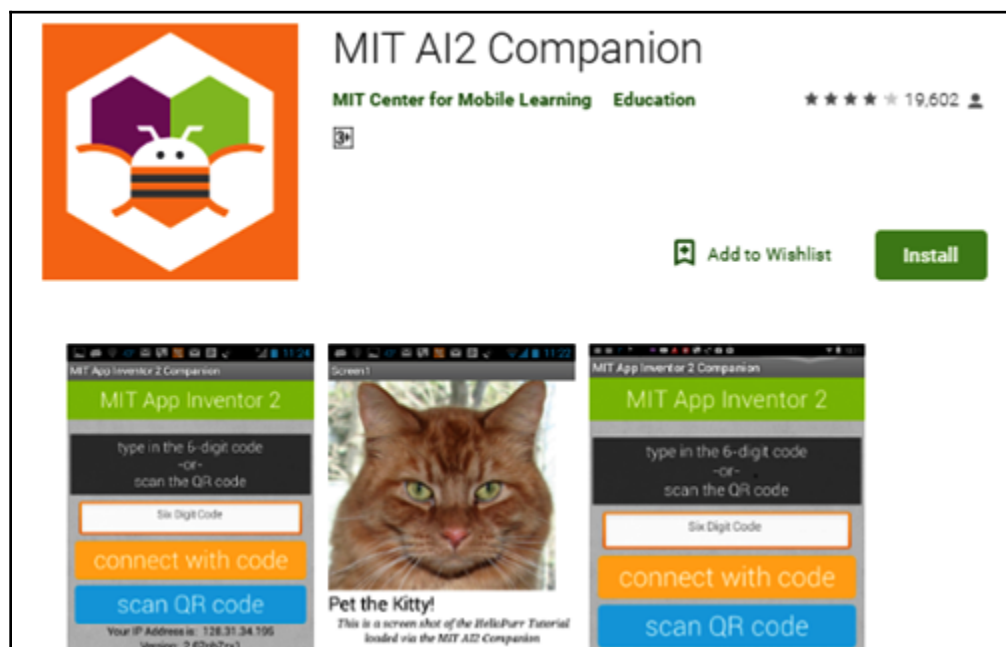
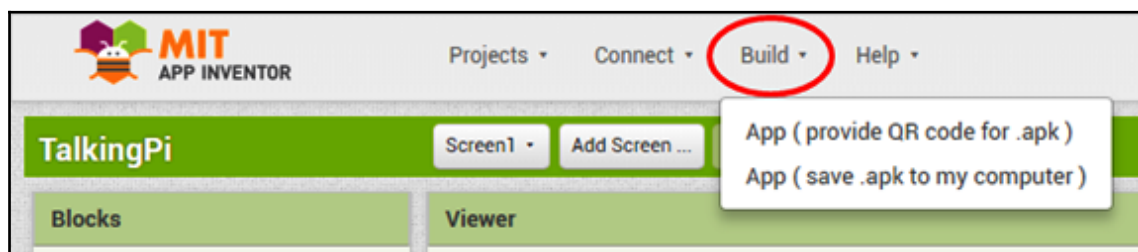
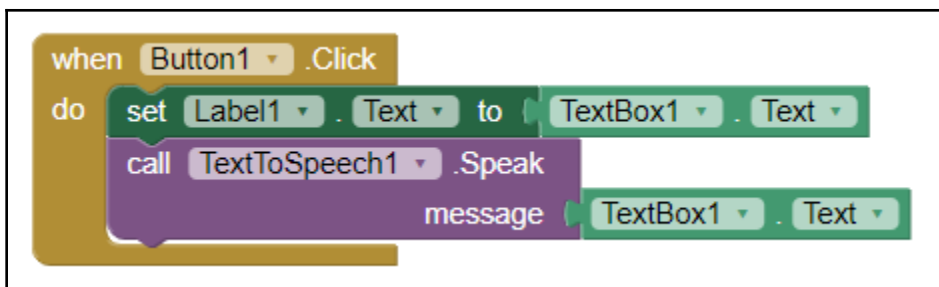


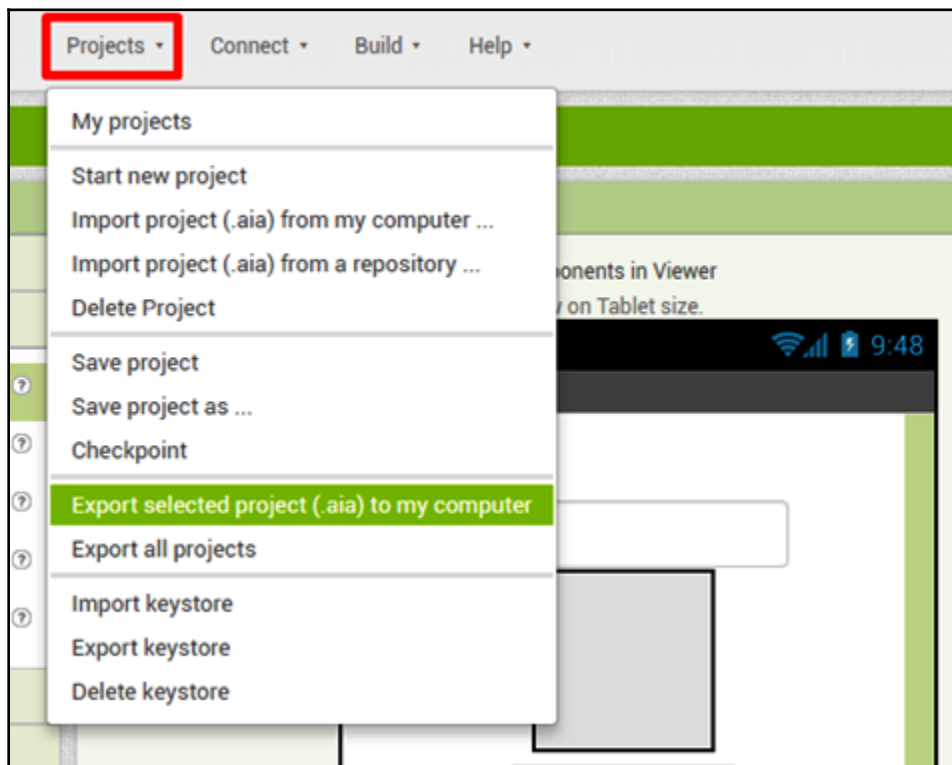
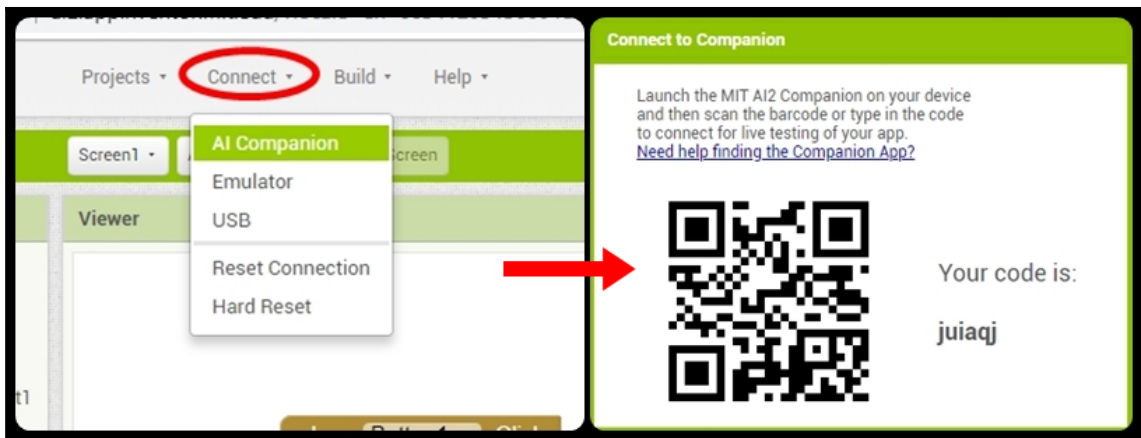


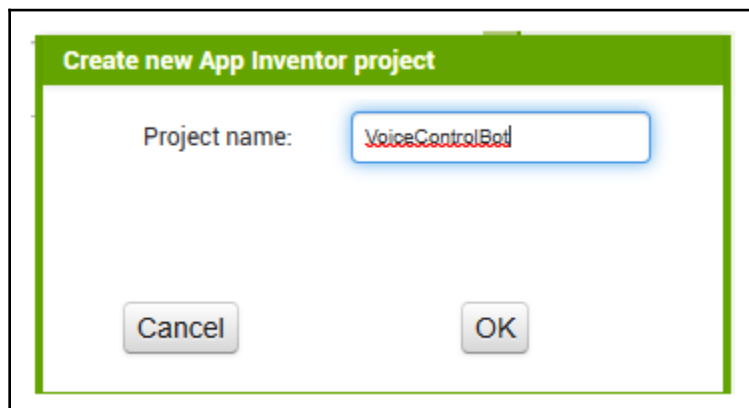
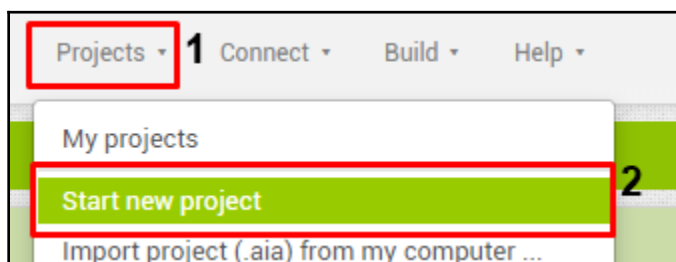
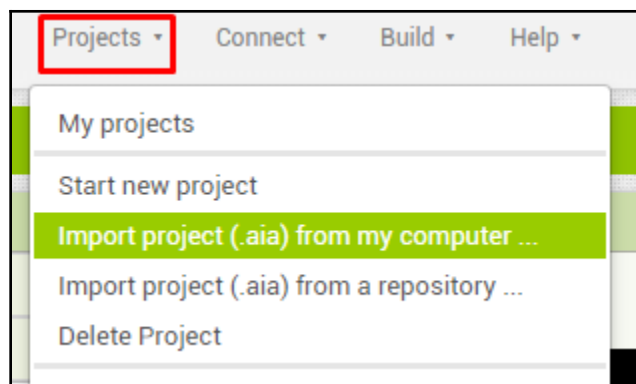


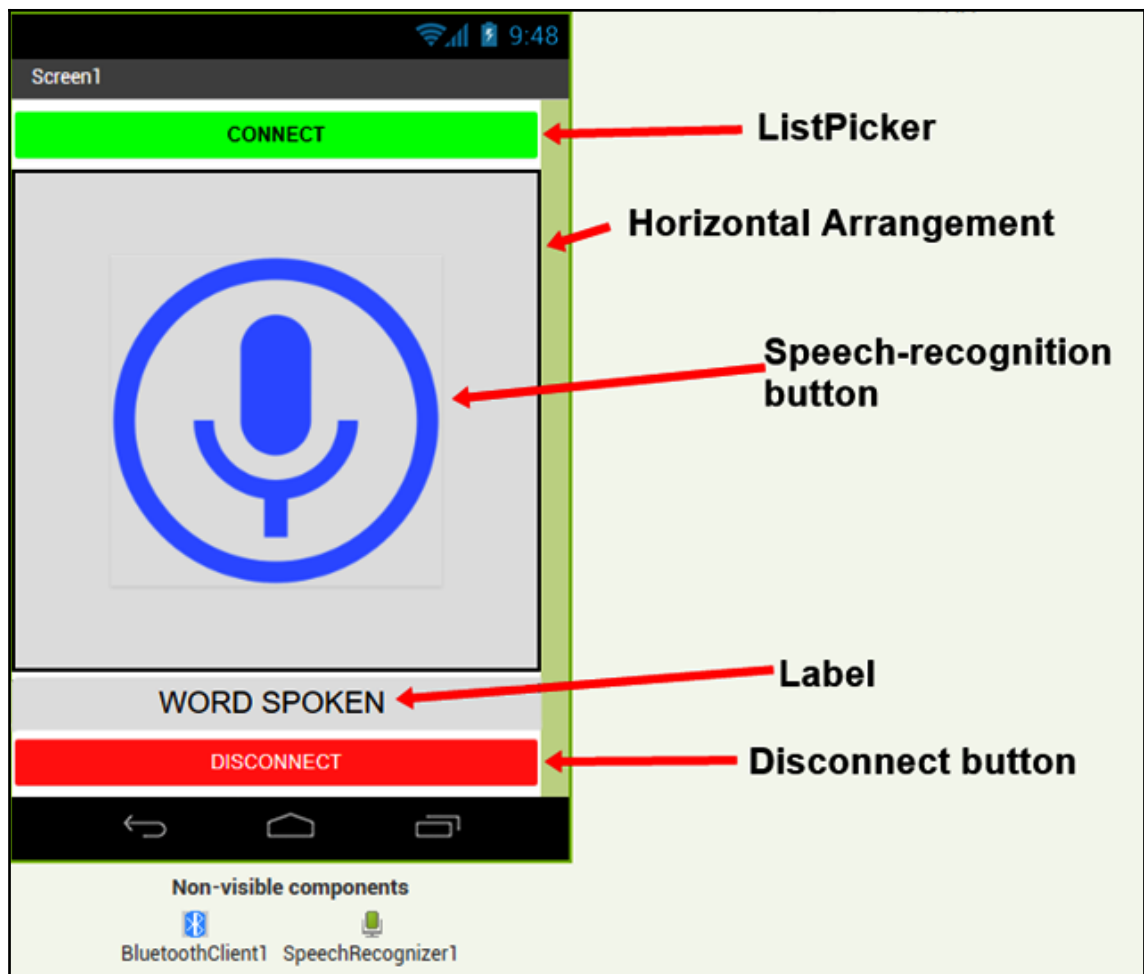


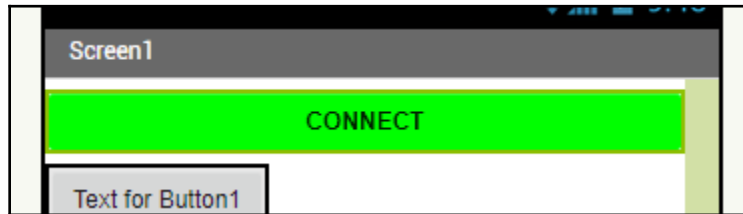
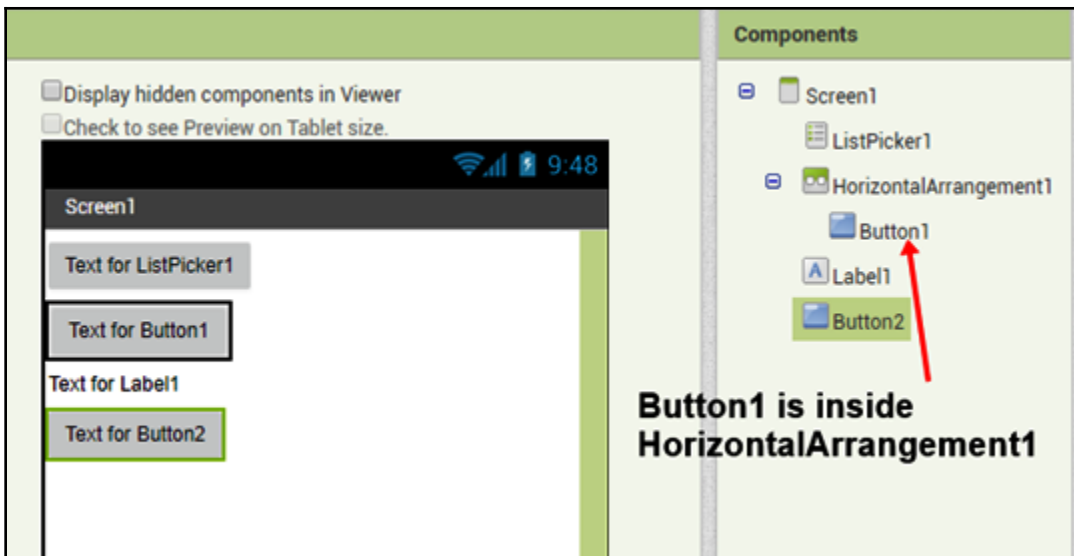


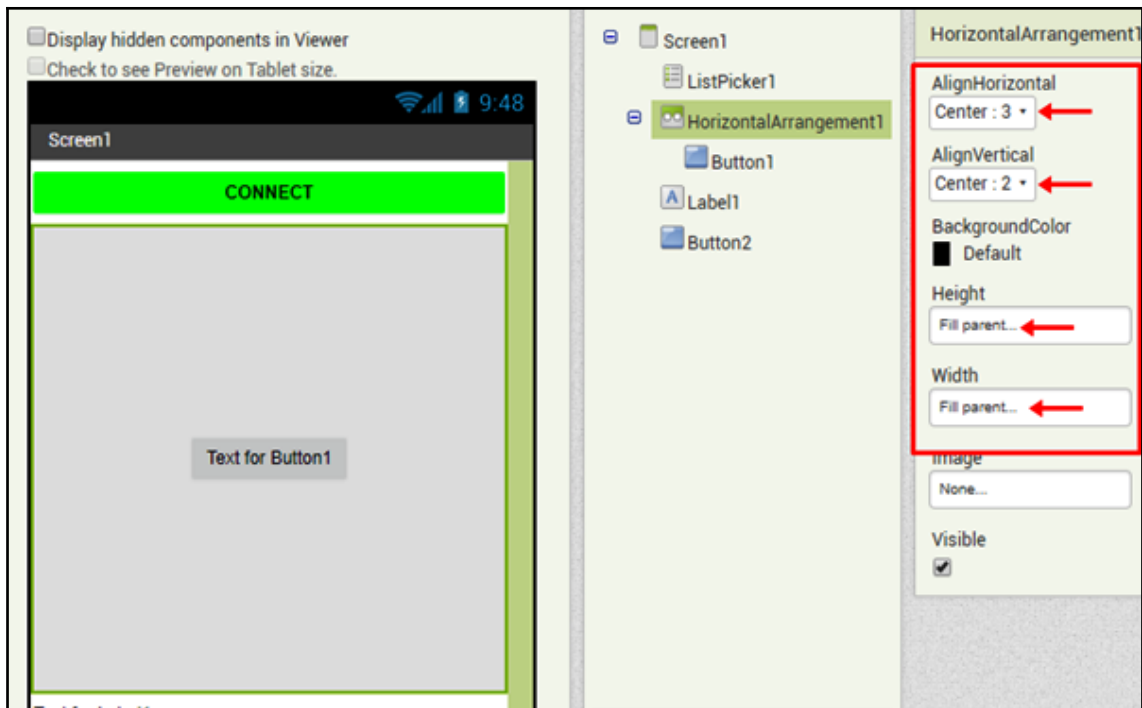


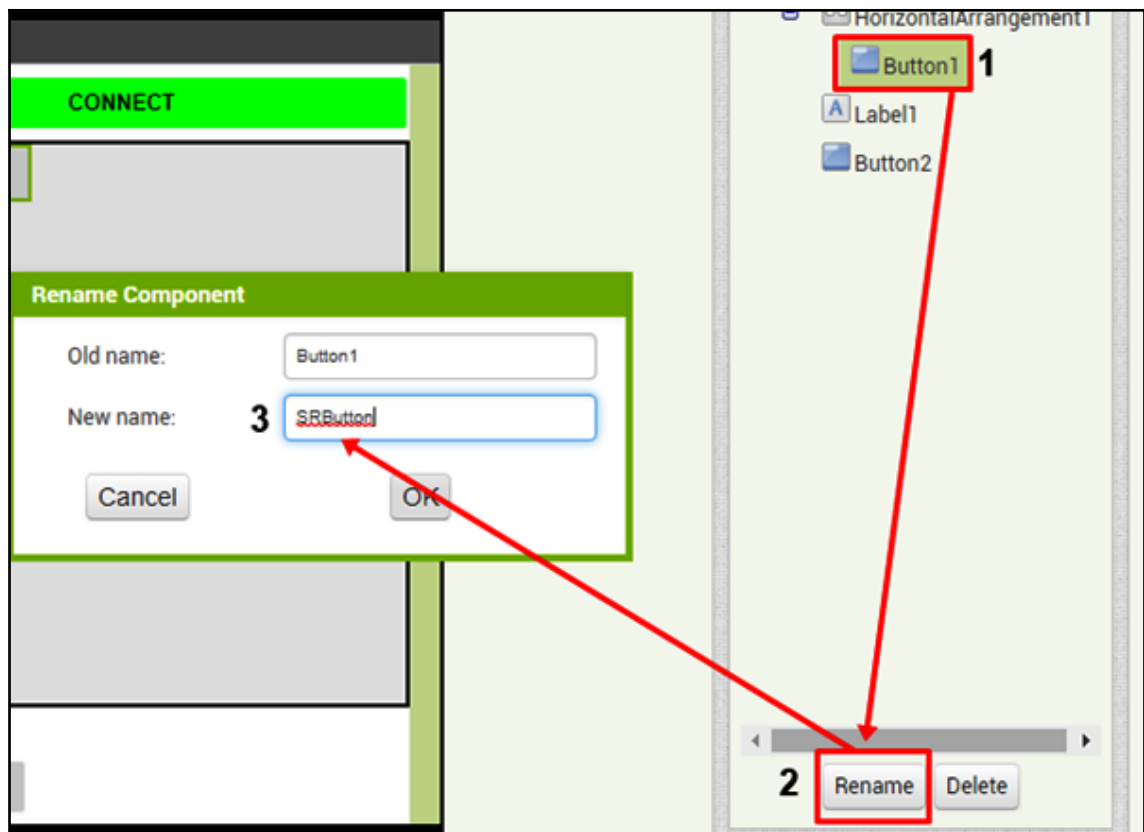


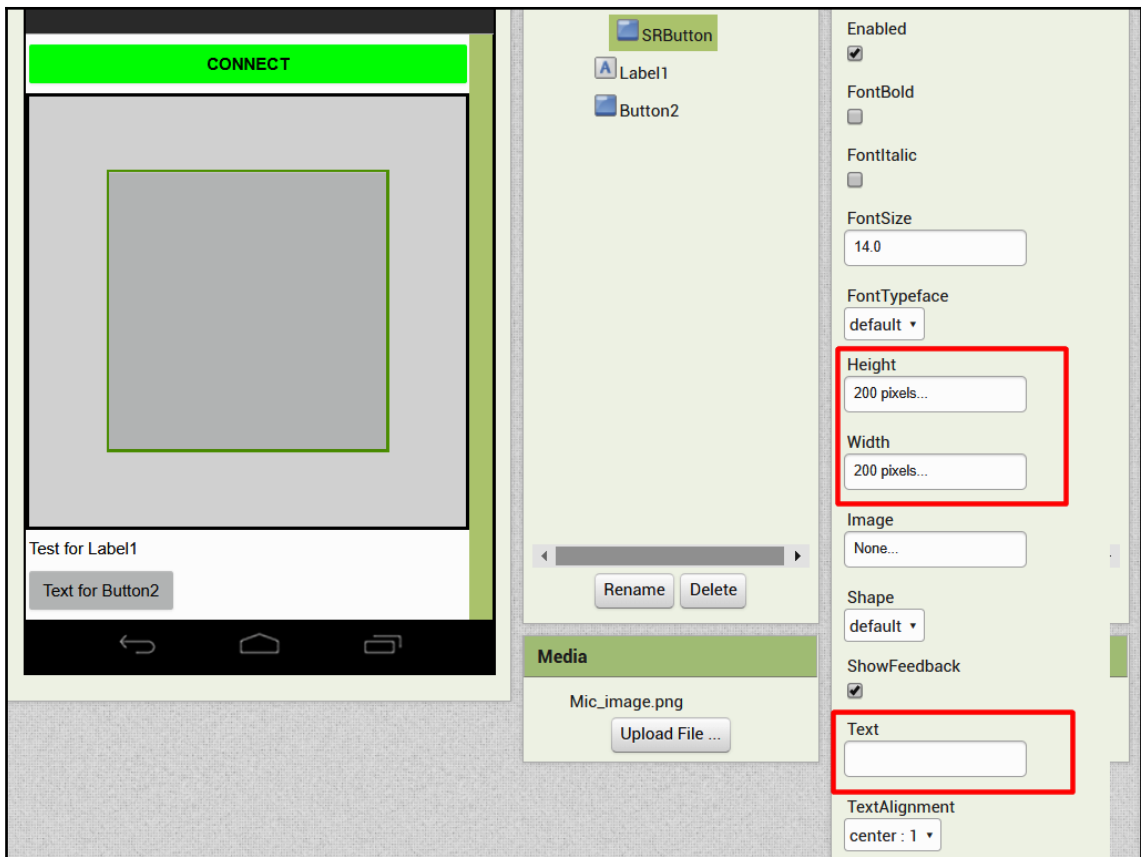


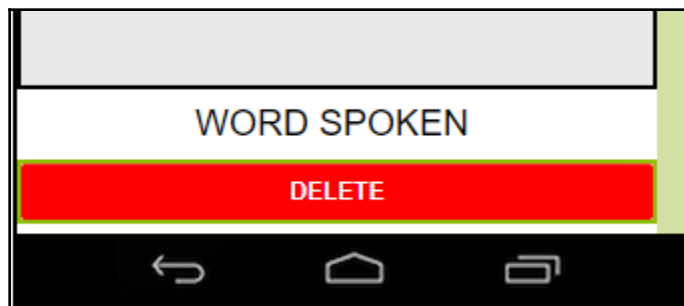
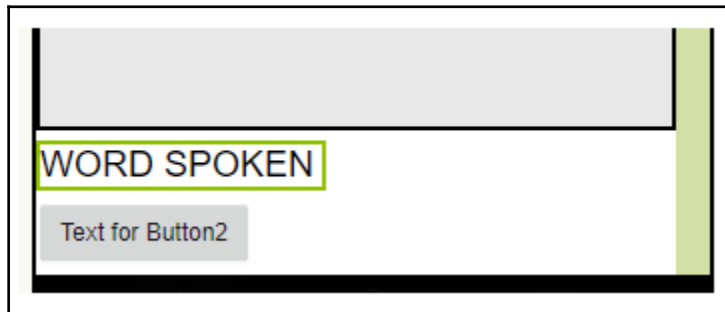


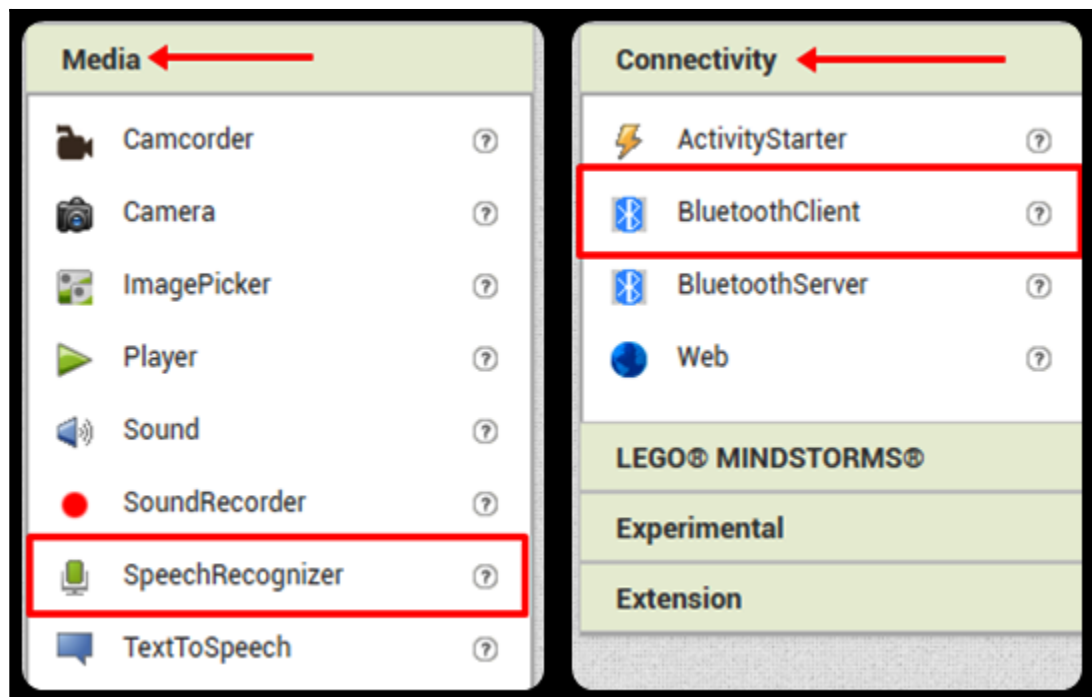


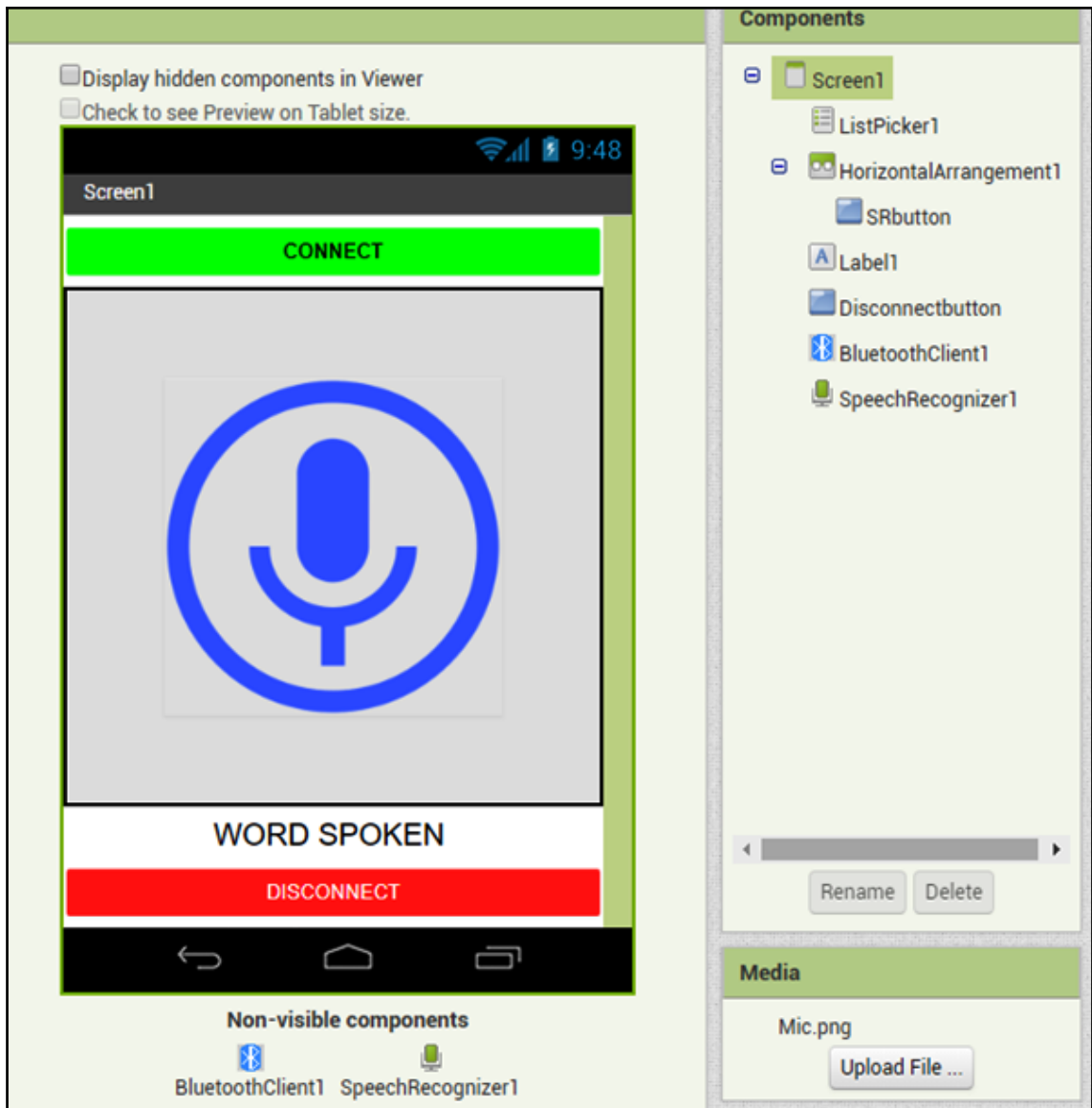




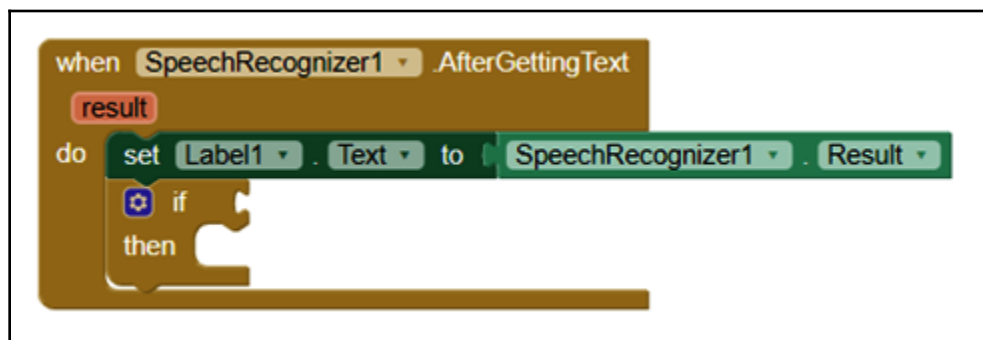
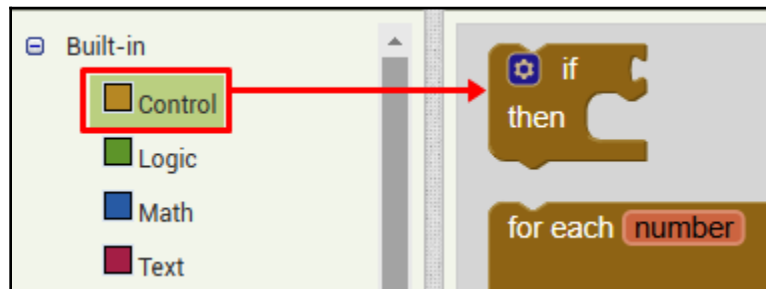
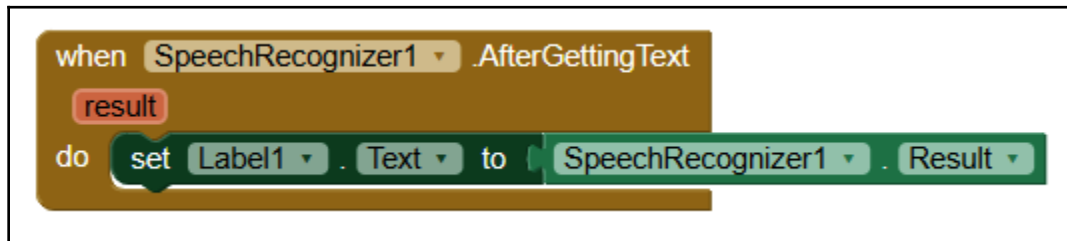
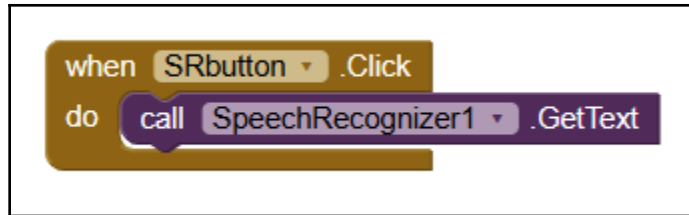
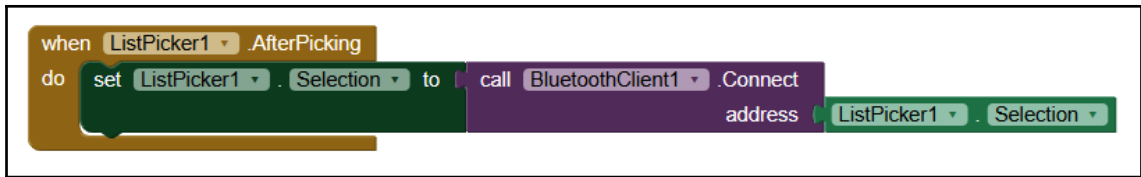


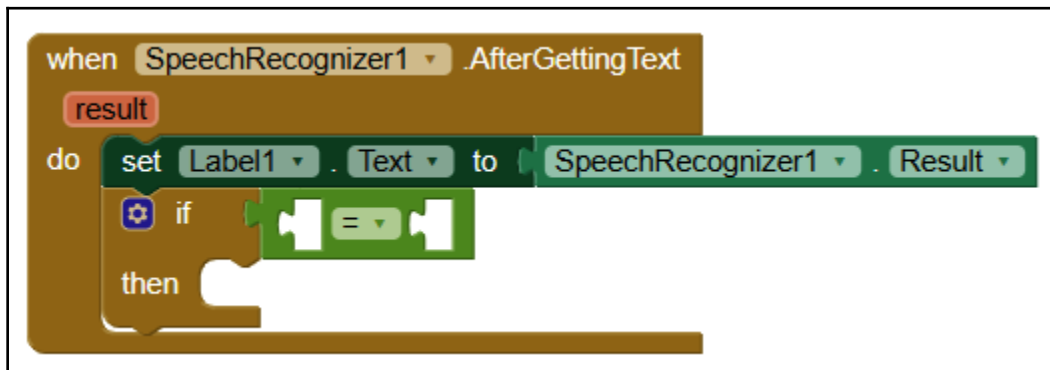
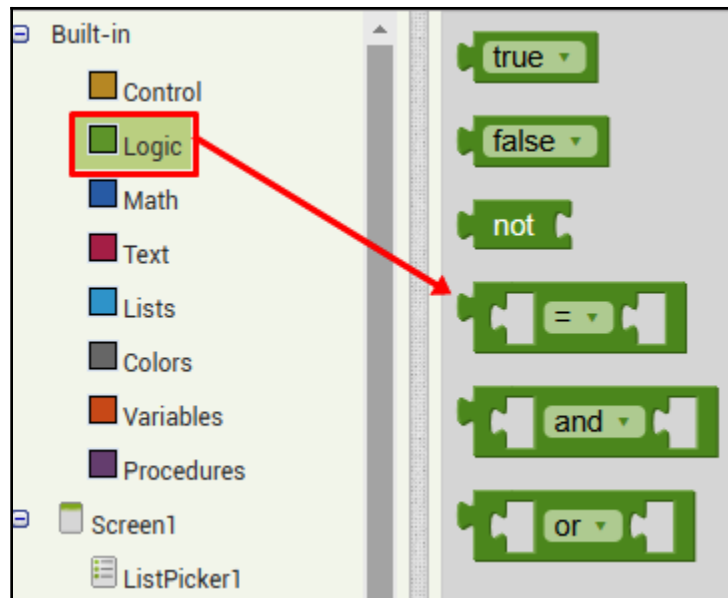


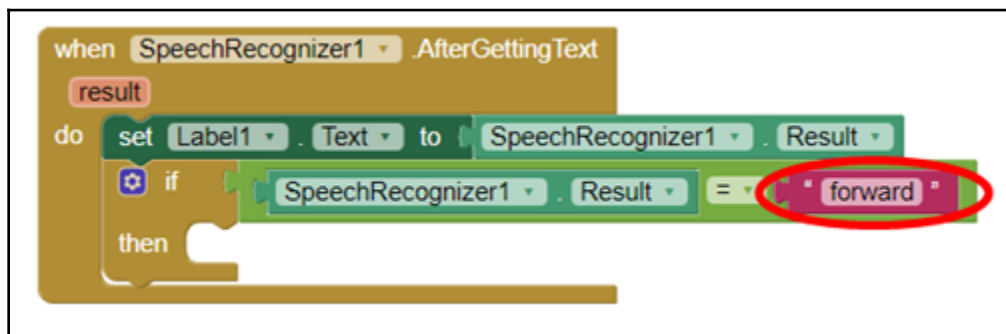
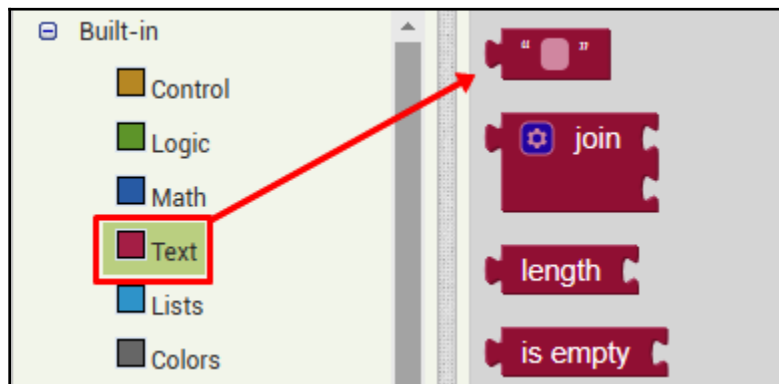
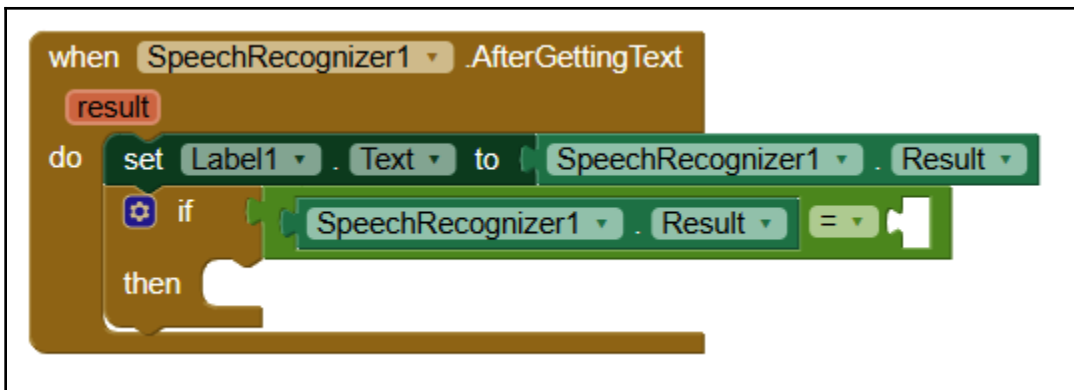


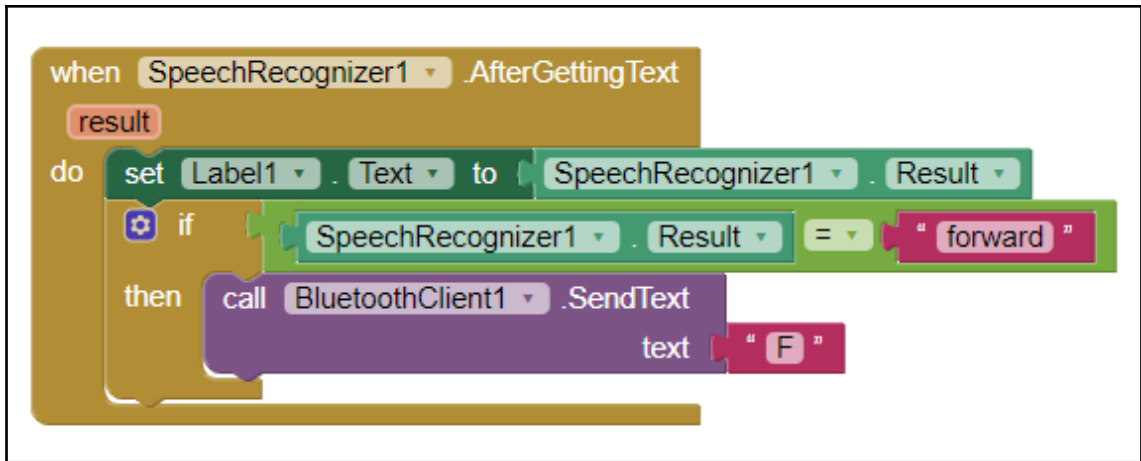


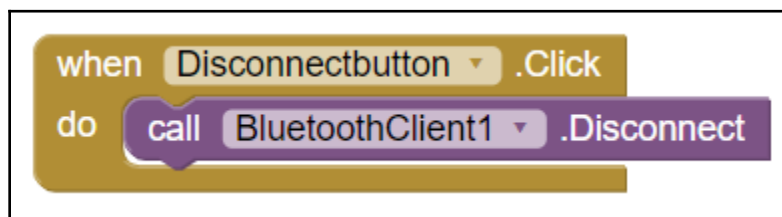
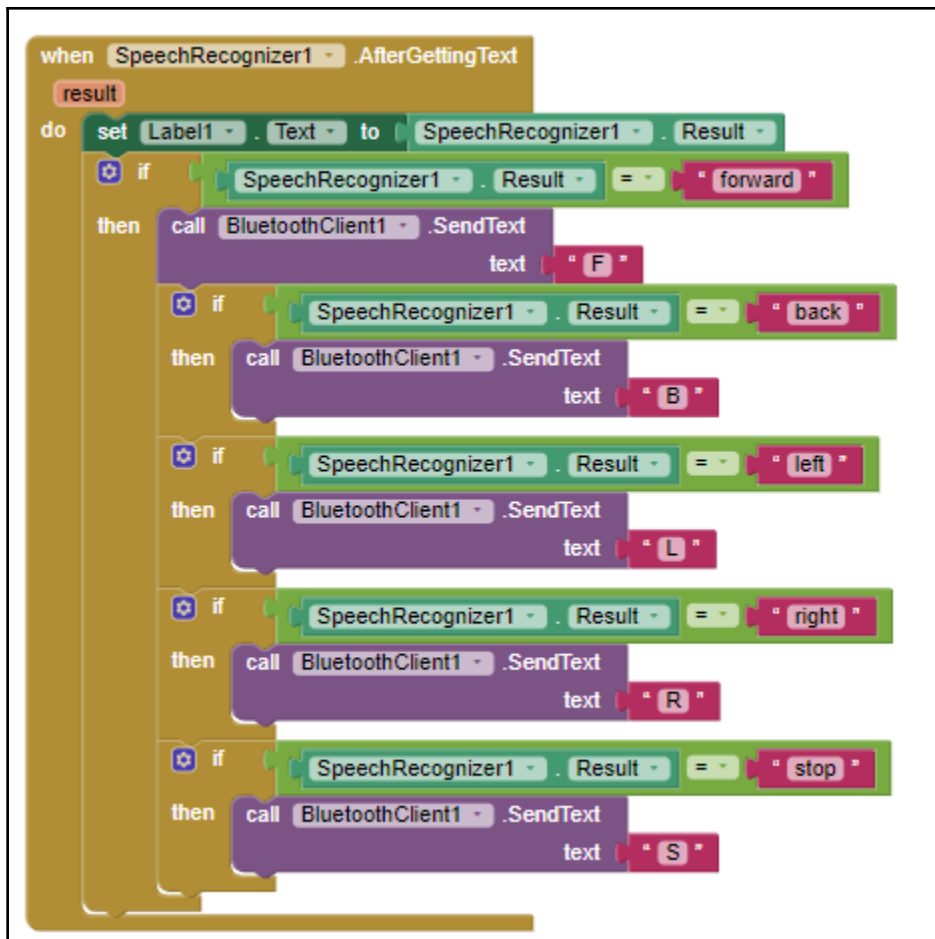
```
when ListPicker1.BeforePicking  
do set ListPicker1.Elements to BluetoothClient1.AddressesAndNames
```











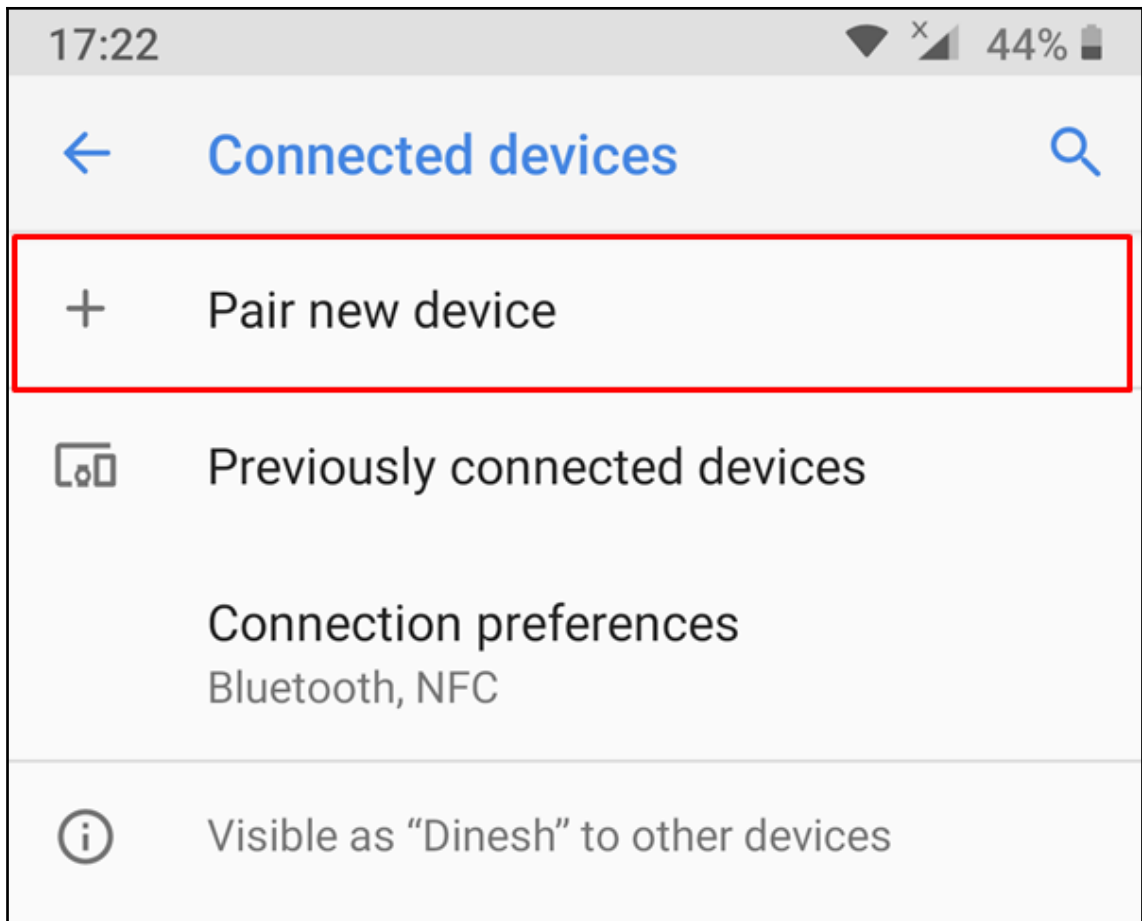
```
pi@raspberrypi: ~  
File Edit Tabs Help  
pi@raspberrypi:~ $ sudo apt-get install libbluetooth-dev  
Reading package  
Building dependency tree  
Reading state information... Done  
libbluetooth-dev is already the newest version (5.43-2+rpt2+deb9u2).  
0 upgraded, 0 newly installed, 0 to remove and 0 not upgraded.  
pi@raspberrypi:~ $
```

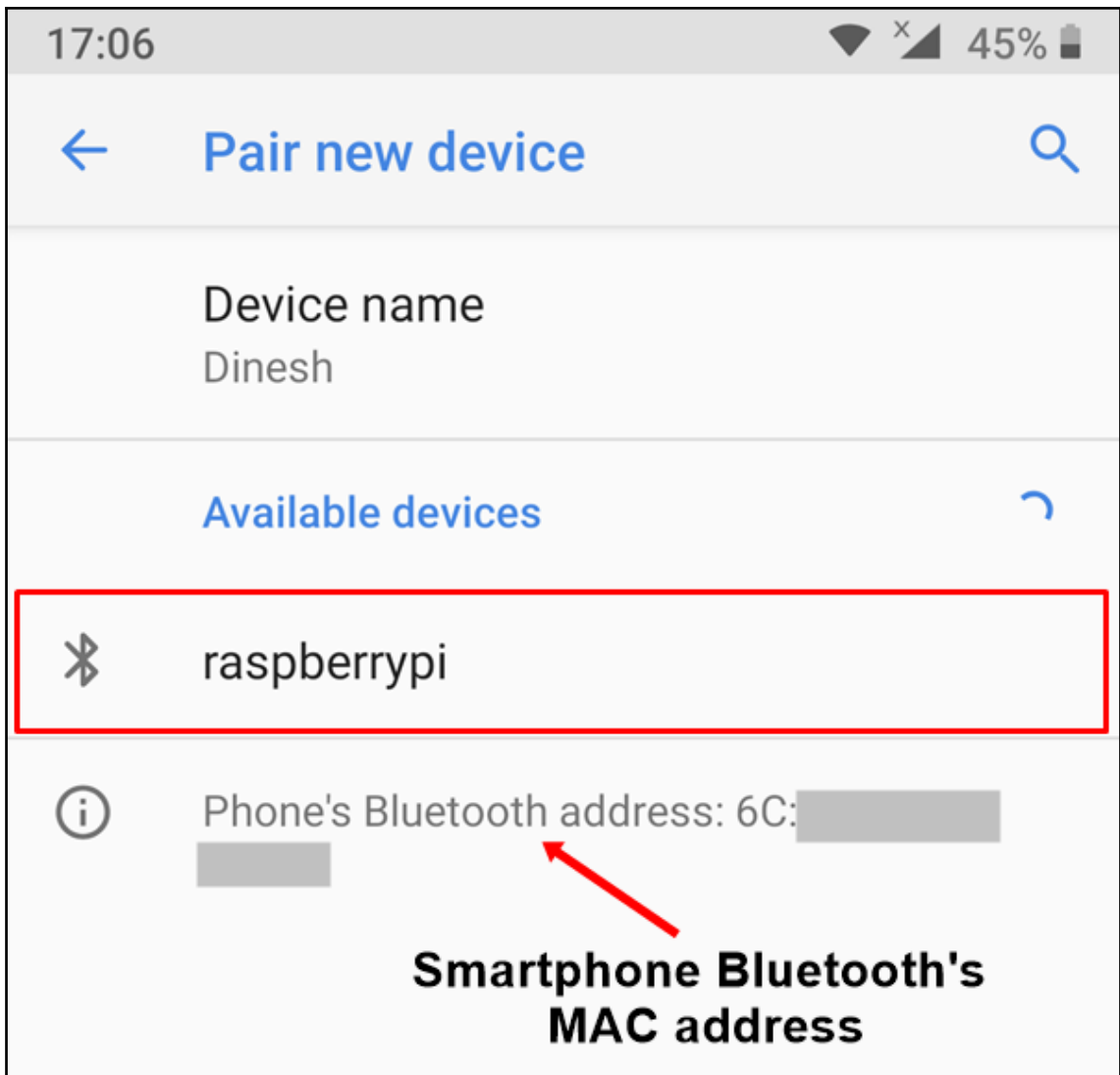
```
GNU nano 2.7.4 File: /lib/systemd/system/bluetooth.service  
[Unit]  
Description=Bluetooth service  
Documentation=man:bluetoothd(8)  
ConditionPathIsDirectory=/sys/class/bluetooth  
[Service]  
Type=dbus  
BusName=org.bluez  
ExecStart=/usr/lib/bluetooth/bluetoothd -C  
NotifyAccess=main  
#WatchdogSec=10  
#Restart=on-failure  
CapabilityBoundingSet=CAP_NET_ADMIN CAP_NET_BIND_SERVICE  
LimitNPROC=1
```

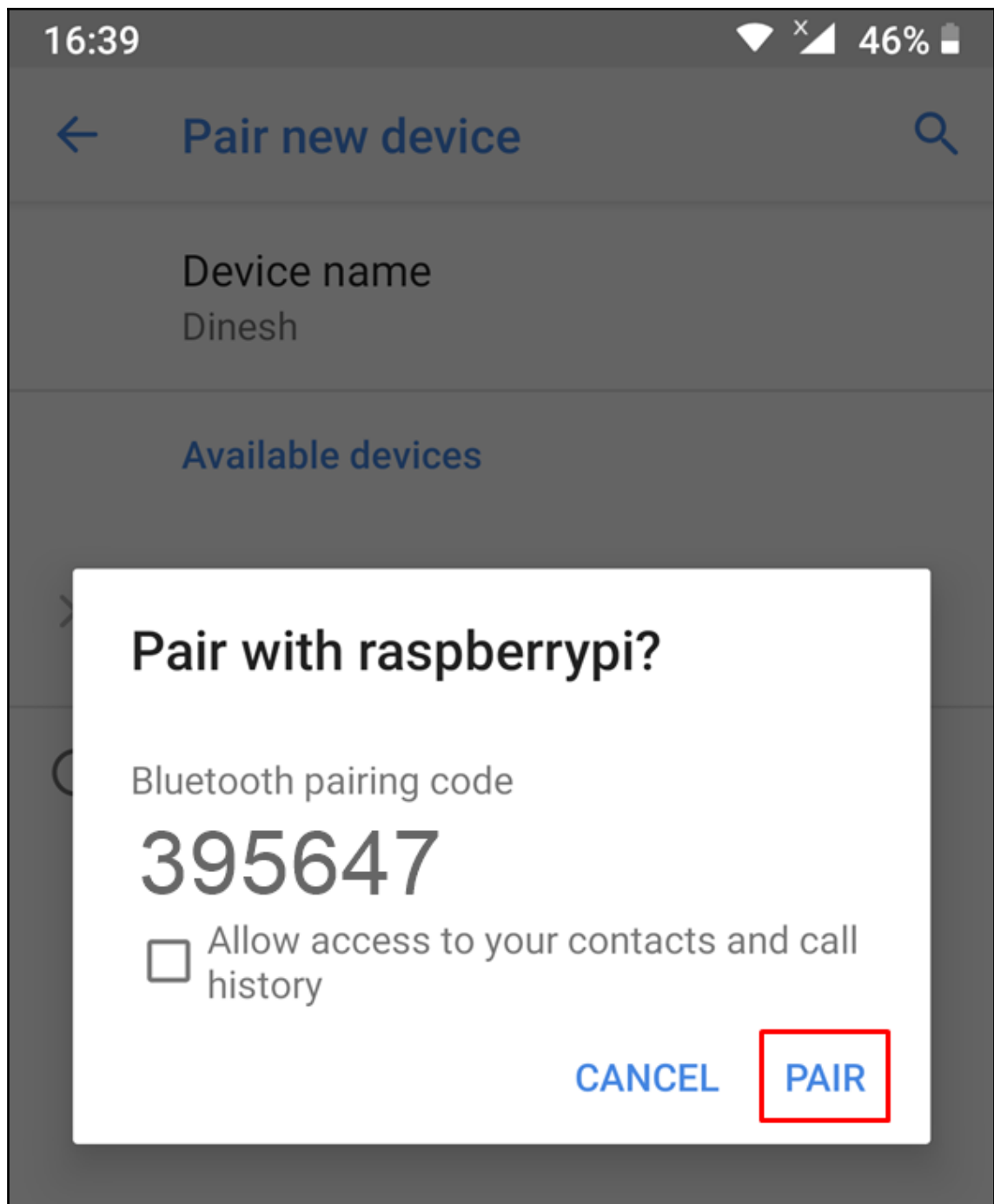
```
pi@raspberrypi: ~  
File Edit Tabs Help  
pi@raspberrypi:~$ sudo service bluetooth status  
• bluetooth.service - Bluetooth service  
  Loaded: loaded (/lib/systemd/system/bluetooth.service; enabled; vendor preset  
  Active: active (running) since Tue 2019-03-19 07:03:23 GMT; 41s ago  
  Docs: man:bluetoothd(8)  
Main PID: 516 (bluetoothd)  
Status: "Running"  
CGroup: /system.slice/bluetooth.service  
        └─516 /usr/lib/bluetooth/bluetoothd -C  
  
Mar 19 07:03:23 raspberrypi systemd[1]: Starting Bluetooth service...  
Mar 19 07:03:23 raspberrypi bluetoothd[516]: Bluetooth daemon 5.43  
Mar 19 07:03:23 raspberrypi systemd[1]: Started Bluetooth service.  
Mar 19 07:03:23 raspberrypi bluetoothd[516]: Starting SDP server  
Mar 19 07:03:23 raspberrypi bluetoothd[516]: Bluetooth management interface 1.14  
Mar 19 07:03:23 raspberrypi bluetoothd[516]: Failed to obtain handles for "Servi  
Mar 19 07:03:24 raspberrypi bluetoothd[516]: Sap driver initialization failed.  
Mar 19 07:03:24 raspberrypi bluetoothd[516]: sap-server: Operation not permitted  
Mar 19 07:03:24 raspberrypi bluetoothd[516]: Endpoint registered: sender=:1.10 p  
Mar 19 07:03:24 raspberrypi bluetoothd[516]: Failed to set privacy: Rejected (0x  
lines 1-19/19 (END)
```

```
pi@raspberrypi: ~  
File Edit Tabs Help  
pi@raspberrypi:~$ sudo bluetoothctl  
[NEW] Controller [redacted] raspberrypi [default]  
[bluetooth]#
```

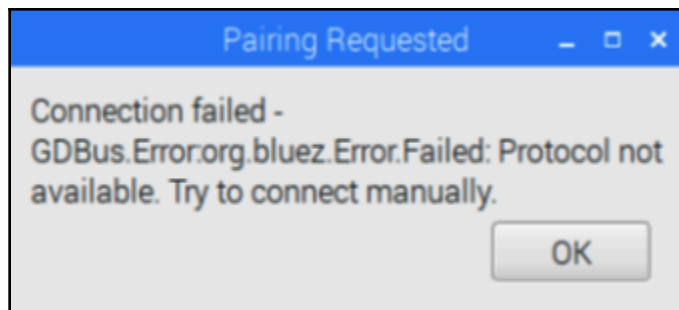
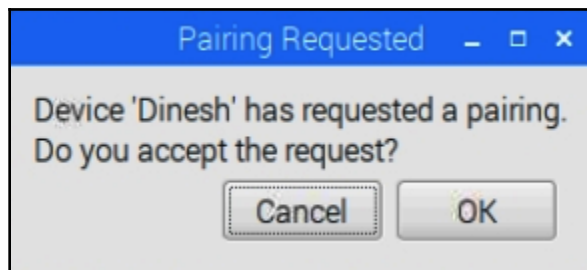
Bluetooth MAC address **Bluetooth name**



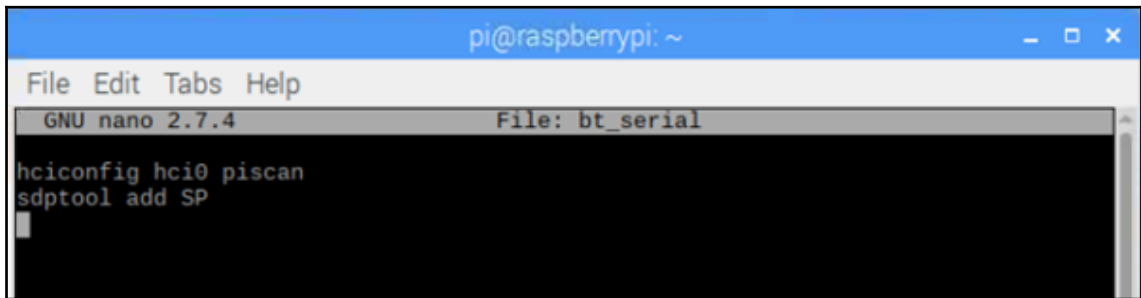




```
pi@raspberrypi: ~  
File Edit Tabs Help  
pi@raspberrypi:~$ sudo bluetoothctl  
[NEW] Controller B8:27:EB:53:8D:87 raspberrypi [default]  
[NEW] Device 00:E0:4C:74:AB:C9 00-E0-4C-74-AB-C9  
[bluetooth]# power on  
Changing power on succeeded  
[bluetooth]# pairable on  
Changing pairable on succeeded  
[bluetooth]# discoverable on  
Changing discoverable on succeeded  
[CHG] Controller B8:27:EB:53:8D:87 Discoverable: yes  
[bluetooth]# agent on  
Agent registered  
[bluetooth]# default-agent  
Default agent request successful  
[NEW] Device 6C:C4:D5:5C:97:1D Dinesh  
Request confirmation  
[agent] Confirm passkey 395647 (yes/no): yes
```

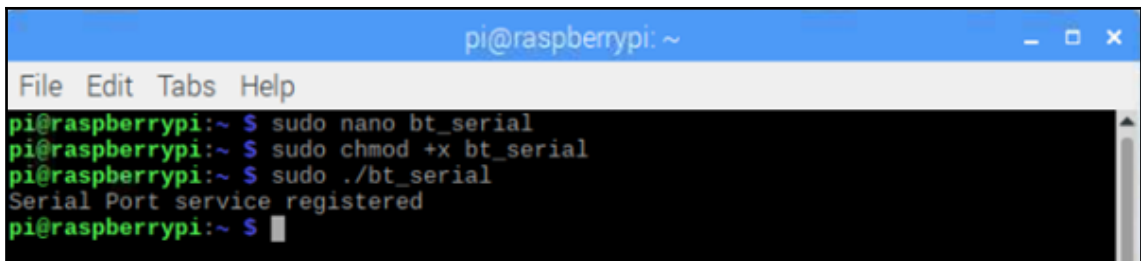


```
[bluetooth]# exit
Agent unregistered
[DEL] Controller B8:27:EB:BE:D3:C0 raspberrypi [default]
pi@raspberrypi:~ $ sudo bluetoothctl
[NEW] Controller B8:27:EB:BE:D3:C0 raspberrypi [default]
[NEW] Device 6C:00:00:00:00:00 Dinesh
[bluetooth]#
```



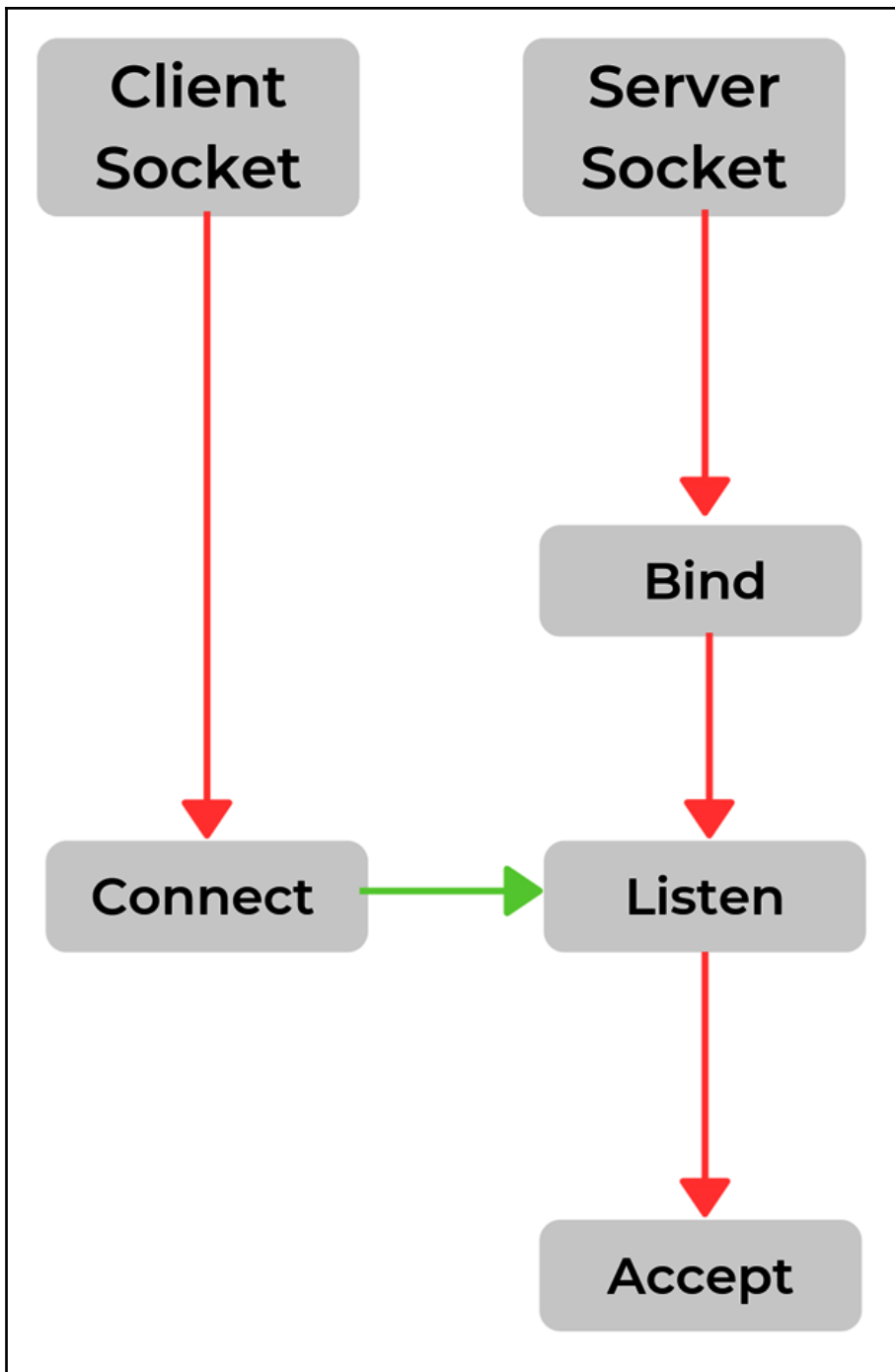
A terminal window titled "pi@raspberrypi: ~" with a menu bar "File Edit Tabs Help". The window shows the GNU nano 2.7.4 editor editing a file named "bt_serial". The content of the file is:

```
hciconfig hci0 piscan
sdptool add SP
```

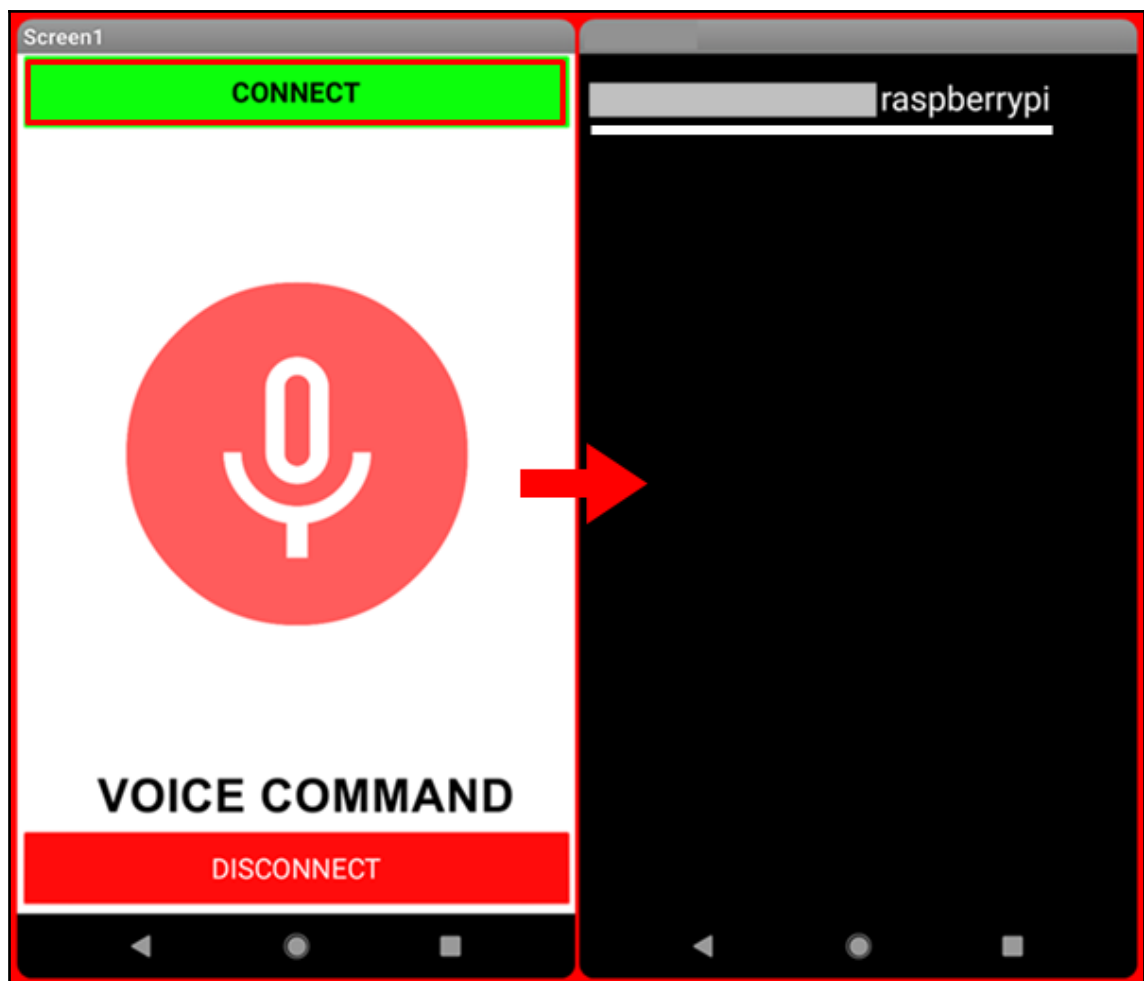


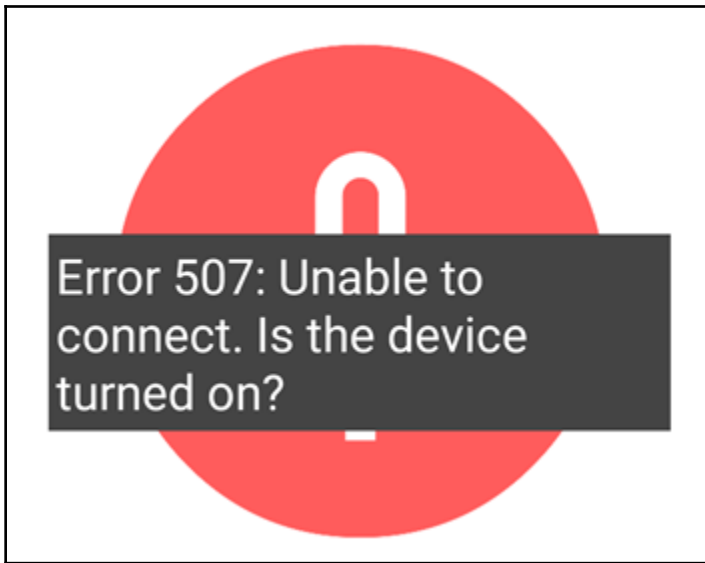
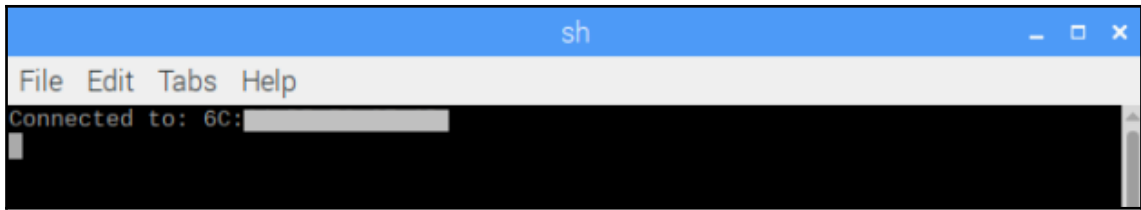
A terminal window titled "pi@raspberrypi: ~" showing the execution of several commands:

```
pi@raspberrypi:~ $ sudo nano bt_serial
pi@raspberrypi:~ $ sudo chmod +x bt_serial
pi@raspberrypi:~ $ sudo ./bt_serial
Serial Port service registered
pi@raspberrypi:~ $
```



Set Build Commands				
#	Label	Command	Working directory	Reset
C commands				
1.	Compile	%f" -lblueetooth -lwiringPi		
2.	Build	%f" -lblueetooth -lwiringPi		
3.	Lint	cppcheck --language=c		





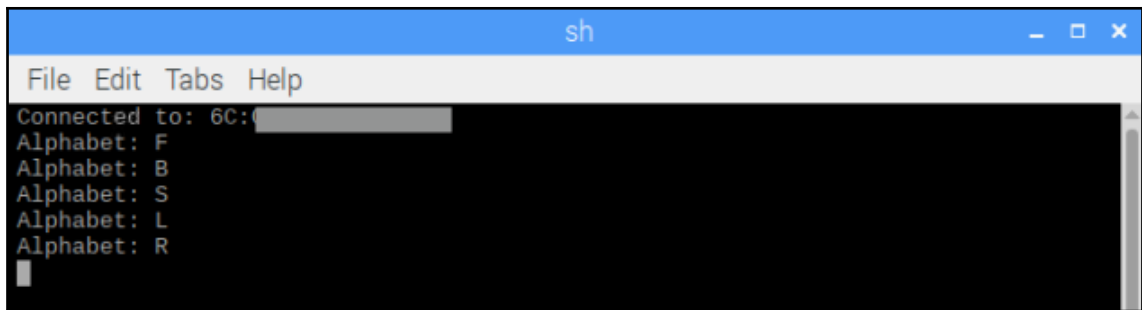
Screen1

CONNECT



forward

DISCONNECT



A screenshot of a terminal window with a blue title bar labeled 'sh'. The window has a menu bar with 'File', 'Edit', 'Tabs', and 'Help'. The terminal content shows a connection status 'Connected to: 6C:0' followed by a list of characters: 'Alphabet: F', 'Alphabet: B', 'Alphabet: S', 'Alphabet: L', and 'Alphabet: R'. A cursor is visible on the line following the last entry.

```
Connected to: 6C:0
Alphabet: F
Alphabet: B
Alphabet: S
Alphabet: L
Alphabet: R

```